

$\rho$

$$\langle A \rangle = \text{Tr}(\rho A)$$

$$\text{Tr} \rho = 1 \quad \Rightarrow \text{Pure system}$$
$$\rho^2 = \rho.$$

For a pure system  $S(\rho) = 0$

$$S(\rho) = -\text{Tr}[\rho \log_2 \rho]$$

$$S(\rho) = -\sum_i \lambda_i \log \lambda_i$$

$$S(\rho) = - \sum_i \lambda_i \log \lambda_i$$

For a pure system

$$\lambda_i = 1 \quad \text{for specific } i$$

$$= 0 \quad \text{everything else}$$

$$S(\rho) = 0$$

$$S(\rho) = \log D.$$

$$S(\rho_{AB}) \leq S(\rho_A) + S(\rho_B)$$

Equality  $\rho_{AB} = \rho_A \otimes \rho_B$

$$S = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \quad S(S) = 0$$

$$|\psi\rangle = \frac{1}{\sqrt{2}} (|0\rangle + |1\rangle)$$

$$S = |\psi\rangle\langle\psi|$$

$$= \frac{1}{2} \begin{bmatrix} (1 & 1) \\ (1 & 1) \end{bmatrix}$$

$$= \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

$$|0\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$|1\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$S(S) = 0.$$

$$s = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix}$$

$$\begin{aligned} S(s) &= -\log_2\left(\frac{1}{2}\right) \\ &= \log_2 2 = 1. \end{aligned}$$

$$|\psi\rangle = \cos\theta |00\rangle + \sin\theta |11\rangle$$

$$\rho^A = \text{Tr}_B(\rho_{AB})$$

$$\begin{aligned} \rho_{AB} &= (\cos\theta |00\rangle + \sin\theta |11\rangle)(\cos\theta \langle 00| + \sin\theta \langle 11|) \\ &= \cos^2\theta |00\rangle\langle 00| + \sin^2\theta |11\rangle\langle 11| \\ &\quad + \cos\theta \sin\theta (|00\rangle\langle 11| + |11\rangle\langle 00|) \end{aligned}$$

$$\text{Tr}_B \rho_{AB} = \cos^2\theta |0\rangle\langle 0| + \sin^2\theta |1\rangle\langle 1|$$

$$P_A = \begin{pmatrix} \cos^2 \theta & 0 \\ 0 & \sin^2 \theta \end{pmatrix}$$

$$S^A = -\cos^2 \theta \log(\cos^2 \theta) - \sin^2 \theta \log(\sin^2 \theta)$$

$$= -2 \cos^2 \theta \log(\cos \theta) - 2 \sin^2 \theta \log(\sin \theta)$$

$$S^B = -2 \cos^2 \theta \log(\cos \theta) - 2 \sin^2 \theta \log \sin \theta.$$

$$S^A + S^B = -4 \left[ \cos^2 \theta \log(\cos \theta) + \sin^2 \theta \log(\sin \theta) \right]$$

$> 0$