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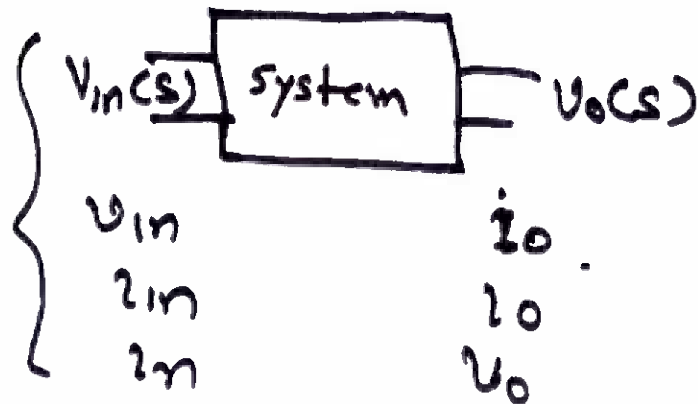
Slide No. 1

Frequency Response of Amplifier

S-Domain Analysis
We know

$$j\omega = s$$

Any Transfer Function of a Network is given as



$$H(s) = H(j\omega) = \frac{V_o(s)}{V_{in}(s)}$$
$$= K \frac{(s-z_1)(s-z_2) \dots (s-z_m)}{(s-p_1)(s-p_2) \dots (s-p_n)}$$

where z is called 'zero' of the T. function
& p is called 'pole' of the T. function

Course Name

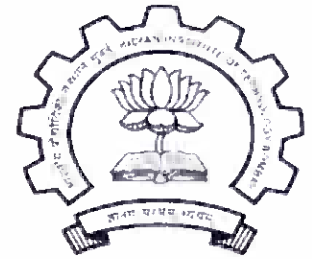
Analog Circuits

Lecture No. 10

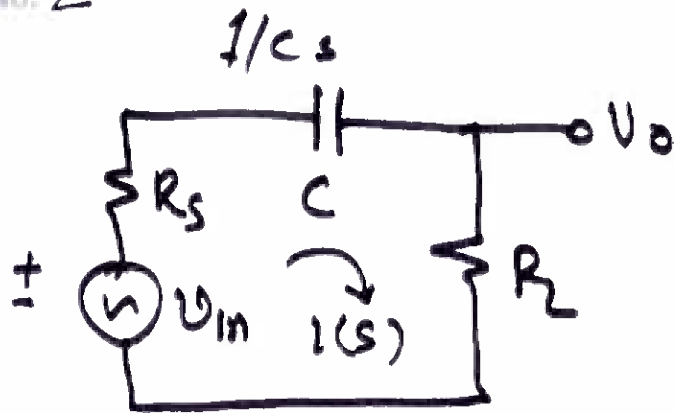
Instructor's Name

Prof. A. N. Chandorkar

Slide No. 2



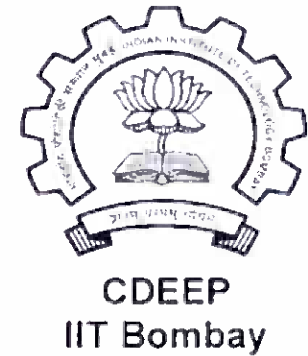
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$$V_o(s) = i(s) \cdot R_L$$

$$i(s) = \frac{V_{in}}{R_s + \frac{1}{Cs} + R_L} = \frac{V_{in} Cs}{(R_s + R_L)Cs + 1}$$

$$\text{or } \frac{V_o(s)}{V_{in}(s)} = \frac{R_L C \cdot s}{(R_L + R_s)C \cdot s + 1} = H(s)$$



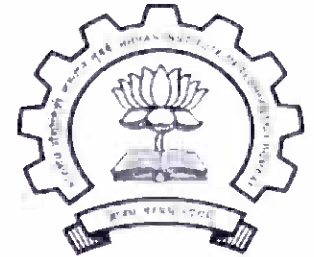
① If $s = 0$ then $H(s) \rightarrow 0$
 \therefore we have a 'Zero' at $\omega = 0$

② If $(R_L + R_S)C \cdot s = -1$
 Then ~~also~~ $H(s) \rightarrow \infty$
 \therefore at $s = \frac{-1}{(R_L + R_S)C}$ we have a Pole,

~~RC~~ We see that RC has unit of Time

$$\therefore \tau_s = (R_L + R_S)C$$

Slide No: 4



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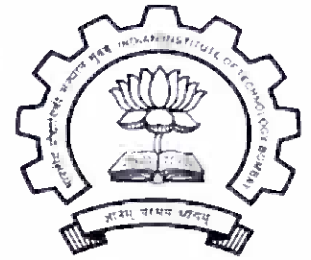
We can Rewrite $H(s)$ as

$$H(s) = \frac{V_o(s)}{V_{in}(s)} = \frac{R_L}{R_L + R_S} \cdot \frac{(R_L + R_S)C \cdot s}{1 + (R_L + R_S)C \cdot s}$$

$$= K \frac{\tau_s s}{1 + s \tau_s}$$

$$\text{or } A_v(s) = \frac{R_L}{R_L + R_S} \cdot \frac{j\omega \tau_s \rightarrow \textcircled{2}}{1 + j\omega \tau_s \rightarrow \textcircled{3}}$$

①



$$\therefore |A_v(j\omega)| = \frac{R_L}{R_L + R_s} \cdot \left[\frac{\omega \tau_s}{\sqrt{1 + \omega^2 \tau_s^2}} \right]$$

Where $\omega = 2\pi f$

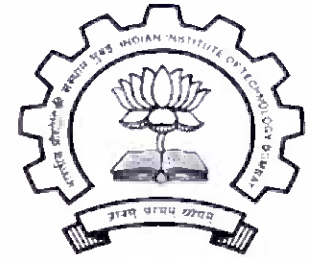
$$\therefore |A_v(jf)| = \frac{R_L}{R_L + R_s} \left[\frac{2\pi f \tau_s}{(1 + 4\pi^2 f^2 \tau_s^2)^{1/2}} \right]$$

In db.

$$|A_v(jf)|_{db} = 20 \log_{10} [|A_v(j\omega)|]$$

$$P_{db} = 20 \log \frac{P_2}{P_1}$$

$$A_{v,db} = 20 \log \frac{V_2}{V_1}$$

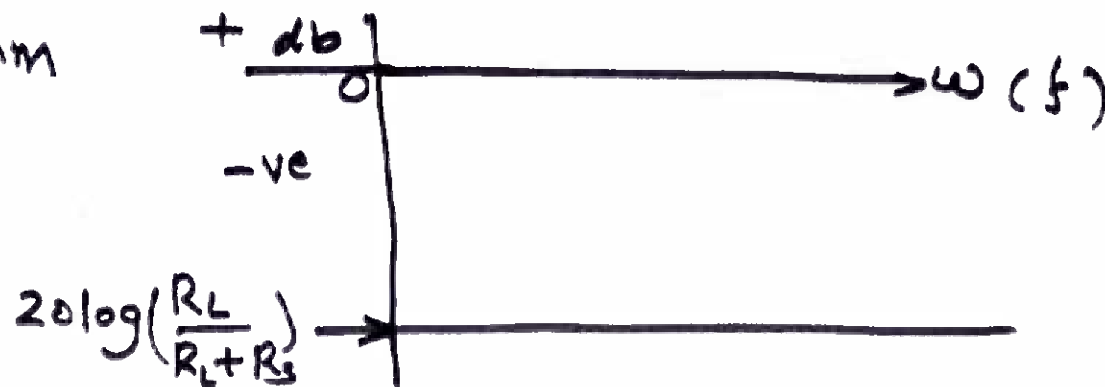


$$\therefore |A_v(\omega)|_{db} = 20 \log \left(\frac{R_L}{R_L + R_s} \right)$$

$$+ 20 \log (2\pi f \tau_s)$$

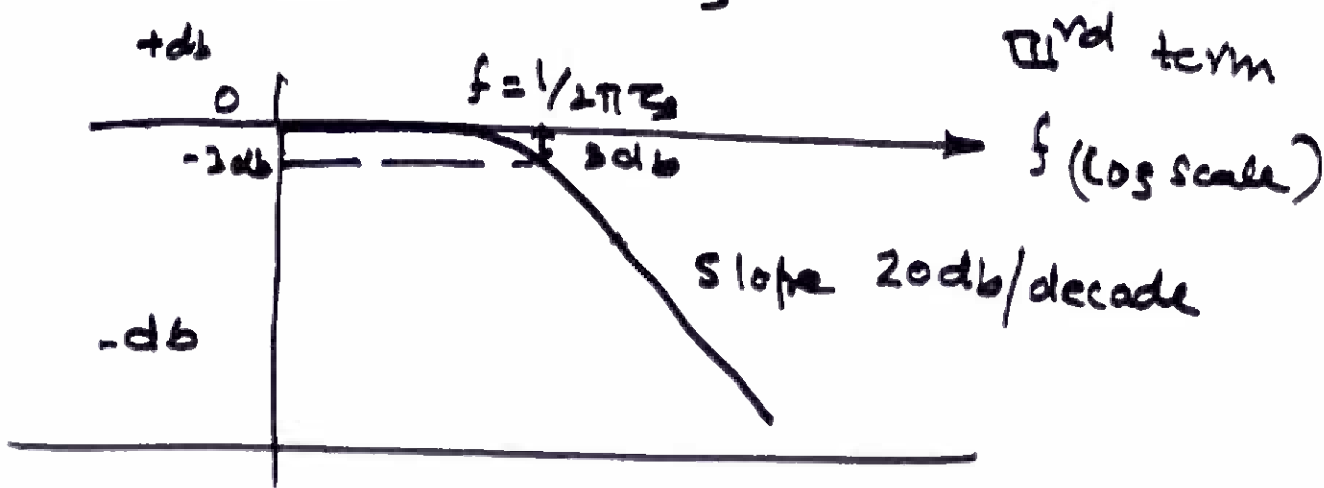
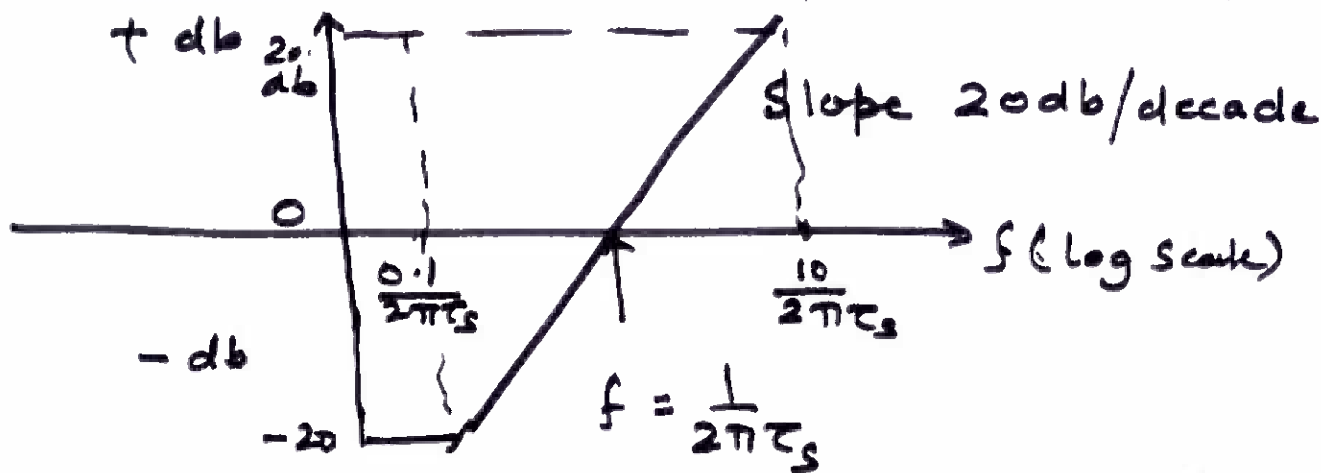
$$- 20 \log \left[\sqrt{1 + (2\pi f \tau_s)^2} \right]$$

1st Term

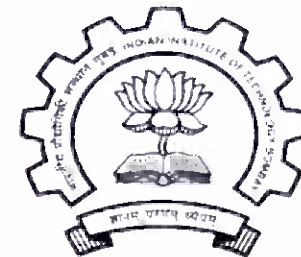


□nd Term

$$f = \frac{1}{2\pi\tau_s}$$



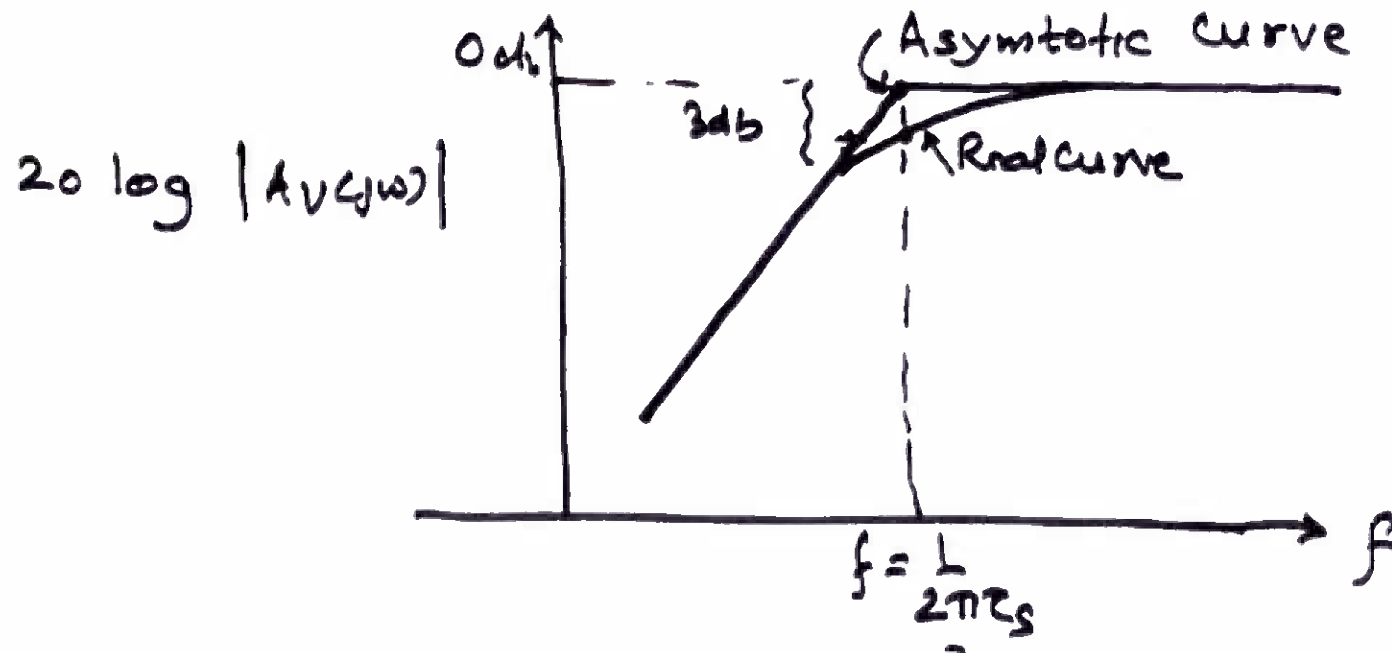
$$-20 \log(\sqrt{2})$$



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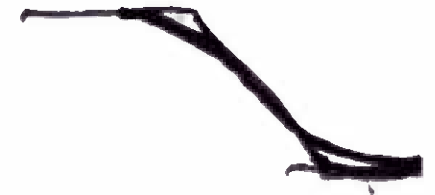


Complete Function 'Av(jw)'s frequency response can then be plotted as



Corner Frequency

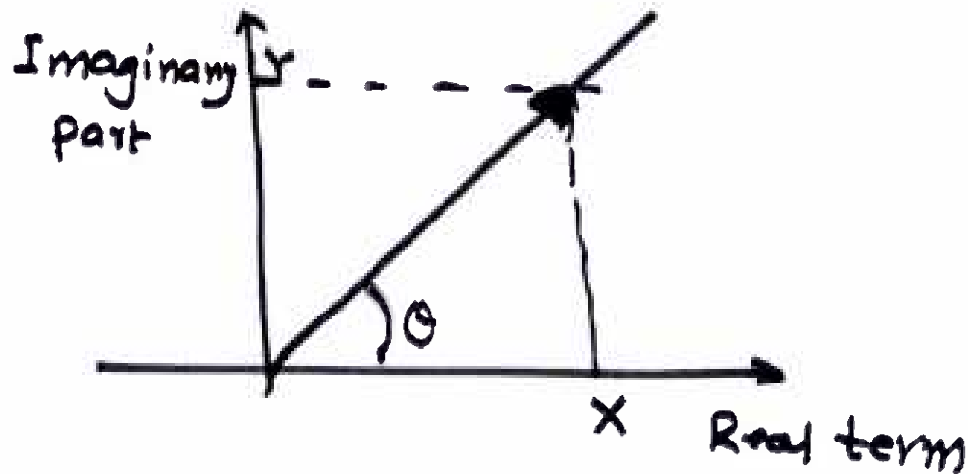
BODE PLOT



A complex term = $x + jy = f$

Then $|f| = \sqrt{x^2 + y^2}$ - Magnitude

$\angle \theta = \angle f(j\omega) = \tan^{-1} \frac{y}{x}$ - Phase.



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Phase part

$$F = X + jY$$

$$\tan^{-1} \frac{Y}{X} = \theta$$

If $Y = X$ $\tan^{-1} 1$ then $\theta = 45^\circ$

If $Y = 0$ $\tan^{-1} 0$ then $\theta = 0^\circ$

If $X = 0$
 $\text{or } Y \rightarrow \infty$ $\tan^{-1} \infty$ then $\theta = 90^\circ$

Take a case of frequency response

$$\theta = \tan^{-1} \frac{\omega}{\omega_0}$$

At $\omega = \omega_0$ $\theta = 45^\circ$

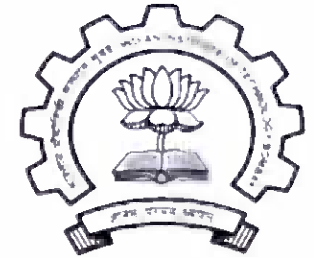
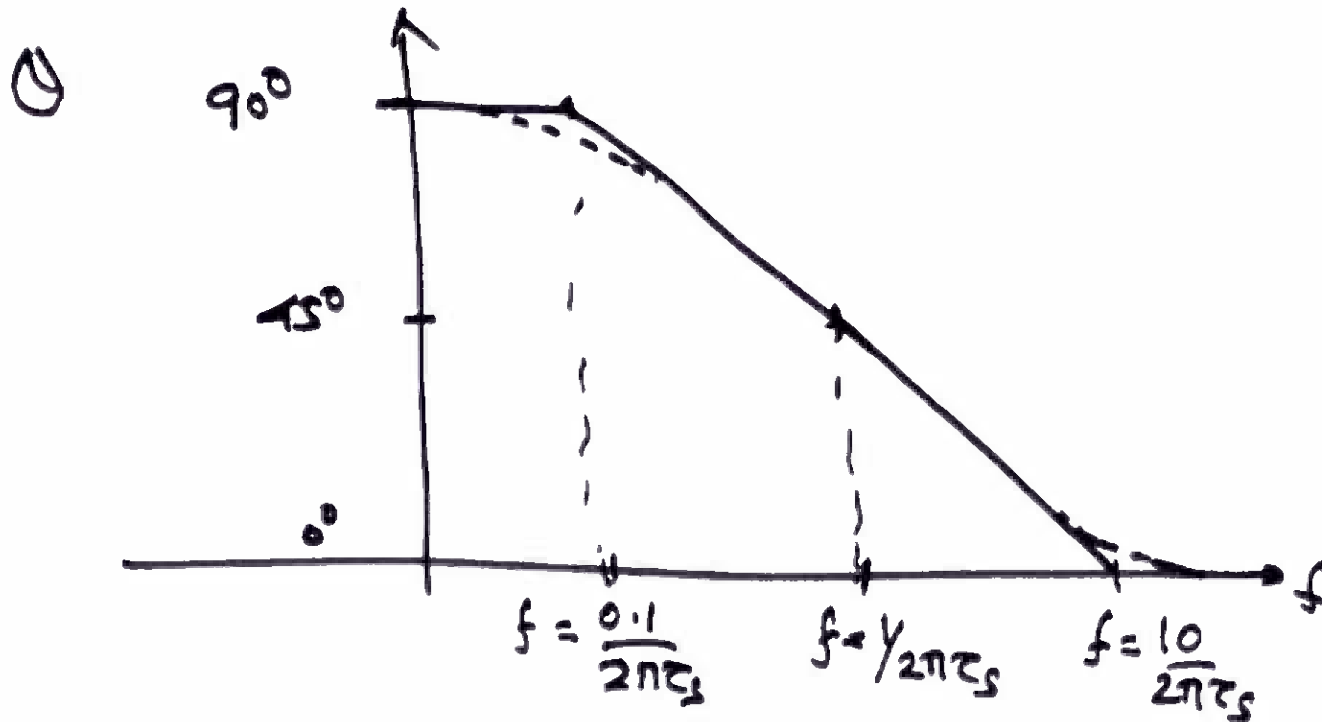
At $\omega = 0.1\omega_0$ $\theta = \tan^{-1}(0.1) \rightarrow 0^\circ$

At $\omega = 10\omega_0$ $\tan^{-1} 10 = \theta \rightarrow 90^\circ$

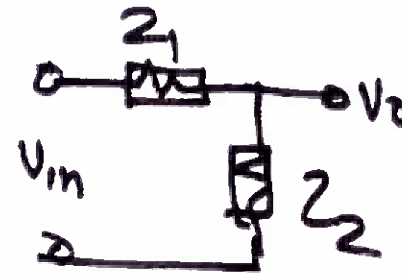
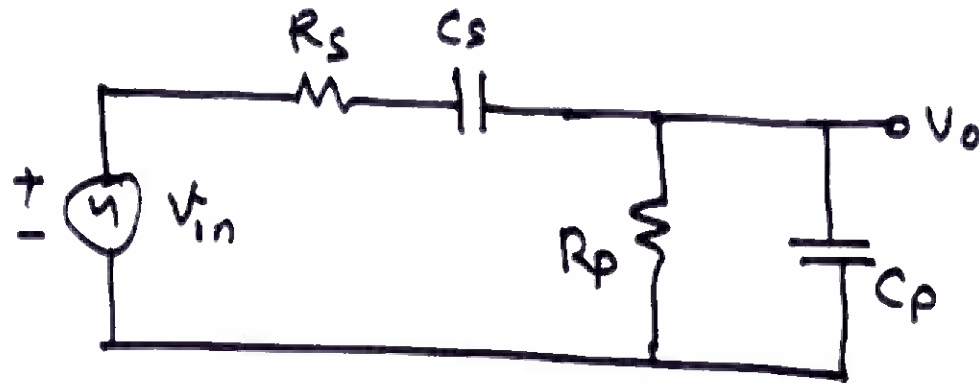
i.e. θ changes $45^\circ/\text{decade}$



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Phase Response of $A_v(j\omega)$ CDEEP
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Two Pole Circuit



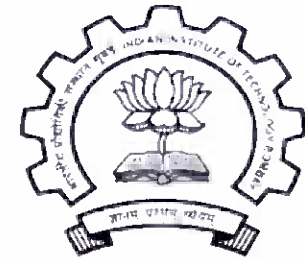
$$V_o = \frac{Z_2}{Z_1 + Z_2} \cdot V_{in}$$

Then

$$\frac{V_o(s)}{V_{in}(s)} = A_v(s) = \frac{R_p}{R_p + R_s} \cdot \frac{1}{\left[1 + \frac{R_p}{R_p + R_s} \left(\frac{C_p}{C_s} \right) + \frac{1}{s\tau_s} + s\tau_p \right]}$$

where $\tau_s = (R_s + R_p) C_s$

$\tau_p = (R_s \parallel R_p) C_p$



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τ_s is called open circuit Time Constant

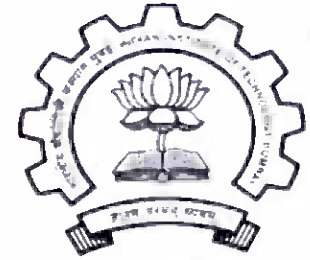
i.e. when $\frac{1}{C_p \omega} \rightarrow \infty$

∴ τ_s represents time constant associated with C_s
Similarly

τ_p is called Short Circuit Time Constant

i.e. when $\frac{1}{C_s s} \rightarrow 0$

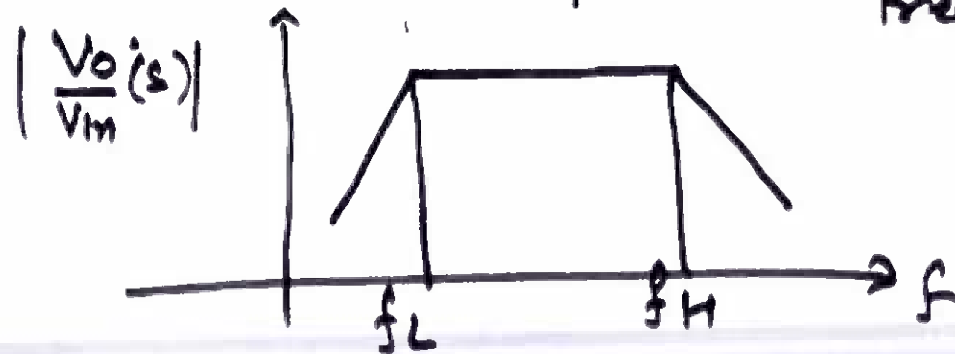
∴ τ_p is time constant associated with C_p



Two poles are associated with these two time constants. We shall see later that

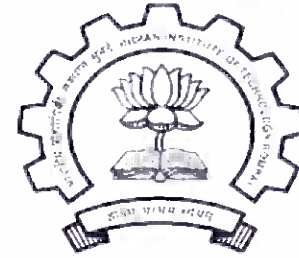
$f_L = \frac{1}{2\pi\tau_s}$ & is called Lower Corner (3db) Frequency

and $f_H = \frac{1}{2\pi\tau_p}$ and is called Upper Corner (3db) Frequency,

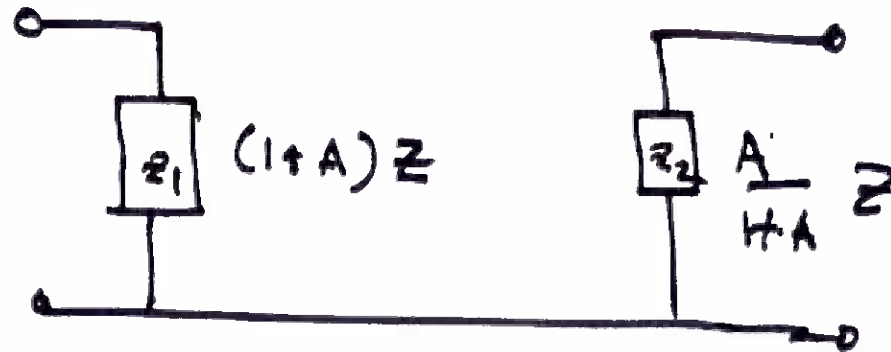
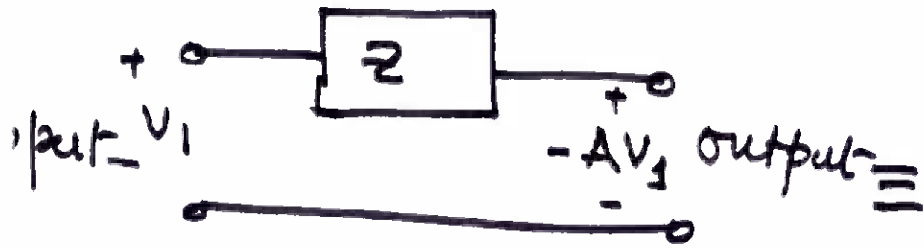


$f_H - f_L$ is called Midband and is essentially Bandwidth.

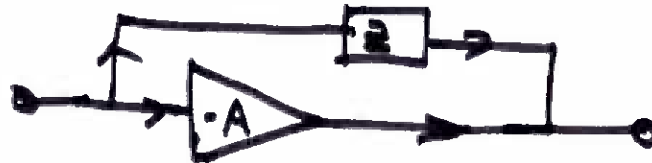
Miller's Theorem



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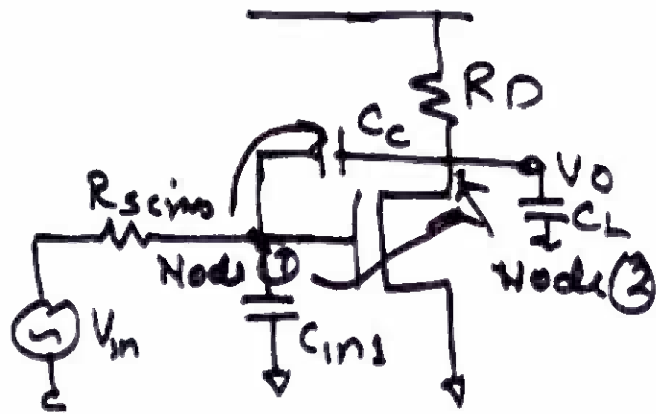
Condition for Validity of Miller's Theorem:



We must have Two Paths from Input to Output.

Concept of Pole-Zero (Revisited)

A typical Amplifier is shown here



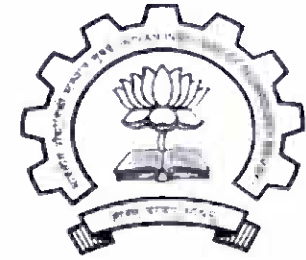
If C_{in} is input capacitance at Node ① then C_{in} must contain contribution

from C_{in1} and C_c

C_c is of course capacitance at node ① and node ② too

We can say pole's association is with Time Constant

$$\therefore P_1 = \frac{1}{R_s C_{in}}$$

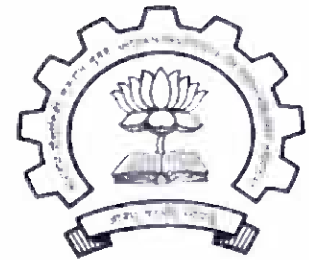


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For our Amplifier, the Gain

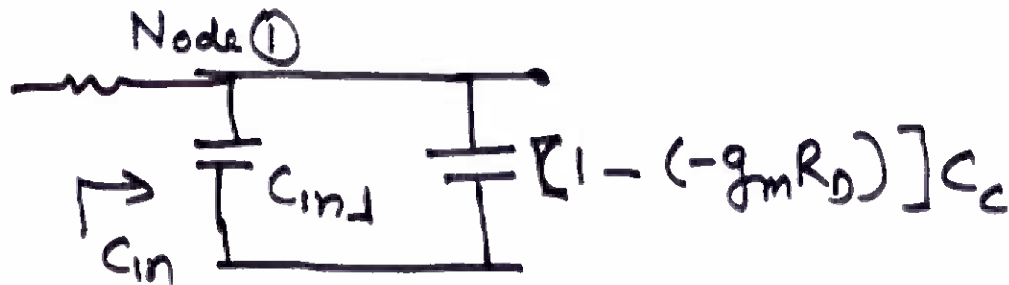
$$A_v = -g_m R_D$$

∴ If C_c acts like component (Impedance) between Input & Output, we can convert it's contribution on Input & Output side independently using Miller's theorem



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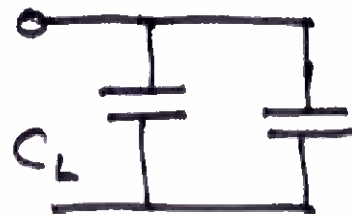
On Input Side



$$\text{or } C_{in} = C_{in1} + (1 + g_m R_D) C_c$$

$$\Rightarrow C_{in1} + (g_m R_D) C_c = C_{in1} + |A_v| C_c$$

On the Output side when

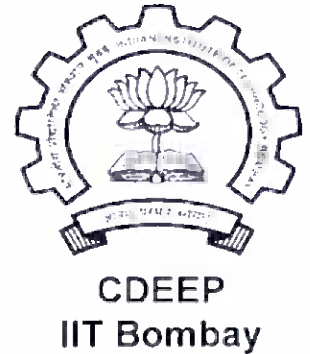


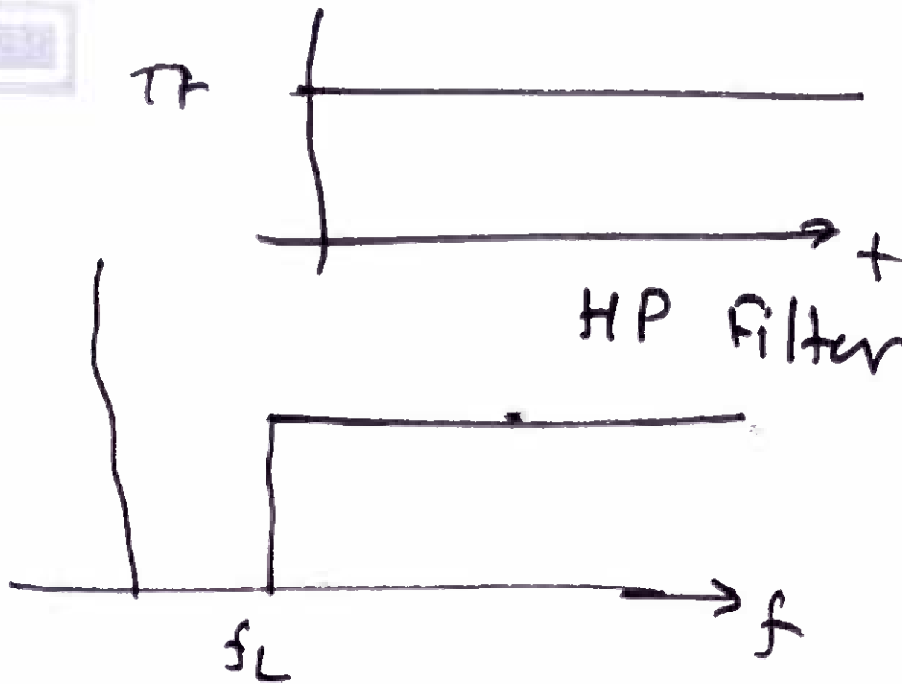
$$C_c \left(\frac{A}{1+A} \right) \approx C_c$$

$$\therefore C_{out} = C_L + C_c$$

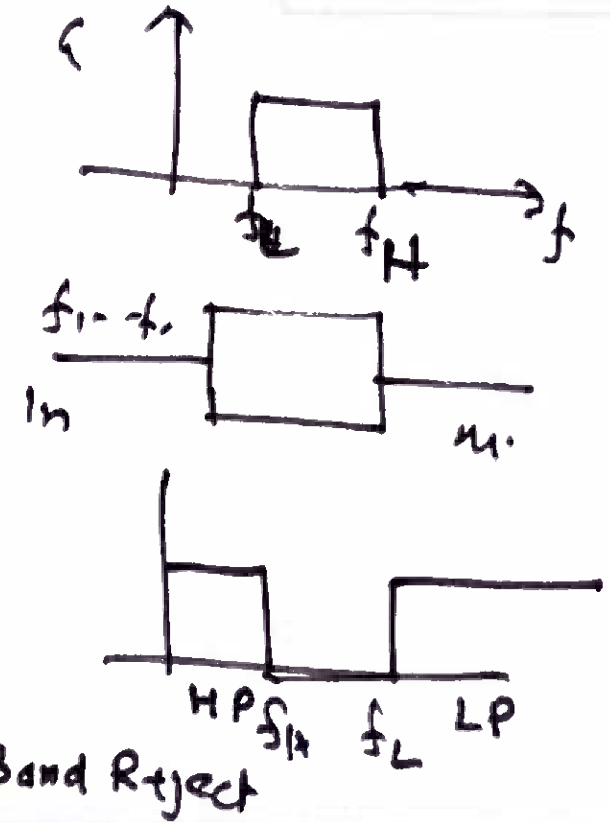
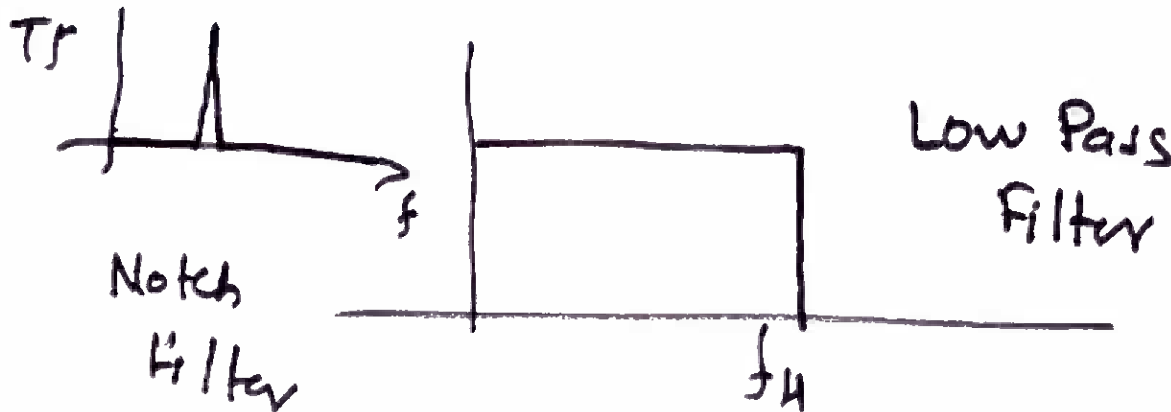
$$\therefore \text{Pole}_2 = p_2 = \frac{1}{R_D C_{out}} = \frac{1}{R_D (C_L + C_c)}$$

$$P_1 \approx \frac{1}{R_s \cdot C_{in}} \quad 1 \text{ kHz}$$



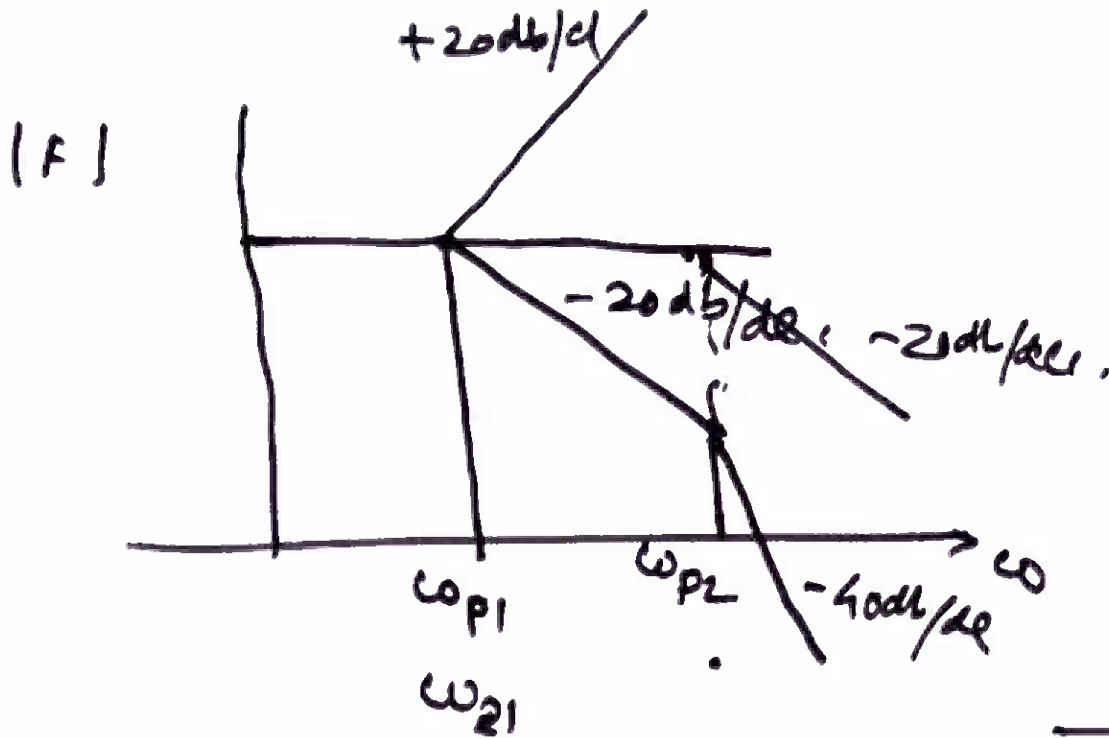


All Pass.





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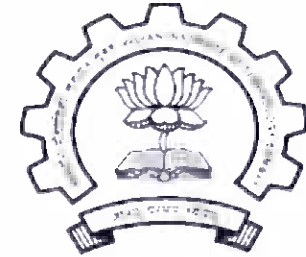
Stability



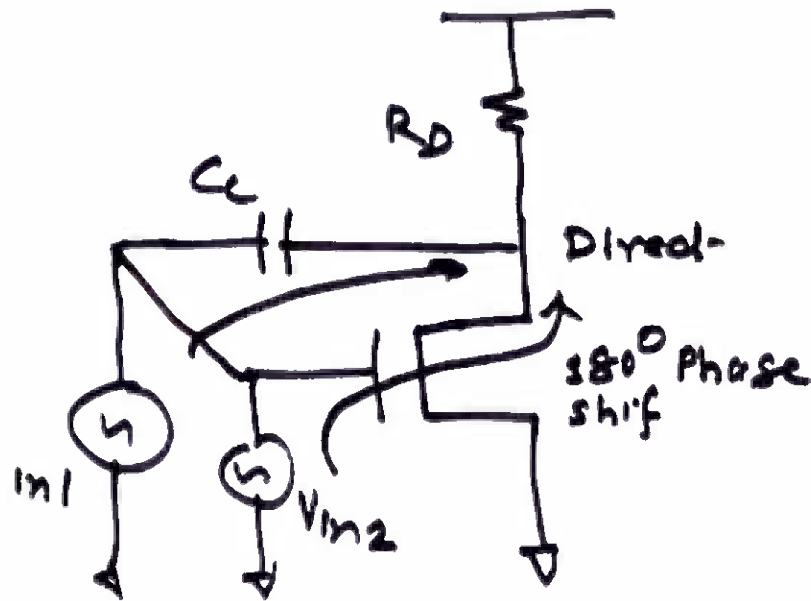
$$\frac{1}{s^2 + as + c}$$

$$= \frac{1}{(s + s_1)(s + s_2)} = \frac{1}{s_1 s_2} \frac{1}{(\frac{s}{s_1} + 1)(\frac{s}{s_2} + 1)}$$

Concept of Zero



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It can be shown

$$z_1 = \frac{g_m}{C_C}$$

If Magnitude of two signals
Direct & 180° phase out one
are equal, then net
 $V_o = 0$ due to 180° phase shift

\therefore This is called Zero