

Module 7:Data Representation

Lecture 34: DFT and DCT

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The Lecture Contains:

-  Fourier analysis

 Discrete Fourier Transform (DFT)
 - Properties
 - Coefficients
 - Dimensionality reduction

 Discrete Cosine Transform (DCT)

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Fourier analysis

- Fourier analysis represents a periodic wave as a sum of (infinite) sine and cosine waves
- Way to analyze the frequency components in a signal
- Fourier transform is a transformation from time domain $f(x)$ to frequency domain $g(u)$

$$g(u) = \int_{-\infty}^{\infty} f(x) e^{-2\pi u x i} dx$$

- $f(x)$ can be obtained from $g(u)$ by the inverse transformation

$$f(x) = \int_{-\infty}^{\infty} g(u) e^{2\pi u x i} du$$

- $f(x)$ and $g(u)$ form a Fourier transform pair

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Discrete Fourier Transform (DFT)

- For discrete case, assume vector x has N components
- DFT of x , denoted by X , has N components given by

$$X_k = 1. \sum_{n=0}^{N-1} x_n e^{-(2\pi/N)kn\mathbf{i}} \quad k = 0, \dots, N-1$$

- Inverse transformation (IDFT) is given by

$$x_n = \frac{1}{N} \cdot \sum_{k=0}^{N-1} X_k e^{(2\pi/N)kn\mathbf{i}} \quad n = 0, \dots, N-1$$

- To avoid using separate scaling factors, both can be taken as $(1/\sqrt{N})$

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Properties

- **Parseval's theorem:** $\|x\|_2 = \|X\|_2$, i.e., length of vectors is preserved

$$\sum_{n=0}^{N-1} |x_n|^2 = \sum_{k=0}^{N-1} |X_k|^2$$

- When both scaling factors are $(1/\sqrt{N})$
- Contractive mapping
- Invertible, linear transformation
- Essentially, a rotation in N-dimensional space

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Coefficients

- Expanding $e^{\theta i} = \cos \theta + i \sin \theta$,

$$\begin{aligned}
 X_k &= \sum_{n=0}^{N-1} x_n e^{-(2\pi/N)kn i} \\
 &= \sum_{n=0}^{N-1} x_n \left(\cos\left(\frac{2\pi}{N}kn\right) - i \sin\left(\frac{2\pi}{N}kn\right) \right) \\
 \therefore X_0 &= \sum_{n=0}^{N-1} x_n (\cos 0 - i \sin 0) \\
 &= \sum_{n=0}^{N-1} x_n
 \end{aligned}$$

- First coefficient is (scaled) sum or average
- Other coefficients define the frequency components (cosine and sine) at frequencies $2\pi(k/N)$ for $k = 0, 1, \dots, N-1$

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Dimensionality reduction

- Retain k lower frequency components
- Discard higher frequency noise

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Dimensionality reduction

- Retain k lower frequency components
- Discard higher frequency noise
- Alternatively, for a database of objects, retain those coefficients whose variances are highest

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Discrete Cosine Transform (DCT)

- Way to represent a signal in terms of cosine waves of different frequencies (and amplitudes)
- Various definitions

$$X_k^{(1)} = \sqrt{\frac{2}{N}} \sum_{n=0}^{N-1} u_n^{(1)} x_n \cos \left[\frac{\pi}{N} \left(n + \frac{1}{2} \right) k \right] \quad k = 0, \dots, N-1$$

$$X_k^{(2)} = \sqrt{\frac{2}{N}} \sum_{n=0}^{N-1} u_n^{(2)} x_n \cos \left[\frac{\pi}{N} \left(n + \frac{1}{2} \right) \left(k + \frac{1}{2} \right) \right] \quad k = 0, \dots, N-1$$

$$u_n^{(1)} = 1/\sqrt{2} \quad n = 0$$

$$u_n^{(1)} = 1 \quad n = 1, \dots, N-1$$

$$u_n^{(2)} = 1 \quad n = 0, \dots, N-1$$

- Length preserving
- Inverses are the same functions