



Unit 13 - Week 8 : Quantitative feedback theory (Part 2/2)

Course outline

How to access the portal

Prerequisite Assignment

MATLAB Download and Introduction

MATLAB Learning Modules

Week 1: Linear System Theory, Fourier and Laplace Transforms

Week 2: Introduction to feedback control, Nyquist stability theory

Week 3 : Bode plots, Steps for performing control design, General controllers

Week 4: Bode-plot and root-locus based control design

Week 5: Control of systems with some known parameters, Introduction to 2-degree of freedom control

Week 6: 2-Degree of freedom control

Week 8 Assessment

The due date for submitting this assignment has passed. **Due on 2018-09-26, 23:59 IST**
As per our records you have not submitted this assignment.

1) What is the role of Controller and Pre-filter in Nichols plot based 2-DOF control system design? **1 point**



C(s) restricts the spread in the closed-loop response $\delta(j\omega)$ and F(s) is designed to obtain the desired nominal response.



F(s) restricts the spread in the closed-loop response $\delta(j\omega)$ and C(s) is designed to obtain the desired nominal response.



Both C(s) and F(s) together restrict the spread in the closed-loop response which results in the desired nominal response.



Both C(s) and F(s) are designed to obtain the desired nominal response which in turn restricts the spread in the closed-loop response $\delta(j\omega)$.

No, the answer is incorrect.

Score: 0

Accepted Answers:

C(s) restricts the spread in the closed-loop response $\delta(j\omega)$ and F(s) is designed to obtain the desired nominal response.

2) Which of the following statements define plant template for a plant whose gain and one pole location are uncertain? **1 point**



The region in the Nichols plot occupied by the plant's transfer function $P(j\omega)$ at a given frequency ω for all possible variations in the gain and pole of P is called plant template.



The region in the Nichols plot occupied by a plant at a given frequency for all possible variations in its gain alone is called the plant template.



The region in the Nichols plot occupied by a plant at a given frequency for all possible variations in its pole location alone is called the plant template.



The union of regions in the Nichols plot occupied by the frequency ω is swept from 0 to ∞

No, the answer is incorrect.

Score: 0

Accepted Answers:

The region in the Nichols plot occupied by the plant's transfer function $P(j\omega)$ at a given frequency ω for possible variations in the gain and pole of P is called plant template.

3)

1 point

design for robustness

Week 7:
Quantitative feedback theory (Part 1/2)Week 8 :
Quantitative feedback theory (Part 2/2)

- ☐ Robust control design using Quantitative feedback theory (Part 1/2)
- ☐ Robust control design using Quantitative feedback theory (Part 2/2)
- ☐ Tutorial on QFT Toolbox software (Part 1/3)
- ☐ Tutorial on QFT Toolbox software (Part 2/3)
- ☐ Tutorial on QFT Toolbox software (Part 3/3)
- ☐ Quiz : Week 8 Assessment

Lecture Notes(Week 1 - 8)

Week 9:
Fundamental properties of feedback systems

Week 10 :Nonminimum phase system

Week 11:
Unstable systemsWeek 12
Describing functions

Assignment solutions

The transfer function of a plant is given as $P(s) = \frac{K}{s(\frac{s}{p} + 1)}$. The nominal value of K is 10 and it

varies between 1 and 20. Similarly the nominal value of p is 2 and it varies between 1 and 4 respectively. Identify the plant template at $\omega = 1 \text{ rad/s}$ from below:



No, the answer is incorrect.

Score: 0

Accepted Answers:

4) At what frequency does the shape of the plant template become a vertical straight line?

1 point



At a frequency where upper value of the transmission function ($T_{upper}(s)$) drops down to -20dB.



At any frequency much higher than the corner frequencies of the plant.



At a frequency where the permissible spread between upper and lower transmission functions is 3.5 dB.



At any frequency close to the corner frequencies of the plant.

No, the answer is incorrect.

Score: 0

Accepted Answers:

At any frequency much higher than the corner frequencies of the plant.

5) Till what frequency should one restrict the permissible spread between the upper and lower bounds $\delta(j\omega)$? **1 point**



Till the frequency where nominal value of the transmission function ($T_{nominal}(s)$) rises to +20dB.



Till the frequency where nominal value of the transmission function ($T_{nominal}(s)$) drops down to -20dB.



Till the frequency where upper value of the transmission function ($T_{upper}(s)$) rises to +20dB.



Till the frequency where upper value of the transmission function ($T_{upper}(s)$) drops down to -20dB.

No, the answer is incorrect.

Score: 0

Accepted Answers:

Till the frequency where upper value of the transmission function ($T_{upper}(s)$) drops down to -20dB.

6) What should approximately be the structure of the nominal transmission function's transfer function? **1 point**



A general second order system because of the location of requisite dominant closed loop poles.



A general second order system cascaded with a pole near origin.



A general first order system.



A general first order system cascaded with a pole near the origin.



No, the answer is incorrect.

Score: 0

Accepted Answers:

A general second order system because of the location of requisite dominant closed loop poles.

7) What does the robust tracking bound on loop gain at a given frequency in the Nichols plot indicate? **1 point**

- ☐ The region above which the plant template gain lies such that the permissible spread between the upper and lower transmission functions are met.
- ☐ The region above which the nominal lies such that the permissible spread between the upper and lower transmission functions are met.
- ☐ The region above which the nominal plant lies.
- ☐ It is the region traced by the open loop transfer function when the gain and phase of the plant varies.

No, the answer is incorrect.

Score: 0

Accepted Answers:

The region above which the nominal lies such that the permissible spread between the upper and lower transmission functions are met.

8) The transmission function of a system is given by $T = \frac{L}{1+L}$ where L is open-loop gain. Identify the phase margin Φ (Hint : $|L|=1$ at gain cross-over frequency) **0 points**

- ☐ $\Phi = 40^\circ$
- ☐ $\Phi = 60^\circ$
- ☐ $\Phi = 30^\circ$
- ☐ $\Phi = 35^\circ$

No, the answer is incorrect.

Score: 0

Accepted Answers:

$\Phi = 40^\circ$

9) Identify the width of the stability bound w_d using the plant template obtained in Q3. **1 point**

- ☐ 120°
- ☐ 123°
- ☐ 143.12°
- ☐ 111°

No, the answer is incorrect.

Score: 0

Accepted Answers:

111°

10) For the plant specified in Q3 a controller $C_1(s)$ ensures that the plant template at $\omega = 1 \text{ rad/s}$ is shifted to new region (shown in red). Similarly another controller $C_2(s)$ ensures that the plant template at $\omega = 1 \text{ rad/s}$ is shifted to new region (shown in green). Identify $C_1(j1)$ and $C_2(j1)$ from below: **1 point**

- ☐ $C_1(j1) = -j10$ and $C_2(j1) = -0.1 + j0.1$
- ☐

$C_1(j1) = -0.1 + j0.1$ and $C_2(j1) = -j10$

$C_1(j1) = 0.5 + j1$ and $C_2(j1) = 0.5 + j0.75$

$C_1(j1) = 2 + j3$ and $C_2(j1) = 3 + j7$

No, the answer is incorrect.

Score: 0

Accepted Answers:

$C_1(j1) = -j10$ and $C_2(j1) = -0.1 + j0.1$



Previous Page

End

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