

Course outline

How does an NPTEL online course work?

MATLAB

Overview and Pre-Requisites

Week-1: Background and Introduction

Week-2: Linear Algebra

Week 3: Discrete-Time Step Response Models

Week 4: Discrete-Time Models and Model Conversion

Week 5: Dynamic Matrix Control (DMC)

Week 6: DMC Algorithm and Implementation

Week 7: Linear Time Invariant (LTI) Models

Week 8 : Linear Quadratic (LQ) Control

Week 9 : State Estimation

Week 10 : Linear Quadratic Gaussian (LQG) Control

Week 11: State-Space MPC

Week 12: Practical Issues in MPC

Download Videos

Live Session

Text transcripts

Model Predictive Control: Theory and Applications

Model Predictive Control (MPC) is one of the predominant advanced control techniques. MPC originated in the chemical process industry and is now applicable to a wide range of application areas. MPC is an optimization-based technique, which uses predictions from a model over a future control horizon to determine control inputs. This course will provide an overview of MPC, and will cover both theory and practical applications. The course will involve MATLAB-based hands-on learning modules for understanding and solving advanced control problems. The course will cover multiple aspects of MPC implementation, including dynamical system models, state estimation, unconstrained and constrained optimal control, and model identification. Applications of practical / industrial relevance will also be discussed.

The objectives of this course include

- Provide historical insight into MPC and its role in industry and research
- To develop linear state estimation and linear quadratic control theories
- To introduce the concept of receding horizon in MPC and its practical implementation
- To discuss tools for model building for MPC
- To introduce tools for parameter identification
- To provide hands-on learning using practically relevant examples
- To discuss challenges and opportunities in research as well as industrial applications

INTENDED AUDIENCE : Post-Graduate students; final year UG; industry / research professionals

PREREQUISITES : UG Math (covering linear algebra) and Any of the following courses: Process Control; Control Engineering / Systems; Digital Control

INDUSTRIES SUPPORT : Automation companies, such as: ABB, Honeywell, Yokogawa, Aspen Tech, Siemens, Emerson, Rockwell, Schnieder and GE. Chemical Process Companies, such as: Shell, IOCL, HPCL, BPCL, Reliance, ONGC, Exxon Mobil, Praxair, etc.



Prof. Niket Kaisare

IIT Madras

Prof. Niket Kaisare is a Professor of Chemical Engineering in IIT-Madras. He works in the area of modeling, design and control for energy applications. He has over ten years of research/teaching experience in academia, and three-year experience in Industrial R&D. He uses computational software, including MATLAB, FORTRAN, Aspen and FLUENT extensively in his research and teaching.

Faculty web-page: <http://www.che.iitm.ac.in/~nkaisare/>

COURSE TYPE

Elective

COURSE LEVEL

Postgraduate

COURSE LAYOUT

Week 0: a. Introduction to Model Predictive Control
b. Recap of Linear Algebra

Week 1: Models for MPC: Step-Response Models
Finite impulse and step response models; Model prediction; Parameter estimation

Week 2: Models for MPC: Linear Time Invariant (LTI) models
State-space models; Transfer function models; Model transformation

Week 3: Model analysis and Disturbance Modeling
Model stability; Observability and controllability Representing uncertainty; White, colored and integrating noise

Week 4: Dynamic Matrix Control
Step-response based MPC

Week 5: Linear State Estimation
State observer; Pole placement; Stability

Week 6: Optimal Linear State Estimation
Kalman Filter; Stochastic filtering theory

Week 7: Linear Control Systems
Linear control; pole placement; stability

Week 8: Unconstrained linear quadratic control
LQ control theory

Week 9: Constrained LQ control
Constrained LQ control theory

Week 10: State-Space MPC
State-space MPC; deterministic formulation; state feedback control

Week 11: State-Space Output-Feedback MPC
Separation principle; Implementation of output feedback MPC

Week 12: Practical Implementation
Nonlinear systems; Multi-rate system; Inferential control

BOOKS AND REFERENCES

1. J.B. Rawlings, D.Q. Mayne and M.M. Diehl (2018) Model Predictive Control: Theory, Computation, and Design, Nobb Hill.
2. E.F. Camacho and C. Bordons (2007) Model Predictive Control, Springer.

CERTIFICATE

The course is free to enroll and learn from. But if you want a certificate, you have to register and write the proctored exam conducted by us in person at any of the designated exam centres.

The exam is optional for a fee of Rs 1000/- (Rupees one thousand only).

Date and Time of Exams: **24 April 2021** Morning session 9am to 12 noon; Afternoon Session 2pm to 5pm.

Registration url: Announcements will be made when the registration form is open for registrations.

The online registration form has to be filled and the certification exam fee needs to be paid. More details will be made available when the exam registration form is published. If there are any changes, it will be mentioned then.

Please check the form for more details on the cities where the exams will be held, the conditions you agree to when you fill the form etc.

CRITERIA TO GET A CERTIFICATE

Average assignment score = 25% of average of best 8 assignments out of the total 12 assignments given in the course.

Exam score = 75% of the proctored certification exam score out of 100

Final score = Average assignment score + Exam score

YOU WILL BE ELIGIBLE FOR A CERTIFICATE ONLY IF AVERAGE ASSIGNMENT SCORE $\geq 10/25$ AND EXAM SCORE $\geq 30/75$. If one of the 2 criteria is not met, you will not get the certificate even if the Final score $\geq 40/100$.

Certificate will have your name, photograph and the score in the final exam with the breakup. It will have the logos of NPTEL and IIT Madras. It will be e-verifiable at nptel.ac.in/noc.

Only the e-certificate will be made available. Hard copies will not be dispatched.

Once again, thanks for your interest in our online courses and certification. Happy learning.

- NPTEL team