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Necessary and Sufficient condition for Convergence

We shall now study the necessary and sufficient condition for convergence of a general one-step method which is given in the following theorem:

Theorem: If $\Phi(\mathbf{y}, t, h)$ is continuous in \mathbf{y}, t, h , for $0 \leq t \leq b, 0 \leq h \leq h_0$ and all \mathbf{y} , and if it satisfies a Lipschitz condition in \mathbf{y} in that region, a necessary and sufficient condition for convergence is that

$$\Phi(\mathbf{y}(t), t, 0) = f(\mathbf{y}(t), t) \quad (5.4)$$

Remark: The equation (5.4) is called the condition of consistency. Since, by suitable choice of initial conditions, $\mathbf{y}(t)$ can take on any value for a given t , the equation (5.4) will hold for any \mathbf{y} in the form

$$\Phi(\mathbf{y}, t, 0) = f(\mathbf{y}, t)$$

Proof: Let $\Phi(\mathbf{y}, t, 0) = g(\mathbf{y}, t)$

Since g satisfies the conditions of existence and uniqueness of the solution, the IVP

$$z' = g(z, t)$$

$$z_0 = y_0 \quad (5.5)$$

has a unique differentiable solution. We shall show that the numerical solution given by (5.1) converges to $\mathbf{z}(t)$, and hence $f = g$ is a necessary and sufficient condition.

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The numerical solution satisfies

$$y_{n+1} = y_n + h\Phi(y_n, t_n, h) \quad (5.6)$$

By the mean value theorem,

$$z^i(t_{n+1}) = z^i(t_n) + hg^i(z(t_n + \theta^i h), t_n + \theta^i h) \text{ for } 0 < \theta^i < 1$$

Subtracting this from (5.6) and setting

$$\varepsilon_n = y_n - z(t_n), \text{ we get}$$

$$\begin{aligned} \varepsilon_{n+1} &= \varepsilon_n + h[\Phi^i(y_n, t_n, h) - g^i(z(t_n + \theta^i h), t_n + \theta^i h)] \\ &= \varepsilon_n + h[\Phi^i(y_n, t_n, h) - \Phi^i(z(t_n), t_n, h) + \Phi^i(z(t_n), t_n, h) - \Phi^i(z(t_n), t_n, 0) + \Phi^i(z(t_n), t_n, 0) - \\ &\quad g^i(z(t_n + \theta^i h), t_n + \theta^i h)] \end{aligned} \quad (5.7)$$

Now, if we assume that Φ satisfies a Lipschitz condition in t and h , as will happen in practice, we get the following bounds:

$$\|\Phi(y_n, t_n, h) - \Phi(z(t_n), t_n, h)\| \leq L \|y_n - z(t_n)\| = L \|\varepsilon_n\|$$

$$\|\Phi(z(t_n), t_n, h) - \Phi(z(t_n), t_n, 0)\| \leq L_1 h$$

and

$$\begin{aligned} &\left| \left\{ \Phi^i(z(t_n), t_n, 0) - g^i(z(t_n + \theta^i h), t_n + \theta^i h) \right\} \right| \\ &= \left| \left\{ g^i(z(t_n), t_n) - g^i(z(t_n + \theta^i h), t_n + \theta^i h) \right\} \right| \leq L |z'(t_n + \xi \theta^i h)| \theta^i h + L_3 \theta^i h \end{aligned}$$

(by using Lipschitz condition and mean value theorem)

$$\leq L_2 h$$

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Hence the norm of the last two expressions on the R.H.S. of (5.7) can be bounded by $L_2 h$. Substituting these in (5.7), we get

$$\|\varepsilon_{n+1}\| \leq \|\varepsilon_n\| + hL \|\varepsilon_n\| + h^2(L_1 + L_2) = (1 + hL)\|\varepsilon_n\| + h^2(L_1 + L_2) \quad (5.8)$$

This is a difference equation of the type given in Lemma in Module 2 from which we have

$$\|\varepsilon_N\| \leq (L_1 + L_2)h \frac{e^{Lb} - 1}{L} + e^{Lb} \|\varepsilon_0\| \quad (Nh = b)$$

This converges to zero as h and $\|\varepsilon_0\| \rightarrow 0$, so the numerical solution converges to the solution of (5.5). Sufficiency of the condition $g(y, t) = f(y, t)$ follows immediately.

If, on the other hand, we have convergence, then $z(t)$, the solution of (5.5), is identical to $y(t)$, the solution of $y'(t) = f(y(t), t)$.

Suppose also that f and g differ at some point (y_a, t_a) . If we consider the initial value problem starting from (y_a, t_a) , we have

$$y'(t_a) = f(y(t_a), t_a) \neq g(y(t_a), t_a) = g(z(t_a), t_a) = z'(t_a)$$

leading to a contradiction. Hence the theorem.

Application of the above theorem:

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Illustrative Example:

Let us now apply the above theorem to illustrate the convergence of Classical Runge-Kutta method applied to the system of first order equations $y' = f(y)$.

We are given that f satisfies a Lipschitz condition. Thus, $K_1(y) = hf(y)$ satisfies

$$\|K_1(y) - K_1(y^*)\| \leq hL\|y - y^*\|$$

$$K_2(y) = hf\left(y + \frac{1}{2}K_1(y)\right) \text{ satisfies}$$

$$\|K_2(y) - K_2(y^*)\| \leq hL \left\| y - y^* + \frac{1}{2}K_1(y) - \frac{1}{2}K_1(y^*) \right\| \leq hL \left(1 + \frac{1}{2}hL\right) \|y - y^*\|$$

$$K_3(y) = hf\left(y + \frac{1}{2}K_2(y)\right) \text{ satisfies}$$

$$\|K_3(y) - K_3(y^*)\| \leq hL \left\| y - y^* + \frac{1}{2}K_2(y) - \frac{1}{2}K_2(y^*) \right\| \leq hL \left[1 + \frac{1}{2}hL + \frac{1}{4}(hL)^2\right] \|y - y^*\|$$

and $K_4(y) = hf(y + K_3(y))$ satisfies

$$\begin{aligned} \|K_4(y) - K_4(y^*)\| &\leq hL\|y - y^* + K_3(y) - K_3(y^*)\| \\ &\leq hL \left[1 + hL + \frac{1}{2}(hL)^2 + \frac{1}{4}(hL)^3\right] \|y - y^*\| \end{aligned}$$

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Therefore,

$\phi(\mathbf{y}, \mathbf{t}, \mathbf{h}) = \frac{1}{6h} (K_1 + 2K_2 + 2K_3 + K_4)$ satisfies

$$\begin{aligned} \|\phi(\mathbf{y}, \mathbf{t}, \mathbf{h}) - \phi(\mathbf{y}^*, \mathbf{t}, \mathbf{h})\| & \\ & \leq \frac{L}{6} \left[1 + 2 + hL + 2 + hL + \frac{1}{2}(hL)^2 + 1 + hL + \frac{1}{3}(hL)^2 + \frac{1}{4}(hL)^3 \right] \|\mathbf{y} - \mathbf{y}^*\| \\ & \leq L \left[1 + \frac{1}{2}(hL) + \frac{1}{6}(hL)^2 + \frac{1}{24}(hL)^3 \right] \|\mathbf{y} - \mathbf{y}^*\| \end{aligned}$$

Hence ϕ satisfies a Lipschitz condition in \mathbf{y} . It can also be seen to be continuous in \mathbf{h} . Thus we can conclude that the classical fourth order Runge-Kutta method converges for a system of equations.

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