

Introduction to Machine-Independent Optimizations - 2 Data-Flow Analysis

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Outline of the Lecture

- What is code optimization? (in part 1)
- Illustrations of code optimizations (in part 1)
- Examples of data-flow analysis
- Fundamentals of control-flow analysis
- Algorithms for two machine-independent optimizations
- SSA form and optimizations

Data-Flow Analysis Schema

- A *data-flow value* for a program point represents an abstraction of the set of all possible program states that can be observed for that point
- The set of all possible data-flow values is the *domain* for the application under consideration
 - Example: for the *reaching definitions* problem, the domain of data-flow values is the set of all subsets of definitions in the program
 - A particular data-flow value is a set of definitions
- $IN[s]$ and $OUT[s]$: data-flow values *before* and *after* each statement s
- The *data-flow problem* is to find a solution to a set of constraints on $IN[s]$ and $OUT[s]$, for all statements s

Data-Flow Analysis Schema (2)

- Two kinds of constraints
 - Those based on the semantics of statements (*transfer functions*)
 - Those based on flow of control
- A DFA schema consists of
 - A control-flow graph
 - A direction of data-flow (forward or backward)
 - A set of data-flow values
 - A confluence operator (usually set union or intersection)
 - Transfer functions for each block
- We always compute *safe* estimates of data-flow values
- A decision or estimate is *safe* or *conservative*, if it never leads to a change in what the program computes (after the change)
- These safe values may be either subsets or supersets of actual values, based on the application

The Reaching Definitions Problem

- We *kill* a definition of a variable a , if between two points along the path, there is an assignment to a
- A definition d reaches a point p , if there is a path from the point immediately following d to p , such that d is not *killed* along that path
- Unambiguous and ambiguous definitions of a variable

$a := b+c$

(unambiguous definition of 'a')

...

* $p := d$

(ambiguous definition of 'a', if 'p' may point to variables other than 'a' as well; hence does not kill the above definition of 'a')

...

$a := k-m$

(unambiguous definition of 'a'; kills the above definition of 'a')

The Reaching Definitions Problem(2)

- We compute supersets of definitions as *safe* values
- It is safe to assume that a definition reaches a point, even if it does not.
- In the following example, we assume that both $a=2$ and $a=4$ reach the point after the complete if-then-else statement, even though the statement $a=4$ is not reached by control flow

```
if (a==b) a=2; else if (a==b) a=4;
```

The Reaching Definitions Problem (3)

- The data-flow equations (constraints)

$$\begin{aligned} IN[B] &= \bigcup_{P \text{ is a predecessor of } B} OUT[P] \\ OUT[B] &= GEN[B] \cup (IN[B] - KILL[B]) \\ IN[B] &= \phi, \text{ for all } B \text{ (initialization only)} \end{aligned}$$

- If some definitions reach B_1 (entry), then $IN[B_1]$ is initialized to that set
- Forward flow DFA problem (since $OUT[B]$ is expressed in terms of $IN[B]$), confluence operator is \cup
 - Direction of flow does not imply traversing the basic blocks in a particular order
 - The final result does not depend on the order of traversal of the basic blocks

The Reaching Definitions Problem (4)

- $GEN[B]$ = set of all definitions inside B that are “visible” immediately after the block - *downwards exposed* definitions
 - If a variable x has two or more definitions in a basic block, then only the last definition of x is downwards exposed; all others are not visible outside the block
- $KILL[B]$ = union of the definitions in all the basic blocks of the flow graph, that are killed by individual statements in B
 - If a variable x has a definition d_i in a basic block, then d_i kills all the definitions of the variable x in the program, except d_i

Reaching Definitions Analysis: GEN and KILL

In other blocks:

```
d5: b = a+4  
d6: f = e+c  
d7: e = b+d  
d8: d = a+b  
d9: a = c+f  
d10: c = e+a
```

```
d1: a = f + 1  
d2: b = a + 7  
d3: c = b + d  
d4: a = d + c
```

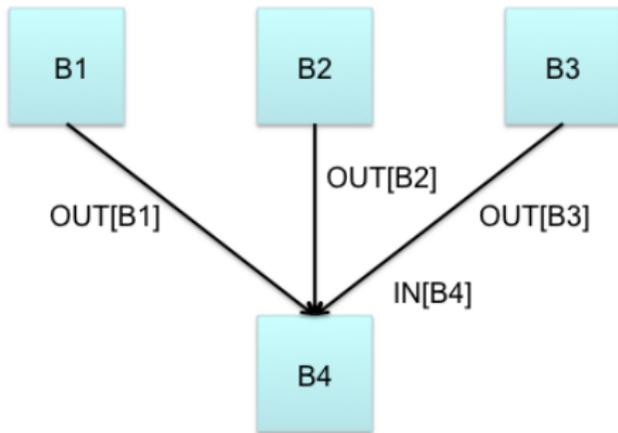
B

Set of all definitions = {d1,d2,d3,d4,d5,d6,d7,d8,d9,10}

GEN[B] = {d2,d3,d4}

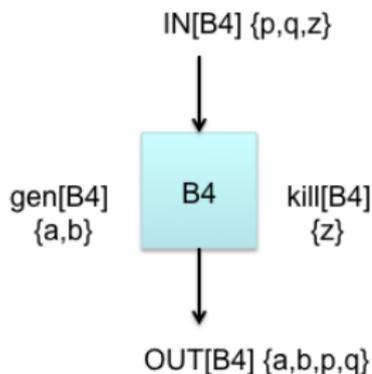
KILL[B] = {d4,d9,d5,d10,d1}

Reaching Definitions Analysis: DF Equations



$$IN[B4] = OUT[B1] \cup OUT[B2] \cup OUT[B3]$$

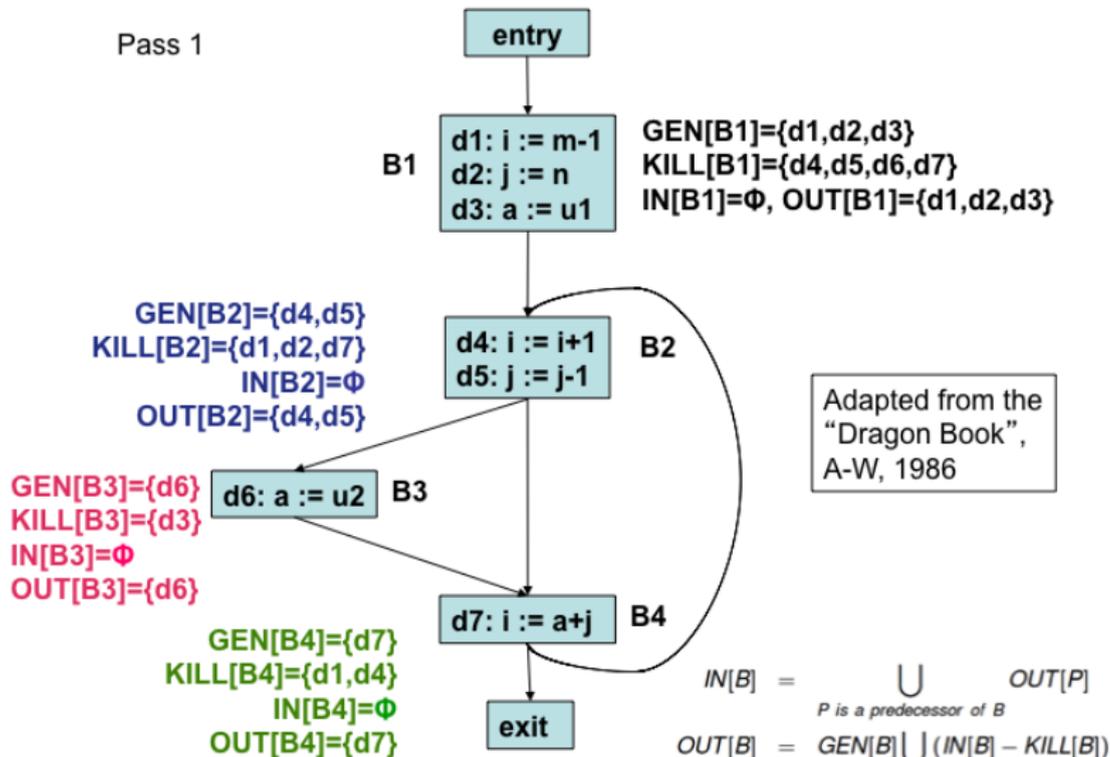
$$IN[B] = \bigcup_{P \text{ is a predecessor of } B} OUT[P]$$
$$OUT[B] = GEN[B] \cup (IN[B] - KILL[B])$$



$$OUT[B4] = gen[B4] \cup (IN[B4] - kill[B4])$$

Reaching Definitions Analysis: An Example - Pass 1

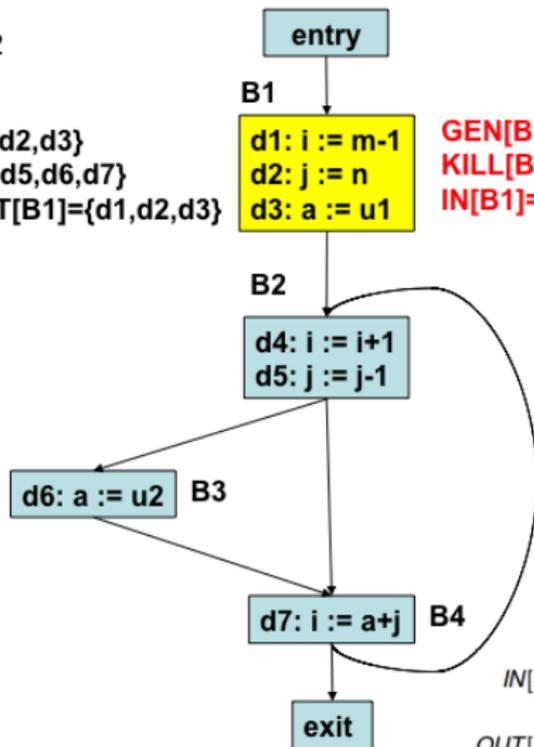
Pass 1



Reaching Definitions Analysis: An Example - Pass 2.1

Pass 2

$GEN[B1]=\{d1,d2,d3\}$
 $KILL[B1]=\{d4,d5,d6,d7\}$
 $IN[B1]=\Phi, OUT[B1]=\{d1,d2,d3\}$

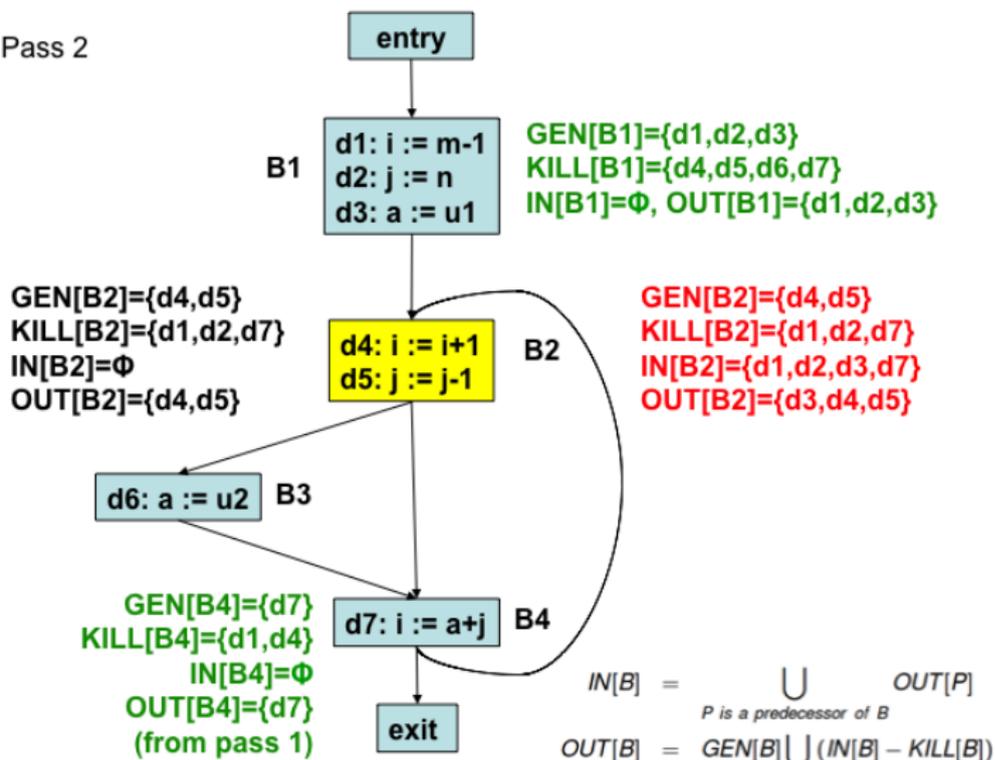


$GEN[B1]=\{d1,d2,d3\}$
 $KILL[B1]=\{d4,d5,d6,d7\}$
 $IN[B1]=\Phi, OUT[B1]=\{d1,d2,d3\}$

$$IN[B] = \bigcup_{P \text{ is a predecessor of } B} OUT[P]$$
$$OUT[B] = GEN[B] \cup (IN[B] - KILL[B])$$

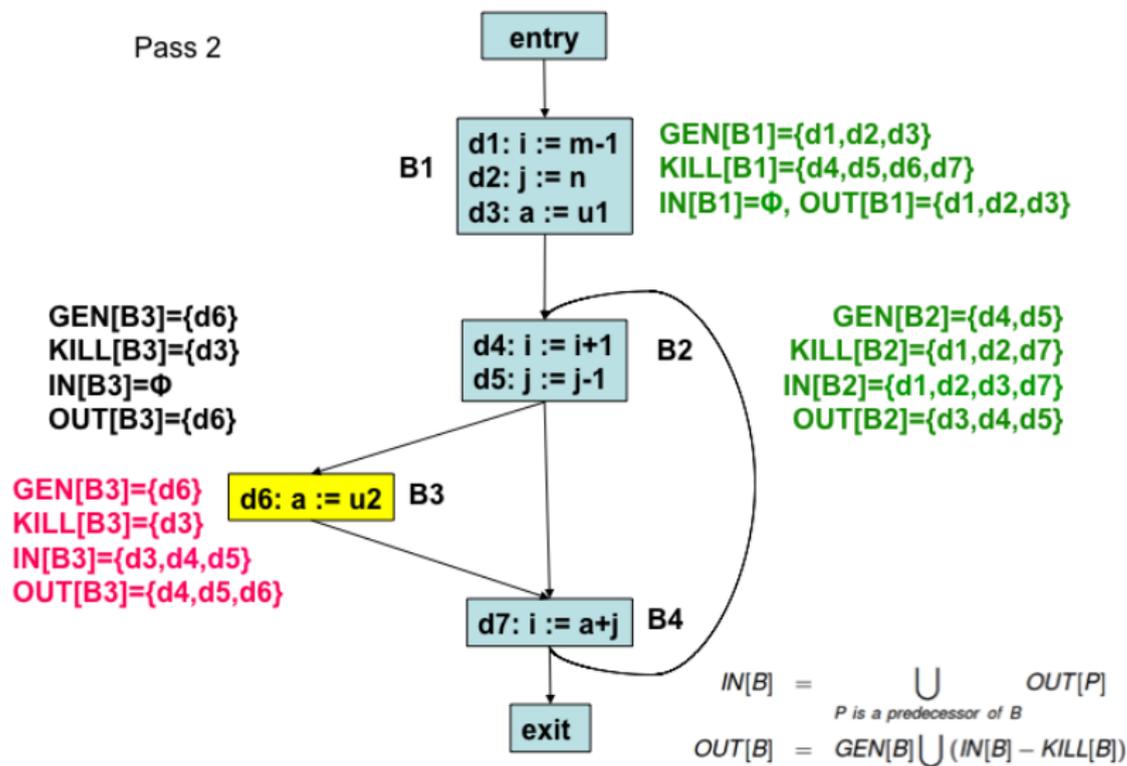
Reaching Definitions Analysis: An Example - Pass 2.2

Pass 2



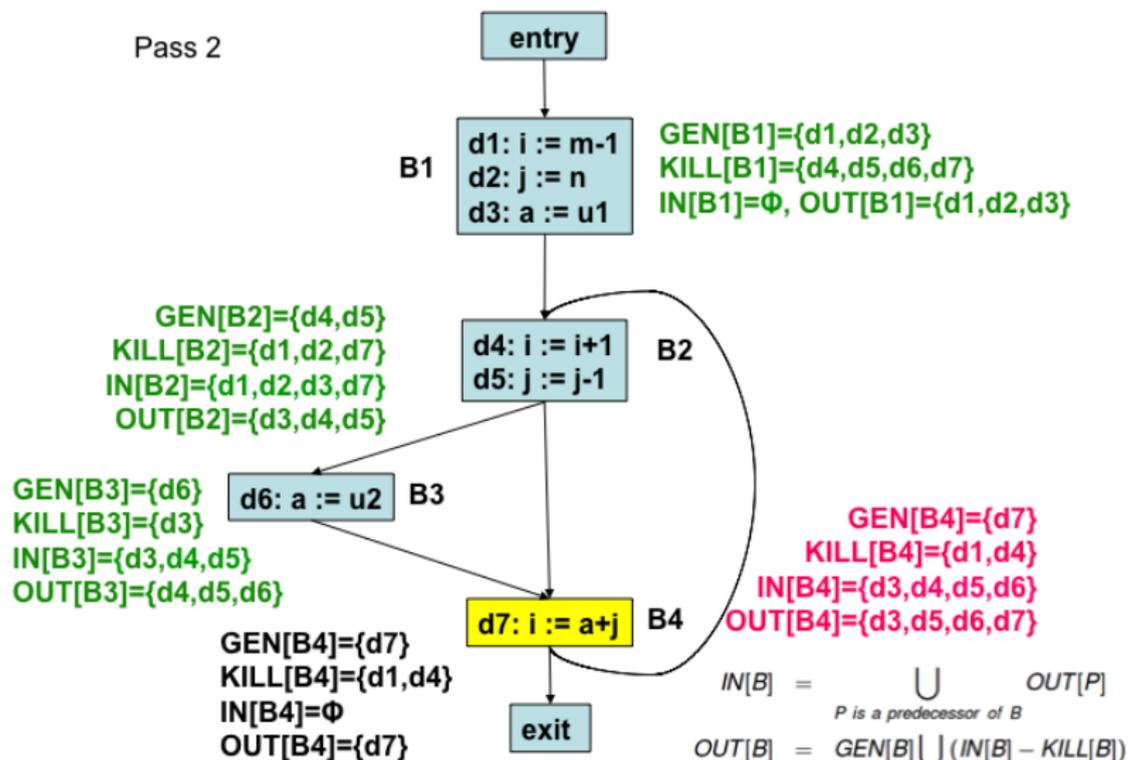
Reaching Definitions Analysis: An Example - Pass 2.3

Pass 2



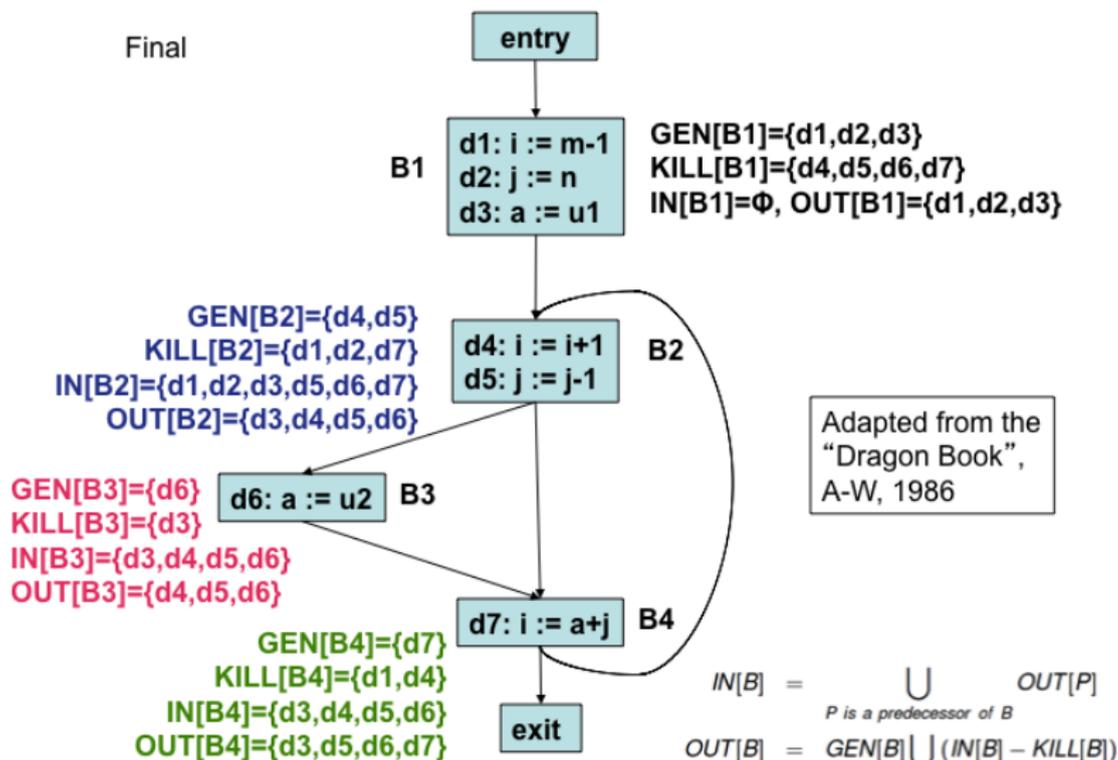
Reaching Definitions Analysis: An Example - Pass 2.4

Pass 2



Reaching Definitions Analysis: An Example - Final

Final



An Iterative Algorithm for Computing Reaching Def.

```
for each block  $B$  do {  $IN[B] = \phi$ ;  $OUT[B] = GEN[B]$ ; }  
 $change = true$ ;  
while  $change$  do {  $change = false$ ;  
  for each block  $B$  do {
```

$$IN[B] = \bigcup_{P \text{ a predecessor of } B} OUT[P];$$

$$oldout = OUT[B];$$

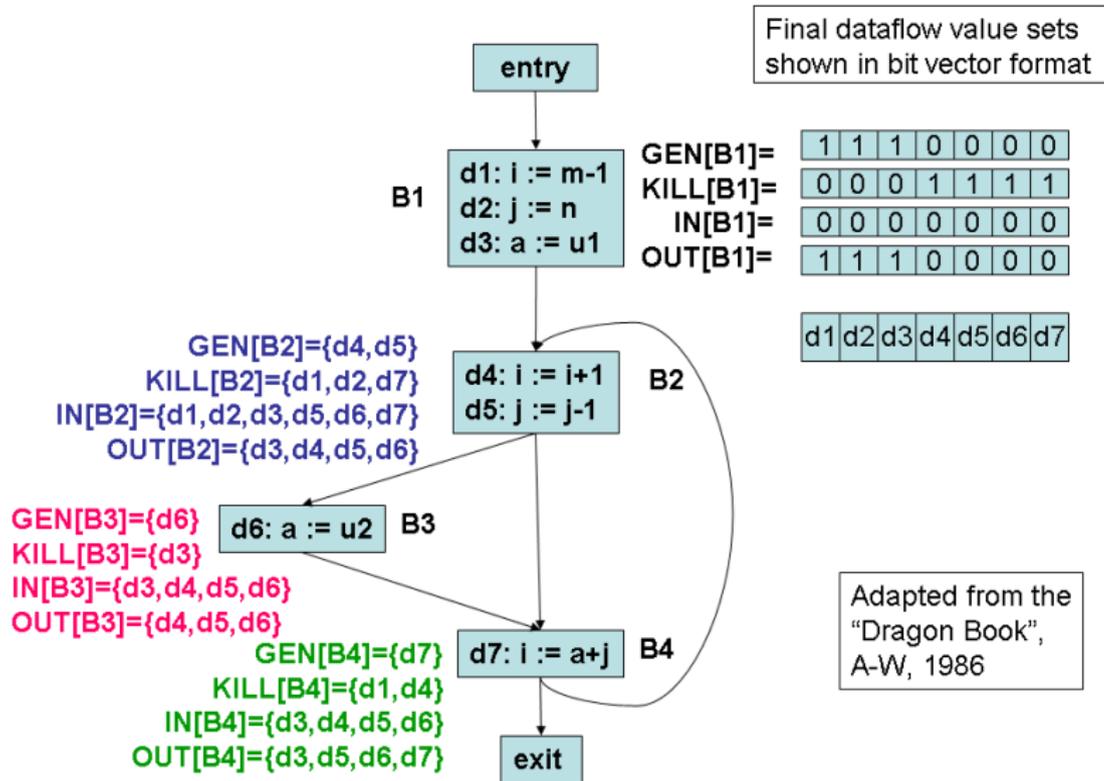
$$OUT[B] = GEN[B] \cup (IN[B] - KILL[B]);$$

```
  if ( $OUT[B] \neq oldout$ )  $change = true$ ;
```

```
  }  
}
```

- GEN , $KILL$, IN , and OUT are all represented as bit vectors with one bit for each definition in the flow graph

Reaching Definitions: Bit Vector Representation

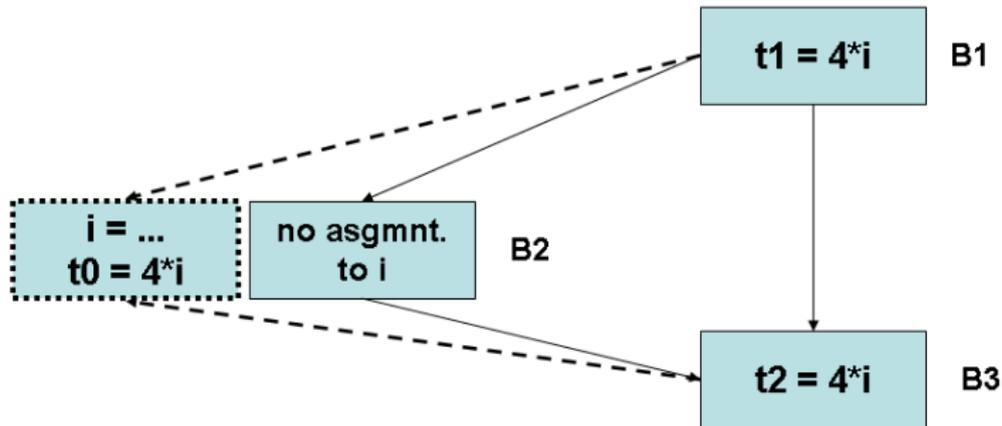


Available Expression Computation

- Sets of expressions constitute the domain of data-flow values
- Forward flow problem
- Confluence operator is \cap
- An expression $x + y$ is *available* at a point p , if every path (not necessarily cycle-free) from the initial node to p evaluates $x + y$, and after the last such evaluation, prior to reaching p , there are no subsequent assignments to x or y
- A block *kills* $x + y$, if it assigns (or may assign) to x or y and does not subsequently recompute $x + y$.
- A block *generates* $x + y$, if it definitely evaluates $x + y$, and does not subsequently redefine x or y

Available Expression Computation(2)

- Useful for global common sub-expression elimination
- $4 * i$ is a CSE in $B3$, if it is available at the entry point of $B3$ *i.e.*, if i is not assigned a new value in $B2$ or $4 * i$ is recomputed after i is assigned a new value in $B2$ (as shown in the dotted box)



Computing e_gen and e_kill

- For statements of the form $x = a$, step 1 below does not apply
- The set of all expressions appearing as the RHS of assignments in the flow graph is assumed to be available and is represented using a hash table and a bit vector

$$e_gen[q] = A \quad \begin{array}{l} \text{q} \cdot \\ x = y + z \\ \text{p} \cdot \end{array}$$

$$e_kill[q] = A \quad \begin{array}{l} \text{q} \cdot \\ x = y + z \\ \text{p} \cdot \end{array}$$

Computing e_gen[p]

1. $A = A \cup \{y+z\}$
2. $A = A - \{\text{all expressions involving } x\}$
3. $e_gen[p] = A$

Computing e_kill[p]

1. $A = A - \{y+z\}$
2. $A = A \cup \{\text{all expressions involving } x\}$
3. $e_kill[p] = A$