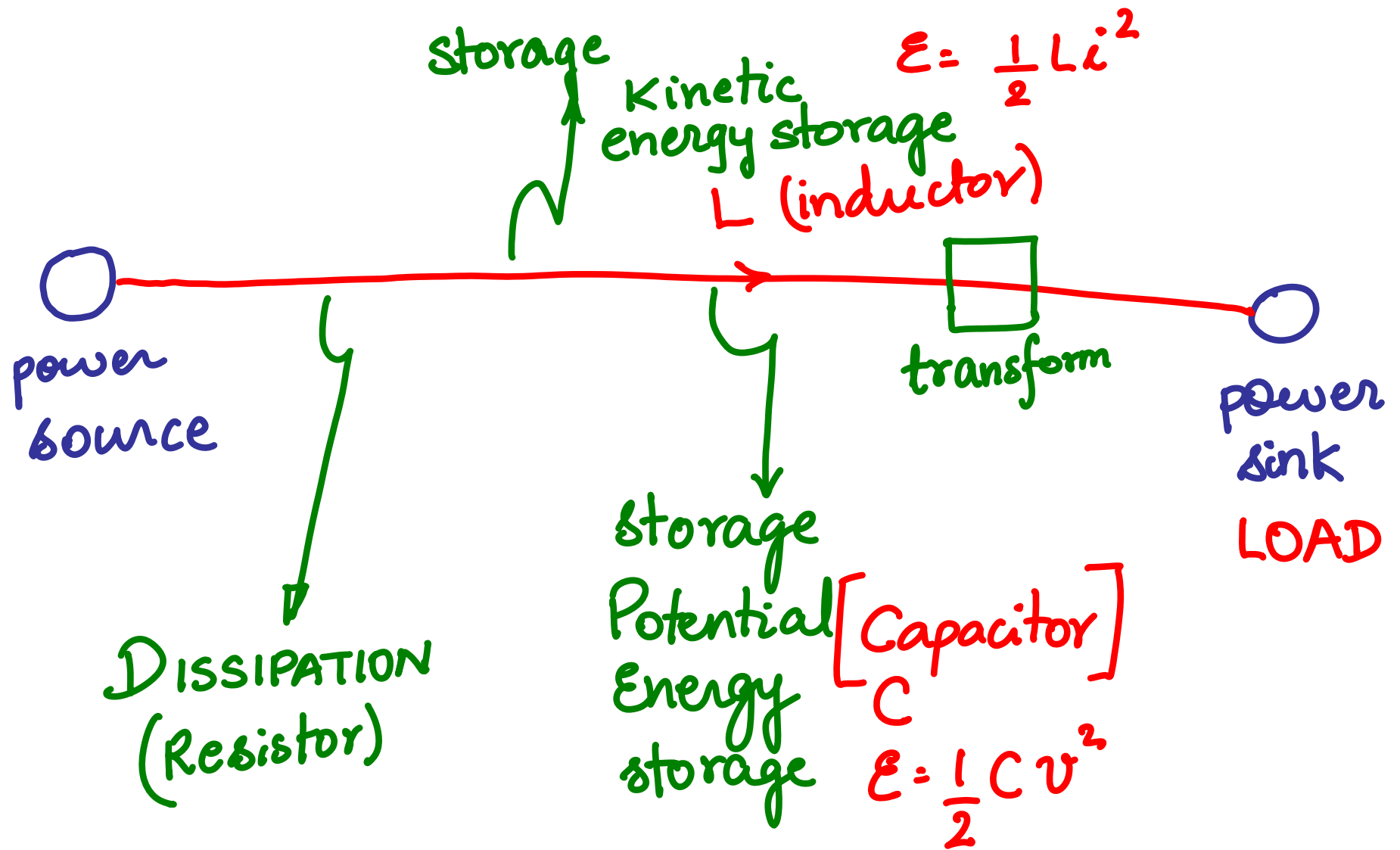
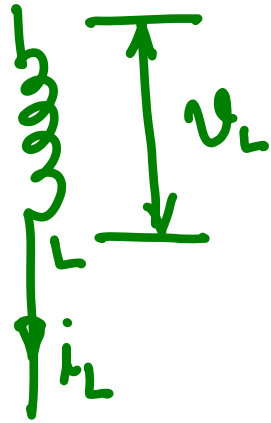


State Space Representation

State



Inductor, $L \Rightarrow \underline{v_L} = L \frac{di_L}{dt}$ — ①

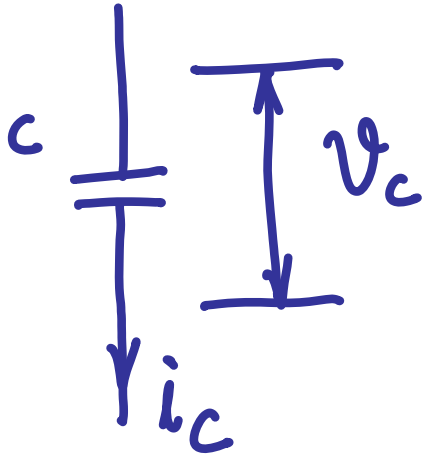


or $\underline{i_L} = \frac{1}{L} \int \underline{v_L} dt$ — ②

CAUSALITY

Integral Causal

Capacitor, $C =$ $v_c = \frac{1}{C} \int i_c dt$ — ①

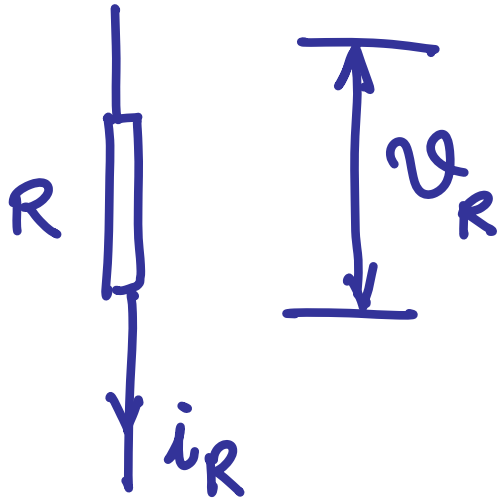


or

$$i_c = C \frac{dv_c}{dt} \quad \text{--- ②}$$

models

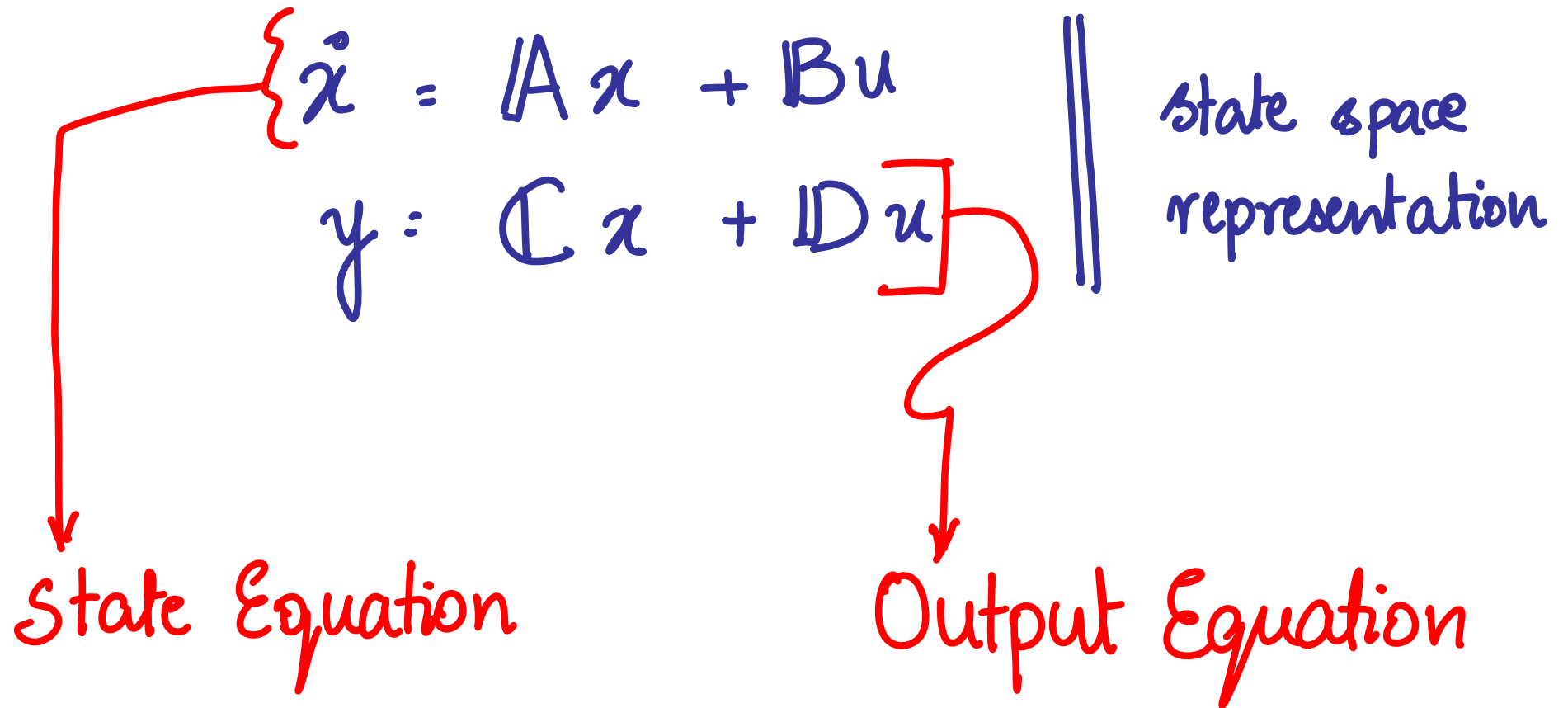
Dissipator, Resistor, R



$$\underline{V_R = i_R \cdot R} \quad \text{--- ①}$$

or

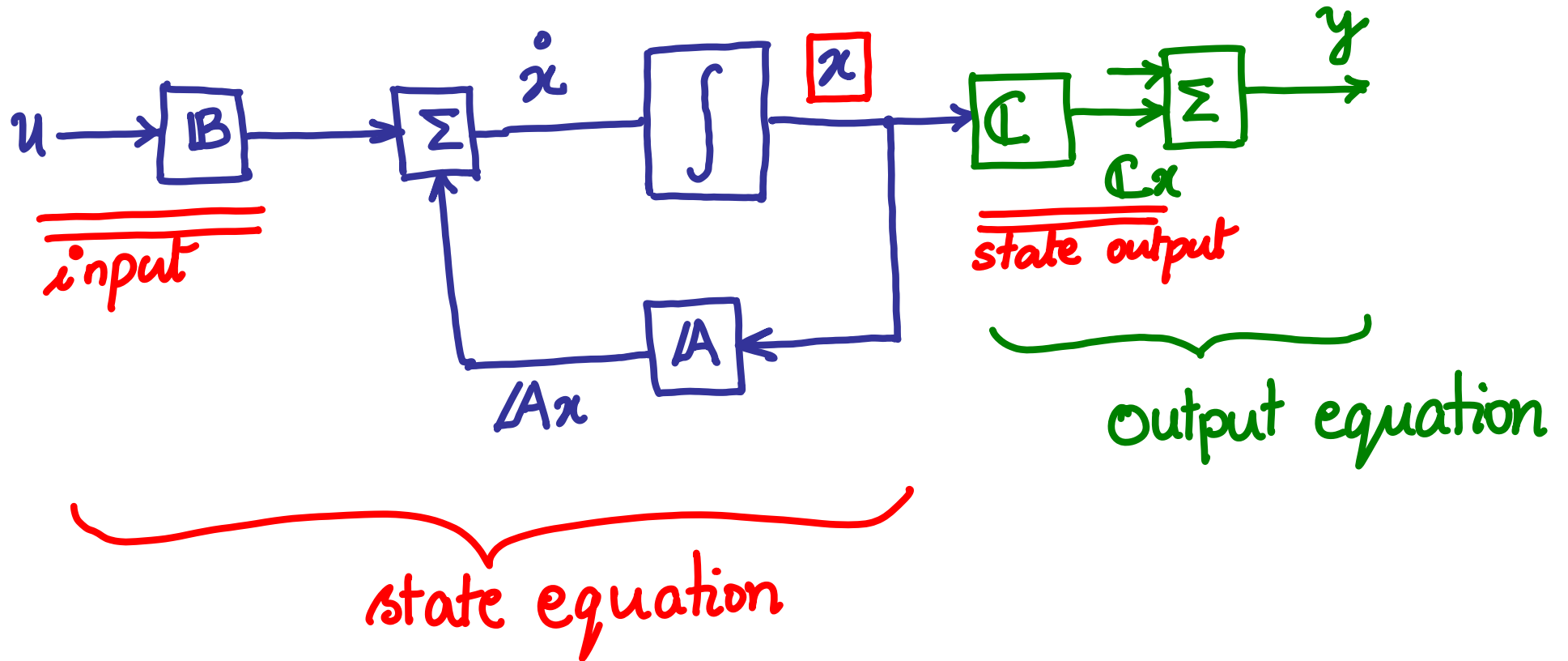
$$\underline{i_R = \frac{V_R}{R}} \quad \text{--- ②}$$

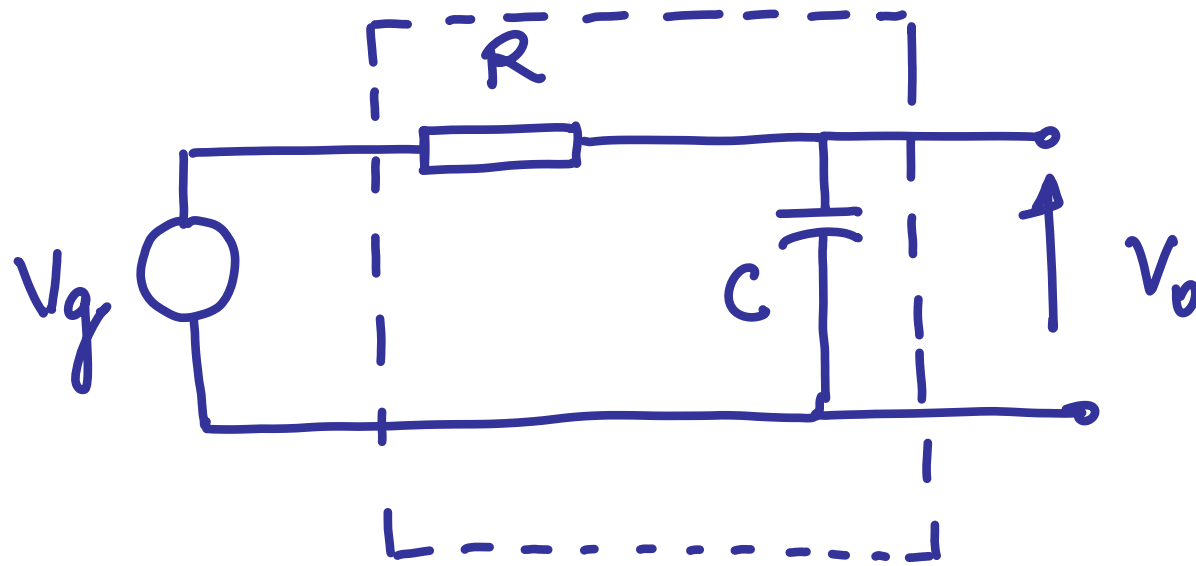


STANDARD

$$\dot{x} = \underline{\underline{A}}x + \underline{\underline{B}}u //$$

$$y = \underline{\underline{C}}x$$





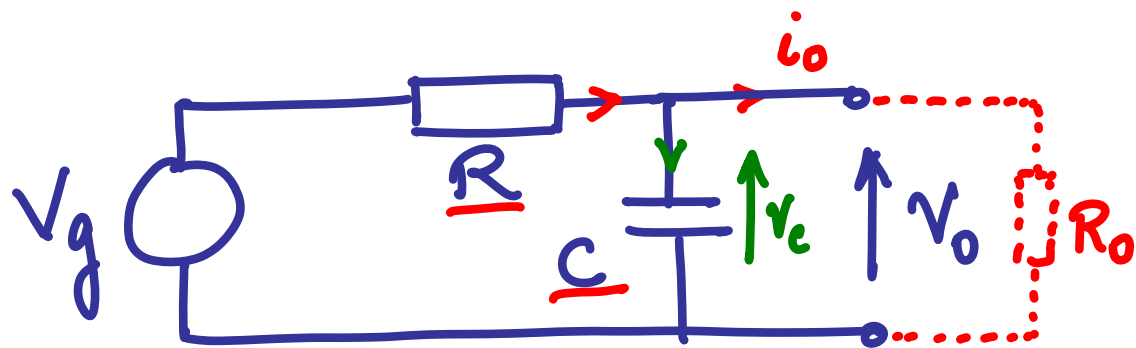
Step 1: Identify energy storing elements
ORDER of system
 $\rightarrow = 1$ first order system

Step 2: I identify the variables
that will be used for modelling

System's response \Rightarrow ① Input - u
② Integrator output
values.

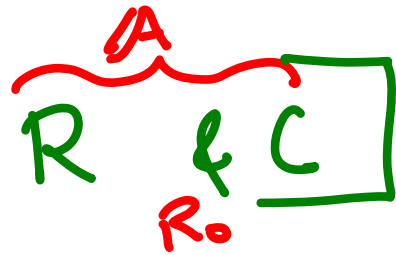
u_s x_s

state variables
 x



Step 3: Starting with dynamic elements obtain differential equations

(u) (x)
 $V_g, V_c,$
 $(V_c = V_o)$



$$V_c = \frac{1}{C} \int i_c dt$$

$$i_R - i_o$$

$$\frac{dV_c}{dt} = \frac{[V_g - V_c]}{CR} - \frac{1}{C R_o} V_c = \frac{\left(\frac{V_g - V_c}{R}\right) - \frac{V_c}{R_o}}{1}$$

Step 4: Segregate into form

$$\dot{x} = \underbrace{Ax}_{\text{state}} + \underbrace{Bu}_{\text{input}}$$

$$\dot{x} = Ax + Bu$$

state
space

$$\dot{v}_c = \begin{pmatrix} -\frac{1}{RC} & -\frac{1}{R_0 C} \end{pmatrix} v_c + \left(\frac{1}{RC} \right) v_g$$

— state
equation

representation

$$y = Cx + Du$$

$$v_o = [1] v_c + [0] v_g$$

— output
equation

- Steps
- 1 Identify the energy storage elements
 - 2 Identify variables – u , x , $[A]$
 - 3 Starting from Dynamic components
 - 4 Put all equations in the form

$$\begin{aligned}\dot{x} &= A x + B u \\ y &= C x + D u\end{aligned} \quad \parallel$$

Practice

