
Machine Code Generation - 2

Y. N. Srikant

Computer Science and Automation

Indian Institute of Science

Bangalore 560 012

NPTEL Course on Principles of Compiler Design



Outline of the Lecture

- Mach. code generation – main issues (in part 1)
- Samples of generated code
- Two Simple code generators
- Optimal code generation
 - Sethi-Ullman algorithm
 - Dynamic programming based algorithm
 - Tree pattern matching based algorithm
- Code generation from DAGs
- Peephole optimizations

Samples of Generated Code – Static Allocation (no JSR instruction)

Three Address Code

```
// Code for function F1
action code seg 1
    call F2
action code seg 2
    Halt
```

```
// Code for function F2
action code seg 3
    return
```

Activation Record for F1 (48 bytes)

0	return address
4	
	data array A
40	
44	variable x
	variable y

Activation Record for F2 (76 bytes)

0	return address
4	parameter 1
	data array B
72	
	variable m

Samples of Generated Code – Static Allocation (no JSR instruction)

```
// Code for function F1
200:   Action code seg 1
// Now store return address
240:   Move #264, 648
252:   Move val1, 652
256:   Jump 400 // Call F2
264:   Action code seg 2
280:   Halt
      ...
// Code for function F2
400:   Action code seg 3
// Now return to F1
440:   Jump @648
      ...
```

```
//Activation record for F1
//from 600-647
600:   //return address
604:   //space for array A
640:   //space for variable x
644:   //space for variable y
//Activation record for F2
//from 648-723
648:   //return address
652:   // parameter 1
656:   //space for array B
      ...
720:   //space for variable m
```

Samples of Generated Code – Static Allocation (with JSR instruction)

Three Address Code

// Code for function F1
action code seg 1
call F2
action code seg 2
Halt

// Code for function F2
action code seg 3
return

Activation Record for F1 (44 bytes)

0

data array
A

36

variable x

40

variable y

Activation Record for F2 (72 bytes)

0

data array
B

68

variable m

return address need not be stored

Samples of Generated Code – Static Allocation (with JSR instruction)

```
// Code for function F1
200:   Action code seg 1
// Now jump to F2, return addr
// is stored on hardware stack
240:   JSR 400 // Call F2
248:   Action code seg 2
268:   Halt
      ...
// Code for function F2
400:   Action code seg 3
// Now return to F1 (addr 248)
440:   return
      ...
```

```
//Activation record for F1
//from 600-643
600:   //space for array A
636:   //space for variable x
640:   //space for variable y
//Activation record for F2
//from 644-715
644:   //space for array B
      ...
712:   //space for variable m
```

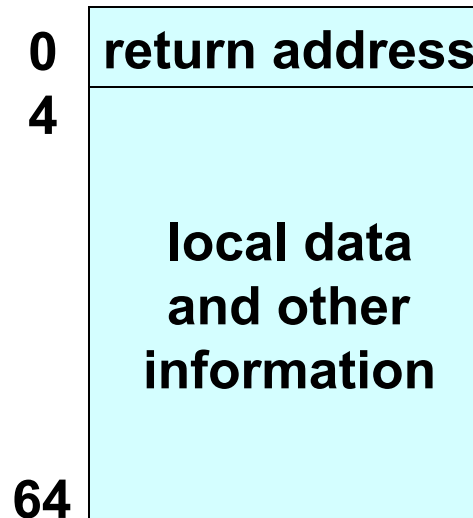
Samples of Generated Code – Dynamic Allocation (no JSR instruction)

Three Address Code

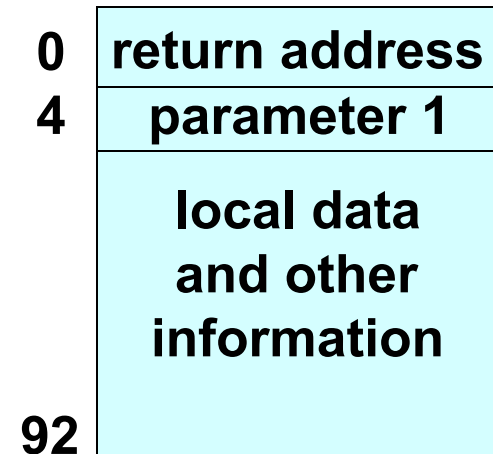
```
// Code for function F1
  action code seg 1
    call F2
  action code seg 2
    return
```

```
// Code for function F2
  action code seg 3
    call F1
  action code seg 4
    call F2
  action code seg 5
    return
```

Activation Record for F1 (68 bytes)



Activation Record for F2 (96 bytes)



Samples of Generated Code – Dynamic Allocation (no JSR instruction)

//Initialization

100: Move #800, SP

...

//Code for F1

200: Action code seg 1

230: Add #96, SP

238: Move #258, @SP

246: Move val1, @SP+4

250: Jump 300

258: Sub #96, SP

266: Action code seg 2

296: Jump @SP

//Code for F2

300: Action code seg 3

340: Add #68, SP

348: Move #364, @SP

356: Jump 200

364: Sub #68, SP

372: Action code seg 4

400: Add #96, SP

408: Move #424, @SP

416: Move val2, @SP+4

420: Jump 300

428: Sub #96, SP

436: Action code seg 5

480: Jump @SP

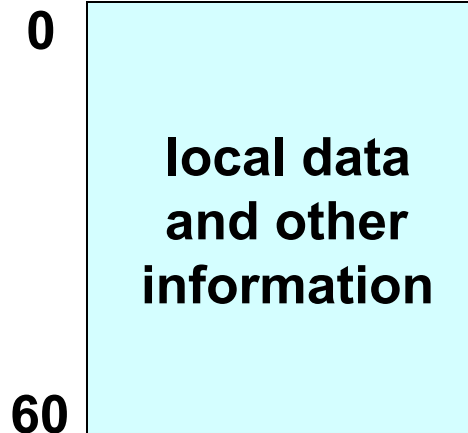
Samples of Generated Code – Dynamic Allocation (with JSR instruction)

Three Address Code

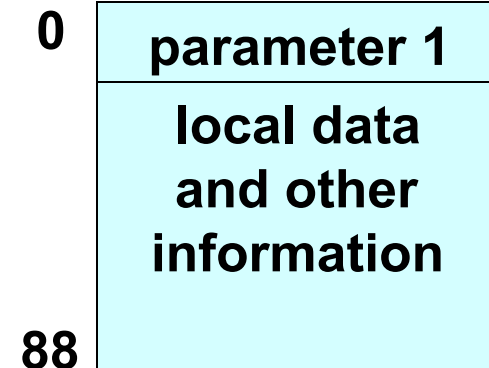
```
// Code for function F1
action code seg 1
    call F2
action code seg 2
    return
```

```
// Code for function F2
action code seg 3
    call F1
action code seg 4
    call F2
action code seg 5
    return
```

Activation Record for F1 (64 bytes)



Activation Record for F2 (92 bytes)



Samples of Generated Code – Dynamic Allocation (with JSR instruction)

//Initialization

100: Move #800, SP

...

//Code for F1

200: Action code seg 1

230: Add #92, SP

238: Move val1, @SP

242: JSR 290

250: Sub #92, SP

258: Action code seg 2

286: return

//Code for F2

290: Action code seg 3

330: Add #64, SP

338: JSR 200

346: Sub #64, SP

354: Action code seg 4

382: Add #92, SP

390: Move val2, @SP

394: JSR 290

402: Sub #92, SP

410: Action code seg 5

454: return

A Simple Code Generator – Scheme A

- Treat each quadruple as a ‘macro’
 - Example: The quad $A := B + C$ will result in
 - Load B, R1 OR Load B, R1**
 - Load C, R2**
 - Add R2, R1 Add C, R1**
 - Store R1, A Store R1, A**
 - Results in inefficient code
 - Repeated load/store of registers
 - Very simple to implement

A Simple Code Generator – Scheme B

- Track values in registers and reuse them
 - If any operand is already in a register, take advantage of it
 - Register descriptors
 - Tracks <register, variable name> pairs
 - A single register can contain values of multiple names, if they are all copies
 - Address descriptors
 - Tracks <variable name, location> pairs
 - A single name may have its value in multiple locations, such as, memory, register, and stack

A Simple Code Generator – Scheme B

- Leave computed result in a register as long as possible
- Store only at the end of a basic block or when that register is needed for another computation
 - A variable is **live** at a point, if it is used later, possibly in other blocks – obtained by dataflow analysis
 - On exit from a basic block, store only **live variables** which are not in their memory locations already (use address descriptors to determine the latter)
 - If liveness information is not known, assume that all variables are live at all times

Example

- $A := B + C$
 - If B and C are in registers R1 and R2, then generate
 - $ADD\ R2, R1$ (cost = 1, result in R1)
 - legal only if B is *not live* after the statement
 - If R1 contains B, but C is in memory
 - $ADD\ C, R1$ (cost = 2, result in R1) **or**
 - $LOAD\ C, R2$
 $ADD\ R2, R1$ (cost = 3, result in R1)
 - legal only if B is *not live* after the statement
 - attractive if the value of C is subsequently used (it can be taken from R2)

Next Use Information

- Next use info is used in code generation and register allocation
- Next use of A in quad i is j if

Quad i : $A = \dots$ (assignment to A)



(control flows from i to j with no assignments to A)

Quad j : $\quad = A \text{ op } B$ (usage of A)

- In computing next use, we assume that on exit from the basic block
 - All temporaries are considered non-live
 - All programmer defined variables (and non-temps) are live
- Each procedure/function call is assumed to start a basic block
- Next use is computed on a backward scan on the quads in a basic block, starting from the end
- Next use information is stored in the symbol table

Example of computing Next Use

3	T1 := 4 * I	T1 – (nlv, lu 0, nu 5), I – (lv, lu 3, nu 10)
4	T2 := addr(A) – 4	T2 – (nlv, lu 0, nu 5)
5	T3 := T2[T1]	T3 – (nlv, lu 0, nu 8), T2 – (nlv, lu 5, nnu), T1 – (nlv, lu 5, nu 7)
6	T4 := addr(B) – 4	T4 – (nlv, lu 0, nu 7)
7	T5 := T4[T1]	T5 – (nlv, lu 0, nu 8), T4 – (nlv, lu 7, nnu), T1 – (nlv, lu 7, nnu)
8	T6 := T3 * T5	T6 – (nlv, lu 0, nu 9), T3 – (nlv, lu 8, nnu), T5 – (nlv, lu 8, nnu)
9	PROD := PROD + T6	PROD – (lv, lu 9, nnu), T6 – (nlv, lu 9, nnu)
10	I := I + 1	I – (lv, lu 10, nu 11)
11	if I ≤ 20 goto 3	I – (lv, lu 11, nnu)

Scheme B – The algorithm

- We deal with one basic block at a time
- We assume that there is no global register allocation
- For each quad $A := B \text{ op } C$ do the following
 - Find a location L to perform $B \text{ op } C$
 - Usually a register returned by $GETREG()$ (could be a mem loc)
 - Where is B ?
 - B' , found using address descriptor for B
 - Prefer register for B' , if it is available in memory and register
 - Generate $\text{Load } B', L$ (if B' is not in L)
 - Where is C ?
 - C' , found using address descriptor for C
 - Generate $\text{op } C', L$
 - Update descriptors for L and A
 - If B/C have no next uses, update descriptors to reflect this information

Function *GETREG()*

Finds L for computing $A := B \text{ op } C$

1. If B is in a register (say R), R holds no other names, and
 - B has no next use, and B is not live after the block, then return R
2. Failing (1), return an empty register, if available
3. Failing (2)
 - If A has a next use in the block, OR
if $B \text{ op } C$ needs a register (e.g., op is an indexing operator)
 - Use a *heuristic* to find an occupied register
 - a register whose contents are referenced farthest in future, or
 - the number of next uses is smallest etc.
 - *Spill* it by generating an instruction, $\text{MOV } R, \text{mem}$
 - mem is the memory location for the variable in R
 - That variable is not already in mem
 - Update *Register* and *Address* descriptors
4. If A is not used in the block, or no suitable register can be found
 - Return a memory location for L

Example

T,U, and V are temporaries - **not live** at the end of the block
W is a non-temporary - **live** at the end of the block, **2 registers**

Statements	Code Generated	Register Descriptor	Address Descriptor
T := A * B	Load A, R0 Mult B, R0	R0 contains T	T in R0
U := A + C	Load A, R1 Add C, R1	R0 contains T R1 contains U	T in R0 U in R1
V := T - U	Sub R1, R0	R0 contains V R1 contains U	U in R1 V in R0
W := V * U	Mult R1, R0	R0 contains W	W in R0
	Store R0, W		W in memory (restored)

Optimal Code Generation

- The Sethi-Ullman Algorithm

- Generates the shortest sequence of instructions
 - Provably optimal algorithm (w.r.t. length of the sequence)
- Suitable for expression trees (basic block level)
- Machine model
 - All computations are carried out in registers
 - Instructions are of the form $op\ R, R$ or $op\ M, R$
- **Always computes the left subtree into a register and reuses it immediately**
- Two phases
 - Labelling phase
 - Code generation phase

The Labelling Algorithm

- Labels each node of the tree with an integer:
 - fewest no. of registers required to evaluate the tree with no intermediate stores to memory
 - Consider binary trees
- For leaf nodes
 - ***if* n is the leftmost child of its parent *then***
 $\text{label}(n) := 1$ *else* $\text{label}(n) := 0$
- For internal nodes
 - **$\text{label}(n) = \max(l_1, l_2)$, if $l_1 \neq l_2$**
 $= l_1 + 1$, if $l_1 = l_2$

Labelling - Example

