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Module 7: Multistep Methods

Lecture 18: Multistep Methods

Introduction: The methods discussed so far have required knowledge of the differential equations and initial values only. Consequently, given an approximation to the value of $y(t)$ at $t = n$, say, y_n , they have provided a technique for computing $y_{n+1} \cong y(t_{n+1})$. They could therefore be called one-step methods because they only required the value at one mesh point to compute the value at the next. Once the values at a number of points, say for $t \leq t_n$, have been computed, they can be used to obtain the solution at $t = t_{n+1}$. Thus the methods which make use of the information about the dependent variable at $t \leq t_n$, to compute the value of the dependent variable at $t = t_{n+1}$ are called multistep methods.

Consequently, a K-step multistep method is a method which uses the information about the dependent variable at K different mesh points $t_n, t_{n-1}, t_{n-2}, \dots, t_{n-k+1}$ to compute the value of the dependent variable at $t = t_{n+1}$.

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Methods based on numerical integration:

An exact solution of the differential equation $y' = f(t, y)$ by definition satisfies the identity

$$y(t+K) - y(t) = \int_t^{t+K} f(t, y(t)) dt$$

for any two points t and $t+K$ in the interval $[a, b]$. The methods now to be discussed are based on replacing the function $f(t, y(t))$, which is unknown, by an interpolating polynomial having the values $f_n = f(t_n, y_n)$ on a set of points t_n where y_n has already been computed or is just about to be computed, evaluating the integral and accepting its value as the increment of the approximate values y_n between t and $t+K$. We shall assume that the interpolating points are $t_p, t_{p-1}, \dots, t_{p-q}$. To approximate $f(t, y)$ by an interpolating polynomial through the above values, we use the Newton backward difference formula. If $f(t, y) = f(t)$ has a continuous $(q+1)$ the derivative, $t_p = t_0 + ph, f_p = f(t_p)$ and backward differences are given by

$$\nabla^{q+1} f_p = \nabla^q f_p - \nabla^q f_{p-1}$$

where $\nabla^0 f_p = f_p$, then

$$f(t) = f_p + \frac{t-t_p}{h} \nabla f_p + \frac{(t-t_p)(t-t_{p-1})}{2!}$$

$$\frac{\nabla^2 f_p}{h^2} + \dots + \frac{(t-t_p)(t-t_{p-1}) \dots (t-t_{p-q+1})}{q!}$$

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$$\frac{\nabla^q f_p}{h^q} + \frac{(t - t_p)(t - t_{p-1}) \cdots (t - t_{p-q})}{(q+1)!} f^{(q+1)}(\xi) \quad (7.1)$$

where $f^{(q+1)}(\xi)$ is the $(q+1)^{\text{th}}$ derivative of f evaluated at some point ξ in an interval containing t , t_{p-q} , and t_p .

If we set

$$S = \frac{t - t_p}{h}$$

(7.1) becomes

$$f(t) = \binom{-S}{0} f_p - \binom{-S}{1} \nabla f_p + \cdots + (-1)^q \binom{-S}{q} \nabla^q f_p + (-1)^{q+1} h^{q+1} \binom{-S}{q+1} f^{(q+1)}(\xi) \quad (7.2)$$

where

$$\binom{S}{q} = \frac{s(s-1)\cdots(s-q+1)}{q!}$$

$$\text{and } \binom{S}{0} = 1$$

Alternatively, (7.2) can be written as

$$f(t) = \sum_{m=0}^q (-1)^m \binom{-S}{m} \nabla^m f_p + (-1)^{q+1} h^{q+1} \binom{-S}{q+1} f^{(q+1)}(\xi)$$

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The positive integer q is arbitrary in principle, but in practice rarely exceeds 6, say. Several classes of methods can now be distinguished according to the position of t and $t + K$ relative to the interpolating points, see the following Table.

Method	t	$t + K$
Adams-Bashforth	t_p	t_{p+1}
Adams-Moulton	t_{p-1}	t_p
Nystrom	t_{p-1}	t_{p+1}
Milne-Simpson	t_{p-2}	t_p

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i) The Adams-Bashforth method:

Here we have

$$\begin{aligned}
 y_{p+1} - y_p &= \int_{t_p}^{t_{p+1}} f(t) dt \\
 &= h \sum_{m=0}^q \gamma_m \nabla^m f_p
 \end{aligned} \tag{7.3}$$

where the constants

$$\begin{aligned}
 \gamma_m &= (-1)^m \frac{1}{h} \int_{t_p}^{t_{p+1}} \binom{-S}{m} dt \\
 &= (-1)^m \int_0^1 \binom{-S}{m} dS
 \end{aligned} \tag{7.4}$$

are independent of f and will be calculated numerically below. If the values $y_p, y_{p-1}, \dots, y_{p-q}$ are known, the corresponding values $f_n = f(t_n, y_n)$ can be calculated and the differences $\nabla^m f_p$ are easily formed. The expression on the right of (7.3) is thus known, and $y_{p+1} - y_p$ and hence y_{p+1} can be calculated. The index p is then increased by 1, and the same formula is used to calculate y_{p+2} , etc. The method breaks down if some of the values $y_p, y_{p-1}, \dots, y_{p-q}$ are not known. Such is the case at the beginning of the computation, where the initial condition furnishes only one of the required $q + 1$ values. In such cases the missing values have to be secured by an independent method.

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In order to find recurrence relation, numerical values, and other useful properties of the coefficients Y_m we use the method of generating functions. Such we call the function $G(t)$ which has the Y_m as coefficients in its Maclaurin expansion. Using the general form of the binomial theorem, we find

$$\begin{aligned} G(t_1) &= \sum_{m=0}^{\infty} Y_m t_1^m = \sum_{m=0}^{\infty} (-t_1)^m \int_0^1 \binom{-S}{m} dS \\ &= \int_0^1 \sum_{m=0}^{\infty} (-t_1)^m \binom{-S}{m} dS \\ &= \int_0^1 (1 - t_1)^{-S} dS \end{aligned}$$

The integral is easily evaluated by writing $(1 - t_1)^{-S} = e^{-S \log(1-t_1)}$. We thus find

$$G(t_1) = - \frac{t_1}{(1-t_1) \log(1-t_1)} \quad (7.5)$$

which can be written as

$$- \frac{\log(1-t_1)}{t_1} G(t_1) = \frac{1}{1-t_1},$$

Using the well-known expansions

$$\begin{aligned} \frac{1}{1-t_1} &= 1 + t_1 + t_1^2 + \dots \\ - \frac{\log(1-t_1)}{t_1} &= 1 + \frac{1}{2} t_1 + \frac{1}{3} t_1^2 + \dots \end{aligned} \quad (7.6)$$

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we obtain the following identity between power series:

$$\left(1 + \frac{1}{2} t_1 + \frac{1}{3} t_1^2 + \dots\right) (\gamma_0 + \gamma_1 t_1 + \gamma_2 t_1^2 + \dots) = 1 + t_1 + t_1^2 + \dots$$

By comparing the coefficients of corresponding powers of t , we find the relation

$$\gamma_m + \frac{1}{2} \gamma_{m-1} + \frac{1}{3} \gamma_{m-2} + \dots + \frac{1}{m+1} \gamma_0 = 1, \quad m = 0, 1, 2, \dots$$

which makes it possible to calculate the γ_m recursively.

m	0	1	2	3	4	5	6
γ_m	1	$\frac{1}{2}$	$\frac{5}{12}$	$\frac{3}{8}$	$\frac{251}{720}$	$\frac{95}{288}$	$\frac{19087}{60480}$

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