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reviewer2@nptel.iitm.ac.in ▼ Courses » Estimation for Wireless Communications – MIMO/OFDM Cellular and Sensor Networks Announcements Course Ask a Question Progress Unit 3 - Week 2 - Vector **Estimation** Assignment-2 Course outline The due date for submitting this assignment has passed. Due on 2017-08-06, 23:59 IS As per our records you have not submitted this assignment. How to Access the Portal? 1) Consider the fading channel estimation problem where the output symbol y(k) 1 point is y(k) = hx(k) + v(k) with h, x(k), v(k) denoting the *real* channel coefficient, pilot Week 1 - Basics of Estimation, symbol and noise sample respectively. Let $\mathbf{x} = [x(1), x(2), \dots, x(N)]^T$ denote the pilot Maximum vector of transmitted pilot symbols and $\mathbf{v} = [v(1), v(2), \dots, v(N)]^T$ denote the Likelihood (ML) corresponding received symbol vector. Let v(k) be IID Gaussian noise with zero-mean Week 2 - Vector and variance σ^2 . The expected value of the maximum likelihood \hat{h} is, **Estimation** Lecture 06 - $\mathbf{x}^T \mathbf{y}$ Estimation of Complex Parameters -Symmetric Zero Mean Complex Gaussian Noise $h\mathbf{x}^T\mathbf{v}$ O Lecture 07 -Wireless Fading h Channel Estimation -No, the answer is incorrect. **Pilot Symbols** Score: 0 and Likelihood Function **Accepted Answers:** h Lecture 08 -Wireless Fading 2) Consider the fading channel estimation problem where the output symbol y(k) 1 point Channel is y(k) = hx(k) + v(k), with h, x(k), v(k) denoting the *real* channel coefficient, pilot Estimation symbol and noise sample respectively. Let $\mathbf{x} = \begin{bmatrix} \frac{3}{2}, \frac{1}{2}, \frac{1}{2}, -2 \end{bmatrix}^T$ denote the pilot vector of **Pilot Training** based transmitted pilot symbols and $\mathbf{y} = \begin{bmatrix} 2, -\frac{1}{2}, -1, \frac{3}{2} \end{bmatrix}^T$ denote the corresponding received Maximum Likelihood ML symbol vector. Let v(k) be IID Gaussian noise with zero-mean and dB variance Estimate $\sigma^2 = -3dB$. The maximum likelihood estimate of the channel coefficient h is, O Lecture 09 -Wireless Fading Channel Estimation -1

15

2

Mean and Variance of Pilot

Training Based Channel Estimate Maximum Likelihood Lecture 10 -Example – Wireless Fading 26/07/2020

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Channel Estimation for Downlink Mobile Communication

 Quiz : Assignment-2

 Assignment-2 Solution

Week 3 - Cramer-Rao Bound (CRB), Vector Parameter Estimation, Multi-Antenna Downlink Mobile Channel Estimation

Week 4 - Least Squares (LS) Principle, Pseudo-Inverse, Properties of LS Estimate, Examples – Mullti-Antenna Downlink and MIMO Channel Estimation

Week 5 - Inter Symbol Interference, Channel Equalization, Zero-forcing equalizer, Approximation error of equalizer

Week 6 -Introduction to Orthogonal Frequency Division Multiplexing (OFDM) and Pilot Based OFDM Channel Estimation, Example

Week 7 - OFDM – Comb Type Pilot (CTP) Transmission, Channel Estimation in Time/ Frequency Domain, CTP Example, Frequency Domain Equalization (FDE), Example-FDE

Week 8 -Sequential Least Squares (SLS) Estimation – Scalar/ Vector No, the answer is incorrect. Score: 0 Accepted Answers: $-\frac{2}{15}$ 3) Consider the fading channel estimation problem where the output symbol y(k) is 1 point y(k) = hx(k) + v(k), with h, x(k), v(k) denoting the real channel coefficient, pilot symbol and noise sample respectively. Let $\mathbf{x} = \left[\frac{3}{2}, 1, \frac{1}{2}, -2\right]^T$ denote the pilot vector of transmitted pilot symbols and $\mathbf{y} = \left[2, -\frac{1}{2}, -1, \frac{3}{2}\right]^T$ denote the corresponding received symbol vector. Let v(k) be IID Gaussian noise with zero-mean and dB variance $\sigma^2 = -3dB$. The variance of the maximum likelihood estimate of the channel coefficient h is, $\frac{1}{15}$ $\frac{3}{15}$ $\frac{4}{15}$ $\frac{4}{15}$

No, the answer is incorrect. Score: 0

Accepted Answers:

15

4) Consider the fading channel estimation problem where the output symbol y(k) **1** point is y(k) = hx(k) + v(k), with h, x(k), v(k) denoting the *complex* channel coefficient, pilot symbol and noise sample respectively. Let

 $\mathbf{x} = [1 - 2j \quad 2 + j \quad 1 - j \quad 2 - j]^T$ denote the pilot vector of transmitted pilot symbols and $\mathbf{y} = [1 - j \quad -1 + 2j \quad 1 \quad 1 - 2j]^T$ denote the corresponding received symbol vector. Let v(k) be IID Gaussian noise with zero-mean and dB variance $\sigma^2 = -9dB$. The maximum likelihood estimate of the channel coefficient *h* is,

 $\begin{array}{c}
\frac{6}{17}j \\
8}{17} + \frac{4}{17}j \\
-\frac{4}{17} - \frac{6}{17}j \\
\frac{8}{17} - \frac{4}{17}j
\end{array}$

No, the answer is incorrect. Score: 0

Feedback:

Accepted Answers: $\frac{8}{17} + \frac{4}{17}j$

5) Consider the fading channel estimation problem where the output symbol y(k) **1** point is y(k) = hx(k) + v(k), with h, x(k), v(k) denoting the *complex* channel coefficient, pilot symbol and noise sample respectively. Let

 $\mathbf{x} = \begin{bmatrix} 1 - 2j & 2 + j & 1 - j & 2 - j \end{bmatrix}^T$ denote the pilot vector of transmitted pilot symbols and $\mathbf{y} = \begin{bmatrix} 1 - j & -1 + 2j & 1 & 1 - 2j \end{bmatrix}^T$ denote the corresponding received symbol vector. Let v(k) be IID Gaussian noise with zero-mean and dB variance

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Cases, Applications -Wireless Fading Channel Estimation. SLS Example

 $\sigma^2 = -9dB$. The variance of the maximum likelihood estimate of the channel coefficient h is, 1 120 f Y D in 136 150 1 196

No, the answer is incorrect. Score: 0

Accepted Answers: $\frac{1}{136}$

6) Consider the fading channel estimation problem where the output symbol v(k) 1 point is y(k) = hx(k) + v(k), with h, x(k), v(k) denoting the *complex* channel coefficient, pilot symbol and noise sample respectively. Let

 $\mathbf{x} = \begin{bmatrix} 1 - 2j & 2 + j & 1 - j & 2 - j \end{bmatrix}^T$ denote the pilot vector of transmitted pilot symbols and $\mathbf{y} = \begin{bmatrix} 1 - j & -1 + 2j & 1 & 1 - 2j \end{bmatrix}^T$ denote the corresponding received symbol vector. Let v(k) be IID Gaussian noise with zero-mean and dB variance $\sigma^2 = -9dB$. The variance of the real part of the maximum likelihood \hat{h} is,

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240
   1
  196
  272
  \frac{1}{75}
No, the answer is incorrect.
Score: 0
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Accepted Answers: __1 272

7) Consider the fading channel estimation problem where the output symbol y(k) 1 point is y(k) = hx(k) + v(k), with h, x(k), v(k) denoting the *complex* channel coefficient, pilot symbol and noise sample respectively. Let

 $\mathbf{x} = \begin{bmatrix} 1 - 2j & 2 + j & 1 - j & 2 - j \end{bmatrix}^T$ denote the pilot vector of transmitted pilot symbols and $\mathbf{y} = \begin{bmatrix} 1 & j & -1 + 2j & 1 & 1 - 2j \end{bmatrix}^T$ denote the corresponding received symbol vector. Let v(k) be IID Gaussian noise with zero-mean and dB variance $\sigma^2 = -9dB$. The variance of the imaginary part of the maximum likelihood h is,

g+

No, the answer is incorrect. Score: 0 Accepted Answers:

1 272

8) Consider the fading channel estimation problem where the output symbol y(k) **1** point is y(k) = hx(k) + v(k), with h, x(k), v(k) denoting the *complex* channel coefficient, pilot symbol and noise sample respectively. Let

 $\mathbf{x} = \begin{bmatrix} 1 - 2j & 2 + j & 1 - j & 2 - j \end{bmatrix}^T$ denote the pilot vector of transmitted pilot symbols and $\mathbf{y} = \begin{bmatrix} 1 - j & -1 + 2j & 1 & 1 - 2j \end{bmatrix}^T$ denote the corresponding received symbol vector. Let v(k) be IID Gaussian noise with zero-mean and dB varianc $\sigma^2 = -9dB$. The errors in the real and imaginary parts of the maximum likelihood \hat{h} are Equal

- Equal
- Correlated
- Independent
- All of the above

No, the answer is incorrect. Score: 0

Accepted Answers: Independent

9) Consider the fading channel estimation problem where the output symbol y(k) 1 point is y(k) = hx(k) + v(k), with h, x(k), v(k) denoting the *real* channel coefficient, pilot symbol and noise sample respectively. Let $\mathbf{x} = [x(1), x(2), \dots, x(N)]^T$ denote the pilot vector of transmitted pilot symbols and $\mathbf{v} = [v(1), v(2), \dots, v(N)]^T$ denote the corresponding received symbol vector. Let v(k) be independent Gaussian noise with zeromean and variance $k\sigma^2$. And let **R** denote the covariance matrix of the noise vector $\mathbf{v} = [v(1), v(2), \dots, v(N)]^T$. The ML estimate of the channel coefficient is,

$$\hat{h} = \frac{1}{N} \sum_{k=1}^{N} \frac{y(k)}{k}$$
$$\hat{h} = \frac{\sum_{k=1}^{N} \frac{x(k)y(k)}{k}}{\sum_{k=1}^{N} \frac{x(k)y(k)}{k}}$$

No, the answer is incorrect. Score: 0

Accepted Answers:

$$\hat{h} = \frac{\sum\limits_{k=1}^{N} \frac{x(k)y(k)}{k}}{\sum\limits_{k=1}^{N} \frac{x^2(k)}{k}}$$

10)Consider the fading channel estimation problem where the output symbol y(k) 1 point is y(k) = hx(k) + v(k), with h, x(k), v(k) denoting the *real* channel coefficient, pilot symbol and noise sample respectively. Let $\mathbf{x} = [x(1), x(2), \dots, x(N)]^T$ denote the pilot vector of transmitted pilot symbols and $\mathbf{y} = [y(1), y(2), \dots, y(N)]^T$ denote the corresponding received symbol vector. Let v(k) be independent Gaussian noise with zeromean and variance $k\sigma^2$. And let **R** denote the covariance matrix of the noise vector

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