

Lecture 58:

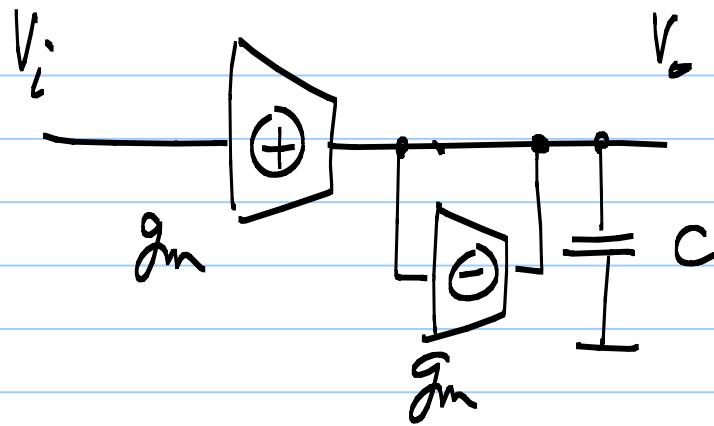
Higher order filters:

Even order: can be factored into 2nd order poly.

Odd order: can be factored into 2nd order poly
& 1 1st order poly.

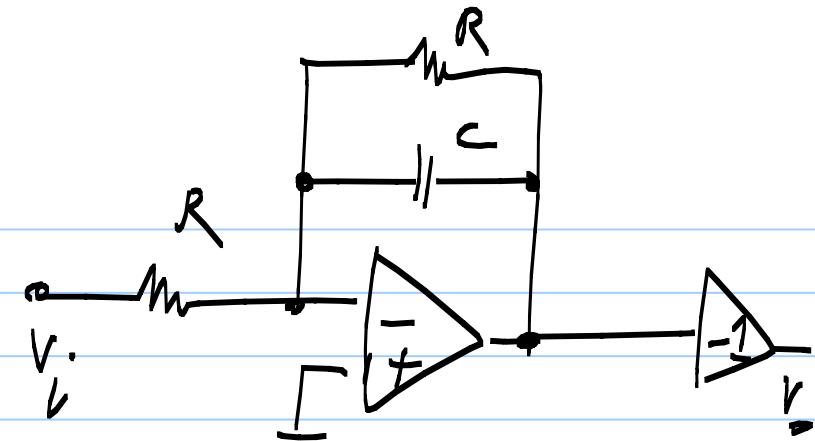
6th order: $3 \times 2^{\text{nd}} \text{ order}$

7th order: $3 \times 2^{\text{nd}} \text{ order} + 1^{\text{st}} \text{ order}$



$$\frac{V_o}{V_i} = \frac{g_m}{g_m + sc}$$

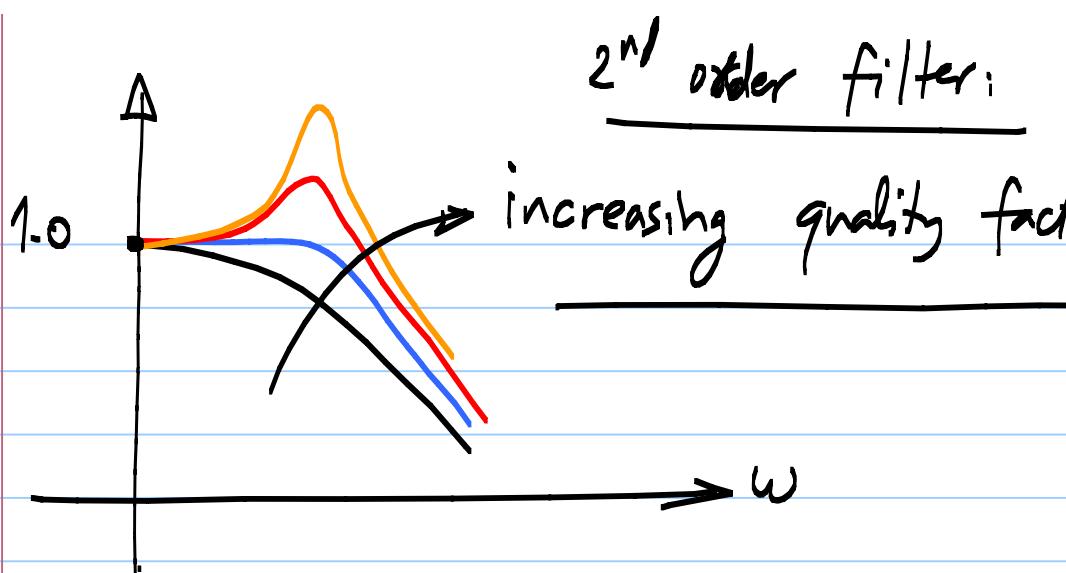
$$= \frac{1}{1 + sc/g_m}$$



$$\frac{V_o}{V_i} = \frac{1}{1 + sc_1 R}$$

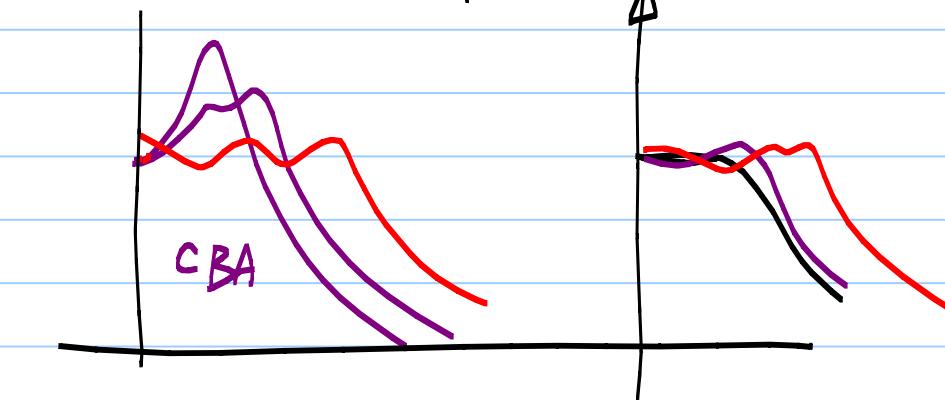
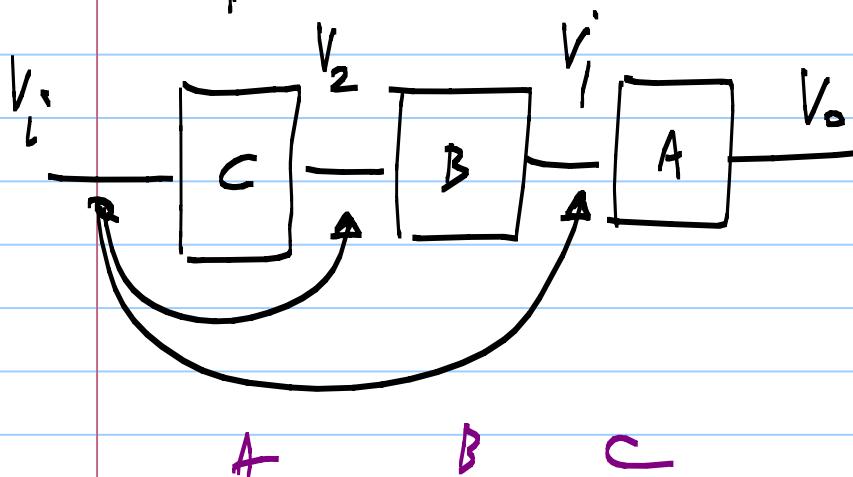
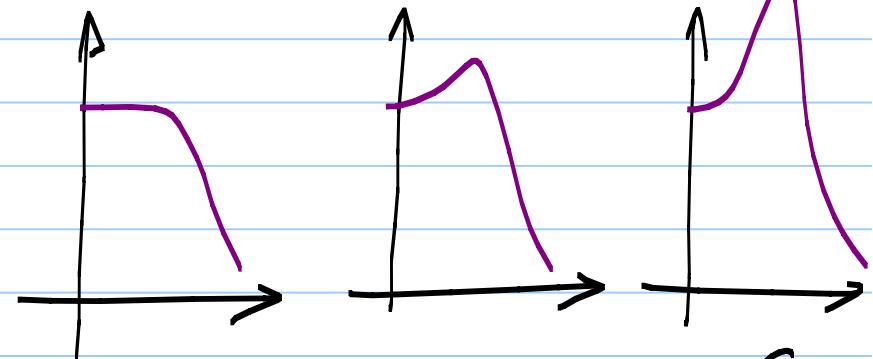
High order filter realization: Nth order filter

* Cascade of $\frac{N}{2}$ ($\frac{N-1}{2}$ if N is odd) 2nd order filters (and one 1st order if N is odd)
{} both g_m-c & active-RC



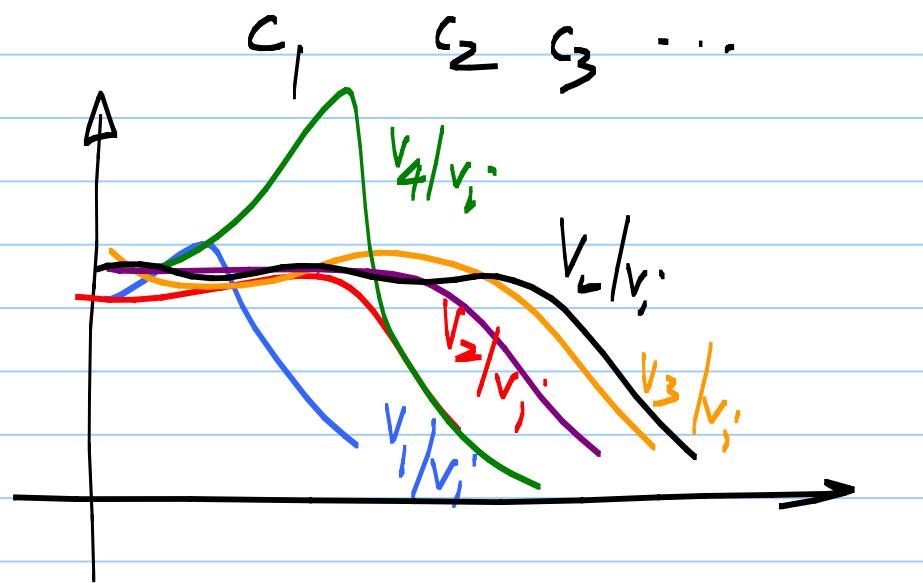
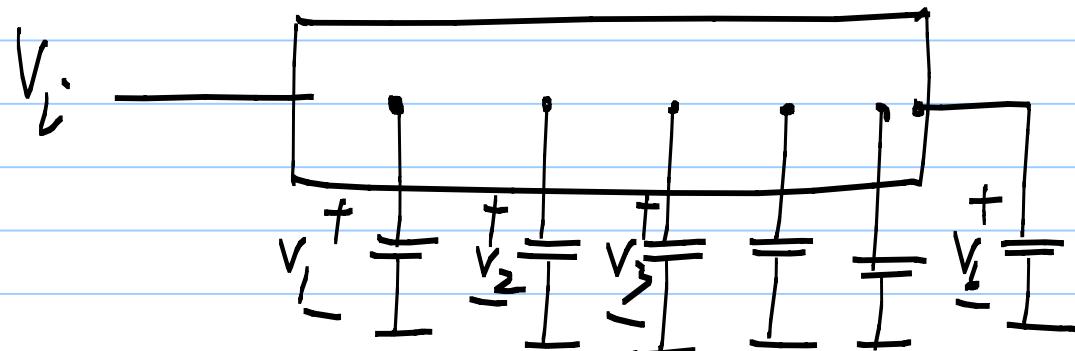
2ⁿ order filter:

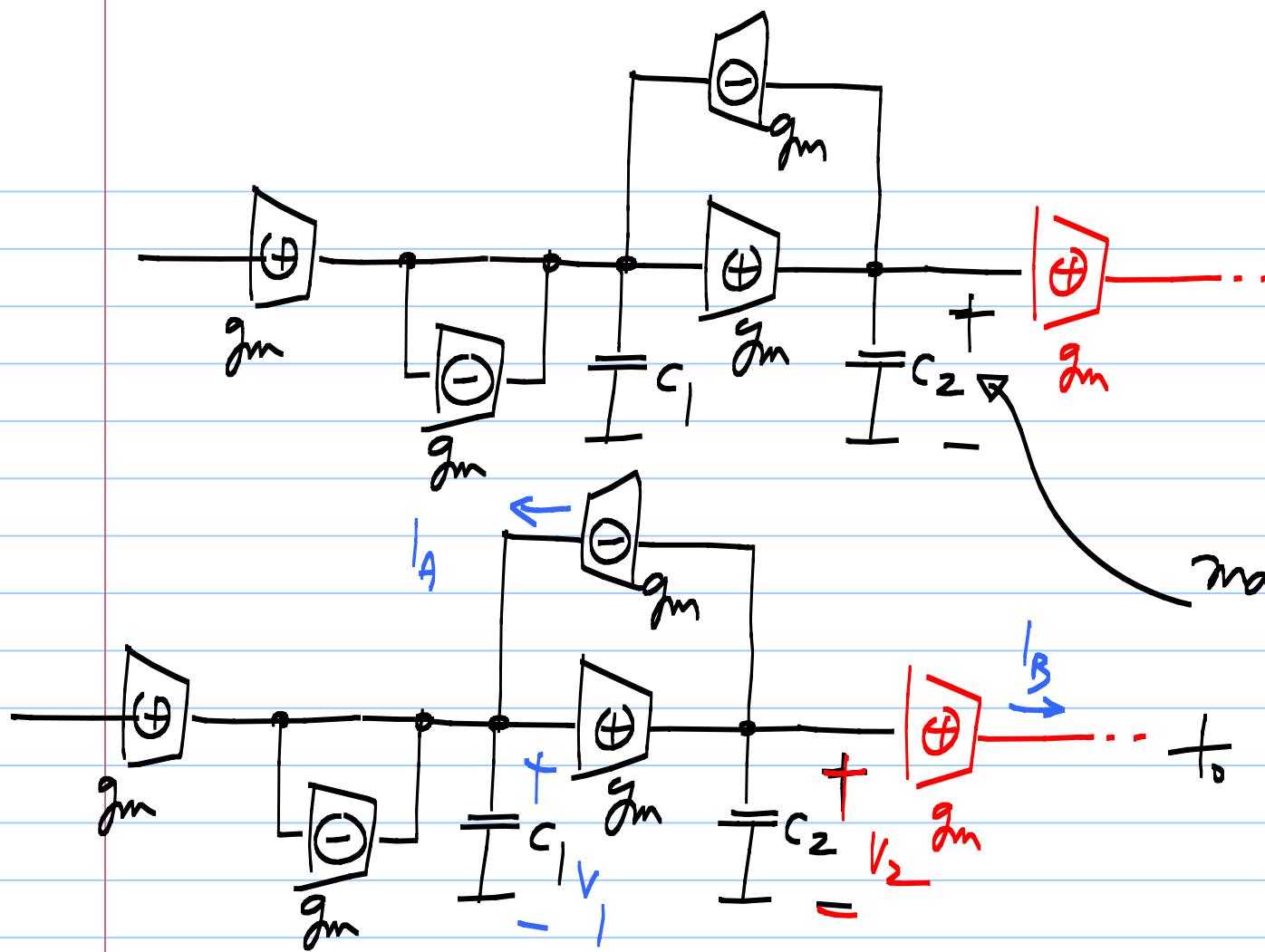
increasing quality factor



Ordering of 2nd order sections:

- * 1st order ; 2nd order sections with -the lowest quality factor filter first increasing quality factors
- * Equalize the maximum of transfer function magnitudes from the input to all the g_m (opamp) outputs in the circuit.

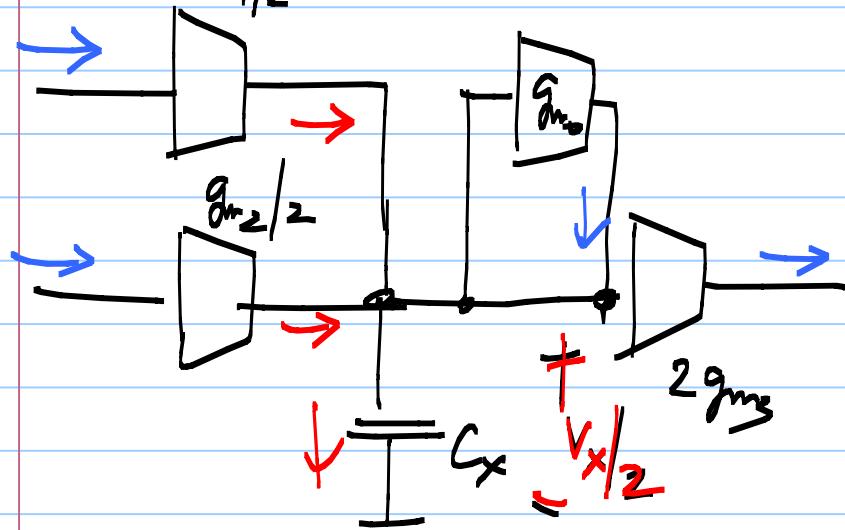
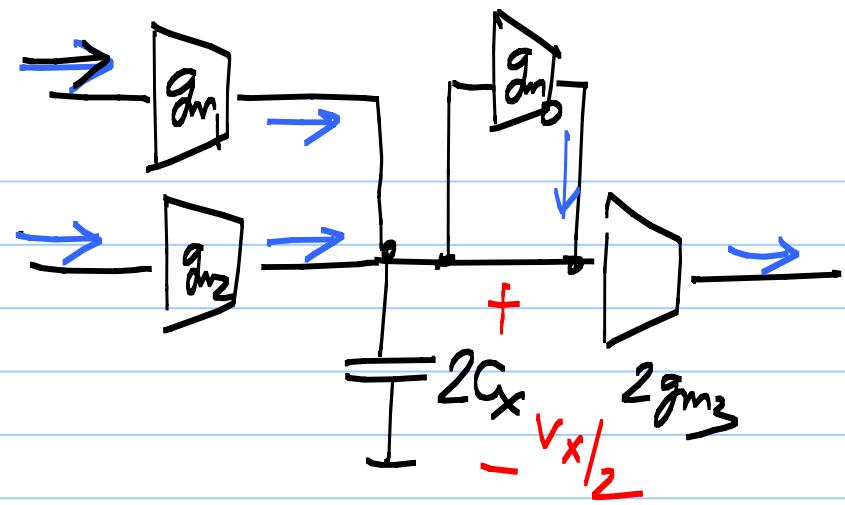
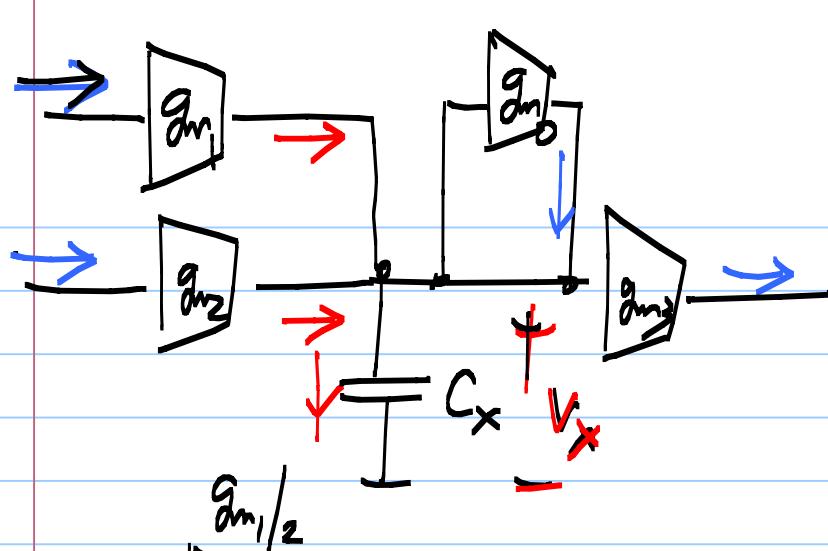




max. of transfer fn.
magnitude has
to be reduced by 2x
 $\{6dB\}$

g_m -C filter:

- * Voltage across capacitor C_x must be reduced by $2x$
- * Current flowing through C_x reduced by $2x$
 - $\Rightarrow g_{ms}$ whose outputs are connected to C_x must reduce by $2x$
 - g_{ms} whose inputs are connected to C_x must increase by $2x$
 - g_{ms} with i/p & o/p connected to C_x : unchanged

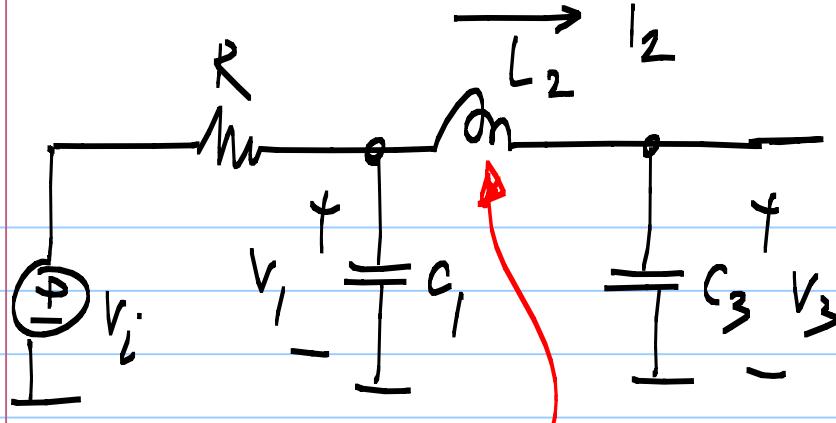


* Increase C_x by 2x

gms whose inputs are connected to C_x

must increase by 2x

[Node scaling to maintain equal transfer
fn. magnitude peaks]



$$V_1 = \frac{V_1 - V_1}{R} - I_2$$

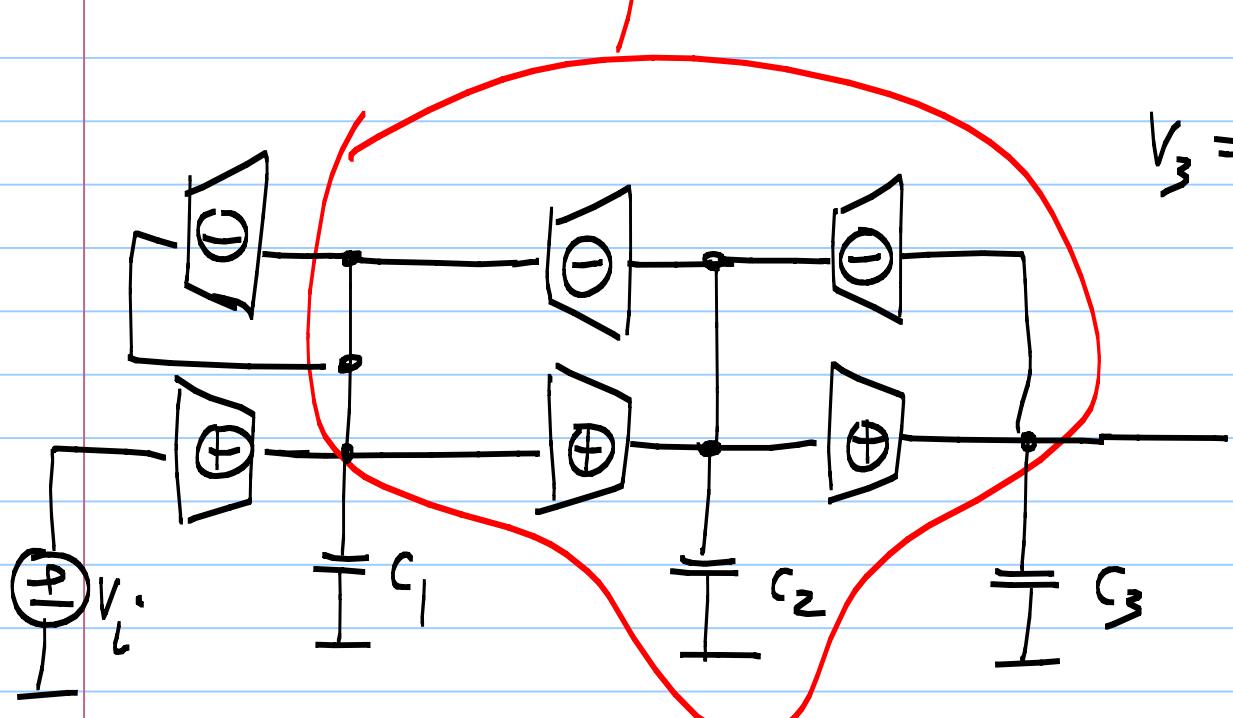
sC_1

$$I_2 = \frac{V_1 - V_3}{sC_2}$$

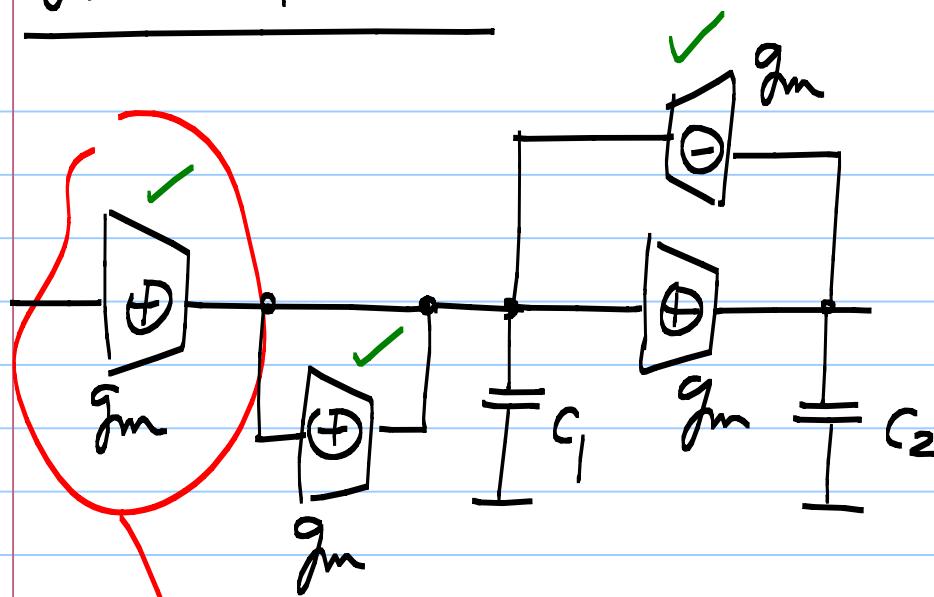
sC_2

$$V_3 = \frac{I_2}{sC_3}$$

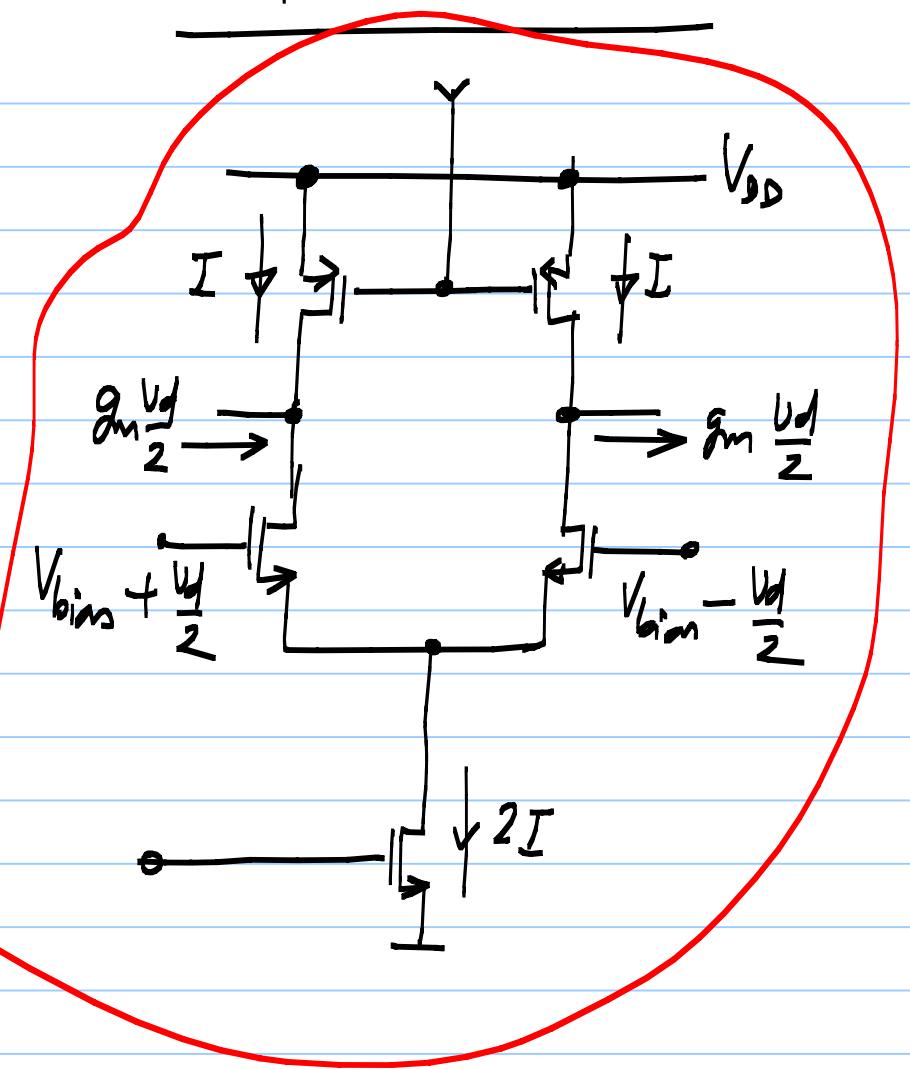
sC_3

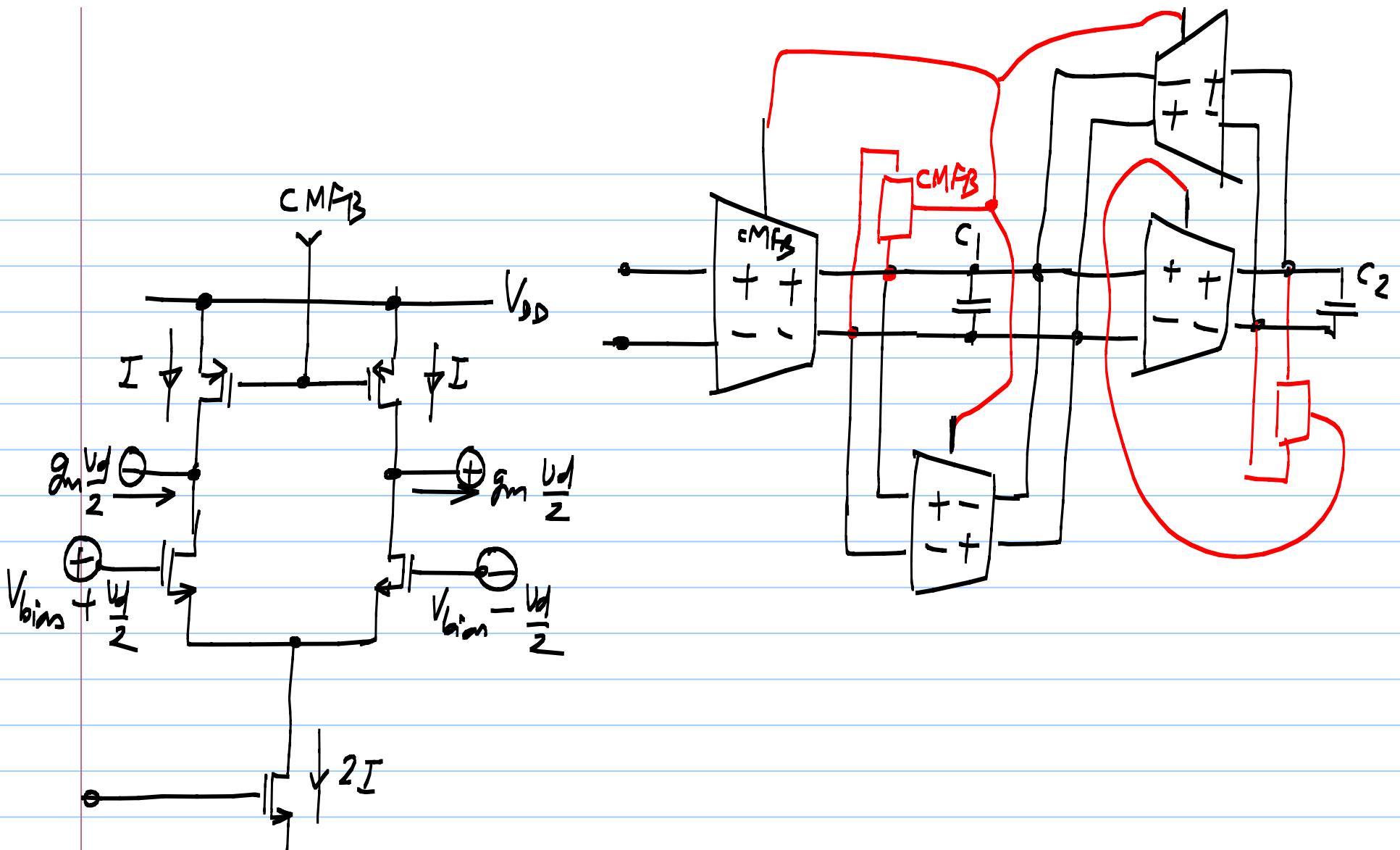


g_m -C filter:

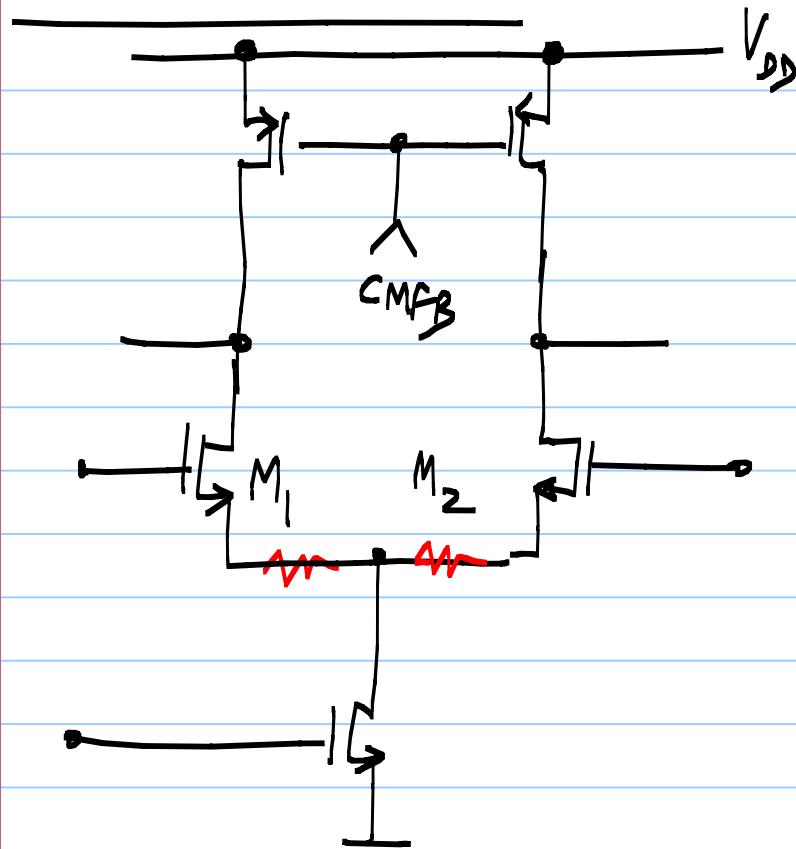


Differential pair:





Transconductor:



* Linearity: Use as high

$V_{GS} - V_T$ as possible for

$M_{1,2}$

* Degeneration resistors
improved linearity

$$g_m = \frac{g_{m1}}{1 + g_{m1} R} \approx \frac{1}{R}$$

Active filter design :

- * Determine type, order, transfer function
[MATLAB, filter tables]
- * Cascade of biquads / high order
(operational simulation)
- * Active prototype implementation
- * Node scaling (equal max. magnitude response)
- * Choose g_m / opamp & implement the filter

* Simulate the noise / distortion

* Noise \longleftrightarrow Impedance scaling

$$\left. \begin{array}{l} g_m \rightarrow N g_m \\ R \rightarrow R/N \\ C \rightarrow C \\ W/L \rightarrow N \cdot W/L \end{array} \right\} \Rightarrow \begin{array}{l} N \text{ times lower} \\ \sqrt{I}^2 \\ N \text{ times higher} \\ \text{power} \end{array}$$

