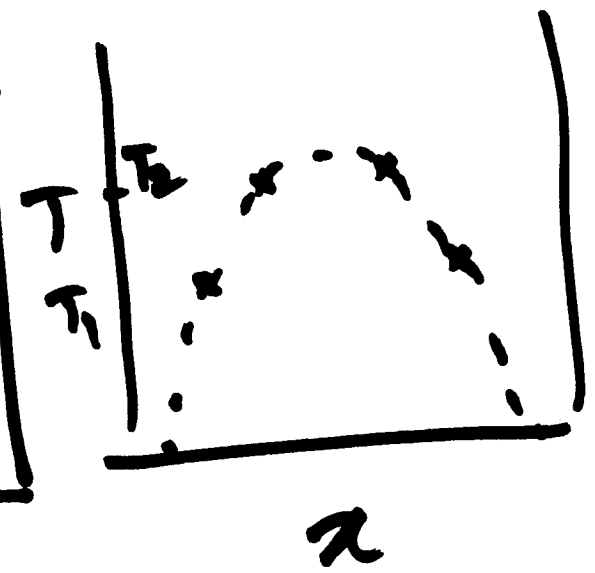
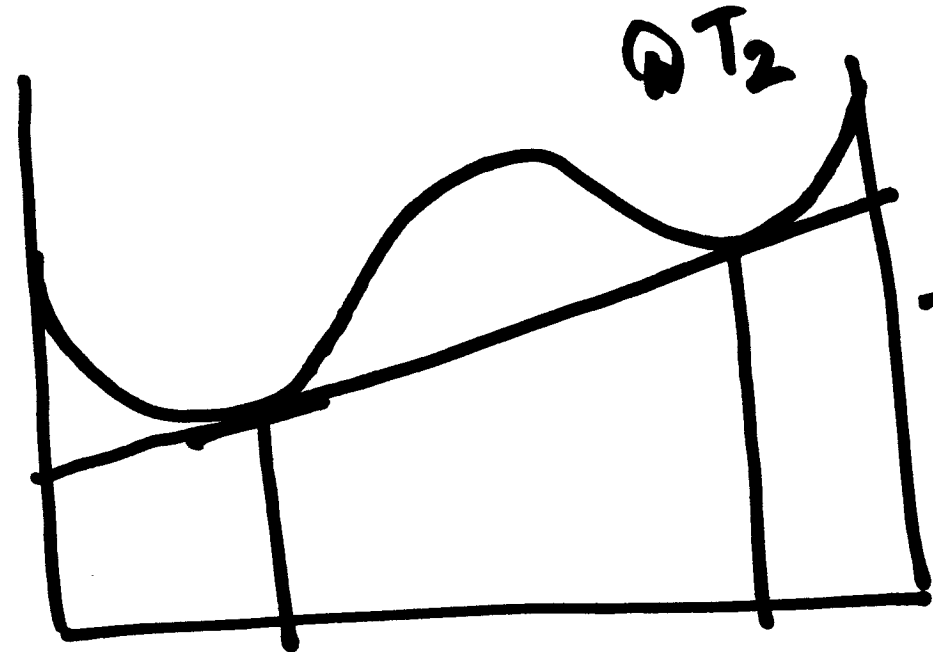
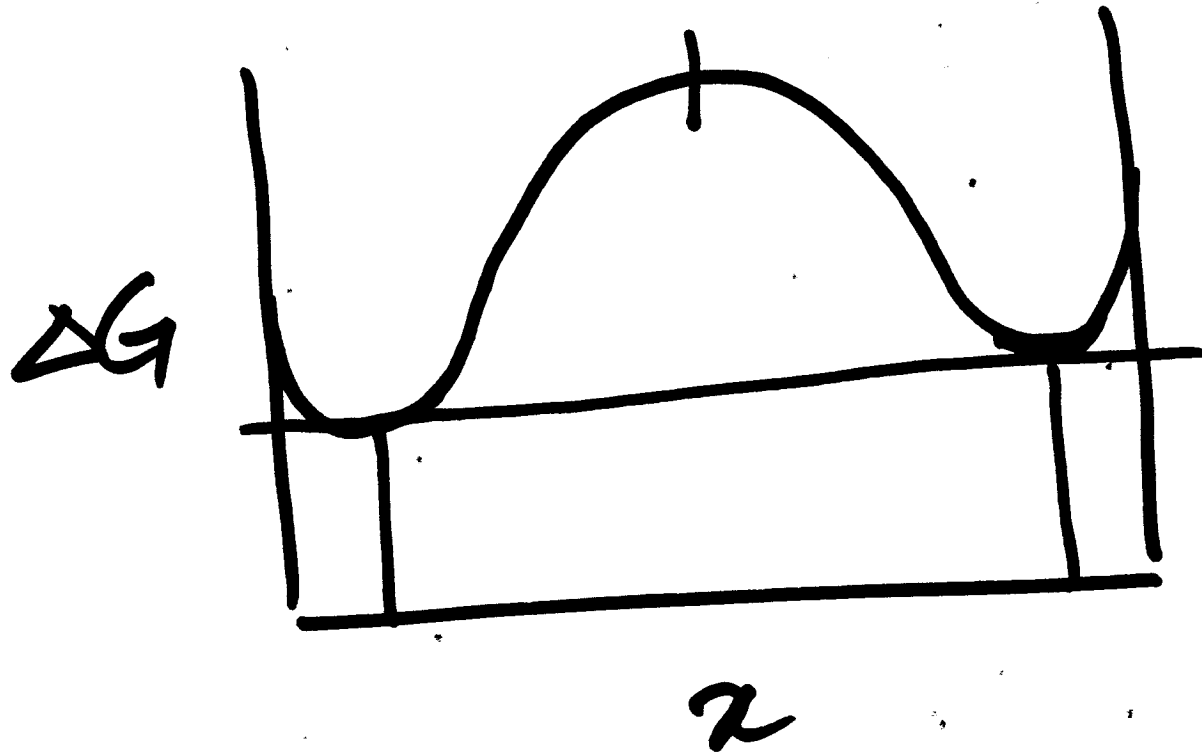


$$T_2 > T_1$$





$$DG = \frac{\Delta G}{RT} = \alpha \frac{x(1-x)}{RT} + x \ln x + (1-x) \ln(1-x)$$

$$DG = \frac{\Delta G}{RT} = \alpha(x)(1-x) + x \ln x + (1-x) \ln(1-x)$$

$$\frac{\partial (DG)}{\partial x} = DG' = \alpha(1-x) - Kx + \cancel{\frac{1}{x}} + \ln x - \ln(1-x) - \cancel{\frac{1}{(1-x)}}$$

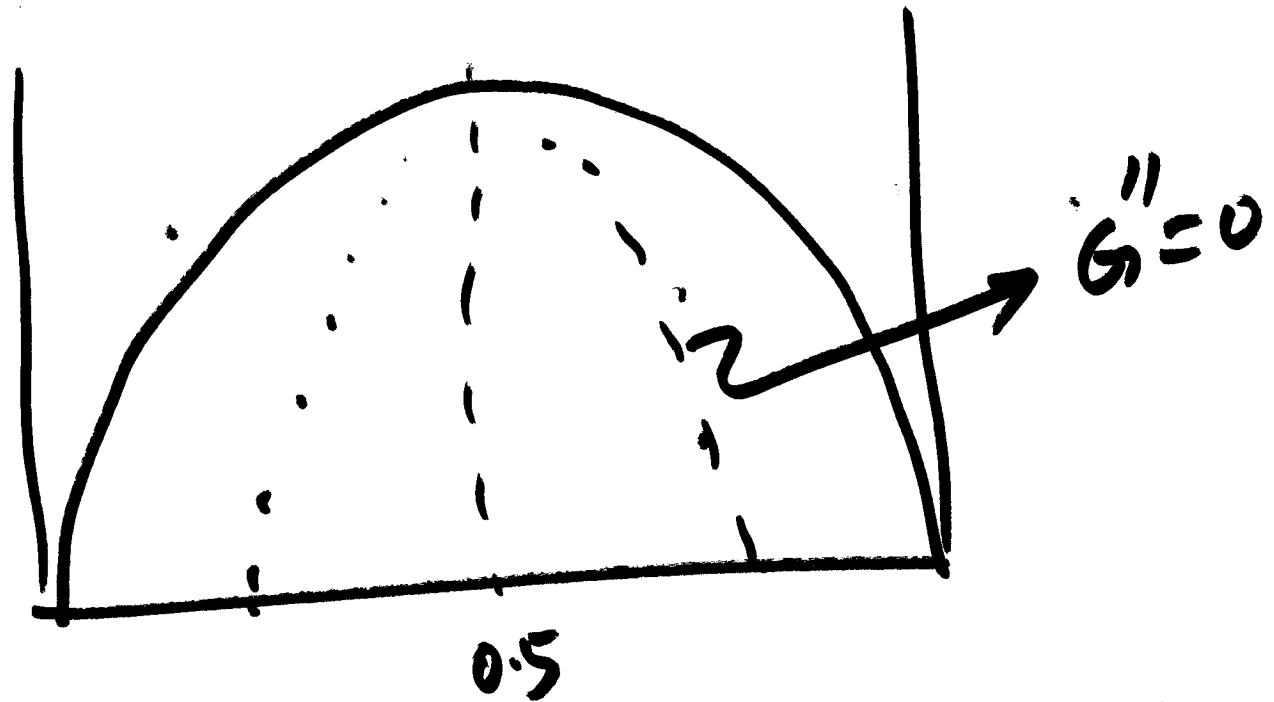
$$= \alpha - 2\alpha x + \ln\left(\frac{x}{1-x}\right)$$

$$\frac{\partial (DG')}{\partial x} = DG''$$

$$= -2\alpha + \frac{1-x}{x} \left[\frac{1}{1-x} + \frac{x}{(1-x)^2} \right]$$

$$= -2\alpha + \frac{1}{x} + \frac{1}{1-x}$$

$$G'' = \frac{\partial^2 \left(\frac{\Delta G}{RT} \right)}{\partial x^2} = -2x + \frac{1}{x} + \frac{1}{1-x} = 0$$



Function $\rightarrow \Delta G$. Define .

$\alpha \rightarrow$ Vary

$$\alpha = \frac{\Omega}{RT}$$

$T \Rightarrow$ Varied .



α

C_1

C_2

2.0

2.01

2.02 .

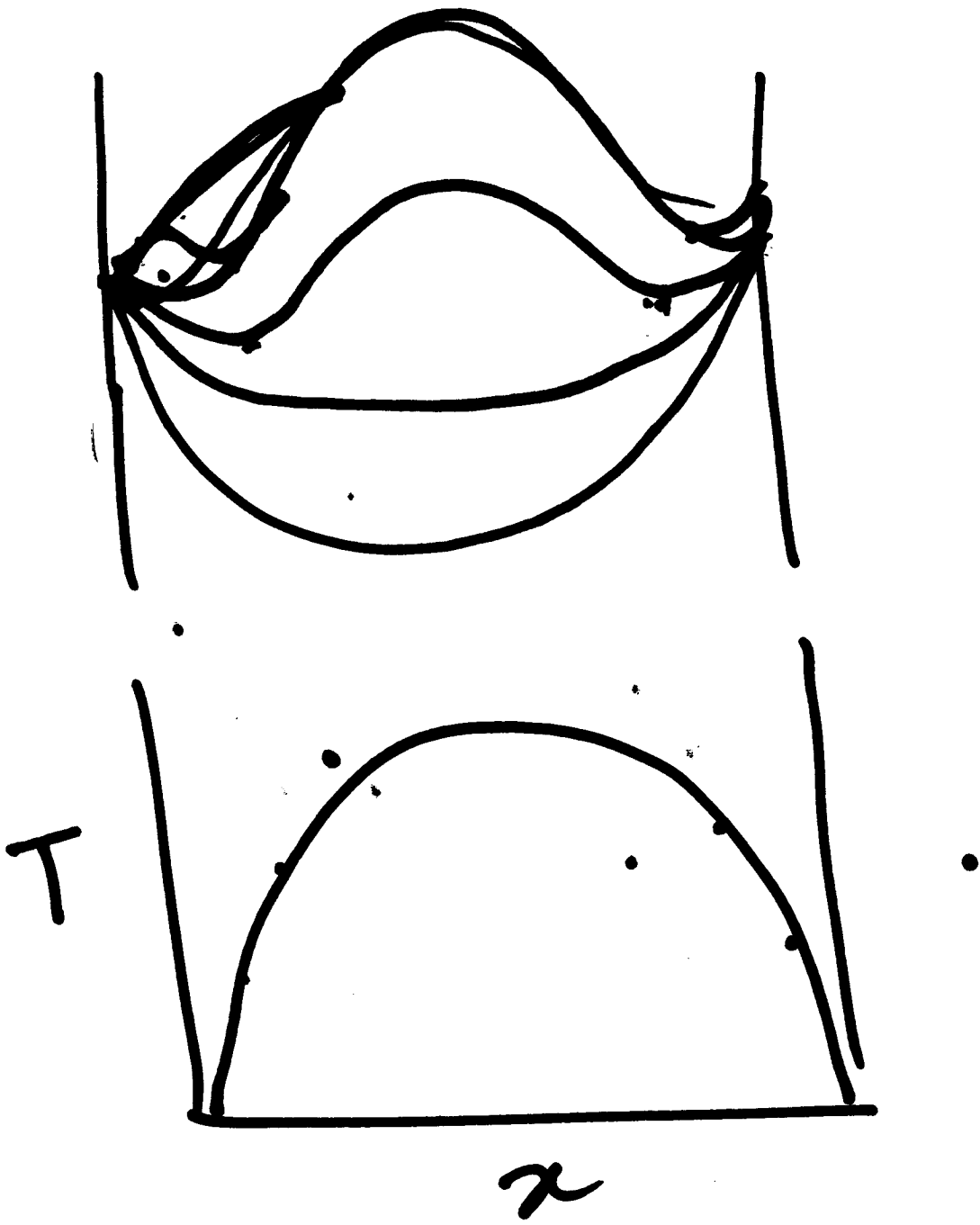
$\frac{RT}{b}$

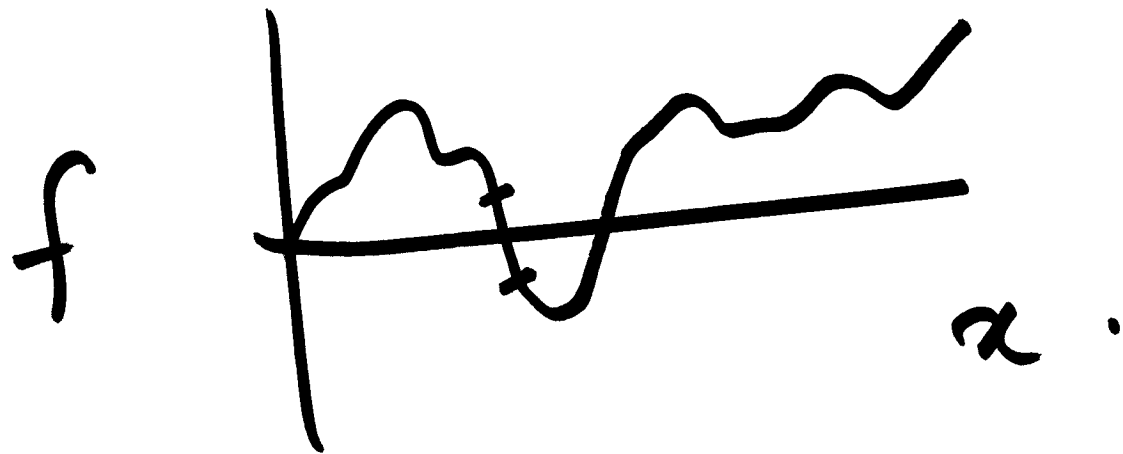
$\left(\frac{P}{P_0}\right)$

$\rightarrow \alpha$

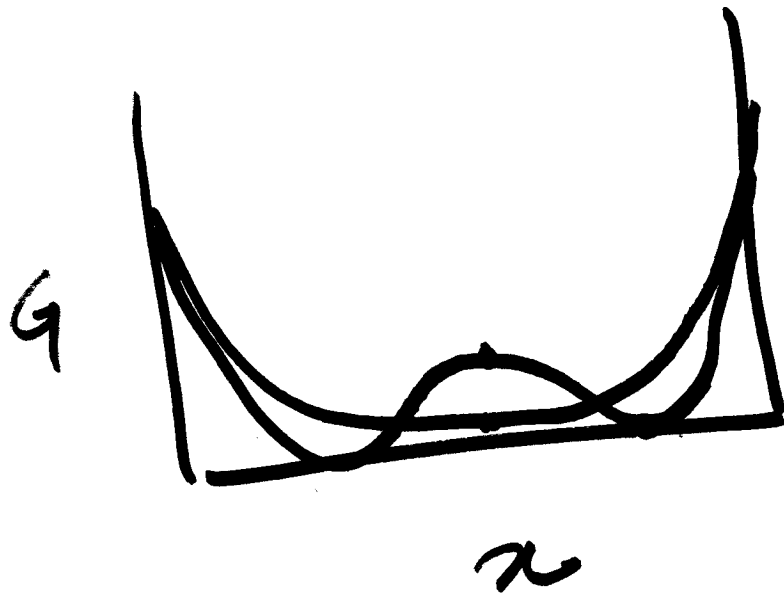


C





$x=2$



$$\Delta G = \Omega x(1-x) + RT \left[x \ln x + (1-x) \ln(1-x) \right]$$

$$\frac{\Delta G}{RT} = \left(\frac{\Omega}{RT} \right) x(1-x) + x \ln x + (1-x) \ln(1-x)$$

$$\alpha \quad \frac{\partial C}{\partial t} = D \frac{\partial^2 C}{\partial x^2}$$

t — time — [T]
 x → position — [L]
 D — $\frac{m^2}{sec}$ — [L²T⁻¹]

$$\frac{\partial C}{\partial t} = D \frac{\partial^2 C}{\partial x^2}$$

Characteristic time τ .

Characteristic length L_0

$$\frac{1}{\tau} \frac{\partial C}{\partial (t/\tau)} = D \frac{\partial^2 C}{\partial (x/L_0)^2}$$

$$\frac{\partial C}{\partial t'} = \underbrace{\frac{D\tau}{L_0^2}}_{D'} \frac{\partial^2 C}{\partial x'^2}$$

$$\frac{\partial C}{\partial t'} = D' \frac{\partial^2 C}{\partial x'^2}$$

$$D' = 1$$

$$\frac{\partial C}{\partial t'} = \frac{\partial^2 C}{\partial x'^2}$$

$$\frac{D \tau}{L^2}$$

$$= k$$