

An introduction to coding theory

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Lecture #16A: Turbo Decoding



Concatenated codes

Outline of the lecture

- Review of BCJR algorithm in log domain.



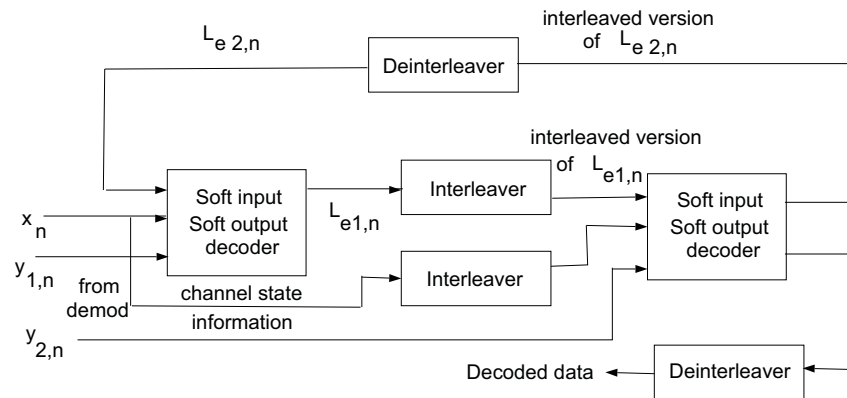
Concatenated codes

Outline of the lecture

- Review of BCJR algorithm in log domain.
- Turbo decoding for rate $R = 1/3$ code.



Turbo decoding



BCJR Algorithm

- Define $\max^*(\cdot)$ function:

$$\max^*(x, y) \equiv \ln(e^x + e^y) = \max(x, y) + \ln(1 + e^{-|x-y|})$$

$$\max^*(x, y, z) \equiv \ln(e^x + e^y + e^z) = \max^*[\max^*(x, y), z],$$

BCJR Algorithm

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- Branch metrics:

$$\gamma_l^*(s', s) \equiv \ln \gamma_l(s', s) = \frac{u_l L_a(u_l)}{2} + \frac{L_c}{2} \mathbf{r}_l \cdot \mathbf{v}_l$$

Navigation icons: back, forward, search, etc.

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- Forward metrics initialization:

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BCJR Algorithm

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BCJR Algorithm

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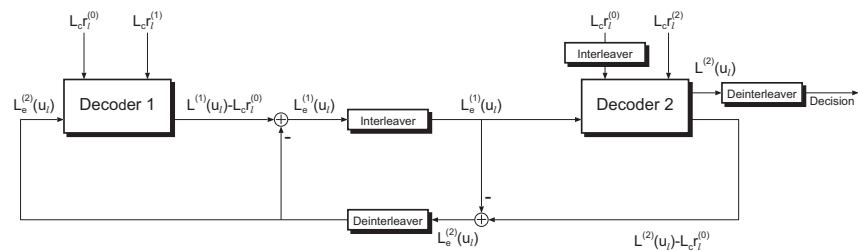
$$\beta_K^*(s) \equiv \ln \beta_K(s) = \begin{cases} 0, & s = \mathbf{0} \\ -\infty, & s \neq \mathbf{0}. \end{cases}$$

- APP L-value:

$$\begin{aligned} L(u_l) = & \max_{(s', s) \in \Sigma_l^+}^* [\beta_{l+1}^*(s) + \gamma_l^*(s', s) + \alpha_l^*(s')] \\ & - \max_{(s', s) \in \Sigma_l^-}^* [\beta_{l+1}^*(s) + \gamma_l^*(s', s) + \alpha_l^*(s')]. \end{aligned}$$

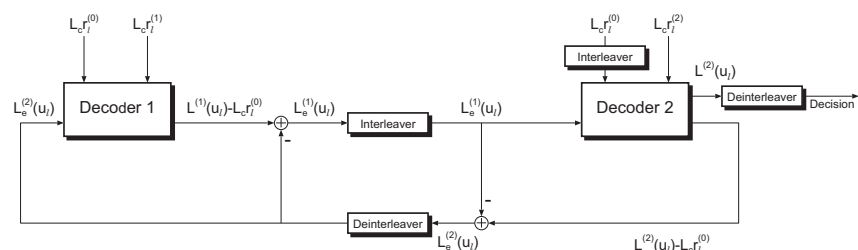


Turbo decoding



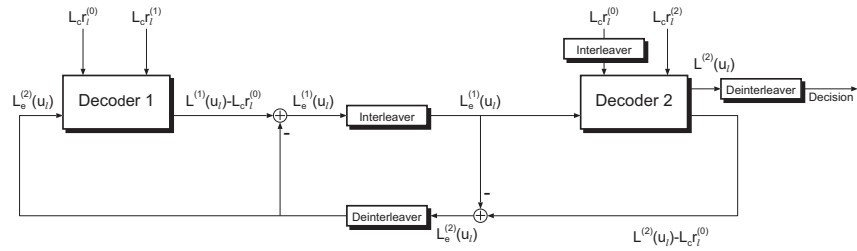
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Turbo decoding



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- It employs two SISO decoders using the MAP algorithm.

Turbo decoding



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- It employs two SISO decoders using the MAP algorithm.
- At each time unit l , three output values are received from the channel, one for the information bit $u_l = v_l^{(0)}$, denoted $r_l^{(0)}$, and two for the parity bits $v_l^{(1)}$ and $v_l^{(2)}$, denoted $r_l^{(1)}$ and $r_l^{(2)}$.

Navigation icons: back, forward, search, etc.

Turbo decoding

- The $3K$ -dimensional received vector is denoted by

$$\mathbf{r} = \left(r_0^{(0)} r_0^{(1)} r_0^{(2)}, r_1^{(0)} r_1^{(1)} r_1^{(2)}, \dots, r_{K-1}^{(0)} r_{K-1}^{(1)} r_{K-1}^{(2)} \right).$$

- Assume 0 is mapped to -1 and 1 to $+1$.
- Then for an AWGN channel, we define the log-likelihood ratio (L-value) $L(u_l | r_l^{(0)})$ (before decoding) of a transmitted information bit u_l given the received value $r_l^{(0)}$ as

$$\begin{aligned} L(u_l | r_l^{(0)}) &= \ln \frac{P(u_l = +1 | r_l^{(0)})}{P(u_l = -1 | r_l^{(0)})} \\ &= \ln \frac{P(r_l^{(0)} | u_l = +1) P(u_l = +1)}{P(r_l^{(0)} | u_l = -1) P(u_l = -1)} \end{aligned}$$

Navigation icons: back, forward, search, etc.

Turbo decoding

$$\begin{aligned}
 L(u_l | r_l^{(0)}) &= \ln \frac{P(r_l^{(0)} | u_l = +1)}{P(r_l^{(0)} | u_l = -1)} + \ln \frac{P(u_l = +1)}{P(u_l = -1)} \\
 &= \ln \frac{e^{-(E_s/N_0)(r_l^{(0)}-1)^2}}{e^{-(E_s/N_0)(r_l^{(0)}+1)^2}} + \ln \frac{P(u_l = +1)}{P(u_l = -1)}, \\
 &= -\frac{E_s}{N_0} \left\{ (r_l^{(0)} - 1)^2 - (r_l^{(0)} + 1)^2 \right\} + \ln \frac{P(u_l = +1)}{P(u_l = -1)} \\
 &= 4 \frac{E_s}{N_0} r_l^{(0)} + \ln \frac{P(u_l = +1)}{P(u_l = -1)} \\
 &= L_c r_l^{(0)} + L_a(u_l),
 \end{aligned}$$

where E_s/N_0 is the channel SNR, u_l and $r_l^{(0)}$ have both been normalized by a factor of $\sqrt{E_s}$, $L_c = 4(E_s/N_0)$ is the channel reliability factor and $L_a(u_l)$ is the a priori L-value of the bit u_l .

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Turbo decoding

- In the case of a transmitted parity bit $v_l^{(j)}$, given the received value $r_l^{(j)}$, $j = 1, 2$, the L-value (before decoding) is given by

$$L(v_l^{(j)} | r_l^{(j)}) = L_c r_l^{(j)} + L_a(v_l^{(j)}) = L_c r_l^{(j)}, \quad j = 1, 2, \quad (\text{why ?})$$

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- $L_a(u_l)$ also equals 0 for the first iteration of decoder 1, but that thereafter the a priori L -values of the information bits are replaced by extrinsic L -values from the other decoder.
- The received soft channel L -values $L_c r_l^{(0)}$ for u_l and $L_c r_l^{(1)}$ for $v_l^{(1)}$ enter decoder 1, while the (properly interleaved) received soft channel L -values $L_c r_l^{(0)}$ for u_l and the received soft channel L -values $L_c r_l^{(2)}$ for $v_l^{(2)}$ enter decoder 2.

Turbo decoding

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Turbo decoding

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- $L^{(1)}(u_l) = \ln \left[P(u_l = +1 \mid \mathbf{r}_1, \mathbf{L}_a^{(1)}) / P(u_l = -1 \mid \mathbf{r}_1, \mathbf{L}_a^{(1)}) \right],$



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- $L_e^{(1)}(u_l) = L^{(1)}(u_l) - [L_c r_l^{(0)} + L_e^{(2)}(u_l)]$,

- $L^{(1)}(u_l)$ is the a posteriori L -value (after decoding) of each information bit produced by decoder 1 given the (partial) received vector $\mathbf{r}_1 \triangleq [r_0^{(0)} r_0^{(1)}, r_1^{(0)} r_1^{(1)}, \dots, r_{K-1}^{(0)} r_{K-1}^{(1)}]$ and the a priori input vector $\mathbf{L}_a^{(1)} \triangleq [L_a^{(1)}(u_0), L_a^{(1)}(u_1), \dots, L_a^{(1)}(u_{K-1})]$ for decoder 1.

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- $L_e^{(1)}(u_l)$ is the extrinsic a posteriori L -value (after decoding) associated with each information bit produced by decoder 1, which, after interleaving, is passed to the input of decoder 2 as the a priori value $L_a^{(2)}(u_l)$.



Turbo decoding

- Subtracting the terms, viz., $L_c r_l^{(0)} + L_e^{(2)}(u_l)$ from $L^{(1)}(u_l)$, removes the effect of the current information bit u_l from $L^{(1)}(u_l)$, and thus providing an independent estimate of the information bit u_l to decoder 2 in addition to the received soft channel L -values at time l .



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- Similarly, the output of decoder 2 contains two terms:
 - $L^{(2)}(u_l) = \ln \left[P(u_l = +1 \mid \mathbf{r}_2, \mathbf{L}_a^{(2)}) / P(u_l = -1 \mid \mathbf{r}_2, \mathbf{L}_a^{(2)}) \right]$,
where \mathbf{r}_2 is the (partial) received vector and $\mathbf{L}_a^{(2)}$ the a priori input vector for decoder 2, and



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 - $L_e^{(2)}(u_l) = L^{(2)}(u_l) - [L_c r_l^{(0)} + L_e^{(1)}(u_l)]$, and the extrinsic a posteriori L -values $L_e^{(2)}(u_l)$ produced by decoder 2, after deinterleaving, are passed back to the input of decoder 1 as the a priori values $L_a^{(1)}(u_l)$.

Turbo decoding

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- In the initial iteration of decoder 1, the extrinsic a posteriori L -values $L_e^{(2)}(u_l) = L_a^{(1)}(u_l)$ are just the original a priori L -values $L_a(u_l)$, which are all equal to 0 for equally likely information bits.

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- Thus the extrinsic L -values passed from one decoder to the other during the iterative decoding process are treated like new sets of a priori probabilities by the MAP algorithm.



Turbo decoding

- Decoding then proceeds iteratively, with each decoder passing its respective extrinsic L -values back to the other decoder.
- Decoding stops after sufficient number of iterations.
- At the output of decoder 2, the decoded information bits are determined from the a posteriori L -values $L^{(2)}(u_l)$.
- Positive L -values are decoded as “+1” and negative L -values as “-1”.

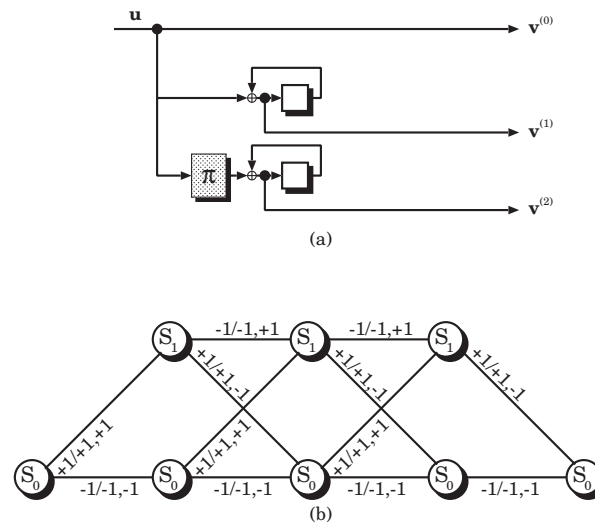
Example:

- Rate $R = 1/3$ turbo code using constituent encoder
$$\mathbf{G}(D) = \begin{bmatrix} 1 & \frac{1}{1+D} \end{bmatrix}$$

(See Figure in the next frame.)



Turbo decoding



Navigation icons: back, forward, search, etc.

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Turbo decoding

- Consider an input sequence of length $K = 4$, including one termination bit, along with a 2×2 block (row-column) interleaver, resulting in a $(12, 3)$ turbo code with overall rate $R = 1/4$.

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- The input block is given by the vector $\mathbf{u} = [u_0, u_1, u_2, u_3]$, the interleaved input block is $\mathbf{u}' = [u'_0, u'_1, u'_2, u'_3] = [u_0, u_2, u_1, u_3]$,



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- The parity vector for the first constituent code is given by $\mathbf{p}^{(1)} = [p_0^{(1)}, p_1^{(1)}, p_2^{(1)}, p_3^{(1)}]$.

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- The parity vector for the first constituent code is given by $\mathbf{p}^{(1)} = [p_0^{(1)}, p_1^{(1)}, p_2^{(1)}, p_3^{(1)}]$.
- The parity vector for the second constituent code is $\mathbf{p}^{(2)} = [p_0^{(2)}, p_1^{(2)}, p_2^{(2)}, p_3^{(2)}]$.

Turbo decoding

- The 12 transmitted bits are represented in a rectangular array, as shown in Figure in the next frame, where the input vector \mathbf{u} determines the parity vector $\mathbf{p}^{(1)}$ in the first two rows and the interleaved input vector \mathbf{u}' determines the parity vector $\mathbf{p}^{(2)}$ in the first two columns.

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- For purposes of illustration, we assume the particular bit values shown in Figure.

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- For purposes of illustration, we assume the particular bit values shown in Figure.
- We also assume a channel SNR of $E_s/N_0 = 1/4$ (-6.02dB), so that the received channel L -values corresponding to the received vector $\mathbf{r} = \left[r_0^{(0)} r_0^{(1)} r_0^{(2)}, r_1^{(0)} r_1^{(1)} r_1^{(2)}, r_2^{(0)} r_2^{(1)} r_2^{(2)}, r_3^{(0)} r_3^{(1)} r_3^{(2)} \right]$ are given by

$$L_c r_l^{(j)} = 4 \left(\frac{E_s}{N_0} \right) r_l^{(j)} = r_l^{(j)}, \quad l = 0, 1, 2, 3, \quad j = 0, 1, 2. \quad (1)$$

Turbo decoding

u_0	u_1	$p_0^{(1)}$	$p_1^{(1)}$
u_2	u_3	$p_2^{(1)}$	$p_3^{(1)}$
$p_0^{(2)}$	$p_2^{(2)}$		
$p_1^{(2)}$	$p_3^{(2)}$		

(12, 3) PCCC

-1	+1	-1	+1
-1	+1	+1	-1
-1	+1		
-1	-1		

Coded Values

+ 0.8	+ 1.0	+ 0.1	- 0.5
- 1.8	+ 1.6	+ 1.1	- 1.6
- 1.2	+ 0.2		
+ 1.2	- 1.1		

Received L-values

Turbo decoding

- In the first iteration of decoder 1 (row decoding), the BCJR algorithm is applied to the trellis of the 2-state $(2, 1, 1)$ code to compute the a posteriori L -values $L^{(1)}(u_I)$ for each of the four input bits and the corresponding extrinsic a posteriori L -values $L_e^{(1)}(u_I)$.

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- For iterative decoding, extrinsic a-posteriori L -values are computed for all input bits, termination bits as well as information bits.
- Before the first iteration of decoding, the a-priori L -values of the termination bits are assumed to be zero.
- Similarly, in the first iteration of decoder 2, the BCJR algorithm uses the extrinsic a posteriori L -values $L_e^{(1)}(u_I)$ received from decoder 1 as the a priori L -values, $L_a^{(2)}(u_I)$ to compute the a posteriori L -values $L^{(2)}(u_I)$ for each of the four input bits and the corresponding extrinsic a posteriori L -values $L_e^{(2)}(u_I)$ to pass back to decoder 1.

Turbo decoding

- In the first iteration of decoder 1 (row decoding), the BCJR algorithm is applied to the trellis of the 2-state $(2, 1, 1)$ code to compute the a posteriori L -values $L^{(1)}(u_I)$ for each of the four input bits and the corresponding extrinsic a posteriori L -values $L_e^{(1)}(u_I)$.
- For iterative decoding, extrinsic a-posteriori L -values are computed for all input bits, termination bits as well as information bits.
- Before the first iteration of decoding, the a-priori L -values of the termination bits are assumed to be zero.
- Similarly, in the first iteration of decoder 2, the BCJR algorithm uses the extrinsic a posteriori L -values $L_e^{(1)}(u_I)$ received from decoder 1 as the a priori L -values, $L_a^{(2)}(u_I)$ to compute the a posteriori L -values $L^{(2)}(u_I)$ for each of the four input bits and the corresponding extrinsic a posteriori L -values $L_e^{(2)}(u_I)$ to pass back to decoder 1.
- Decoding proceeds iteratively in this fashion.

Navigation icons: back, forward, search, etc.

Turbo decoding

-0.32	-0.38
+0.77	+0.47

Extrinsic L -values after first row decoding

-0.88	-0.69
+0.23	-0.04

Extrinsic L -values after first column decoding

-0.40	-0.07
-0.80	+2.03

Soft-output L -values after the first row and column decoding

-0.01	-0.01
+0.43	+0.77

Extrinsic L -values after second row decoding

-0.98	-0.81
+0.07	-0.21

Extrinsic L -values after second column decoding

-0.19	+0.18
-1.30	+2.16

Soft-output L -values after the second row and column decoding

Navigation icons: back, forward, search, etc.