

Module 8 : Robot vision II

Lecture 28 : Image processing (spatial and frequency domain analysis)

Objectives

In this course you will learn the following

- Image Processing
- Spatial Domain processing example
- Frequency domain approach
- Magnitude of F(u)
- 2-D Discrete Fourier Transform
- Spatial Domain

Image Processing

Spatial domain processing

$$g(x,y) = h[f(x,y)]$$

Where,

g- output image

h- depends on properties of p and neighboring pixels

f - input Frequency domain processing

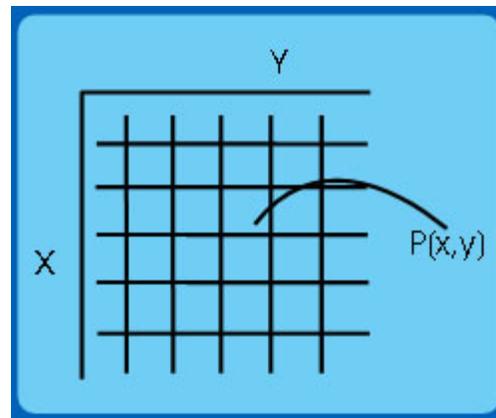


Figure 28.1 Transformation Mapping

$$\sum_{\substack{j=-10,1 \\ k=-10,1}} W_{jk} f(x+j, y+k) = W_{-1,-1} f(x-1, y-1) + W_{-1,0} f(x-1, y) + W_{-1,1} f(x-1, y+1) + \dots \\ = W_1 f(x-1, y-1) + W_2 f(x-1, y) + W_3 f(x-1, y+1) + W_4 f(x, y-1) + W_5 f(x, y) + \\ W_6 f(x, y+1) + W_7 f(x+1, y-1) + W_8 f(x+1, y) + W_9 f(x+1, y+1)$$

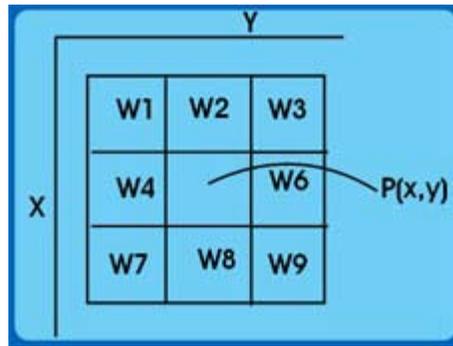


Figure 28.2 Transformation Mapping

Special Case: 1x1 template

$S = T(r)$ Image, Intensity,

Transformation (mapping)

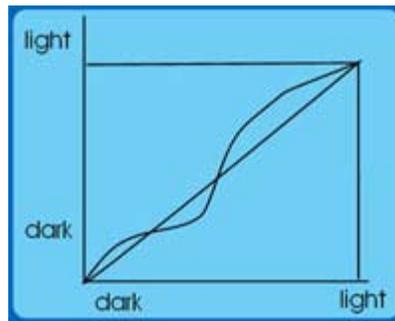


Figure 28.3

Magnitude of $F(u)$

$$|F(0)| = 3.25$$

$$|F(1)| = \sqrt{\frac{(-2)^2 + 1^2}{16}} = \frac{\sqrt{5}}{4}$$

$$|F(3)| = \frac{1}{4}$$

$$|F(4)| = \frac{\sqrt{5}}{4}$$

2-D Discrete Fourier Transform

$$F(u, v) = \frac{1}{N} \sum_{x=0}^{N-1} \sum_{y=0}^{N-1} f(x, y) e^{-\frac{2\pi j}{N}(ux+vy)}$$

$$f(x, y) = \frac{1}{N} \sum_{u=0}^{N-1} \sum_{v=0}^{N-1} F(u, v) e^{\frac{2\pi j}{N}(ux+vy)}$$

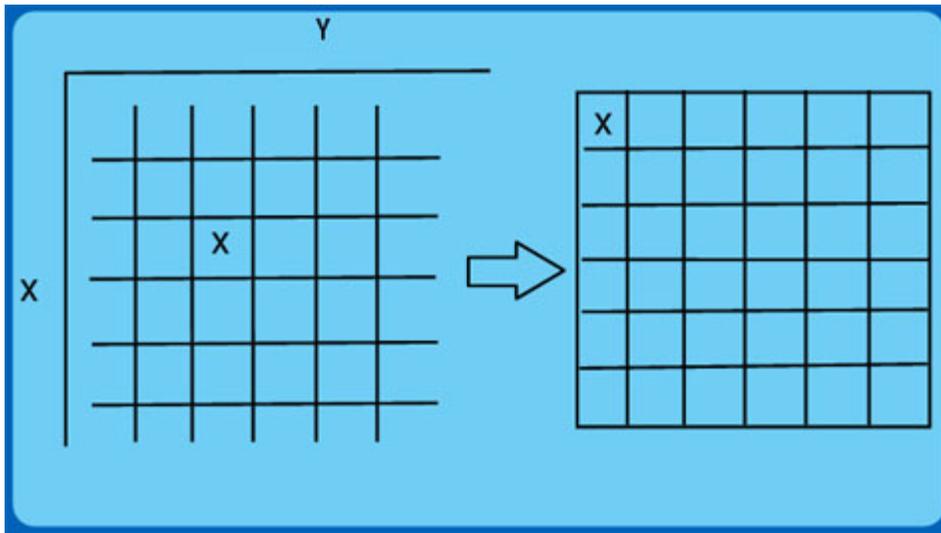


Figure 28.5

Spatial Domain

- Smoothing – reduce the effect of random noise
 - Neighborhood averaging. Boundaries are softer, fuzzier.
 - Median averaging

NA → $103/9 = 11$

MA → 2 9 10 10 11 11 12 13 25

1/9	1/9	1/9	10	12	11
1/9	1/9	1/9	9	13	25
1/9	1/9	1/9	2	10	11

- Image averaging: Intensity averaging across many images of the same scene
 - Better reduction of noise
 - Requires good registration of images
 - Time consuming

	0	0	1
	0	1	

- Binary Image smoothing
- Binary – Boolean expressions. Logic expressions
 - B1 = $p + b.g.(d+e) + d.e.(b+g)$ - fill one pixel whole
 - B2 = $p.[(a+b+d).(e+g+h) + (b+c+e).(d+f+g)]$ - fill notch
 - B3 = $p + (d.f.g).(a+b+c+e+h)$ - fill missing corner

A	B	C
D	P	E
F	G	h

Recap

In this course you have learnt the following

- Image Processing
- Spatial Domain processing example
- Frequency domain approach
- Magnitude of $F(u)$
- 2-D Discrete Fourier Transform
- Spatial Domain

Congratulations, you have finished Lecture 28. To view the next lecture select it from the left hand side menu of the page.