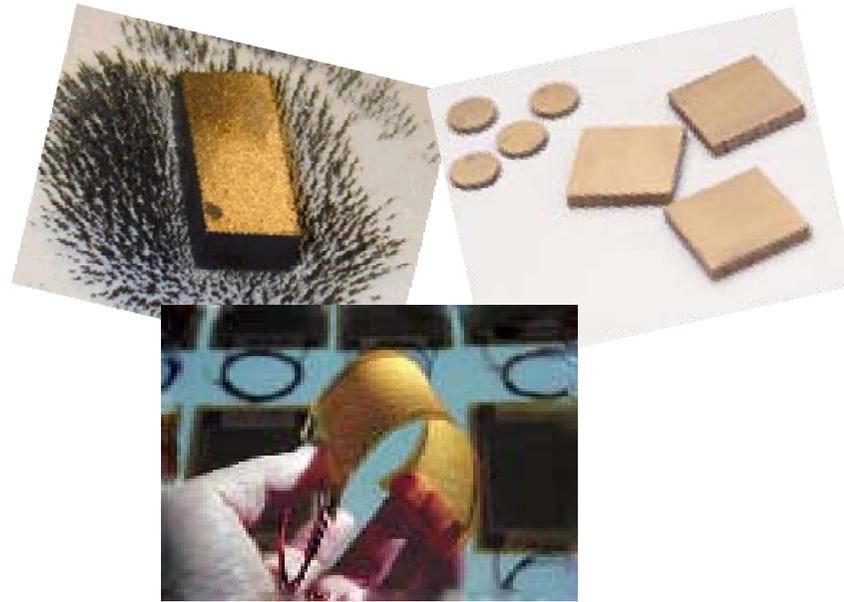


# Module 1: Overview of Smart Materials



Bishakh Bhattacharya and Naciketa Tiwari

Department of Mechanical Engineering

Indian Institute of Technology, Kanpur

# **LECTURE 4:**

## **Magnetostrictive Smart Materials (Part -2)**

# Organization

- **The Constitutive Relationship**
- **Actuators Developed using Terfenol-D**
- **Sensors Developed using Terfenol-D**
- **Magnetostrictive Composites**

# Const. Eqn. of Magnetostrictive Material

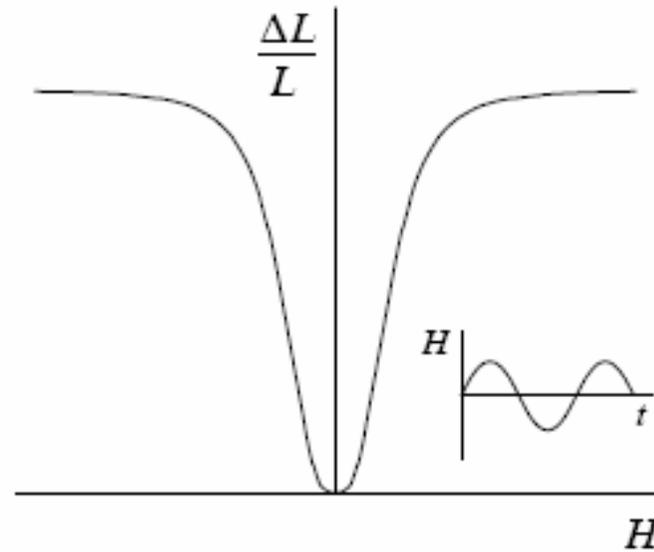
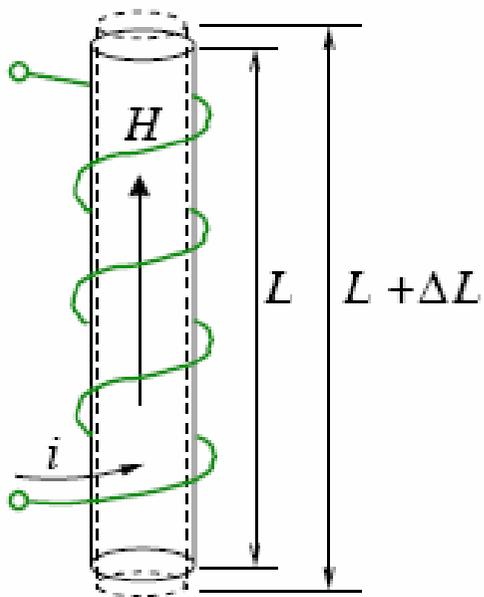
**Joule Effect:  $S_1 = \sigma_1/E_p + d_m H$**

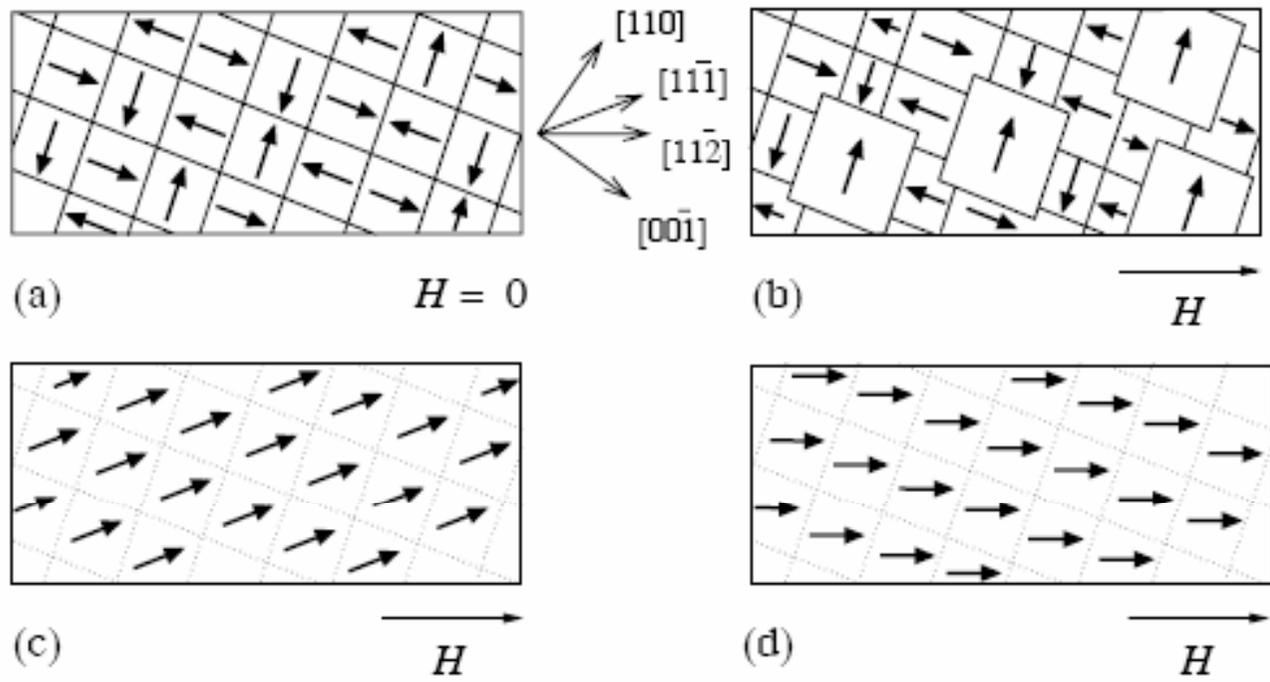
**Villary Effect:  $B = d_m \sigma_1 + \mu H$**

**$\sigma$ -stress,  $S$ -strain,  $B$  - magnetic displacement/flux density,**

**$\mu$  - permeability,  $d_m$ - magnetostrictive constant**

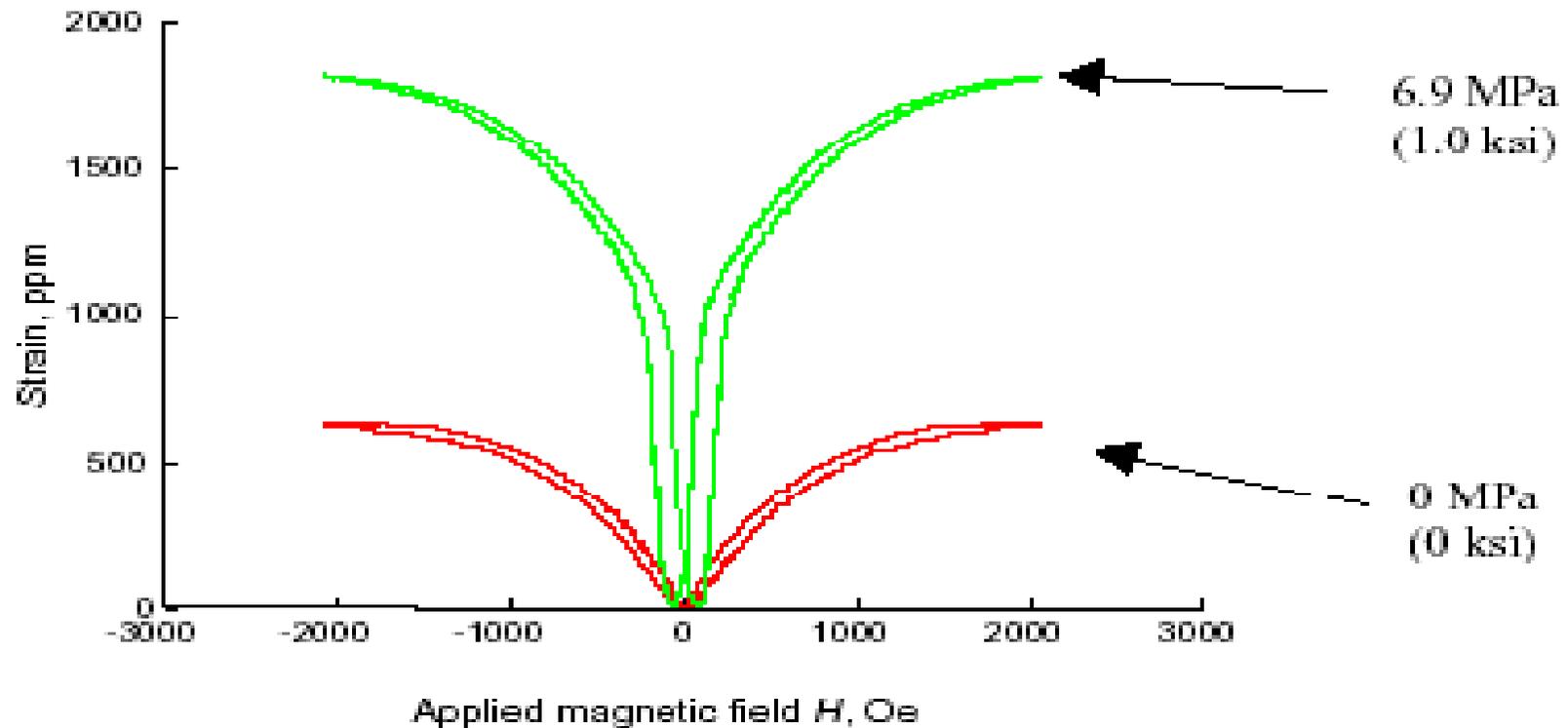
# Magnetostriction in Solid Rod



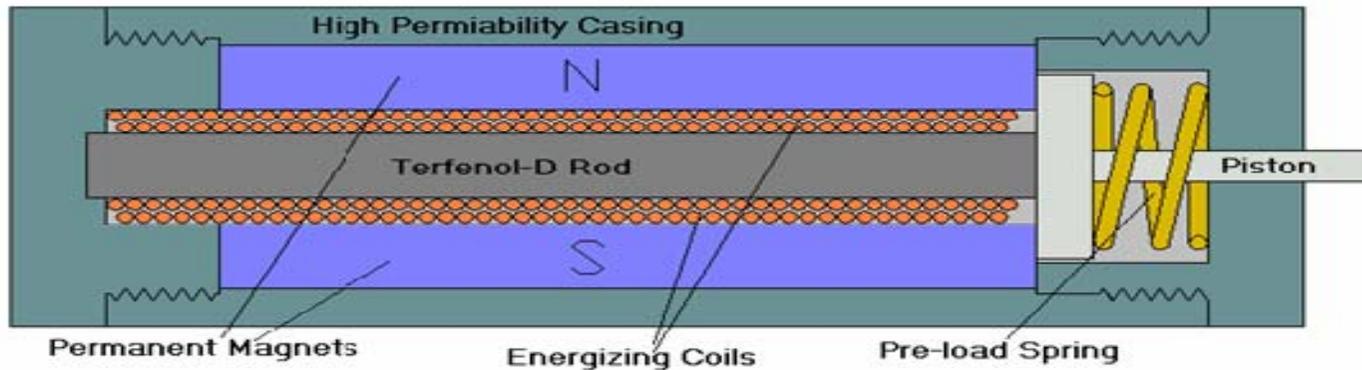


**(a) Demagnetized State (b) Partial Magnetization**  
**(c) Irreversible Domain Magnetization (d) Technical Saturation**

# Butterfly curve for TerFeNOL-D



# Magnetostrictive Mini Actuator (MMA)



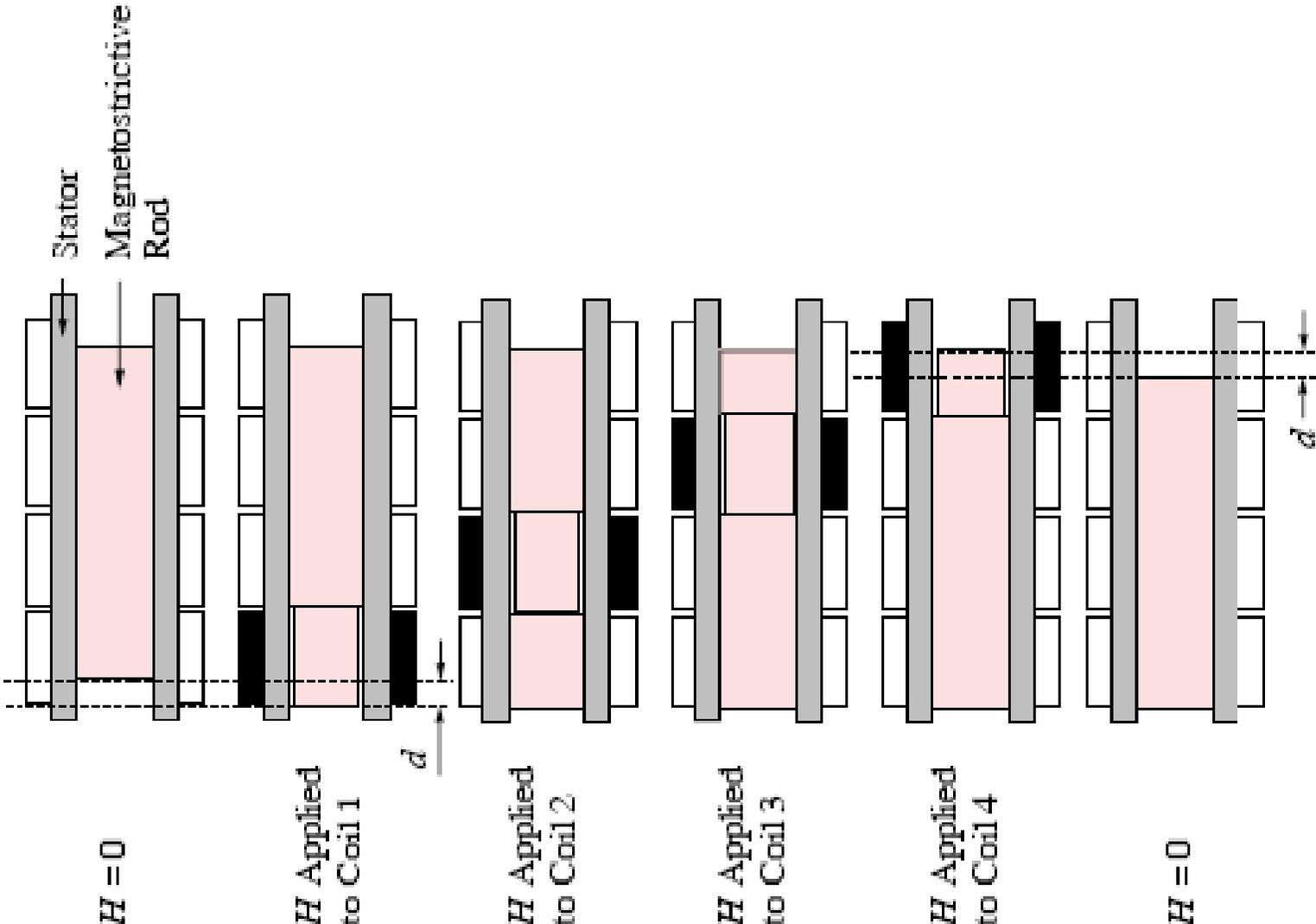
Pre-load springs and permanent magnets are used to put the piston in the zero-position and also to reduce hysteresis. The energizing coil around the rod is used to activate the Terfenol-D rod for dynamic application.

# Actuation Strain by MMA

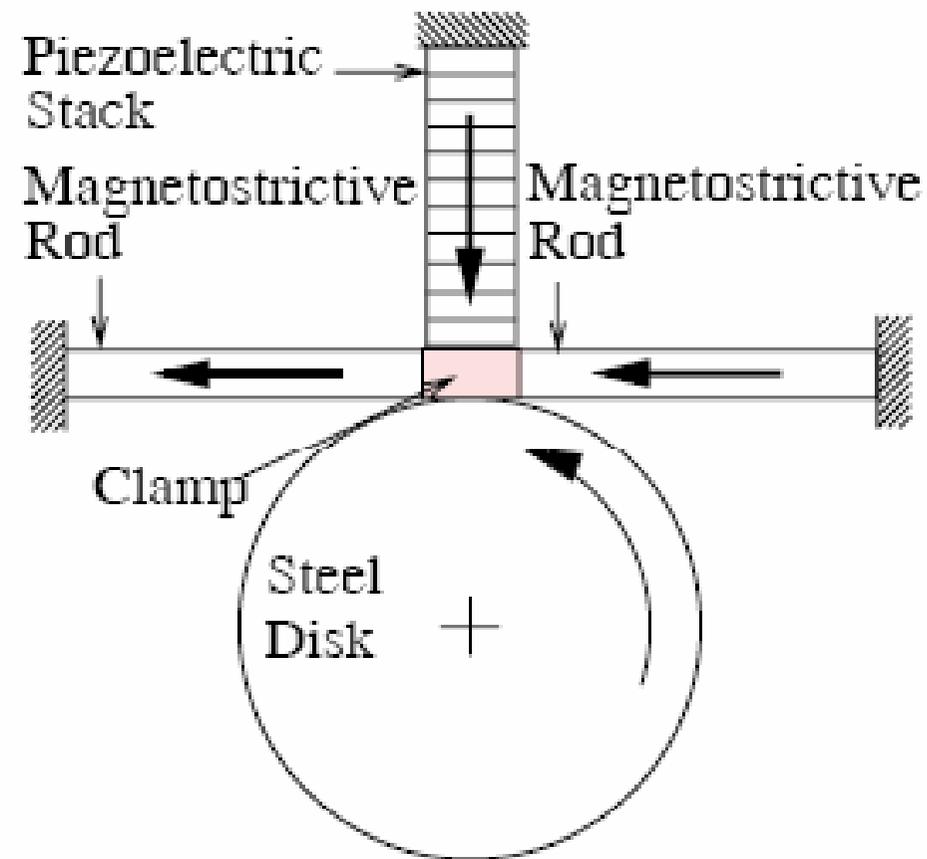
$$\varepsilon_c(t) = S(\sigma + \sigma_0) + d G i(t) + \alpha K \int e^{-t/C} i^2(t) dt$$

$\varepsilon$  - strain,  $S$ - compliance modulus,  $\sigma$  - stress,  $\sigma_0$  – pre-stress,  $d$  – magneto-mechanical constant,  $G$  – control parameter,  $i(t)$  – control current,  $\alpha$  - equivalent thermal coefficient of the housing, and  $C$  – a parametric constant

# A Kiesewetter Inchworm Motor



# Hybrid Transducers

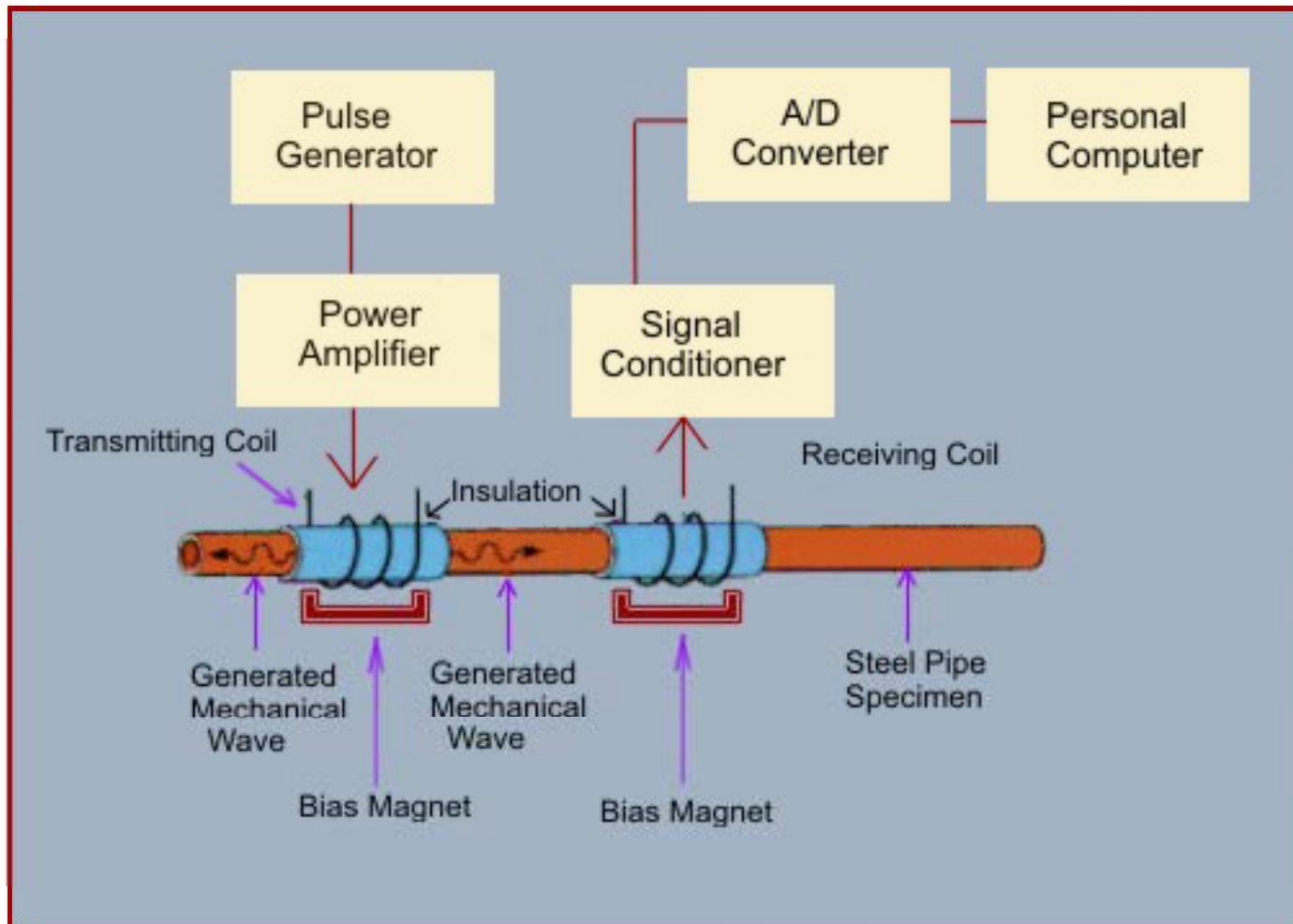


# Vibration Sensing

Two approaches are taken to develop such sensors:

- (a) Development of particulate composite:  
Terfenol-D particles of micron to sub-micron size is dispersed in a suitable resin and cured to form sensors
- (b) Development of thin-film metallic glasses as magnetostrictive (MS) sensors.

# Magnetostrictive Delay Line (MDL) Sensor



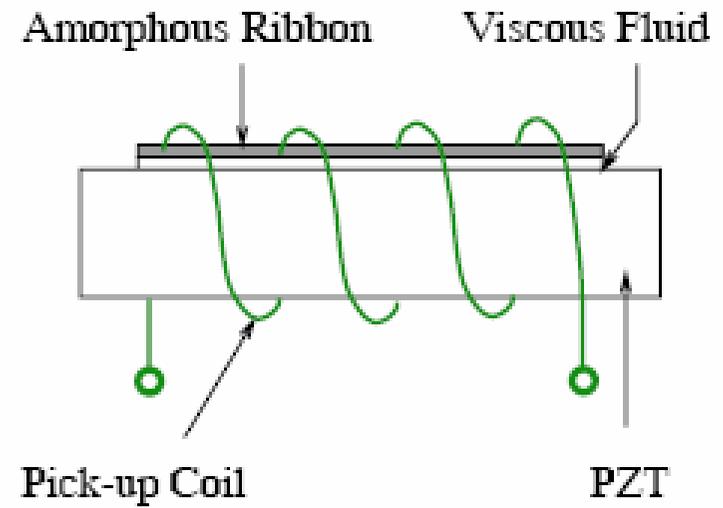
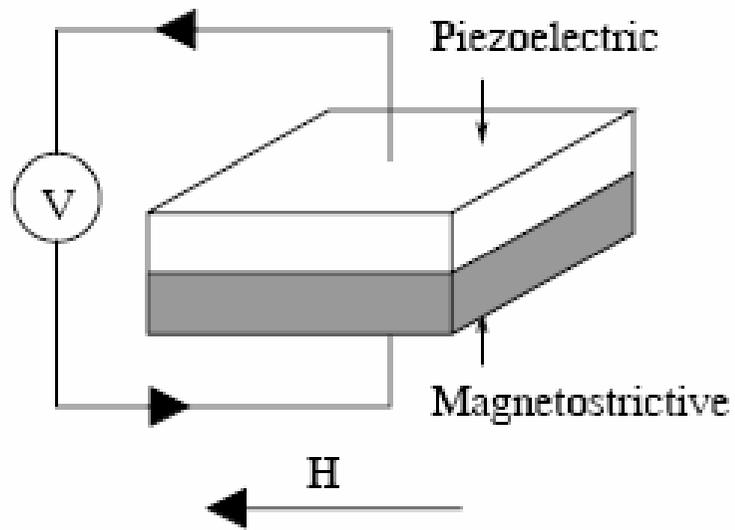
# Constitutive Relationship

$$H(x,t) = f(x) I(t) = 1/(\sqrt{a^2 + x^2}) I(t)$$

$$\lambda(H) = \lambda_s (1 - e^{-\alpha H^2}), \quad \alpha > 0$$

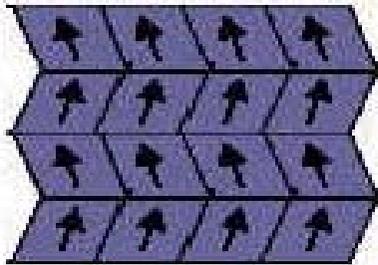
**H – applied pulsed magnetic field, I(t) - applied current, a - distance between the pulsed conductor and MDL,  $\lambda_s$  - saturation magnetostriction,  $\alpha$  - a material parameter**

# Hybrid Sensors

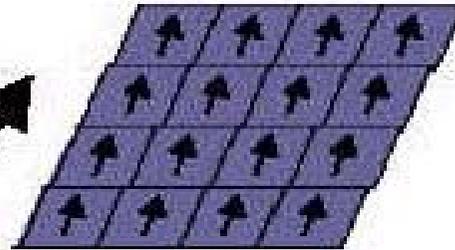


**Future of Magnetostrictive Materials?**

# Ferromagnetic Shape Memory Alloy



**Relaxed state twinned to minimize strain**



**De-twinned by application of magnetic field,  $\epsilon =$  up to 6%**



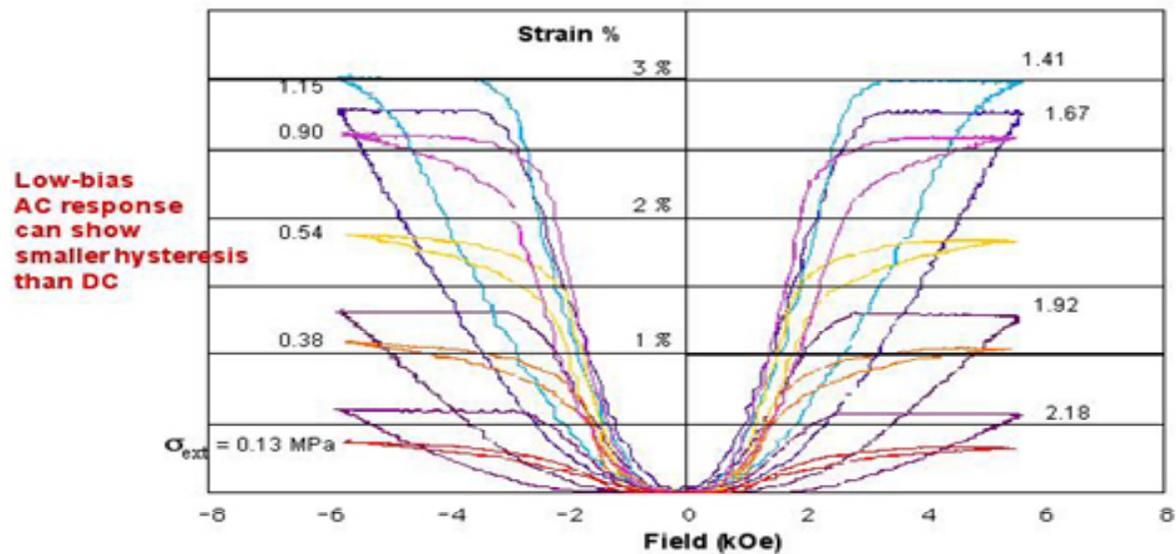
*(From Rob Tickle, et. al. University of Minnesota)*

**Material NiMnGa alloy**

# Strain induced in FSMA

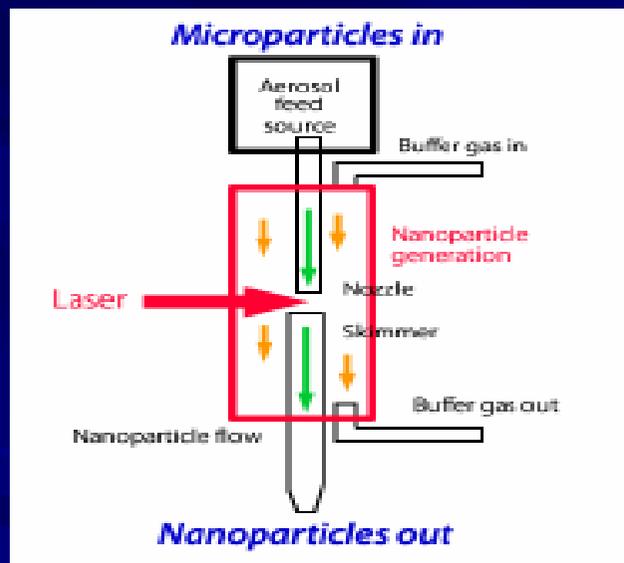
## AC field-induced strain under dynamic stress

Strain vs Field under different opposing stresses, 1 Hz Drive, 2 Hz Response



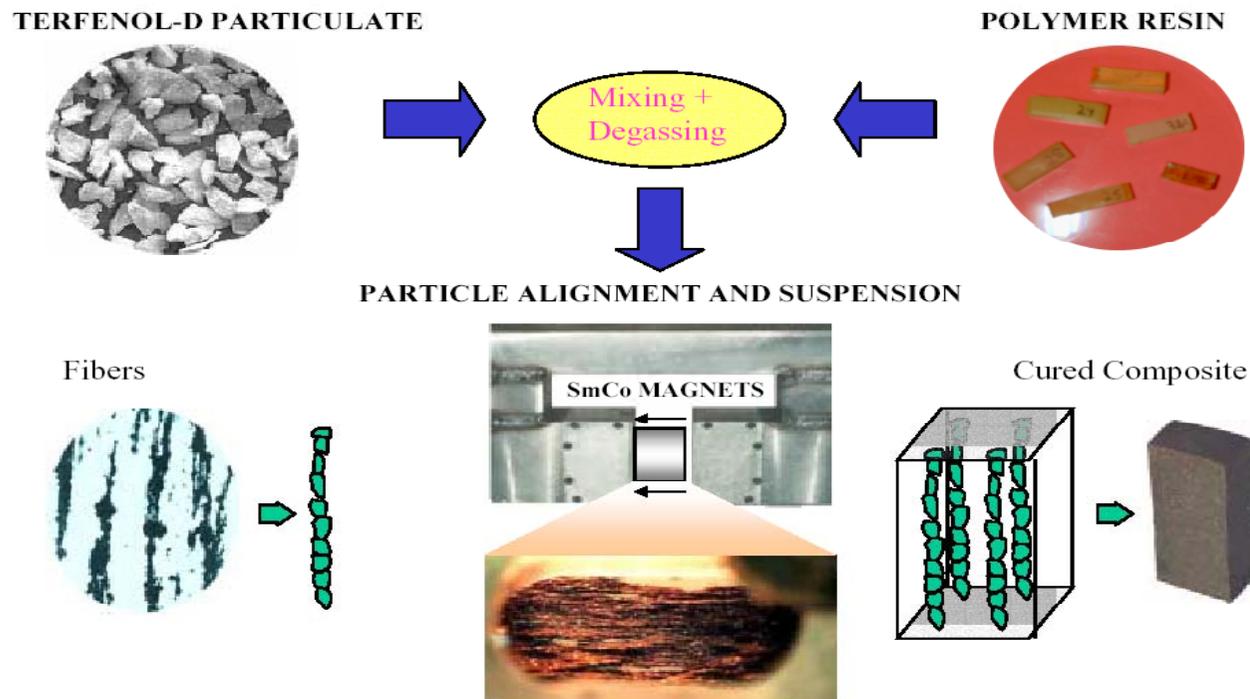
# Magnetostrictive Nanocomposite

## Technology overview: Nanoparticle production

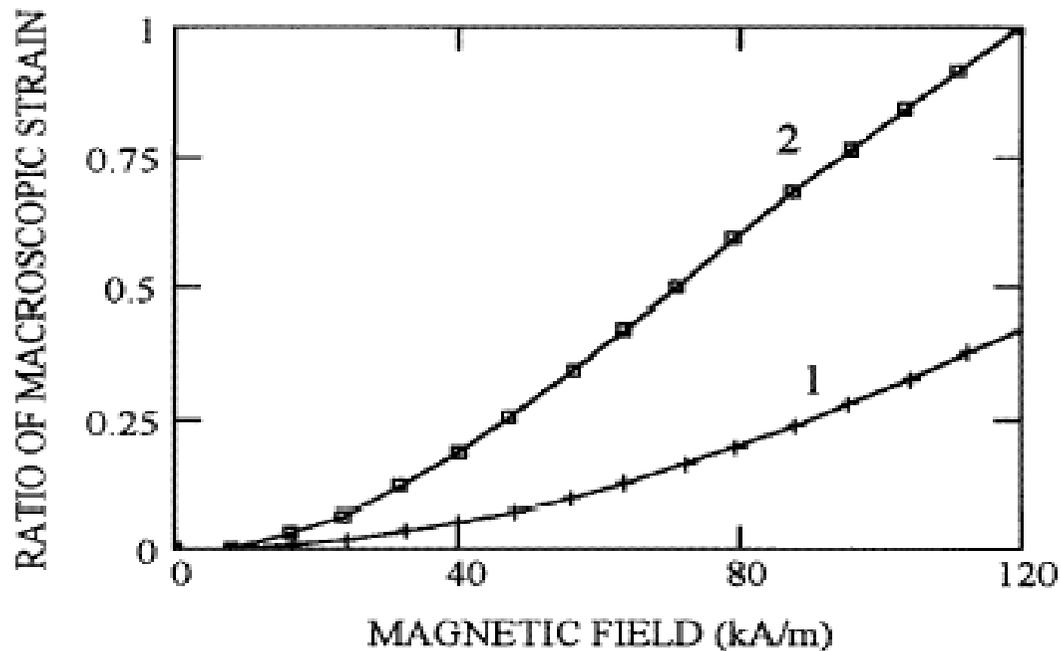


- Laser ablation of microparticle process
- Micron-sized powder particles blown up by laser to produce nanoparticles

# Magnetostrictive Nanocomposite



# Comparison of Free-Strain between a Micron-level particulate composite and Nanocomposite



# References

- M. Anjanappa and Y. Wu, “Magnetostrictive particulate actuators: configuration, modeling and characterization” *Smart Materials and Structures*, 6, pp. 393-402, 1997.
- M.J. Dapino, F.T. Calkins, R.C. Smith and A.B. Flatau, “A magnetoelastic model for magnetostrictive sensors”, *Proceedings of ACTIVE 99*, Vol. 2, pp. 1193-1204, December 02-04 1999.
- Mcknight, G. and Carman G.P., “Oriented Terfenol-D Composites,” *Material Transactions*, Vol.43 No.5 (2002) pp.1008-1014

**END OF LECTURE 4**