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The Lecture Contains:

- ☰ Range tree
 - Multi-dimensional range trees
 - Analysis of range trees
- ☰ Windowing queries
- ☰ Interval tree
 - Example
 - Searching

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Lecture 15: Range Trees and Interval Trees

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Range tree

- In 1-dimension, similar to a balanced binary search tree
- Leaves are sorted and *doubly linked*

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Range tree

- In 1-dimension, similar to a balanced binary search tree
- Leaves are sorted and *doubly linked*
- Range search proceeds by descending to the leaf \leq to the minimum of the range
- Then, traverse forward pointers till maximum of the range is exceeded
- Time taken is $O(\lg N + T)$ where T is size of the answer set
- Space is $O(N)$

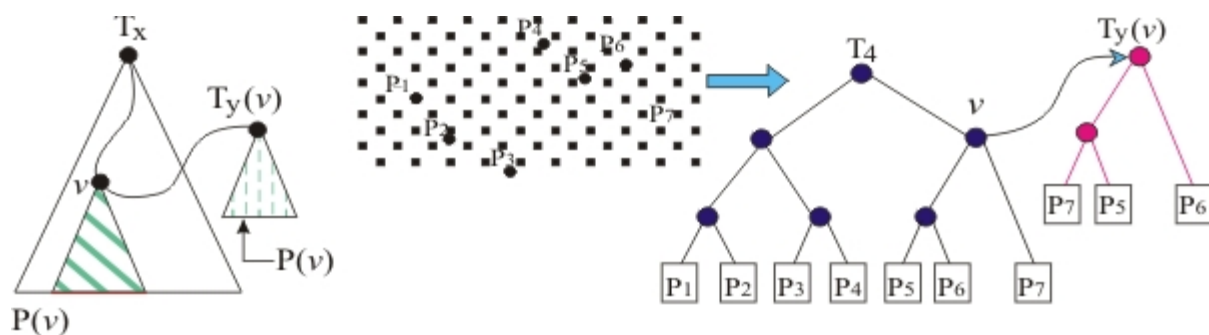
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Multi-dimensional range trees

- BST of BSTs of BSTs of . . .
- 1-dimensional range tree of $(d - 1)$ -dimensional range trees
- Order dimensions as x_1, x_2, \dots, x_d and build accordingly
- For each canonical subset of points for a node built on x_1 , there is a range tree of $(d - 1)$ -dimensionality associated with the node



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Analysis of range trees

- Storage space is $O(N \lg^{d-1} N)$
- Time taken is $O(\lg^d N + T)$

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Analysis of range trees

- Storage space is $O(N \lg^{d-1} N)$
- Time taken is $O(\lg^d N + T)$
- Search in x_1 and identify left-most and right-most leaf nodes L and R that cover x_1 's range
- Find *least common ancestor* Q of L and R
- Perform range search for dimensions x_2, \dots, x_d for all range trees rooted at nodes between Q and L and Q and R

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Analysis of range trees

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- Perform range search for dimensions x_2, \dots, x_d for all range trees rooted at nodes between Q and L and Q and R
- **Fractional cascading** improves search time in 2 dimensions to $O(\lg N + T)$

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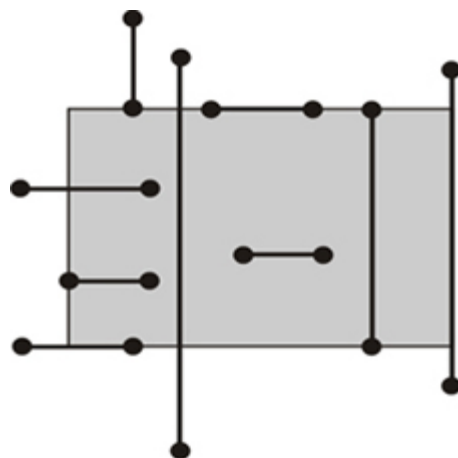
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Windowing queries

- Return all (axis-parallel) segments that are visible through the query window
- Segments which have one (or two) endpoints in the window can be searched using range trees
 - Bookkeeping to avoid duplication of segments with both end-points in the window
- Stabbing queries to find out lines (equivalently points) that cut a particular arm $y = q_y$ of the window
 - Line $x = a$ is equivalent to the point (a, q_y)
 - Interval tree to search these



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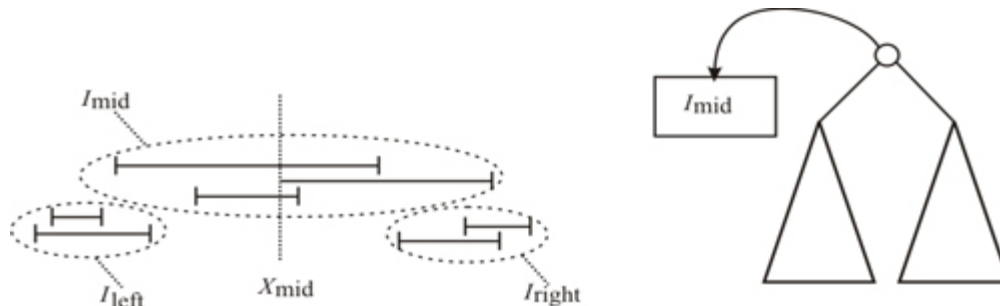
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Interval tree

- Binary tree
- Each node storing 5 different pieces of information:
 - Bookkeeping to avoid duplication of segments with both end-points in the window
 - Median point x_{mid}
 - Left child pointer for intervals I_{left} ending before x_{mid}
 - Right child pointer for intervals I_{right} starting after x_{mid}
 - Lists storing all overlapping intervals I_{mid}
 - Left list L_{left} sorted in ascending order by left end-points
 - Right list L_{right} sorted in descending order by right end-points



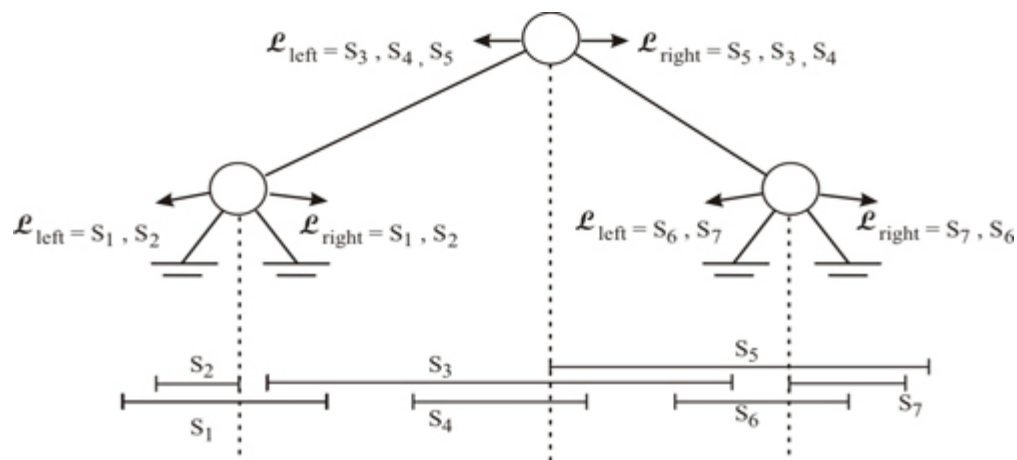
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Example

- $O(N)$ storage
- $O(N \lg N)$ construction time
- $O(\lg N + T)$ query time for *stabbing queries*
 - Find all intervals that intersect (stab) a given vertical line



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Searching

- Find if query q_x is greater than max of left child
 - If not, recurse to left child
- Find if query q_x is lesser than min of right child
 - If not, recurse to right child
- Note that only one of the above cases can occur
 - Max of left child $< x_{mid} <$ of right child
- Find if q_x overlaps intervals in I_{mid}
 - If yes, traverse L_{left} and L_{right}

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Searching

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- Find if query q_x is lesser than min of right child
 - If not, recurse to right child
- Note that only one of the above cases can occur
 - Max of left child $< x_{mid} <$ of right child
- Find if q_x overlaps intervals in I_{mid}
 - If yes, traverse L_{left} and L_{right}
- For interval queries and windowing queries, maintain L_{left} and L_{right} as range trees
 - Searches in y-dimension to nd intersecting segments
 - Searching time becomes $O(\log^2 N + T)$