

# Analysis of Variance and Design of Experiments-II

## MODULE VIII

### LECTURE - 36

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# RESPONSE SURFACE DESIGNS

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## Design for fitting the first-order model

Consider the following first-order model in  $k$  variables for fitting

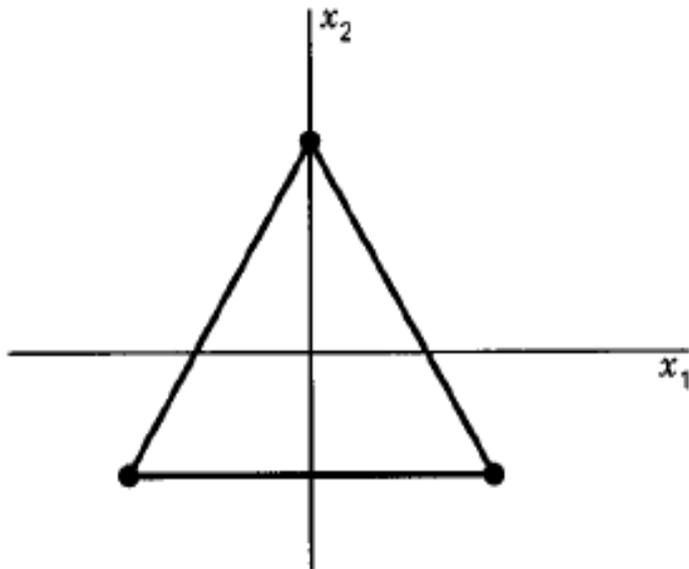
$$y = \beta_0 + \sum_{i=1}^k \beta_i x_i + \varepsilon$$

There is a unique class of designs that minimize the variance of the regression coefficients  $\hat{\beta}_i$ 's. These are the **orthogonal first-order designs**. A first-order design is orthogonal if the off-diagonal elements of the  $(X'X)$  matrix are all zero. This implies that the cross-products of the columns of the  $X$  matrix sum to zero.

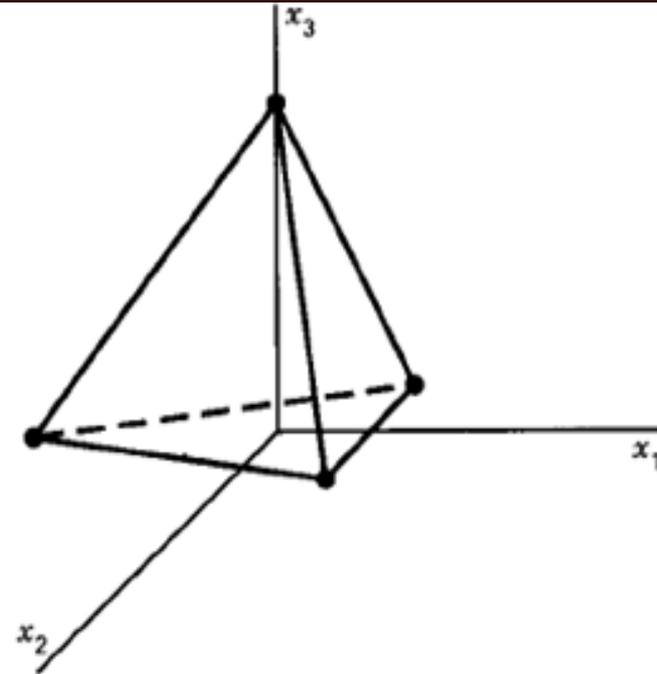
The  $2^k$  factorial and fractions of the  $2^k$  series in which main effects are not aliased with each other belongs to the class of orthogonal first-order designs. Assume that the low and high level of the  $k$  factors are coded as  $\pm 1$  levels to use is such designs.

The  $2^k$  design cannot provide an estimate of the experimental error unless some runs are replicated. A method of including replication in the  $2^k$  design is to augment the design with several observations at the center which is the point  $x_i = 0, i = 1, 2, \dots, k$ . The estimates of  $\hat{\beta}_i$ 's,  $i \geq 1$  are not affected by adding the center points to the  $2^k$  design. Only estimate of  $\beta_0$  changes as it becomes the average of all the observations. The addition of center points does not alter the orthogonally property of the design.

Another orthogonal first-order design is the **simplex**. The simplex is a regularly sides figure with  $k + 1$  vertices in  $k$  dimensions. Thus, for  $k = 2$  the simplex design is an equilateral triangle and for  $k = 3$  it is a regular tetrahedron. Simplex designs in two and three dimensions are shown in the following figure:



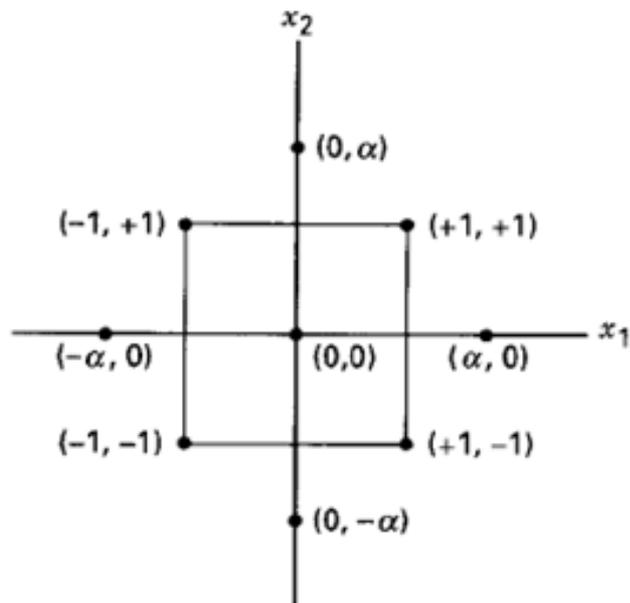
The simplex design for  $k = 2$  variables



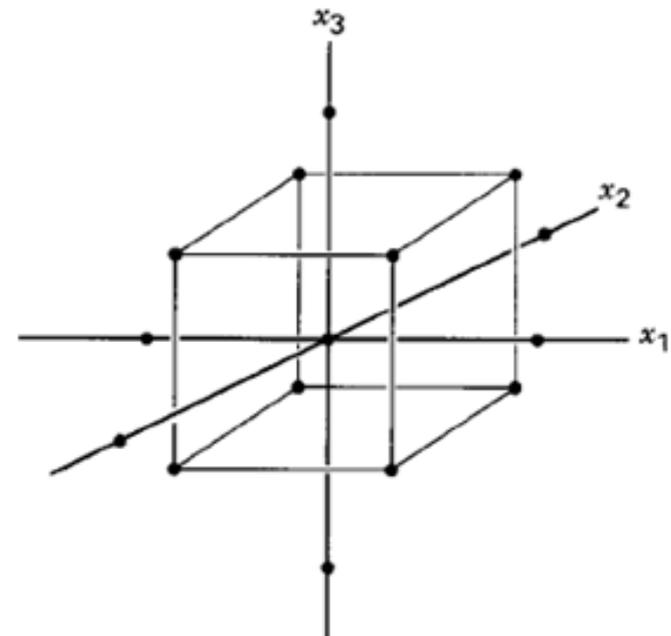
The simplex design for  $k = 3$  variables

## Designs for fitting the second-order model

The **central composite design** or **CCD** are used for fitting a second-order model. The CCD consists of a  $2^k$  factorial with  $n_F$  runs,  $2k$  axial or star runs, and  $n_C$  center runs. Following figure shows the CCD for  $k = 2$  and  $k = 3$  factors.



The central composite design for  $k = 2$  variables



The central composite design for  $k = 3$  variables

The CCD is developed through **sequential experimentation**. Suppose a  $2^k$  is used to fit a first-order model and suppose this model exhibits lack of fit. Then axial runs is added to allow the quadratic terms to be incorporated into the model. The CCD is a very efficient design for fitting the second-order model. There are two parameters in the design that must be specified:

- the distance  $\alpha$  of the axial runs from the design center and
- the number of center points  $n_c$ .

We now discuss the choice of these two parameters.

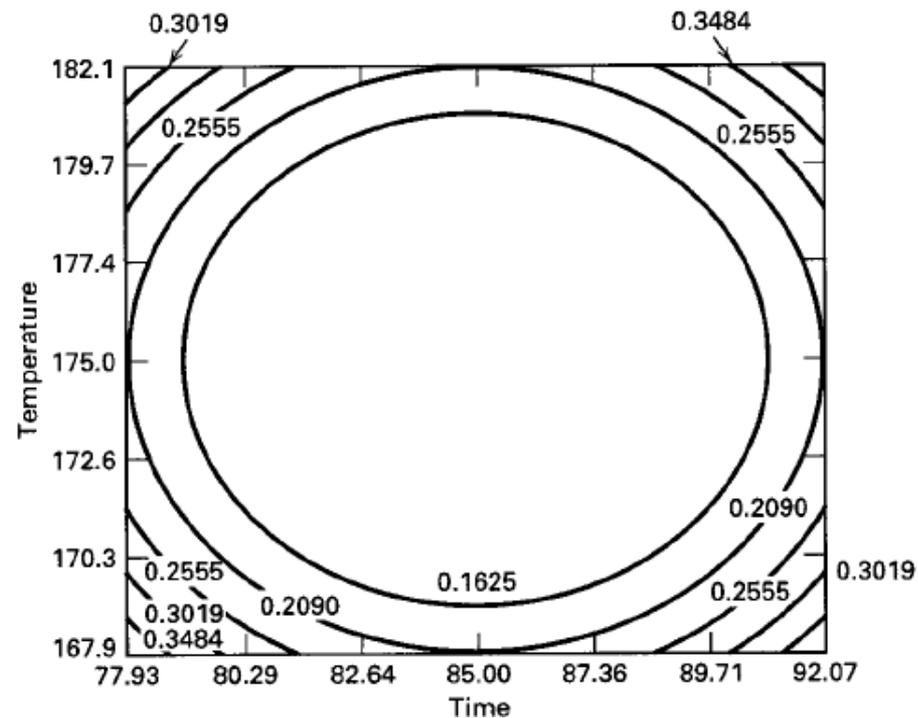
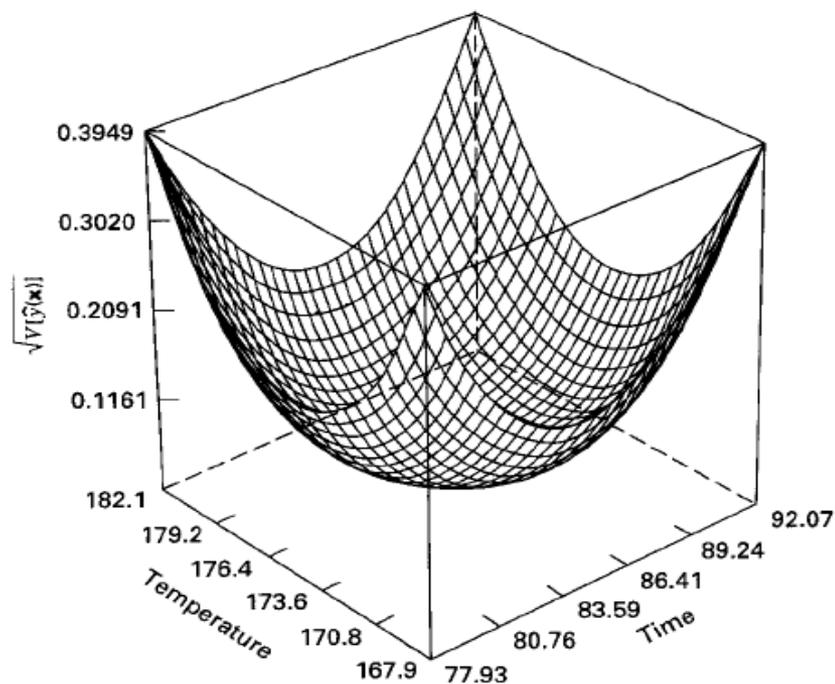
## Readability

It is important for the second-order model to provide good predictions throughout the region of interest. One way to define “good” is to have the model which is a reasonably consistent and has stable variance of the predicted response at points of interest. The variance of the predicted response at some point  $x$  is

$$\text{Var}[\hat{y}(x)] = \sigma^2 x'(X'X)^{-1}x.$$

It is suggested that a second-order response surface design should be **rotatable**. This means that the  $\text{Var}[\hat{y}(x)]$  is the same at all points  $x$  that are at the same distance from the design center. That is, the variance of predicted response is constant on spheres.

Following figure shows contours of constant  $\sqrt{\text{Var}[\hat{y}(x)]}$  for the second-order model fit using the CCD.



Contours of constant standard deviation of predicted response for the rotatable CCD

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Notice that the contours of constant standard deviation of predicted response are concentric circles. A design with this property will leave the variance of  $\hat{y}$  unchanged when the design is rotated about the center  $(0, 0, \dots, 0)$ . Hence it is termed as **rotatable design**.

Rotatability is an important criterion for the selection of a response surface design. The aim of RSM is optimization and the location of the optimum is unknown prior to running the experiment, so it makes sense to use a design that provides equal precision of estimation in all the directions. In fact, any first-order orthogonal design is rotatable.

A central composite design is made rotatable by the choice of  $\alpha$ . The value of  $\alpha$  for rotatability depends on the number of points in the factorial portion of the design. The choice  $\alpha = (n_F)^{1/4}$  yields a rotatable central composite design where  $n_F$  is the number of points used in the factorial portion of the design.

## The spherical CCD

Rotatability is a spherical property. It is an important design criterion when the region of interest is a sphere. It is not important to have the exact rotatability to have a good design. The best choice of  $\alpha$  for a spherical region of interest from a prediction variance view point for the CCD is to set  $\alpha = \sqrt{k}$ . This design called a **spherical CCD**. This puts all the factorial and axial design points on the surface of a sphere of radius  $\sqrt{k}$ .

## Center runs in the CCD

The choice of  $\alpha$  in the CCD is dictated primarily by the region of interest. When this region is a sphere, the design must include center runs to provide reasonably stable variance of predicted response. Generally, three to five center runs are recommended.

## Blocking in response surface designs

When using the response surface designs, it is often necessary to consider blocking to eliminate nuisance variables. Such problem may occur when a higher order, say second-order design is assembled sequentially from lower order, say. Such necessity arises due to various reasons. For example, considerable time may elapse between the running of the first-order design and the running of the supplemental experiments which are required to build up a second-order design, and during this time, the test conditions may change which makes necessary to use blocking.

A response surface design is said to be **block orthogonally** if it is divided into blocks such that block effects do not affect the parameter estimates of the response surface model. If a  $2^k$  or  $2^{k-p}$  design is used as a first-order response surface design, the center points in these designs should be allocated among the blocks.

For a second-order design to block orthogonally, two conditions must be satisfied. If there are  $n_b$  observations in the  $b^{th}$  block, then these conditions are

1. Each block must be a first-order orthogonal design; that is, 
$$\sum_{u=1}^{n_b} x_{iu} x_{ju} = 0 \quad i \neq j = 0, 1, \dots, k \quad \text{for all } b$$

where  $x_{iu}$  and  $x_{ju}$  are the levels of  $i^{th}$  and  $j^{th}$  variables in the  $u^{th}$  run of the experiment with  $x_{0u} = 1$  for all  $u$ .

2. The fraction of the total sum of squares for each variable contributed by every block must be equal to the fraction of the total observations that occur in the block; that is,

$$\frac{\sum_{u=1}^{n_b} x_{iu}^2}{\sum_{u=1}^N x_{iu}^2} = \frac{n_b}{N} \quad i = 1, 2, \dots, k \quad \text{for all } b$$

where  $N$  is the number of runs in the design.