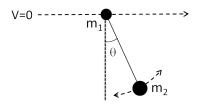
DEPARTMENT OF PHYSICS Indian Institute of Technology Kharagpur **Classical Mechanics-I** Course: PH20007 Assignment-10: Assignment-10 (Lagrangian-2)

- 1. A particle is falling under the influence of gravity when frictional forces obtainable from a dissipative function $\frac{1}{2}kv^2$ are present. The maximum possible velocity for fall from rest is
 - (a) $\frac{mg}{2k}$ (b) $\frac{mg}{5k}$ (c) $\frac{mg}{k}$

 - (d) $\frac{2mg}{h}$
- 2. For Lagrangian (L) of any system, which of the following is true
 - (a) $L = L(p_k, \dot{q_k}, t)$ (b) $L = L(q_k, \dot{q_k}, t)$ (c) $L = L(p_k, \dot{p_k}, t)$ (d) $L = L(q_k, \dot{p_k}, t)$
- 3. A particle of mass moves in a plane in the field of force given by $\vec{F} = -kr \cos \phi \hat{r}$ where k is a constant and \hat{r} is the radial unit vector. which of the following is true Lagrange's equation(s)
 - (a) $m\ddot{r} mr\dot{\phi}^2 + kr\,\cos\phi = 0$ and $mr^2\dot{\phi} = 0$
 - (b) $m\ddot{r} mr\dot{\phi}^2 + kr\,\cos\phi = 0$ and $mr^2\dot{\phi} = constant$
 - (c) $m\ddot{r} mr\dot{\phi}^2 + kr \cos\phi = constant$ and $mr^2\dot{\phi} = 0$
 - (d) $m\ddot{r} mr\dot{\phi}^2 + kr \cos\phi = constant$ and $mr^2\dot{\phi} = constant$
- 4. Point of suspension of a simple pendulum of mass m_2 is attached to a mass m_1 that is moving along x- axis with uniform velocity v_0 .

The Lagrangian of the system is given by



- (a) $L = \frac{1}{2}m_1v_0^2 + \frac{1}{2}m_2(v_0 + l\cos\theta\dot{\theta})^2 + mgl\cos\theta$ (b) $L = \frac{1}{2}m_2v_0^2 + \frac{1}{2}m_1(v_0 + lcos\theta\dot{\theta})^2 + mglcos\theta$ (c) $L = \frac{1}{2}m_1v_0^2 + \frac{1}{2}m_2(v_0 + l\cos\theta\dot{\theta})^2 - mglsin\theta$ (a) $L = \frac{1}{2}m_1v_0^2 + \frac{1}{2}m_2(v_0 + lsin\theta\dot{\theta})^2 + mglcos\theta$
- 5. An electric dipole with opposite charges of masses m_1 and m_2 separated by a distance l is placed in an external electric field. θ is the instantaneous orientation of the dipole w.r.t. \vec{E} .

The lagrangian of the dipole is (p is the magnitude of dipole moment)

(i) $L = \frac{l^2}{2}(m_1 + m_2)\dot{\theta}^2 + pE\cos\theta$ (ii) $L = \frac{l^2}{4}(m_1 + m_2)\dot{\theta}^2 + pE\cos\theta$ (iii) $L = \frac{l^2}{6}(m_1 + m_2)\dot{\theta}^2 + pE\cos\theta$ (iv) $L = \frac{l^2}{8}(m_1 + m_2)\dot{\theta}^2 + pE\cos\theta$

6. Lagrange's equation of motion of an electrical circuit comprising an inductance L and capacitance C (the condenser is charged to q coulombs and the current flowing in the circuit is i amperes) is

(i) $\ddot{q} + \frac{\dot{q}}{LC} = 0$ (ii) $\ddot{q} + \frac{Lq}{C} = 0$ (iii) $\ddot{q} + \frac{Cq}{L} = 0$ (iv) $\ddot{q} + \frac{q^2}{LC} = 0$

- 7. For a compound pendulum Lagrangian can be written as (θ is the instantaneous angle w.r.t. vertical axis and I_0 is the M.I. about the axis of rotation)
 - (a) $L = \frac{1}{2}I_0^2\dot{\theta}^2 mgh\,\cos\,\theta$
 - (b) $L = \frac{1}{2}I_0\dot{\theta}^2 mgh\,\cos\theta$ (c) $L = \frac{1}{2}I_0\dot{\theta}^2 - mgh\,(1 + \cos\theta)$
 - (d) $L = \frac{1}{2}I_0\dot{\theta}^2 mgh\sin\theta$
- 8. A bead slides without friction on a wire which is rotating with angular velocity ω in the force free space. The radial velocity is
 - (a) $\sqrt{\omega^2 r}$
 - (b) $\sqrt{\omega^2 r + +constant}$ (c) $\sqrt{\omega^2 r^2}$
 - (d) $\sqrt{constant \omega^2 r^2}$
- 9. A spring of mass M and spring constant k, is hung vertically (along y-axis). Another mass, m, is suspended from it. The K.E. of the system
 - (a) $\frac{1}{2}M\dot{y}^{2}$ (b) $\frac{1}{2}m\dot{y}^{2}$ (c) $\frac{1}{6}M\dot{y}^{2}$ (d) $\frac{1}{6}M\dot{y}^{2} + \frac{1}{2}m\dot{y}^{2}$
- 10. A spring of mass M and spring constant k, is hung vertically. Another mass, m, is suspended from it. The system will execute simple harmonic motion with a period of

(a)
$$2\pi\sqrt{\frac{M+m}{k}}$$

(b) $2\pi\sqrt{\frac{M+\frac{m}{3}}{k}}$
(c) $2\pi\sqrt{\frac{M}{3}+m}$

(d)
$$2\pi\sqrt{\frac{M-m}{k}}$$

End