

# An introduction to coding theory

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## Lecture #11B: Problem solving session-IV

# Convolutional codes

- **Problem # 1:** Consider rate  $R = 1/3$  convolutional code with encoding matrix

$$G(D) = \begin{pmatrix} \frac{1+D+D^2}{1+D^4} & \frac{1+D^2+D^4}{1+D^4} & \frac{1+D+D^2}{1+D^2} \end{pmatrix}$$

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- a) Is  $G(D)$  catastrophic? Explain.

# Convolutional codes

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$$G(D) = \left( \frac{1 + D + D^2}{1 + D^4} \quad \frac{1 + D^2 + D^4}{1 + D^4} \quad \frac{1 + D + D^2}{1 + D^2} \right)$$

a) Is  $G(D)$  catastrophic? Explain.

- **Solution:** Yes,  $G(D)$  can be equivalently written as

$$G(D) = \frac{1}{1+D^2} \left[ \frac{1+D+D^2}{1+D^2} \quad \frac{1+D^2+D^4}{1+D^2} \quad 1+D+D^2 \right]$$

or equivalently in the form

$$G(D) = \frac{1 + D + D^2}{1 + D^4} [1 \ 1 + D + D^2 \ 1 + D^2]$$

An input of infinite weight  $\frac{1+D^4}{1+D+D^2}$  can result in an output sequence of weight 6.

# Convolutional codes

- b) Find a minimal encoder whose encoding matrix is equivalent to  $G(D)$ .

**Solution:** An equivalent minimal encoder is given by

$$G(D) = [1 \quad 1 + D + D^2 \quad 1 + D^2]$$

# Convolutional codes

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$$G(D) = \begin{bmatrix} D & D^2 & 1 \\ 1 & D^2 & 1 + D + D^2 \end{bmatrix}$$

# Convolutional codes

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- **Solutions:**

- i) Controller canonical form encoder realization is given in Figure 1

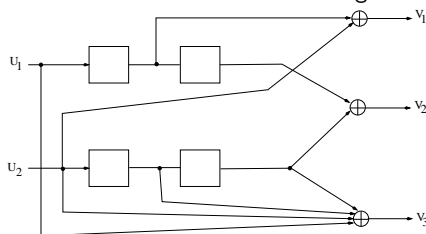


Figure: Canonical Form encoder realization

# Convolutional codes

- ii) Find the generator matrix  $G'(D)$  of the equivalent systematic feedback encoder.

- ii) **Solutions:** We have

$$G(D) = \begin{bmatrix} D & D^2 & 1 \\ 1 & D^2 & 1 + D + D^2 \end{bmatrix}$$

# Convolutional codes

- ii) Find the generator matrix  $G'(D)$  of the equivalent systematic feedback encoder.

ii) **Solutions:** We have

$$G(D) = \begin{bmatrix} D & D^2 & 1 \\ 1 & D^2 & 1 + D + D^2 \end{bmatrix}$$

- Now applying Row 1  $\leftarrow$  (Row 1)/D, we get

$$G(D) = \begin{bmatrix} 1 & D & \frac{1}{D} \\ 1 & D^2 & 1 + D + D^2 \end{bmatrix}$$

Navigation icons: back, forward, search, etc.

# Convolutional codes

- Now applying Row 2  $\leftarrow$  Row 1 + Row 2, we get

$$G(D) = \begin{bmatrix} 1 & D & \frac{1}{D} \\ 0 & D + D^2 & \frac{1+D+D^2+D^3}{D} \end{bmatrix}$$

- Now applying Row 2  $\leftarrow$  (Row 2)/(D + D<sup>2</sup>), we get

$$G(D) = \begin{bmatrix} 1 & D & \frac{1}{D} \\ 0 & 1 & \frac{1+D^2}{D^2} \end{bmatrix}$$

- Now applying Row 1  $\leftarrow$  Row 1 + D (Row 2), we get

$$G(D) = \begin{bmatrix} 1 & 0 & D \\ 0 & 1 & \frac{1+D^2}{D^2} \end{bmatrix}$$

Navigation icons: back, forward, search, etc.

## Convolutional codes

- iii) Is  $G'(D)$  realizable? If not, find an equivalent realizable generator matrix and draw the corresponding minimal encoder realization.
- iii) Equivalent systematic encoder is not realizable, so we can make it realizable by applying  $\text{Row } 2 \leftarrow (\text{Row } 2)(D^2)$ . We get

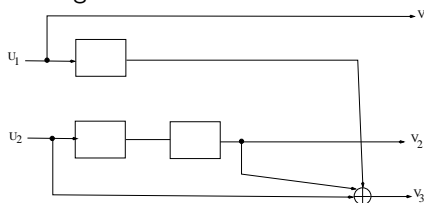
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$$G(D) = \begin{bmatrix} 1 & 0 & D \\ 0 & D^2 & 1 + D^2 \end{bmatrix}$$

- Controller canonical form encoder realization of the equivalent encoder is given in Figure 2



**Figure:** Canonical Form encoder realization of the equivalent encoder



# Convolutional codes

- **Problem # 3:** In Figure 3, a rate  $R = 2/3$  systematic convolutional encoder is shown.

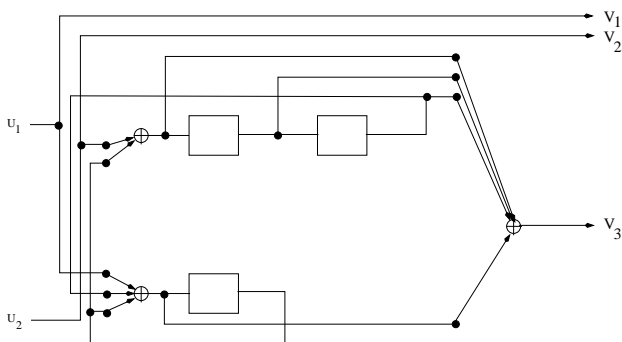


Figure: Figure for Problem 3.

Navigation icons: back, forward, search, etc.

# Convolutional codes

- (a) Give the expression for the generator matrix  $\mathbf{G}(\mathbf{D})$

- **Solutions:**

Navigation icons: back, forward, search, etc.

# Convolutional codes

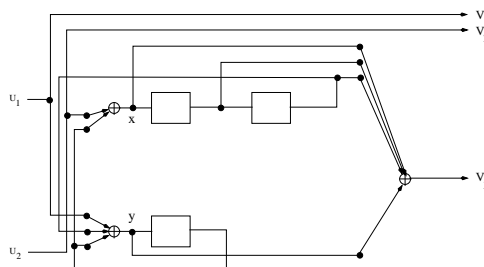
(a) Give the expression for the generator matrix  $\mathbf{G}(D)$

- **Solutions:**
- We can write

$$v_1(D) = u_1(D)$$

$$v_2(D) = u_2(D)$$

$$v_3(D) = (1 + D + D^2)x(D) + y(D)$$



# Convolutional codes

- Also,

$$y(D) = u_1(D) + D^2x(D) + Dy(D)$$

$$x(D) = u_2(D) + Dy(D)$$

- Solving for  $x(D)$  and  $y(D)$ , we get

$$y(D) = \frac{1}{1 + D + D^3} u_1(D) + \frac{D^2}{1 + D + D^3} u_2(D)$$

$$x(D) = \frac{D}{1 + D + D^3} u_1(D) + \frac{1 + D}{1 + D + D^3} u_2(D)$$

- Hence,  $v_3(D)$  is

$$y(D) = \frac{1 + D + D^2 + D^3}{1 + D + D^3} u_1(D) + \frac{1 + D^2 + D^3}{1 + D + D^3} u_2(D)$$

# Convolutional codes

- Therefore,  $\mathbf{G}(\mathbf{D})$  is given by

$$\mathbf{G}(\mathbf{D}) = \begin{bmatrix} 1 & 0 & \frac{1+D+D^2+D^3}{1+D+D^3} \\ 0 & 1 & \frac{1+D^2+D^3}{1+D+D^3} \end{bmatrix}$$

# Convolutional codes

- (b) Realize the convolution encoder in controller canonical form. How many termination bits are required to terminate the encoder for controller canonical form realization.
- Convolutional encoder in controller canonical form.

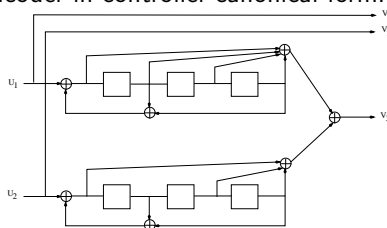


Figure: Answer to Problem 3(b)

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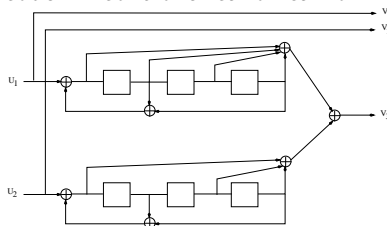


Figure: Answer to Problem 3(b)

- The controller canonical form realization of this encoder uses 6 memory elements, so the encoder will require 6 termination bits to return to all-zero state.

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# Convolutional codes

- Problem # 4:

# Convolutional codes

- **Problem # 4:**

- (a) Show that the a-priori probability can be written in this form

$$P(u_I = \pm 1) = A_I \exp^{u_I L_a(u_I)/2}$$

where  $L_a(\cdot)$  is the a-priori L-values of the information bits.

# Convolutional codes

- **Problem # 4:**

- (a) Show that the a-priori probability can be written in this form

$$P(u_I = \pm 1) = A_I \exp^{u_I L_a(u_I)/2}$$

where  $L_a(\cdot)$  is the a-priori L-values of the information bits.

- (b) Using this result, show that the branch metrics  $\gamma^*(s, s')$  for a continuous-output AWGN channel (in log-domain) can be written as

$$\gamma^*(s, s') = \frac{u_I L_a(u_I)}{2} + L_c \mathbf{r}_I \cdot \mathbf{v}_I$$

where  $L_c = 4E_s/N_0$  is the channel reliability factor. Notations are the same as used in class lectures.

# Convolutional codes

- **Solutions:** We can write

$$\begin{aligned}P(u_l = \pm 1) &= \frac{[P(u_l = +1)/P(u_l = -1)]^{\pm 1}}{\{1 + [P(u_l = +1)/P(u_l = -1)]^{\pm 1}\}} \\&= \frac{e^{\pm L_a(u_l)}}{\{1 + e^{\pm L_a(u_l)}\}} \\&= \frac{e^{-L_a(u_l)/2}}{\{1 + e^{-L_a(u_l)}\}} e^{u_l L_a(u_l)/2} \\&= A_l e^{u_l L_a(u_l)/2},\end{aligned}$$

# Convolutional codes

- Also,

$$\begin{aligned}\gamma_l(s', s) &= A_l e^{u_l L_a(u_l)/2} e^{-(E_s/N_0) \|\mathbf{r}_l - \mathbf{v}_l\|^2}, \\&= A_l e^{u_l L_a(u_l)/2} e^{(2E_s/N_0)(\mathbf{r}_l \cdot \mathbf{v}_l) - (E_s/N_0)(\|\mathbf{r}_l\|^2 + \|\mathbf{v}_l\|^2)} \\&= A_l e^{-(E_s/N_0)(\|\mathbf{r}_l\|^2 + \|\mathbf{v}_l\|^2)} e^{u_l L_a(u_l)/2} e^{(L_c/2)(\mathbf{r}_l \cdot \mathbf{v}_l)} \\&= A_l B_l e^{u_l L_a(u_l)/2} e^{(L_c/2)(\mathbf{r}_l \cdot \mathbf{v}_l)}\end{aligned}$$

- Also,

$$\begin{aligned}\gamma_I(s', s) &= A_I e^{u_I L_a(u_I)/2} e^{-(E_s/N_0) \|\mathbf{r}_I - \mathbf{v}_I\|^2}, \\ &= A_I e^{u_I L_a(u_I)/2} e^{(2E_s/N_0)(\mathbf{r}_I \cdot \mathbf{v}_I) - (E_s/N_0)(\|\mathbf{r}_I\|^2 + \|\mathbf{v}_I\|^2)} \\ &= A_I e^{-(E_s/N_0)(\|\mathbf{r}_I\|^2 + \|\mathbf{v}_I\|^2)} e^{u_I L_a(u_I)/2} e^{(L_c/2)(\mathbf{r}_I \cdot \mathbf{v}_I)} \\ &= A_I B_I e^{u_I L_a(u_I)/2} e^{(L_c/2)(\mathbf{r}_I \cdot \mathbf{v}_I)}\end{aligned}$$

- Thus

$$\gamma_I^*(s', s) = \ln \gamma_I(s', s) = \frac{u_I L_a(u_I)}{2} + \frac{L_c}{2} \mathbf{r}_I \cdot \mathbf{v}_I$$