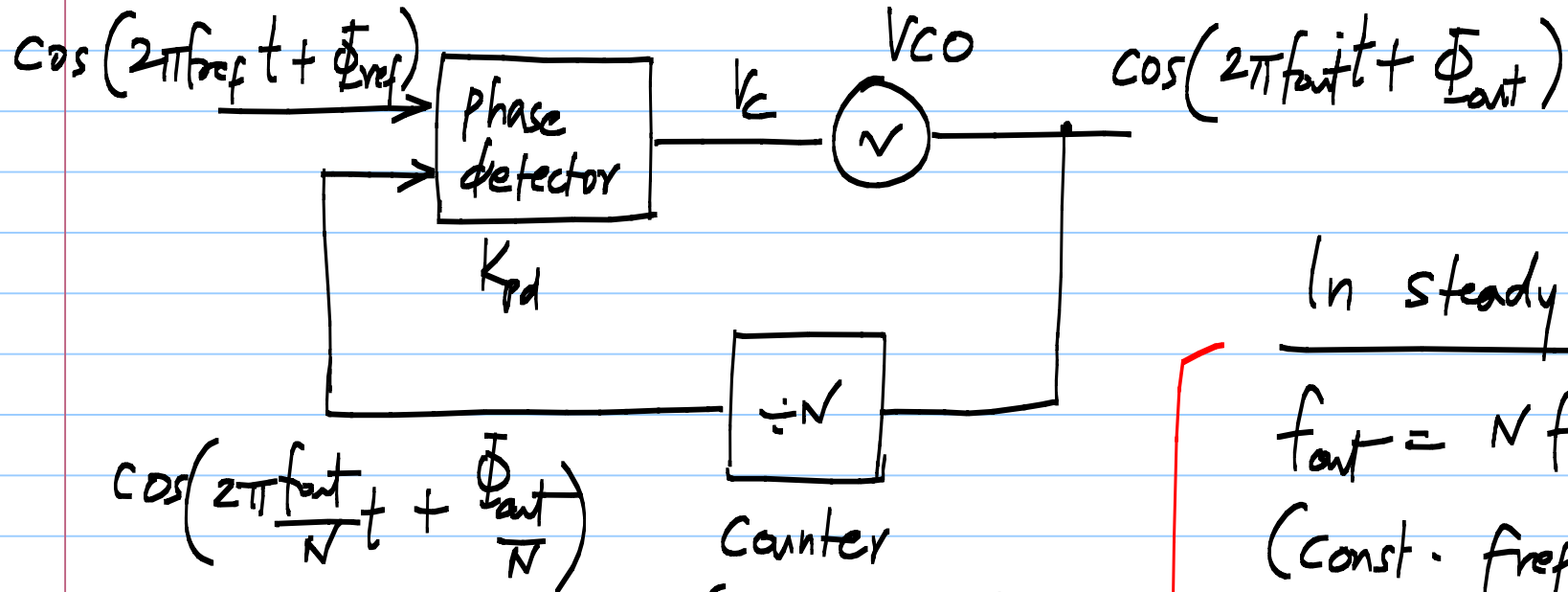


Lecture 46 : Phase locked loop \longrightarrow Type I PLL



In steady state:

$$f_{out} = N f_{ref}$$

(const. f_{ref})

$$K_{VCO} \cdot V_c + f_0 = f_{out} = N f_{ref} \text{ (freq. divider)}$$

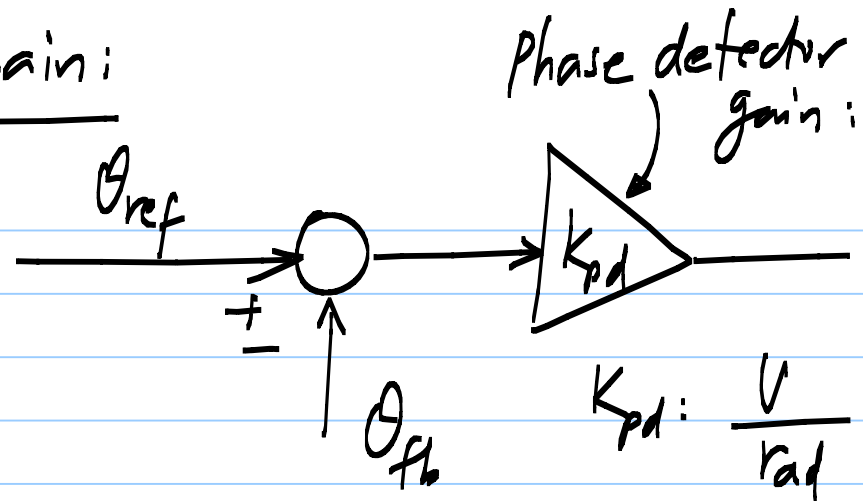
"operating point"

$$V_c = K_{pd} \left(\Phi_{ref} - \frac{\Phi_{out}}{N} \right)$$

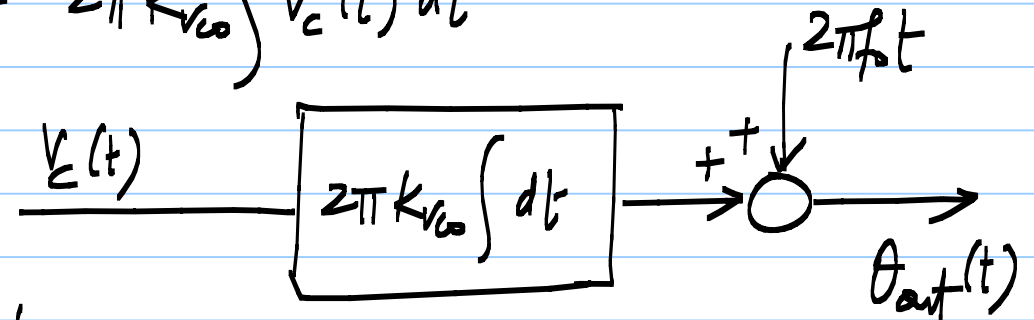
$$= \frac{N f_{ref} - f_0}{K_{VCO}}$$

Model in the phase domain:

Phase detector:

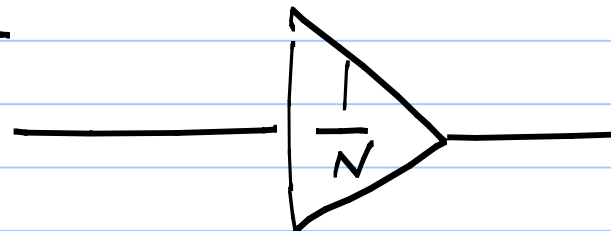


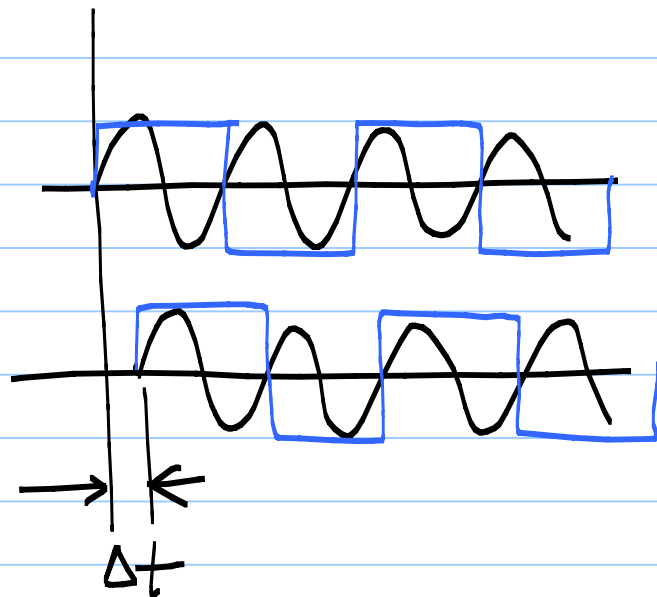
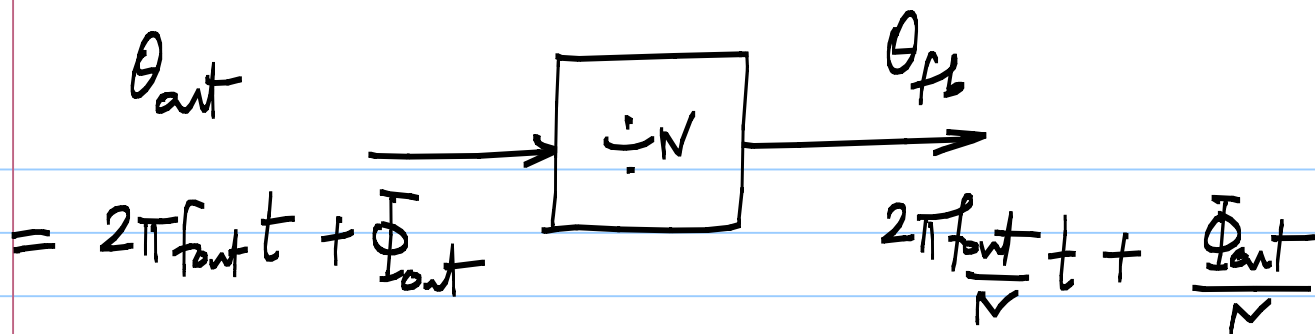
VCO:
$$\theta_{out} = 2\pi f_0 t + 2\pi K_{vco} \int v_c(t) dt$$



Freq. divider:

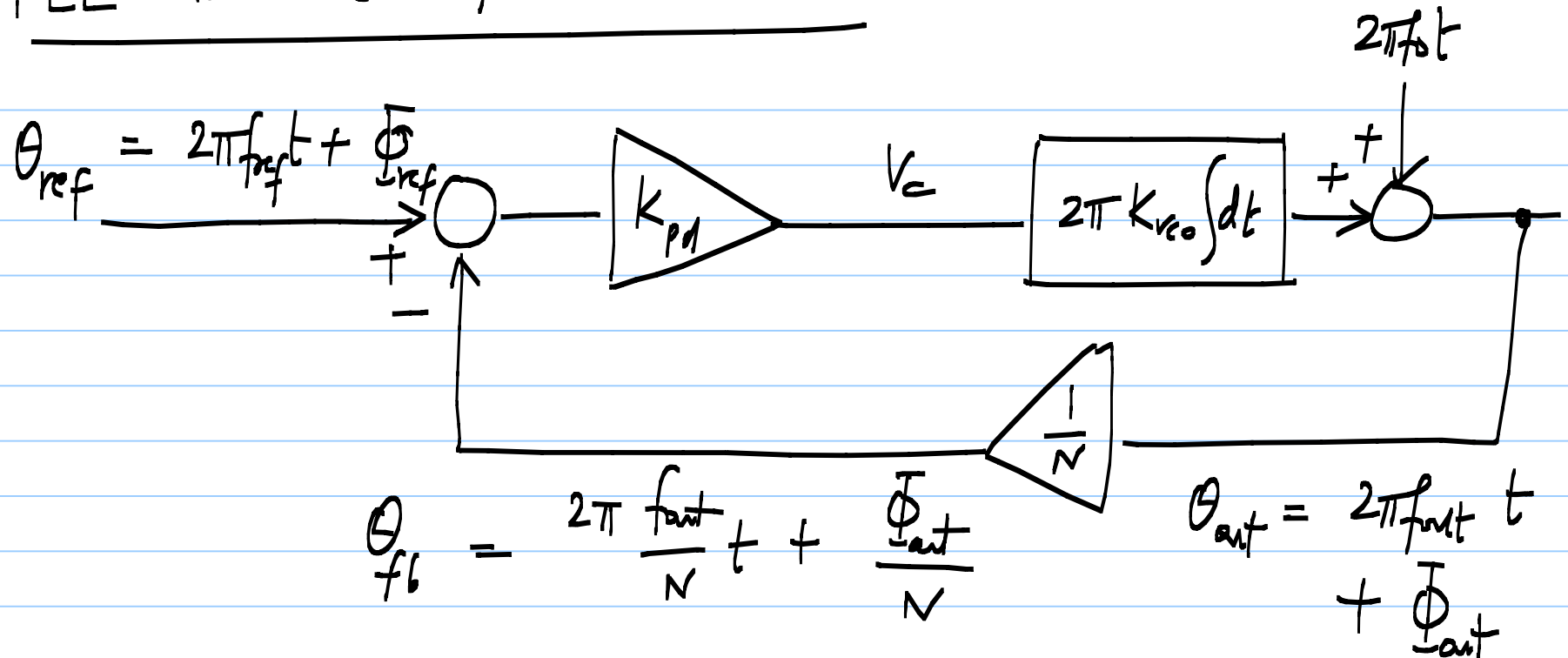
$$\theta_{fb} = \frac{\theta_{out}}{N}$$

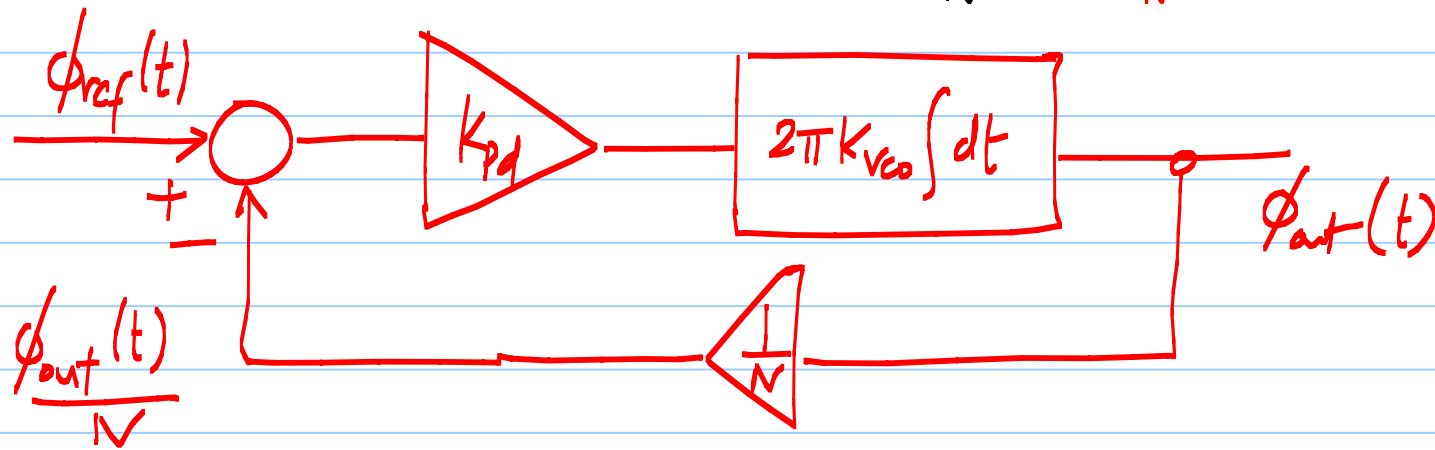
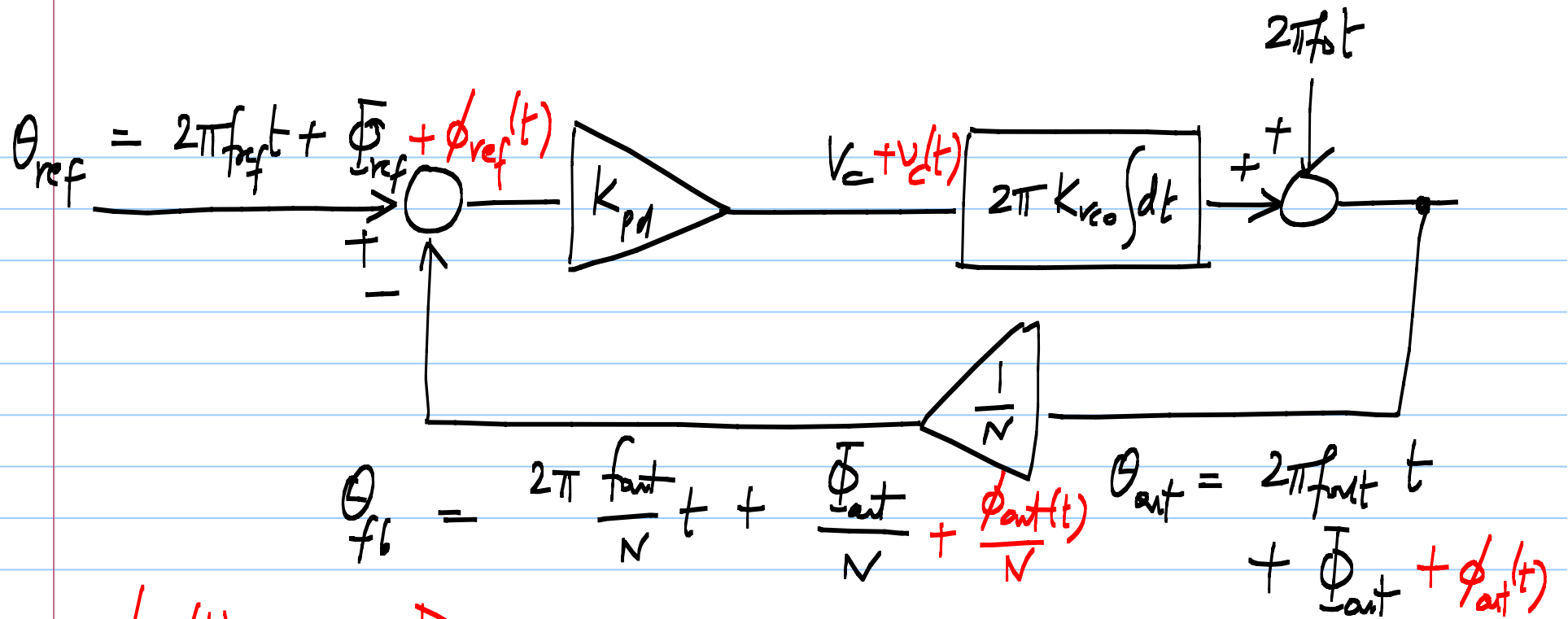


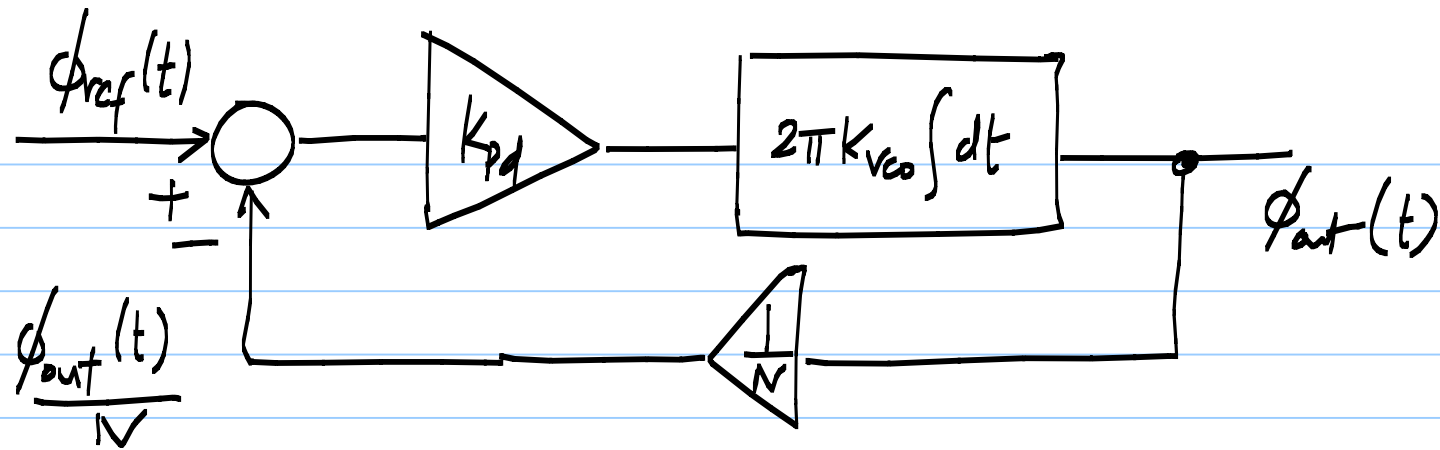


$$\frac{\Delta t}{T_{\text{fb}}} = \frac{1}{2} \cdot \frac{\Delta t}{T_{\text{int}}}$$

PLL in the phase domain :







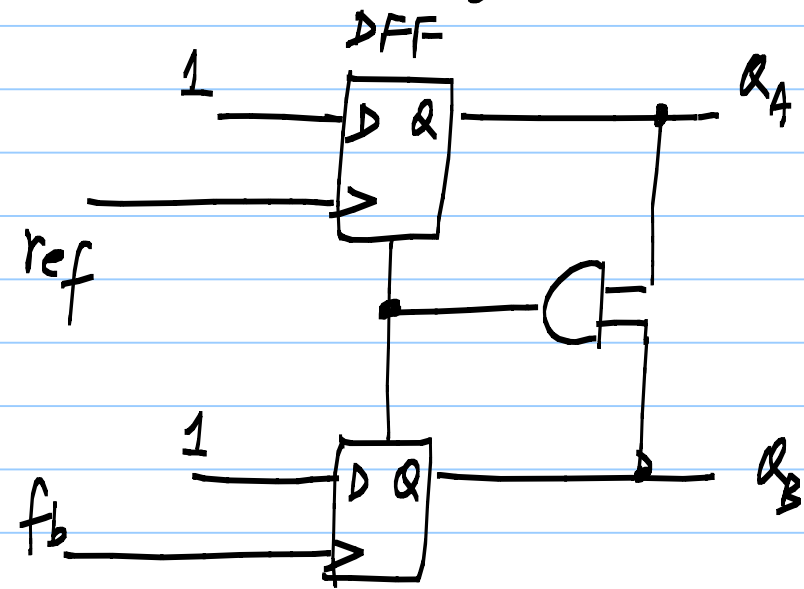
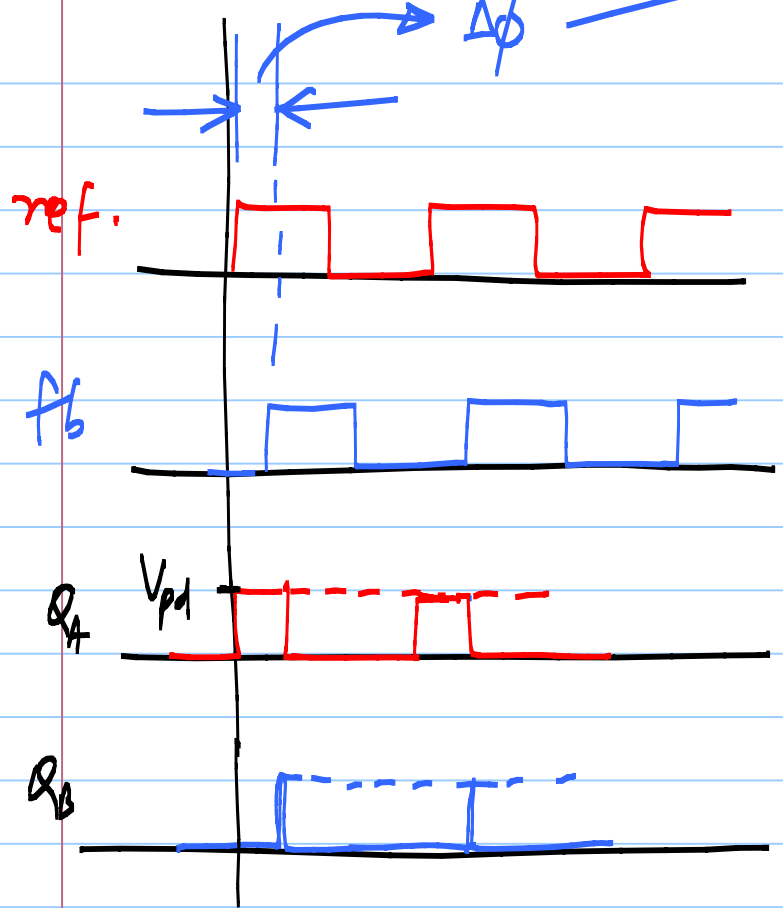
Incremental (linear) model of a PLL

One integrator in the loop = Type-I PLL

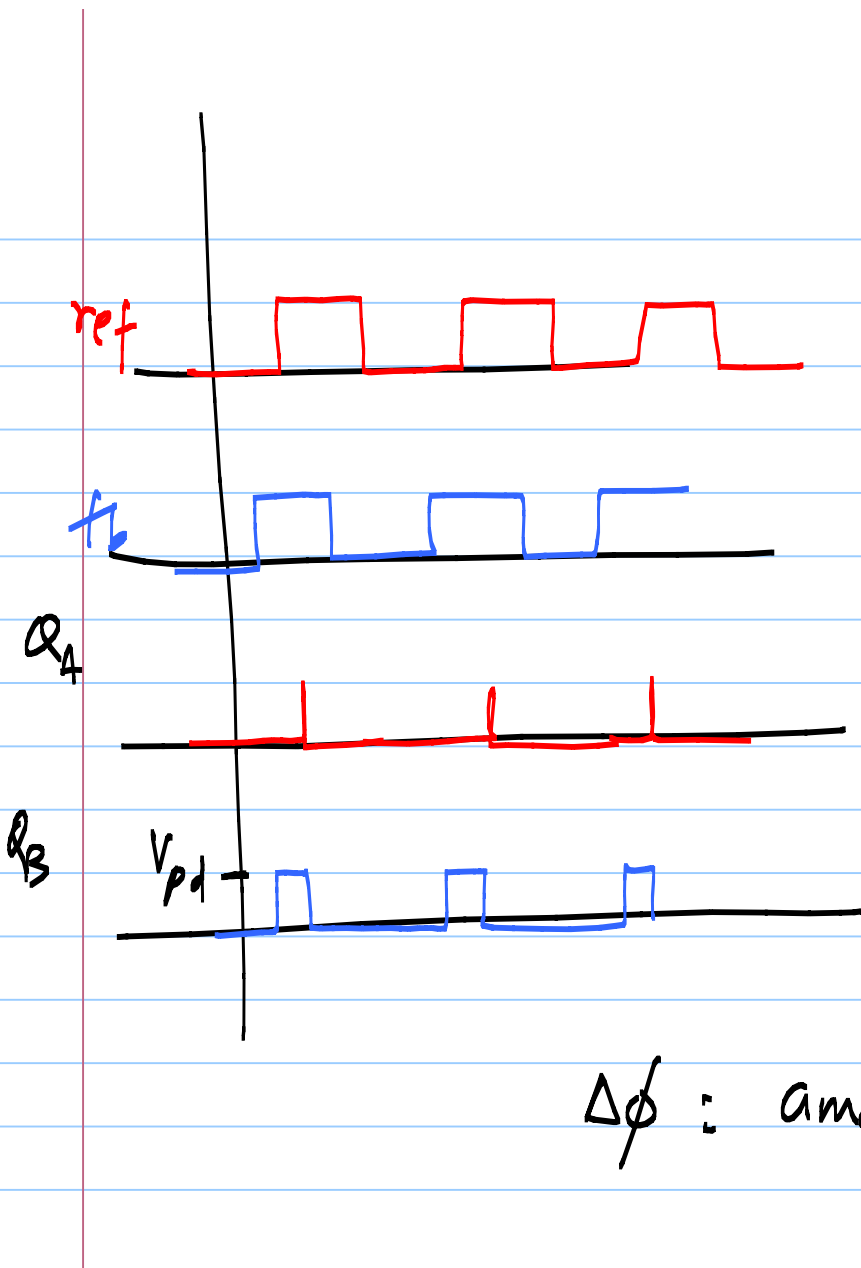
Phase detector:

o/p must be proportional to $\Delta\phi$

* Must be sensitive only to the rising edges



Average value of $Q_A \propto \Delta\phi / 2\pi$



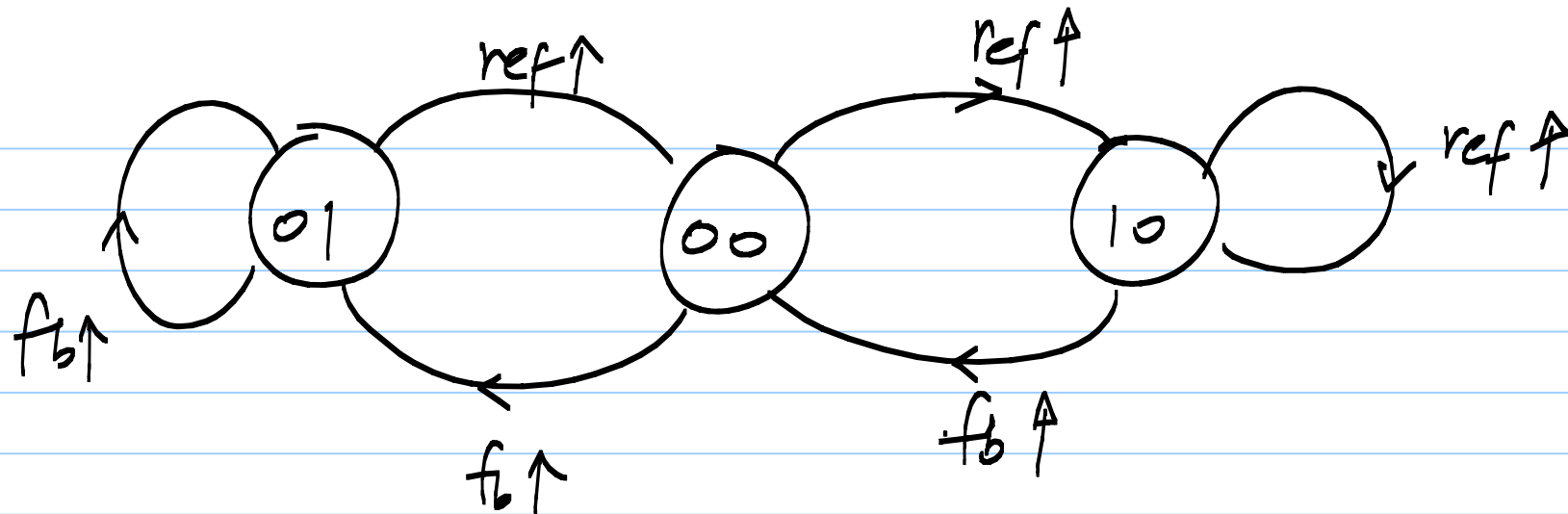
ref. lagging fb.

Average value of $Q_B \propto$
phase difference

average $(Q_A - Q_B)$:

$$\propto \frac{\Delta\phi}{2\pi}$$

$\Delta\phi$: amount by which ref. is leading fb.

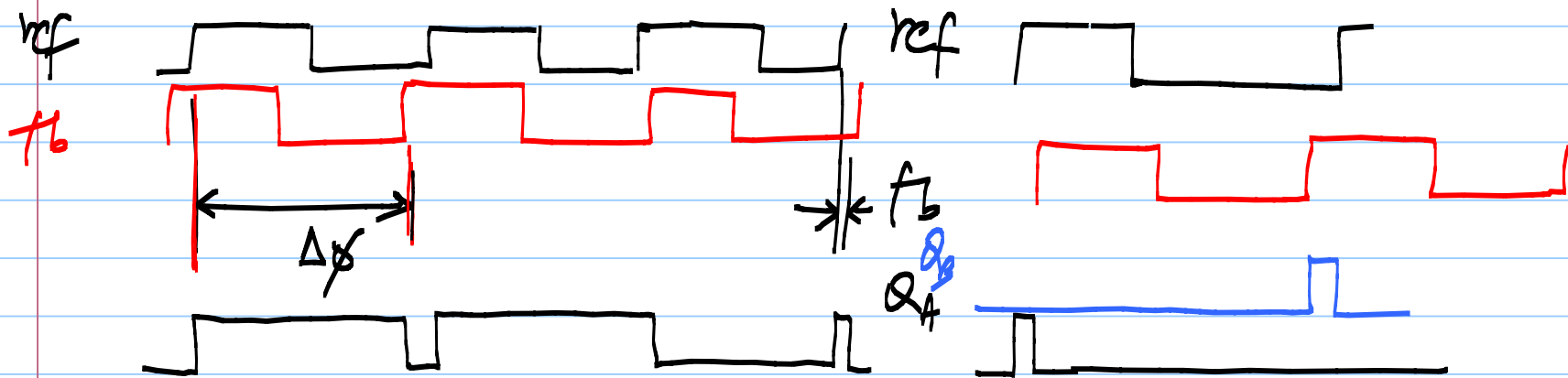
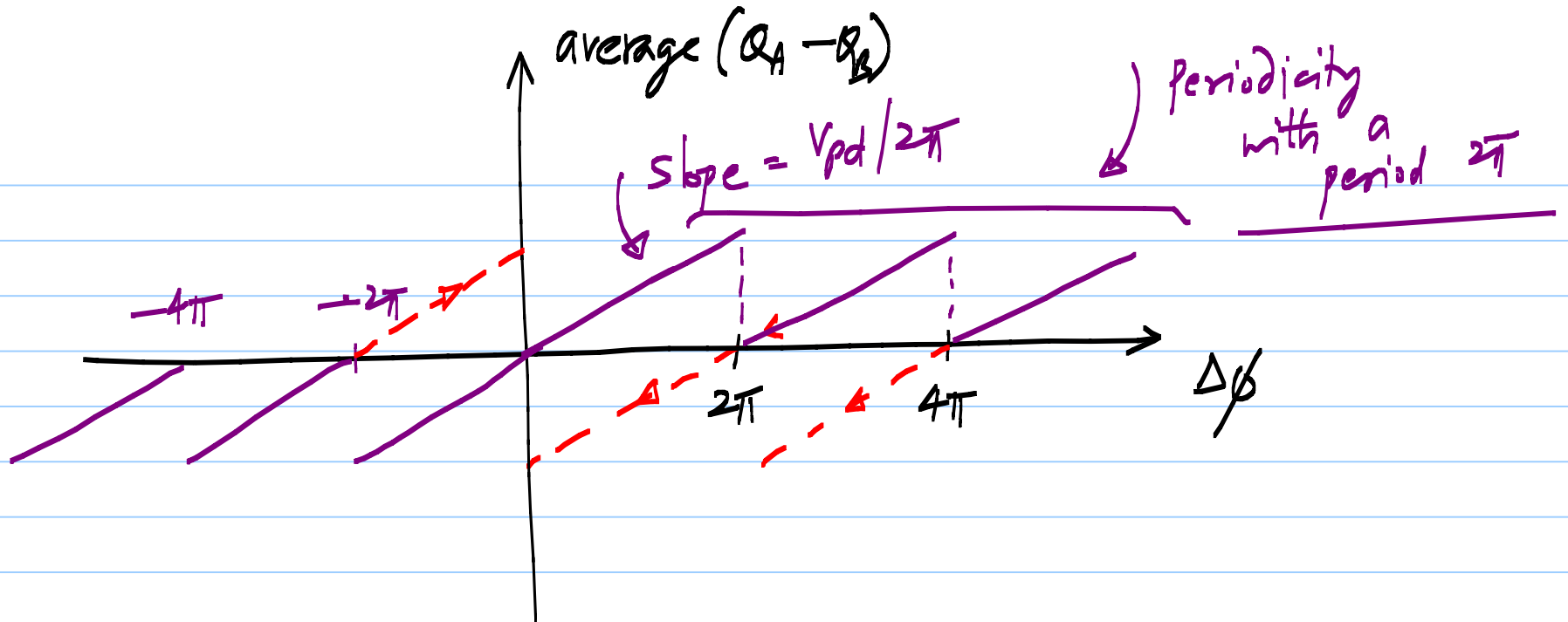


3-state phase detector.

$$\text{State} = Q_A Q_B$$

$$Q_A - Q_B : 3 \text{ values } \{-1, 0, 1\}$$

$$\text{average } (Q_A - Q_B) : \frac{\Delta\phi}{2\pi} \cdot V_{pd}$$



Operating point:

$$V_c = \frac{Nf_{ref} - f_o}{K_{VCO}} = K_{pd} \left(\phi_{ref} - \frac{\phi_o}{N} \right)$$

$$\left| \phi_{ref} - \frac{\phi_o}{N} \right| < 2\pi$$

can be a
maximum of 2π

$$\left| \frac{Nf_{ref} - f_o}{K_{VCO}} \right| < 2\pi \cdot K_{pd}$$

$$|Nf_{ref} - f_0| < 2\pi K_{VCO} \cdot K_{pd}$$

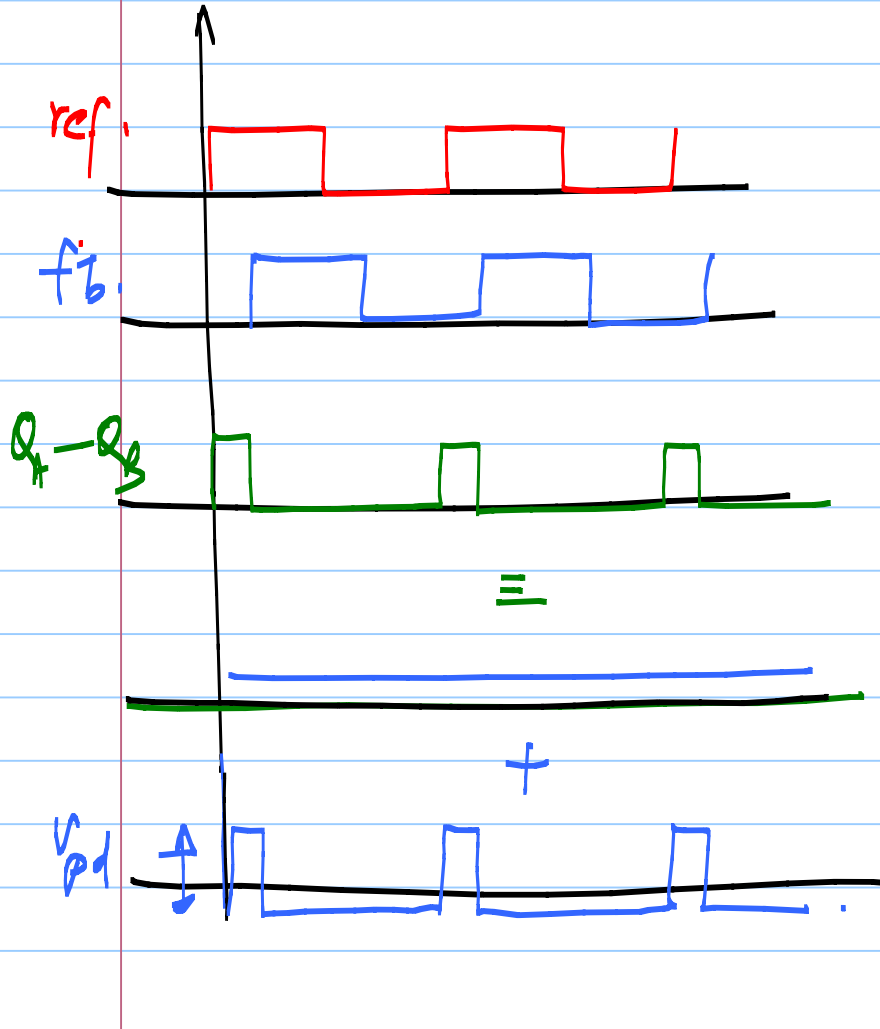
$$|f_{out} - f_0| < 2\pi K_{VCO} \cdot K_{pd}$$

free running frequency

deviation from the free-running frequency

→ Lock range of the type-I PLL

3. state phase detector :



* Average output of $V_{pd} = \frac{\Delta\phi}{2\pi} V_{pd}$

$$K_{pd} = \left(\frac{V_{pd}}{2\pi} \right)$$

average = $K_{p1} \cdot \Delta\phi$

$e(t)$: periodic error with zero average

