

Module 6: Dimensionality Reduction

Lecture 29: Singular Value Decomposition (SVD)

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The Lecture Contains:

- ☰ Singular Value Decomposition (SVD)
- ☰ SVD of real symmetric matrix
- ☰ Transformation using SVD
 - Example
 - Example: compact form
- ☰ Dimensionality reduction using SVD
 - Example of dimensionality reduction ($k = 1$)
- ☰ Compact way of dimensionality reduction ($k = 1$)
- ☰ How many dimensions to retain?

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Singular Value Decomposition (SVD)

- Factorization of a matrix

$$A = U\Sigma V^T$$

- If A is of size $m \times n$, then U is $m \times m$, V is $n \times n$ and Σ is $m \times n$ matrix
- Columns of U are eigenvectors of AA^T
 - Left singular vectors
 - $UU^T = I_m$ (orthonormal)
- Columns of V are eigenvectors of $A^T A$
 - Right singular vectors
 - $V^T V = I_n$ (orthonormal)
- σ_{ii} are the singular values
 - Σ is diagonal
 - Singular values are positive squareroots of eigenvalues of AA^T or $A^T A$
- $\sigma_{11} \geq \sigma_{22} \geq \dots \geq \sigma_{nn}$ (assuming n singular values)

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SVD of real symmetric matrix

- A is real symmetric of size $n \times n$
- $A = A^T$
- $U = V$ since $A^T A = A A^T = A^2$

$$A = Q \Sigma Q^T$$

- Q is of size $n \times n$ and contains eigenvectors of A^2
- This is called spectral decomposition of A
- Σ contains n singular values
- Eigenvectors of $A =$ eigenvectors of A^2
- Eigenvalues of $A =$ squareroot of eigenvalues of A^2
- Eigenvalues of $A =$ singular values of A

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Transformation using SVD

- Transformed data

$$T = AV = U\Sigma$$

- V is called **SVD transform matrix**
- Essentially, T is just a rotation of A
- Dimensionality of T is n
- n different basis vectors than the original space
- Columns of V give the basis vectors in rotated space

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- n different basis vectors than the original space
- Columns of V give the basis vectors in rotated space
- V shows how each dimension can be represented as a linear combination of other dimensions
 - Columns are input basis vectors
- U shows how each object can be represented as a linear combination of other objects
 - Columns are output basis vectors

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Transformation using SVD

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- V shows how each dimension can be represented as a linear combination of other dimensions
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- U shows how each object can be represented as a linear combination of other objects
 - Columns are output basis vectors
- Lengths of vectors are preserved

$$||\vec{a_i}||_2 = ||\vec{t_i}||_2$$

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Example

$$\begin{aligned}
 A \begin{bmatrix} 2 & 4 \\ 1 & 3 \\ 0 & 1 \\ -1 & 0.5 \end{bmatrix} &= U \begin{bmatrix} -0.80 & 0.22 & 0.05 & 0.54 \\ -0.56 & -0.20 & -0.34 & -0.71 \\ -0.16 & -0.31 & 0.90 & -0.21 \\ -0.01 & -0.89 & -0.22 & 0.37 \end{bmatrix} \\
 &\quad \times \Sigma \begin{bmatrix} 5.54 & 0 \\ 0 & 1.24 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \times V^T \begin{bmatrix} -0.39 & -0.92 \\ 0.92 & -0.39 \end{bmatrix}^T \\
 T = AV = U\Sigma &= \begin{bmatrix} 2 & 4 \\ 1 & 3 \\ 0 & 1 \\ -1 & 0.5 \end{bmatrix} \times \begin{bmatrix} -0.39 & -0.92 \\ 0.92 & -0.39 \end{bmatrix} = \begin{bmatrix} -4.46 & 0.27 \\ -3.15 & -0.25 \\ -0.92 & -0.39 \\ -0.06 & -1.15 \end{bmatrix}
 \end{aligned}$$

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Example: compact form

$$A \begin{bmatrix} 2 & 4 \\ 1 & 3 \\ 0 & 1 \\ -1 & 0.5 \end{bmatrix} = U \begin{bmatrix} -0.80 & 0.22 \\ -0.56 & -0.20 \\ -0.16 & -0.31 \\ -0.01 & -0.89 \end{bmatrix} \times \Sigma \begin{bmatrix} 5.54 & 0 \\ 0 & 1.24 \end{bmatrix} \times V^T \begin{bmatrix} -0.39 & -0.92 \\ 0.92 & -0.39 \end{bmatrix}^T$$

- If A is of size $m \times n$, then U is $m \times n$, V is $n \times n$ and Σ is $n \times n$ matrix
- Works because there at most n non-zero singular values in Σ

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Dimensionality reduction using SVD

$$A = U\Sigma V^T = \sum_{i=1}^n (u_i \sigma_{ii} v_i^T)$$

- Use only k dimensions
- Retain first k columns for U and V and first k values for Σ
- First k columns of V give the basis vectors in reduced space
- Best rank k approximation in terms of sum squared error

$$A \approx \sum_{i=1}^k (u_i \sigma_{ii} v_i^T) = U_{1\dots k} \Sigma_{1\dots k} V_{1\dots k}^T$$

$$T \approx AV_{1\dots k}$$

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Example of dimensionality reduction ($k = 1$)

$$\begin{aligned}
 A \approx A_k &= U_k \begin{bmatrix} -0.80 & 0 & 0 & 0 \\ -0.56 & 0 & 0 & 0 \\ -0.16 & 0 & 0 & 0 \\ -0.01 & 0 & 0 & 0 \end{bmatrix} \times \Sigma_k \begin{bmatrix} 5.54 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} \times V_k^T \begin{bmatrix} -0.39 & 0 \\ -0.92 & 0 \end{bmatrix}^T \\
 &= \begin{bmatrix} 1.74 & 4.10 \\ 1.23 & 2.90 \\ 0.35 & 0.84 \\ 0.02 & 0.06 \end{bmatrix} \\
 T \approx T_k &= AV_k = U_k \Sigma_k = \begin{bmatrix} 2 & 4 \\ 1 & 3 \\ 0 & 1 \\ -1 & 0.5 \end{bmatrix} \times \begin{bmatrix} -0.39 & 0 \\ 0.92 & 0 \end{bmatrix} = \begin{bmatrix} -4.46 & 0 \\ -3.15 & 0 \\ -0.92 & 0 \\ -0.06 & 0 \end{bmatrix}
 \end{aligned}$$

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Compact way of dimensionality reduction ($k = 1$)

$$\begin{aligned}
 A \approx A_k &= U_k \begin{bmatrix} -0.80 \\ -0.56 \\ -0.16 \\ -0.01 \end{bmatrix} \times \Sigma_k [5.54] \times V_k^T \begin{bmatrix} -0.39 \\ -0.92 \end{bmatrix}^T \\
 &= \begin{bmatrix} 1.74 & 4.10 \\ 1.23 & 2.90 \\ 0.35 & 0.84 \\ 0.02 & 0.06 \end{bmatrix} \\
 T \approx T_k &= AV_k = U_k \Sigma_k = \begin{bmatrix} 2 & 4 \\ 1 & 3 \\ 0 & 1 \\ -1 & 0.5 \end{bmatrix} \times \begin{bmatrix} -0.39 \\ 0.92 \end{bmatrix} = \begin{bmatrix} -4.46 \\ -3.15 \\ -0.92 \\ -0.06 \end{bmatrix}
 \end{aligned}$$

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How many dimensions to retain?

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How many dimensions to retain?

- There is no easy answer

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How many dimensions to retain?

- There is no easy answer
- Concept of **energy** of a dataset
- Total energy is sum of squares of singular values (aka **spread** or variance)

$$E = \sum_{i=1}^n \sigma_{ii}^2$$

- Retain k dimensions such that $p\%$ of the energy is retained

$$E_k = \sum_{i=1}^k \sigma_{ii}^2$$

$$E_k / E \geq p$$

- Generally, p is between 80% to 95%

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- Generally, p is between 80% to 95%
- In the above example, $k = 1$ retains 95.22% of the energy

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$$E_k/E \geq p$$

- Generally, p is between 80% to 95%
- In the above example, $k = 1$ retains 95.22% of the energy
- Running time: $O(mnr)$ for A of size $m \times n$ and rank r