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Courses » Control System Design

Announcements

Course

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Unit 5 - Week 1: Linear System Theory, Fourier and Laplace Transforms





1 point

1 point

Course outline

How to access the portal

Prerequisite Assignment

MATLAB
Download and
Introduction

MATLAB Learning Modules

Week 1: Linear System Theory, Fourier and Laplace Transforms

- Introduction
- Linear Systems
- Homogeneous linear time invariant ordinary differential equations
- Inhomogeneous linear time invariant ordinary differential equations
- Fourier transforms (Part 1)
- Fourier transforms (Part 2)
- Laplace transforms (Part 1)

Week-1 Assessment

The due date for submitting this assignment has passed. Due on 2018-08-15, 23:59 IS As per our records you have not submitted this assignment.

Week-1 Assessment

1) Following differential equation represents

$$\frac{d^2x(t)}{dt^2} + \frac{tdx(t)}{dt} + 5x^2(t) = u(t)$$

- Linear Time Varying System
- Linear Time Invariant System
- Non-Linear Time Varying System
- Non-Linear Time Invariant System

No, the answer is incorrect.

Score: 0

Accepted Answers:

Non-Linear Time Varying System

2) The solution to the following homogenous differential equation is given by:

$$\ddot{x}(t) + 7\dot{x}(t) + 12x(t) = 0$$

with initial conditions,

$$x(0) = 0, \dot{x}(0) = 12$$

$$12(e^{-3t} - e^{-4t})$$

$$12(e^{3t}-e^{4t})$$

$$12(e^{-3t} + e^{-4t})$$

$$a^{-3t}$$
 a^{-4}

No, the answer is incorrect. Score: 0

Accepted Answers:

$$12(e^{-3t} - e^{-4t})$$

3) A unit step input is applied at time t=0 to a system which has the following input (u)-output (x) relationship:

$$\ddot{x}(t) + 7\dot{x}(t) + 12x(t) = 12u(t)$$

$$x(0) = 0, \dot{x}(0) = 12;$$

The response of the system at time t = 1 second (upto 2 decimal point) is given by

- Laplace transforms (Part 2)
- Quiz : Week-1 Assessment
- Solutions to Assessment 1
- New Lesson Module 1 lecture notes

Week 2: Introduction to feedback control, **Nyquist stability** theory

Week 3: Bode plots, Steps for performing control design, General controllers

Week 4: Bodeplot and rootlocus based control design

Week 5: Control of systems with some known parameters, Introduction to 2degree of freedom control

Week 6: 2-Degree of freedom control design for robustness

Week 7: Quantitative feedback theory (Part 1/2)

Week 8: Quantitative feedback theory (Part 2/2)

Lecture Notes(Week 1 -8)

Week 9: **Fundamental** properties of feedback systems

Week 10 :Nonminimum phase system

Week 11: Unstable systems

No, the answer is incorrect.

Score: 0

Accepted Answers:

(Type: Range) 1.22, 1.24

1 point

4) An LTI system has the impulse response h(t) given by $h(t) = e^{-t} - e^{-2t}$. The system 1 pc is excited by input $u(t) = \delta(t-1) + \delta(t-2)$. The output of the system at t=3s is given by



$$e^{-1} - e^{-2}$$

$$e^{-1} - e^{-4}$$

$$e^{-2} - e^{-4}$$

$$1 - e^{-2}$$



$$-e^{-2}$$

No, the answer is incorrect.

Score: 0

Accepted Answers:

$$e^{-1} - e^{-4}$$

5) The Laplace transform of the following signal is given by

1 point







No, the answer is incorrect.

Score: 0

Accepted Answers:

6) If the step response of LTI system is

1 point

$$y(t) = 1 - e^{-9t}(\cos 40t + 9/40(\sin 40t))$$

The transfer function of the system is given by



$$1681/(s^2 + 18s + 1681)$$

$$169/(s^2 + 18s + 169)$$

$$25/(s^2 + 18s + 25)$$

$$1681/(s^2 + 180s + 1681)$$

No, the answer is incorrect.

Score: 0

Accepted Answers:

$$1681/(s^2 + 18s + 1681)$$

7) The transfer function of a LTI system is given by G(s) = 1/(s+1). The response of **1 point** the system for unit ramp input given by

Week 12 Describing functions

Assignment solutions

- ,	
$(t+e^t-1)$	
$(t + e^{-t} - 1)$	
$(t+e^{-t}+1)$	
$(t+e^{-t})$	

No, the answer is incorrect.

Score: 0



Accepted Answers:

 $(t + e^{-t} - 1)$



8) The transfer function of a system is given by $G(s) = (3s + 2)/(s^2 + s + 1)$ The system is initially at rest and is applied a unit step input at t = 0. If x(t) is the output, the value of dx/dt at t = 0 is, (Hint: use initial value theorem)



2

O 5

0 1

3



No, the answer is incorrect.

Score: 0

Accepted Answers:

3

9) The transfer function of a system is given by $G(s) = s(5s + 4)/(s^3 + s + 1)$ The **opints** system is initially at rest and is applied a ramp input at t = 0. If x(t) is the output, the value of $x(\infty)$

0 4

5

0 1

0

No, the answer is incorrect.

Score: 0

Accepted Answers:

4

10)A second order system with unity DC gain and no zeros has a damping factor of $\xi = 0.2$ and an undamped natural frequency $\omega_n = 10$. The system is initially at rest and is applied a step input at t = 0. The value of the response x(t) at t=0.1s (upto 2 decimal point) is

No, the answer is incorrect.

Score: 0

Accepted Answers:

(Type: Range) 0.39,0.41

1 point

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