

Foundations of Optimizations

References

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FAQS in Optimization

1. Are most optimization problems solvable exactly?
General Rule: optimization problems are in general not solvable exactly.
2. What does optimization algorithms return to us?
They return a point generated by an iterative process and we choose the point which first satisfies a pre-set stopping criteria.
3. What is the difference between local and global convergence of optimization algorithms.
Local convergence: If $\{x_k\}$ is a sequence of iterates generated by an algorithms, then x_k will converge to a local solution if x_o the initial point or starting point is near the solution point. (Newton's method has local convergence)
Global Convergence: Start from anywhere.....

4. Important Algorithm for unconstrained optimization
 - A. Newton's Method
 - B. Quasi-Newton Methods
 - C. Trust-region Methods
 - D. Conjugate gradients Method
 - E. Derivative free techniques
5. Why are convex functions and convex sets important in optimization
If we minimize a convex function over a convex set every minimum is a global minimum.
6. Are convex functions differentiable?
No, they are differentiable everywhere except over a set of measure zero. (See the discussion on sub gradients in the lecture)
7. What are the important algorithms for solving constrained optimization problems?
 - A) Simplex method for linear programming problems.
 - B) Interior point methods for convex programming problems (e.g. karmarkar's algorithm)
 - C) Penalty Function method
 - D) Sequential Quadratic programming techniques.
 - E) Sub gradients methods for convex optimization.
8. Current hot research areas in optimization
 - A) Polynomial Optimization & Semi definite Programming
 - B) Algebraic techniques in discrete optimization
 - C) Variational Analysis
 - D) MPEC Problems, Bi-level problems and Variational in equality
 - E) Stochastic Optimization
 - F) Vector optimization

