



# Unit 15 - Week 9: Fundamental properties of feedback systems

## Course outline

How to access the portal

Prerequisite Assignment

MATLAB Download and Introduction

MATLAB Learning Modules

Week 1: Linear System Theory, Fourier and Laplace Transforms

Week 2: Introduction to feedback control, Nyquist stability theory

Week 3 : Bode plots, Steps for performing control design, General controllers

Week 4: Bode-plot and root-locus based control design

Week 5: Control of systems with some known parameters, Introduction to 2-degree of freedom control

Week 6: 2-Degree of

## Week 9 - Assessment

The due date for submitting this assignment has passed. **Due on 2018-10-03, 23:59 IST.** As per our records you have not submitted this assignment.

1) The loop gain  $L$  of a unity feedback system is

1 point

$$L(s) = \frac{1}{\left(\frac{s}{100} + 1\right)\left(\frac{s}{200} + 1\right)\left(\frac{s}{300} + 1\right)}$$

Further, it is given that,  $\oint_{C=C_1+C_2} \ln S ds = 0$  where

$S$  is the sensitivity function and  $C$  is closed curve in the  $s$ -plane shown below:

Identify the correct equation.



$$\int_{C_2} \ln S ds = \pi$$



$$\int_{C_1} \angle S ds = 2\pi$$



$$\int_0^\infty \ln |S| d\omega = 0$$



$$\int_0^\infty S ds = 0$$

No, the answer is incorrect.

Score: 0

Accepted Answers:

$$\int_0^\infty \ln |S| d\omega = 0$$

2) The natural logarithm of the sensitivity function  $S$  as a function of frequency ( $\omega$ ) for a minimum-phase, stable system is shown below:

1 point

Calculate the value of  $\int_\pi^\infty \ln |S| d\omega$  :



$$\pi/2$$



$$\pi$$



$$3\pi/2$$



$$0$$

No, the answer is incorrect.

Score: 0

Accepted Answers:

## freedom control design for robustness

### Week 7: Quantitative feedback theory (Part 1/2)

### Week 8 : Quantitative feedback theory (Part 2/2)

### Lecture Notes(Week 1 - 8)

### Week 9: Fundamental properties of feedback systems

- ☐ Fundamental properties of the loop gain (part 1/2)
- ☐ Fundamental properties of the loop gain (part 2/2)
- ☐ Ideal Bode Characteristic (Part 1/2)
- ☐ Ideal Bode Characteristic (Part 2/2)
- ☐ Quiz : Week 9 - Assessment
- ☐ Week 9: Lecture Notes

### Week 10 :Nonminimum phase system

### Week 11: Unstable systems

### Week 12 Describing functions

### Assignment solutions

 $\pi$ 

3) The Bode plot for the open loop gain of a unity feedback system is shown below:

1 point

Identify the approximate values of open-loop phase for  $\omega \ll 10$  and  $\omega \gg 10$ .

- ☐ 0 and  $-\pi$  respectively.
- ☐ 0 and  $-\pi/2$  respectively.
- ☐  $-\pi/2$  and  $-\pi$  respectively.
- ☐  $-\pi$  and  $-\pi/2$  respectively.

No, the answer is incorrect.

Score: 0

Accepted Answers:

0 and  $-\pi$  respectively.

4) Calculate the approximate value of open-loop phase at  $\omega = 1 \text{ rad/s}$  for the system specified in Q3.

1 point

- ☐  $-\frac{3}{5\pi}$
- ☐  $\frac{2}{5\pi}$
- ☐  $-\frac{2}{3\pi}$
- ☐  $-\frac{2}{5\pi}$

No, the answer is incorrect.

Score: 0

Accepted Answers:

$-\frac{2}{5\pi}$

5) What information does the ideal bode characteristic plot give?

1 point

- ☐ The minimum necessary gain and phase margins.
- ☐ The maximum possible gain cross-over frequency.
- ☐ The minimum possible gain cross-over frequency.
- ☐ The optimal relative degree of the loop gain.

No, the answer is incorrect.

Score: 0

Accepted Answers:

The minimum possible gain cross-over frequency.

6) The open-loop magnitude for a plant  $P(s)$  has to be maintained at 40 dB for frequency  $\omega \leq 10 \text{ rad/s}$ . Further, it is required that the phase margin should be  $\frac{\pi}{4}$ . Calculate the minimum value of gain cross-over frequency:

1 point

- ☐ 30 rad/s
- ☐ 107 rad/s
- ☐ 39 rad/s
- ☐ 76 rad/s



No, the answer is incorrect.

Score: 0

Accepted Answers:

107 rad/s

7) Identify the ideal bode characteristic for the loop gain  $L(s)=CP(s)$  obtained in Q6 from the options given below:

1 point

- ☐
- ☐
- ☐
- ☐

No, the answer is incorrect.

Score: 0

Accepted Answers:

8) In a certain feedback control system, it is desired to maintain the loop gain constant at 75 dB up to 43 rad/s. The phase margin of the system should be  $40^\circ$  and gain margin should be 10 dB. Determine the value of requisite roll-off (in dB/decade) after 43 rad/s that would lead to minimum gain cross-over frequency.

- ☐ -31.11 dB/decade
- ☐ 31.11 dB/decade
- ☐ -41.11 dB/decade
- ☐ -15.55 dB/decade

No, the answer is incorrect.

Score: 0

Accepted Answers:

-31.11 dB/decade

9) For Q8, find out the frequency ( $\omega'_{gc}$ ) till which the slope should be maintained to obtain the required Gain margin.

1 point

- ☐
- $65.0 \times 10^3 \text{ rad/s}$
- ☐
- $75.2 \times 10^3 \text{ rad/s}$
- ☐
- $20.8 \times 10^3 \text{ rad/s}$
- ☐
- $11.6 \times 10^3 \text{ rad/s}$

No, the answer is incorrect.

Score: 0

Accepted Answers:

$11.6 \times 10^3 \text{ rad/s}$

10) In Q8, if high frequency roll-off is -100 dB/decade then calculate the minimum frequency ( $\omega_2$ ) up to which loop shape will have to be preserved.

1 point

- ☐
- $37.5 \times 10^3 \text{ rad/s}$
- ☐
- $37.2 \times 10^3 \text{ rad/s}$
- ☐
- $45.2 \times 10^3 \text{ rad/s}$
- ☐
- $54.2 \times 10^3 \text{ rad/s}$

**No, the answer is incorrect.**

**Score: 0**

**Accepted Answers:**

$37.2 \times 10^3 \text{ rad/s}$

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