

## Module 4 : Nonlinear elasticity

### Lecture 29 : The slide modules.

#### The Lecture Contains

- ☰ The slide modulus.
- ☰ Hookean Elastic Material.

1. "Mechanics of Incremental Deformations" by M. A. Biot

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## The slide modulus

Let us consider a rectangle block which is subjected to initial stresses  $S_{11}$  and  $S_{22}$  along two principal directions 1 and 2 respectively.

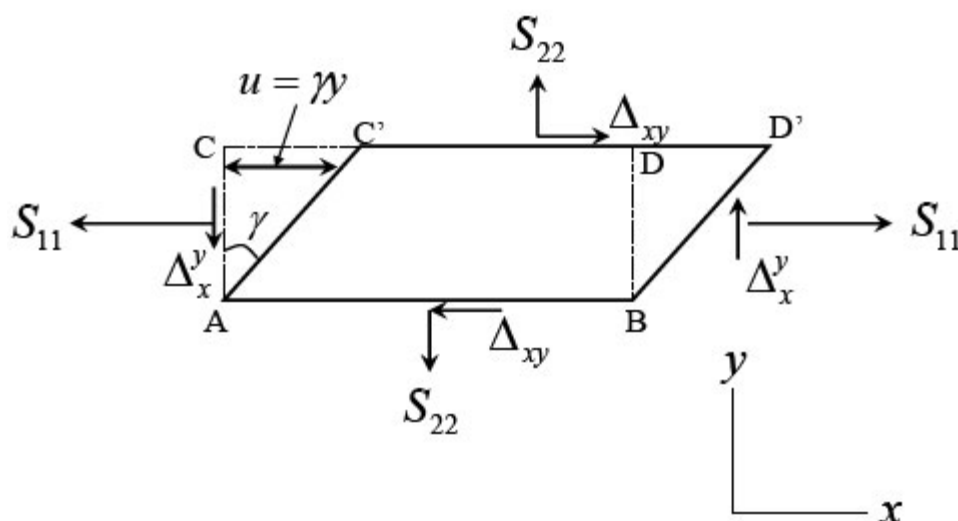


Figure 29.1

Over and above these initial stresses, let us say that it is subjected to shear displacement parallel to the  $x$  direction. Then the displacement components are,

$$u = y \quad v = w = 0 \quad (29.1)$$

This is an in plane deformation in the  $xy$  plane. The rectangle  $ABDC$  in this plane is deformed into the parallelogram  $ABD'C'$ . In order to produce this deformation, we have applied a tangential force on the  $CD$  which can be evaluated from the relation of boundary condition as in equations 13.17; substituting  $S_{12} = 0$ , we obtain

$$\begin{aligned} \Delta f_x &= (S_{11} + S_{11}e_{yy})\cos(n, x) + (S_{12} - S_{22}\omega - S_{11}e_{xy})\cos(n, y) \\ \Delta f_y &= (S_{12} + S_{11}\omega - S_{22}e_{xy})\cos(n, x) + (S_{22} + S_{22}e_{yy})\cos(n, y) \end{aligned} \quad (29.2)$$

These expressions represent the incremental forces acting on a face of the material when the normal directions are defined by the direction cosines,  $\cos(n, x)$  and  $\cos(n, y)$ . For the shear displacement we may write,

$$\begin{aligned} e_{xy} &= -\omega = \frac{1}{2}\gamma \\ e_{xx} &= e_{yy} = e_{zz} = 0 \\ e_{yz} &= e_{zx} = 0 \end{aligned} \quad (29.3)$$

From the stress-strain relations of 13.39 and 13.40 we may derive,

$$\begin{aligned} s_{11} &= s_{22} = 0 \\ s_{12} &= Q_3 \gamma \end{aligned} \quad (29.4)$$

Hence the expression in 29.2 yields,

$$\begin{aligned} \Delta f_x &= 0 \cdot \cos(n, x) + \left( Q_3 + \frac{1}{2} S_{22} - \frac{1}{2} S_{11} \right) \gamma \cos(n, y) = \Delta_{xy} \cos(n, y) \\ \Delta f_y &= \left( Q_3 - \frac{1}{2} S_{11} - \frac{1}{2} S_{22} \right) \gamma \cos(n, x) + 0 \cdot \cos(n, y) = \Delta_x^y \cos(n, x) \end{aligned} \quad (29.5)$$

$\Delta_{xy} = L_{12} \gamma$  represents the tangential stress applied to the face CD in order to produce the tangential stress  $\gamma$  in which the quantity  $L_{12} = Q_3 + \frac{1}{2} S_{22} - \frac{1}{2} S_{11}$  is called the **measurable slide modulus**.

$\Delta_x^y$  represents the vertical stress which is applied to the sides AC and BD. This analysis may be repeated for other co-ordinate planes.

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## Hookean Elastic Material

Let us now consider a Hookean rubbery elastic material, for which the strain energy density function can be written as,

$$W(\lambda_1, \lambda_2) = \frac{\mu_0}{2} \left( \lambda_1^2 + \lambda_2^2 + \frac{1}{\lambda_1^2 \lambda_2} - 3 \right) \quad (29.6)$$

Then the initial stress relations as in 28.11 are obtained as,

$$\begin{aligned} S_{22} - S_{33} &= \mu_0 (\lambda_2^2 - \lambda_3^2) \\ S_{33} - S_{11} &= \mu_0 (\lambda_3^2 - \lambda_1^2) \\ S_{11} - S_{22} &= \mu_0 (\lambda_1^2 - \lambda_2^2) \end{aligned} \quad (29.7)$$

Similarly the relations for incremental stresses are obtained as,

$$\begin{aligned} s_{22} - s_{33} &= 2\mu_0 (\lambda_2^2 e_{yy} - \lambda_3^2 e_{zz}) \\ s_{33} - s_{11} &= 2\mu_0 (\lambda_3^2 e_{zz} - \lambda_1^2 e_{xx}) \\ s_{11} - s_{22} &= 2\mu_0 (\lambda_1^2 e_{xx} - \lambda_2^2 e_{yy}) \end{aligned} \quad (29.8a)$$

Hence,

$$\begin{aligned} A &= 2\mu_0 \lambda_1^2 \\ B &= 2\mu_0 \lambda_2^2 \\ C &= 2\mu_0 \lambda_3^2 \end{aligned} \quad (29.8b)$$

$$\begin{aligned} 3(s_{11} - s) &= 2\mu_0 (2\lambda_1^2 e_{xx} - \lambda_2^2 e_{yy} - \lambda_3^2 e_{zz}) \\ 3(s_{22} - s) &= 2\mu_0 (-\lambda_1^2 e_{xx} + 2\lambda_2^2 e_{yy} - \lambda_3^2 e_{zz}) \\ 3(s_{33} - s) &= 2\mu_0 (-\lambda_1^2 e_{xx} - \lambda_2^2 e_{yy} + 2\lambda_3^2 e_{zz}) \end{aligned} \quad (29.8c)$$

Finally we can derive the elastic constants,

$$\begin{aligned} Q_1 &= \frac{1}{2} \mu_0 (\lambda_2^2 + \lambda_3^2) \\ Q_2 &= \frac{1}{2} \mu_0 (\lambda_3^2 + \lambda_1^2) \\ Q_3 &= \frac{1}{2} \mu_0 (\lambda_1^2 + \lambda_2^2) \end{aligned} \quad (29.8d)$$

If the incremental stresses are applied in plane strain, the equations 29.8 get modified to the following:

$$(29.9)$$

$$s_{22} = B e_{yy}$$

$$s_{11} = A e_{xx}$$

$$s_{12} = 2Q_3 e_{xy}$$

$$s = \frac{1}{2}(s_{11} + s_{22}) = \frac{1}{2}(A e_{xx} + B e_{yy})$$

Which finally results in

$$s_{11} - s = 2\mu e_{xx}$$

$$s_{22} - s = 2\mu e_{yy}$$

$$s_{12} = 2\mu e_{xy}$$

(29.10)

$$\mu = \frac{1}{2}\mu_0(\lambda_1^2 + \lambda_2^2)$$

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## Surface instability of a homogeneous half-space

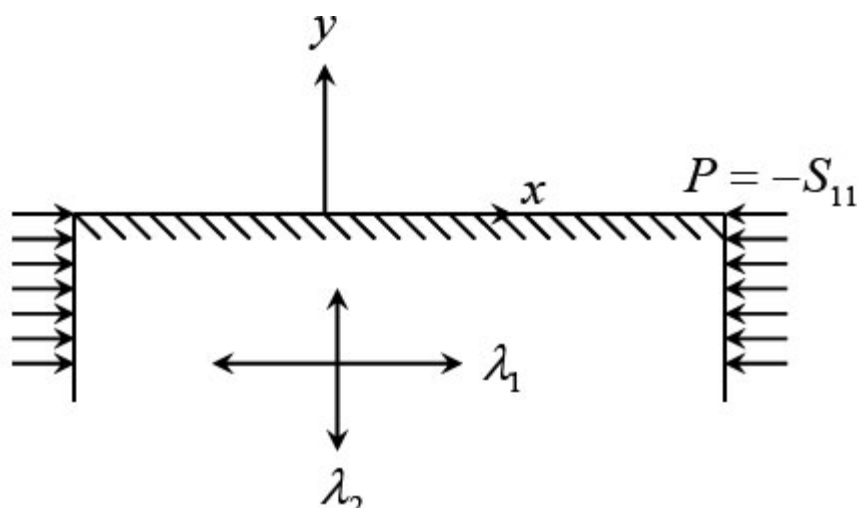


Figure 29.2

Consider a rubber block, an elastic half space, is subjected to a state of initial stress such that it is under compression in  $x$  direction but under zero stress along the  $y$  direction:

$$\begin{aligned} P &= -S_{11} \\ S_{22} &= 0 \end{aligned} \quad (29.11)$$

Since the material is incompressible, the extension ratios satisfy the following relation:

$$\lambda_1 \lambda_2 \lambda_3 = 1 \quad (29.12)$$

Here  $\lambda_1$  and  $\lambda_2$  are extension ratios along  $x$  and  $y$  directions respectively. And  $\lambda_3$  is the extension ratio along the direction normal to the  $xy$  plane. Then the stress-strain relations in equation 29.7 yield:

$$\begin{aligned} -S_{33} &= \mu_0 (\lambda_2^2 - \lambda_3^2) \\ S_{33} + P &= \mu_0 (\lambda_3^2 - \lambda_1^2) \\ -P &= \mu_0 (\lambda_1^2 - \lambda_2^2) \end{aligned} \quad (29.13)$$

Where,  $\mu_0$  is the shear modulus of the rubber block in unstressed state. Under this initial stress condition the block undergoes incremental deformation in the  $xy$  plane. Then the incremental stresses and strain can be represented by equations 29.10. In addition, we have the incompressibility condition:

$$e_{xx} + e_{yy} = 0 \quad (29.14)$$

The equilibrium relations for incremental stresses can be written as,

$$\begin{aligned}\frac{\partial s_{11}}{\partial x} + \frac{\partial s_{12}}{\partial y} - P \frac{\partial \varpi}{\partial y} &= 0 \\ \frac{\partial s_{12}}{\partial x} + \frac{\partial s_{22}}{\partial y} - P \frac{\partial \varpi}{\partial x} &= 0\end{aligned}\quad (29.15)$$

Notice that equation 29.14 can be satisfied by putting the following substitutions:

$$u = -\frac{\partial \phi}{\partial y}, \quad v = \frac{\partial \phi}{\partial x} \quad (29.16)$$

Where  $\phi(x, y)$  is a stress function which is deduced by solving the stress equilibrium relations subjected to relevant boundary conditions. We can write the stress components  $s_{ij}$  in equation 29.10 in terms of that presented in 29.15, which yield,

$$\begin{aligned}\frac{\partial s}{\partial x} - \left( \mu + \frac{P}{2} \right) \frac{\partial}{\partial y} \left( \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \right) &= 0 \\ \frac{\partial s}{\partial y} + \left( \mu - \frac{P}{2} \right) \frac{\partial}{\partial x} \left( \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \right) &= 0\end{aligned}\quad (29.17)$$

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Further eliminating the mean incremental stress  $s$  in equation 29.16, we obtain the following equation in terms of

$$\left(\mu - \frac{P}{2}\right) \frac{\partial^4 \phi}{\partial x^4} + 2\mu \frac{\partial^4 \phi}{\partial x^2 \partial y^2} + \left(\mu + \frac{P}{2}\right) \frac{\partial^4 \phi}{\partial y^4} = 0 \quad (29.18)$$

After algebraic manipulation of equation 29.18, we obtain

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right) \left[ \left(\mu - \frac{P}{2}\right) \frac{\partial^2 \phi}{\partial x^2} + \left(\mu + \frac{P}{2}\right) \frac{\partial^2 \phi}{\partial y^2} \right] = 0 \quad (29.19)$$

Notice that the perturbation solutions can be considered sinusoidal along the  $x$  direction which vanishes at infinite depth  $y = -\infty$ . Such a solution can be represented by the following functional forms:

$$\begin{aligned} \phi &= \frac{1}{l^2} (c_1 e^{\psi} + c_2 e^{-k\psi}) \sin(lx) \\ s &= c_2 P k e^{k\psi} \cos(lx) \end{aligned} \quad (29.20)$$

In which,  $2\pi/l$  defines the wavelength of the instability. The other parameters can be related as

$$\begin{aligned} k &= \sqrt{\frac{1-\zeta}{1+\zeta}} = \frac{\lambda_1}{\lambda_2} \\ \zeta &= \frac{P}{2\mu} = \frac{\lambda_2^2 - \lambda_1^2}{\lambda_2^2 + \lambda_1^2} \end{aligned} \quad (29.21)$$

Since,  $0 < \zeta < 1$ ,  $k$  is real and satisfies the inequality  $0 < k < 1$ .

We will now consider the boundary conditions at the surface of the block, which from equation 28.1(b) can be written as

$$\begin{aligned} \Delta f_x &= s_{12} + P e_{xy} = (2Q + P) e_{xy} \\ \Delta f_y &= s_{22} = s + 2\mu e_{yy} \end{aligned} \quad (29.22)$$

The condition that no incremental force is applied at the surface demands that at  $y = 0$ ,

$$\Delta f_x = \Delta f_y = 0 \quad (29.23)$$

Substituting the solutions  $\phi$  and  $s$  in equation 29.22 and eliminating for constants we obtain the characteristic equation,

$$(1 + \zeta)^2 k - 1 = 0 \quad (29.24)$$

Substituting the expression for  $k$  from 29.21 into 29.24 yields

$$(29.25)$$

$$\zeta^3 + 2\zeta^2 - 2 = 0$$

Which has one real root,  $\zeta = 0.839$  at which the surface turns unstable. From equation 29.21, the value of  $k$  at which instability occurs is obtained as  $k = 0.295$ . Notice that the characteristic equation is independent of  $l$ , which implies that surface can become unstable for all wavelengths.

We can further calculate the initial extension ratios at which the surface becomes unstable, by putting the following,

$$\begin{aligned}\lambda_3 &= 1 \\ \lambda_2 &= \frac{1}{\lambda_1}\end{aligned}\tag{29.26}$$

Which yields the extension ratio corresponding to instability as  $\lambda_1 = 0.544$  and the compressive stress as  $P = 3.08\mu_0$ .

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