

Module 5: Consistency, Stability and Convergence of General Single – Step Methods

Lecture 15: Convergence of General One-Step Methods

The Lecture Contains:

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Necessary and Sufficient condition for Convergence

We shall now study the necessary and sufficient condition for convergence of a general one-step method which is given in the following theorem:

Theorem: If $\Phi(y, t, h)$ is continuous in y, t, h for $0 \leq t \leq b, 0 \leq h \leq h_0$ and all y , and if it satisfies a Lipschitz condition in y in that region, a necessary and sufficient condition for convergence is that

$$\Phi(y(t), t, 0) = f(y(t), t) \quad (5.4)$$

Remark: The equation (5.4) is called the condition of consistency. Since, by suitable choice of initial conditions, $y(t)$ can take on any value for a given t , the equation (5.4) will hold for any y in the form

$$\Phi(y, t, 0) = f(y, t)$$

Proof: Let $\Phi(y, t, 0) = g(y, t)$

Since g satisfies the conditions of existence and uniqueness of the solution, the IVP

$$z' = g(z, t)$$

$$z_0 = y_0 \quad (5.5)$$

has a unique differentiable solution. We shall show that the numerical solution given by (5.1) converges to $z(t)$, and hence $f = g$ is a necessary and sufficient condition.

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The numerical solution satisfies

$$y_{n+1} = y_n + h\Phi(y_n, t_n, h) \quad (5.6)$$

By the mean value theorem,

$$z^i(t_{n+1}) = z^i(t_n) + hg^i(z(t_n + \theta^i h), t_n + \theta^i h) \text{ for } 0 < \theta^i < 1$$

Subtracting this from (5.6) and setting

$$\varepsilon_n = y_n - z(t_n), \text{ we get}$$

$$\begin{aligned} \varepsilon_{n+1}^i &= \varepsilon_n^i + h[\Phi^i(y_n, t_n, h) - g^i(z(t_n + \theta^i h), t_n + \theta^i h)] \\ &= \varepsilon_n^i + h[\Phi^i(y_n, t_n, h) - \Phi^i(z(t_n), t_n, h) + \Phi^i(z(t_n), t_n, h) - \Phi^i(z(t_n), t_n, 0) + \Phi^i(z(t_n), t_n, 0) - \\ &\quad g^i(z(t_n + \theta^i h), t_n + \theta^i h)] \end{aligned} \quad (5.7)$$

Now, if we assume that Φ satisfies a Lipschitz condition in t and h , as will happen in practice, we get the following bounds:

$$\|\Phi(y_n, t_n, h) - \Phi(z(t_n), t_n, h)\| \leq L \|y_n - z(t_n)\| = L \|\varepsilon_n\|$$

$$\|\Phi(z(t_n), t_n, h) - \Phi(z(t_n), t_n, 0)\| \leq L_1 h$$

and

$$\begin{aligned} &\left| \Phi^i(z(t_n), t_n, 0) - g^i(z(t_n + \theta^i h), t_n + \theta^i h) \right| \\ &= \left| g^i(z(t_n), t_n) - g^i(z(t_n + \theta^i h), t_n + \theta^i h) \right| \leq L |z'(t_n + \xi \theta^i h)| \theta^i h + L_3 \theta^i h \end{aligned}$$

(by using Lipschitz condition and mean value theorem)

$$\leq L_2 h$$

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Hence the norm of the last two expressions on the R.H.S. of (5.7) can be bounded by $L_2 h$. Substituting these in (5.7), we get

$$\|\varepsilon_{n+1}\| \leq \|\varepsilon_n\| + hL \|\varepsilon_n\| + h^2(L_1 + L_2) = (1 + hL)\|\varepsilon_n\| + h^2(L_1 + L_2) \quad (5.8)$$

This is a difference equation of the type given in Lemma in Module 2 from which we have

$$\|\varepsilon_N\| \leq (L_1 + L_2)h \frac{e^{Lb} - 1}{L} + e^{Lb} \|\varepsilon_0\| \quad (Nh = b)$$

This converges to zero as h and $\|\varepsilon_0\| \rightarrow 0$, so the numerical solution converges to the solution of (5.5). Sufficiency of the condition $g(y, t) = f(y, t)$ follows immediately.

If, on the other hand, we have convergence, then $z(t)$, the solution of (5.5), is identical to $y(t)$, the solution of $y'(t) = f(y(t), t)$.

Suppose also that f and g differ at some point (y_a, t_a) . If we consider the initial value problem starting from (y_a, t_a) , we have

$$y'(t_a) = f(y(t_a), t_a) \neq g(y(t_a), t_a) = g(z(t_a), t_a) = z'(t_a)$$

leading to a contradiction. Hence the theorem.

Application of the above theorem:

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Illustrative Example:

Let us now apply the above theorem to illustrate the convergence of Classical Runge-Kutta method applied to the system of first order equations $\mathbf{y}' = \mathbf{f}(\mathbf{y})$.

We are given that \mathbf{f} satisfies a Lipschitz condition. Thus, $\mathbf{K}_1(\mathbf{y}) = h\mathbf{f}(\mathbf{y})$ satisfies

$$\|\mathbf{K}_1(\mathbf{y}) - \mathbf{K}_1(\mathbf{y}^*)\| \leq hL\|\mathbf{y} - \mathbf{y}^*\|$$

$$\mathbf{K}_2(\mathbf{y}) = h\mathbf{f}\left(\mathbf{y} + \frac{1}{2}\mathbf{K}_1(\mathbf{y})\right) \text{ satisfies}$$

$$\|\mathbf{K}_2(\mathbf{y}) - \mathbf{K}_2(\mathbf{y}^*)\| \leq hL\left\|\mathbf{y} - \mathbf{y}^* + \frac{1}{2}\mathbf{K}_1(\mathbf{y}) - \frac{1}{2}\mathbf{K}_1(\mathbf{y}^*)\right\| \leq hL\left(1 + \frac{1}{2}hL\right)\|\mathbf{y} - \mathbf{y}^*\|$$

$$\mathbf{K}_3(\mathbf{y}) = h\mathbf{f}\left(\mathbf{y} + \frac{1}{2}\mathbf{K}_2(\mathbf{y})\right) \text{ satisfies}$$

$$\|\mathbf{K}_3(\mathbf{y}) - \mathbf{K}_3(\mathbf{y}^*)\| \leq hL\left\|\mathbf{y} - \mathbf{y}^* + \frac{1}{2}\mathbf{K}_2(\mathbf{y}) - \frac{1}{2}\mathbf{K}_2(\mathbf{y}^*)\right\| \leq hL\left[1 + \frac{1}{2}hL + \frac{1}{4}(hL)^2\right]\|\mathbf{y} - \mathbf{y}^*\|$$

and $\mathbf{K}_4(\mathbf{y}) = h\mathbf{f}(\mathbf{y} + \mathbf{K}_3(\mathbf{y}))$ satisfies

$$\begin{aligned}\|\mathbf{K}_4(\mathbf{y}) - \mathbf{K}_4(\mathbf{y}^*)\| &\leq hL\|\mathbf{y} - \mathbf{y}^* + \mathbf{K}_3(\mathbf{y}) - \mathbf{K}_3(\mathbf{y}^*)\| \\ &\leq hL\left[1 + hL + \frac{1}{2}(hL)^2 + \frac{1}{4}(hL)^3\right]\|\mathbf{y} - \mathbf{y}^*\|\end{aligned}$$

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Therefore,

$\phi(y, t, h) = \frac{1}{6h} (K_1 + 2K_2 + 2K_3 + K_4)$ satisfies

$$\begin{aligned} \|\phi(y, t, h) - \phi(y^*, t, h)\| &\leq \frac{L}{6} \left[1 + 2 + hL + 2 + hL + \frac{1}{2}(hL)^2 + 1 + hL + \frac{1}{3}(hL)^2 + \frac{1}{4}(hL)^3 \right] \|y - y^*\| \\ &\leq L \left[1 + \frac{1}{2}(hL) + \frac{1}{6}(hL)^2 + \frac{1}{24}(hL)^3 \right] \|y - y^*\| \end{aligned}$$

Hence ϕ satisfies a Lipschitz condition in y . It can also be seen to be continuous in h . Thus we can conclude that the classical fourth order Runge-Kutta method converges for a system of equations.

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