

DIGITAL SIGNAL PROCESSING AND ITS APPLICATIONS

PROF. VIKRAM M. GADRE Department of Electrical Engineering IIT Bombay

PRE-REQUISITES : It would help if they have an exposure to Signals and Systems, although this is not a

strict pre-requisite

INTENDED AUDIENCE: Third Year Undergraduates/ First Year Graduate (Masters Students) INDUSTRIES APPLICABLE TO: Texas Instruments, Analog Devices, Samsung, almost any industry which works in communication and signal processing would value this training, as a core discipline. **INDUSTRIES SUPPORT:** Texas Instruments, Analog Devices, Samsung, almost any industry which works in communication and signal processing would value this training, as a core discipline.

COURSE OUTLINE:

The course begins with a discussion on Discrete Time signals and systems. This is followed by an introduction of the Z transform, its properties and system theoretic implications. The foundations of digital filter design and realization are built up. Practice Problems with solutions, summaries of each lecture and illustrative explanations of concepts are all additionally provided, to enhance learning.

ABOUT INSTRUCTOR :

Prof. Vikram M. Gadre completed his B.Tech in 1989 from Electrical Engineering (CGPA 9.90 on scale of 10), Indian Institute of Technology, Delhi and Ph.D in 1994 from from Electrical Engineering, Indian Institute of Technology, Delhi. His research interests are Communication and signal processing, with emphasis on multiresolution and multirate signal processing, especially wavelets and filter banks: theory and applications

COURSE PLAN :

Week 1:	Lecture 1: Introduction: Digital signal processing and its objectives
	Lecture 2A: Introduction to sampling and Fourier Transform
	Lecture 2B: Sampling of sine wave and associate complication
	Lecture 3A: Review of Sampling Theorem
	Lecture 3B: Idealized Sampling, Reconstruction
	Lecture 3C: Filters And Discrete System
Week 2:	Lecture 4A: Answering questions from previous lectures.
	Lecture 4B: Desired requirements for discrete system
	Lecture 4C: Introduction to phasors
	Lecture 4D: Advantages of phasors in discrete systems
	Lecture 5A: What do we want from a discrete system?
	Lecture 5B: Linearity - Homogeneity and Additivity
	Lecture 5C: Shift Invariance and Characterization of LTI systems
	Lecture 6A: Characterization of LSI system using it's impulse response
	Lecture 6B: Introduction to convolution
	Lecture 6C: Convolution: deeper ideas and understanding
Week 3:	Lecture 7A: Characterisation of LSI systems, Convolution-properties
	Lecture 7B: Response of LSI systems to complex sinusoids
	Lecture 7C: Convergence of convolution and BIBO stability
	Lecture 8A: Commutativity & Associativity
	Lecture 8B: BIBO Stability of an LSI system
	Lecture 8C: Causality and memory of an LSI system.
	Lecture 8D: Frequency response of an LSI system.
	Lecture 9A: Introduction and conditions of Stability
	Lecture 9B: Vectors and Inner Product.
	Lecture 9C: Interpretation of frequency Response as Dot Product
	Lecture 9D: Interpretation of Frequency Response as Eigenvalues

Week 4: Lecture 10A: Discrete time fourier transform

Lecture 10B: DTFT in LSI System and Convolution Theorem.

Lecture 10C: Definitions of sequences and Properties of DTFT.

Lecture 11A: Introduction to DTFT, IDTFT

Lecture 11B: Dual to convolution property

Lecture 11C: Multiplication Property, Introduction to Parseval's theorem

Lecture 12A: Introduction And Property of DTFT

Lecture 12B: Review of Inverse DTFT

Lecture 12C: Parseval's Theorem and energy and time spectral density

Week 5: Lecture 13A: Discussion on Unit Step

Lecture 13B: Introduction to Z transform

Lecture 13C: Example of Z transform

Lecture 13D: Region of Convergence

Lecture 13E: Properties of Z transform

Lecture 14A: Z- Transform

Lecture 14B: Rational System

Lecture 15A: Introduction And Examples Of Rational Z Transform And Their Inverses

- Lecture 15B: Double Pole Examples And Their Inverse Z Transform
- Lecture 15C: Partial Fraction Decomposition

Lecture 15D: LSI System Examples

Week 6: Lecture 16A: Why are Rational Systems so important?

Lecture 16B: Solving Linear constant coefficient difference equations which are valid over a finite range of time

Lecture 16C: Introduction to Resonance in Rational Systems

Lecture 17A: Characterization of Rational LSI system

Lecture 17B: Causality and stability of the ROC of the system function

Lecture 18A: Recap Of Rational Systems And Discrete Time Filters

Lecture 18B: Specifications For Filter Design

Lecture 18C: Four Ideal Piecewise Constant Filters

Lecture 18D: Important Characteristics Of Ideal Filters

Week 7: Lecture 19A: Synthesis of Discrete Time Filters, Realizable specifications

Lecture 19B: Realistic Specifications for low pass filter. Filter Design Process

Lecture 20A: Introduction to Filter Design. Analog IIR Filter, FIR discrete-time filter, IIR discrete-

time filter.

Lecture 20B: Analog to discrete transform

Lecture 20C: Intuitive transforms, Bilinear Transformation

Lecture 21A: Steps for IIR filter design

Lecture 21B: Analog filter design using Butterworth Approximation

Week 8: Lecture 22A: Butterworth filter Derivation And Analysis of butterworth system function

Lecture 22B: Chebychev filter Derivation

Lecture 23: Midsem paper review discussion

Lecture 24A: The Chebyschev Approximation

Lecture 24B: Next step in design: Obtain poles

Lecture 25A: Introduction to Frequency Transformations in the Analog Domain

Lecture 25B: High pass transformation

Lecture 25C: Band pass transformation

Week 9: Lecture 26A: Frequency Transformation

Lecture 26B: Different types of filters

Lecture 27A: Impulse invariant method and ideal impulse response

Lecture 27B: Design of FIR of length (2N+1) by the truncation method, Plotting the function V(w)

Lecture 28A: IIR filter using rectangular window, IIR filter using triangular window

Lecture 28B: Proof that frequency response of an fir filter using rectangular window function

centered at 0 is real.

Week 10: Lecture 29A: Introduction to window functions

Lecture 29B: Examples of window functions Lecture 29C: Explanation of Gibb's Phenomenon and it's application

Lecture 30A: Comparison of FIR And IIR Filter's Lecture 30B: Comparison of FIR And IIR Filter's Lecture 30C: Comparison of FIR And IIR Filter's

Language Code.

Lecture 31A: Introduction and approach to realization (causal rational system) Lecture 31B: Comprehension of Signal Flow Graphs and Achievement of Pseudo Assembly

Week 11: Lecture 32A: Introduction to IIR Filter Realization and Cascade Structure

Week 12: Lecture 35A: Introductory Remarks of Discrete Fourier Transform and Frequency Domain Sampling

Lecture 32B: Cascade Parallel Structure Lecture 32C: Lattice Structure Lecture 33A: Recap And Review of Lattice Structure, Realization of FIR Function. Lecture 33B: Backward recursion, Change in the recursive equation of lattice. Lecture 34A: Lattice structure for an arbitrary rational system Lecture 34B: Example realization of lattice structure for rational system Lecture 35B: Principle of Duality, The Circular Convolution