

Dynamic Programming Applications

Design of Continuous Beam

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Optimization Methods: M6L1

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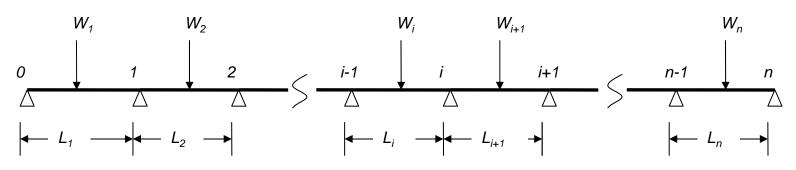
Objectives

- > To discuss the design of continuous beams
- To formulate the optimization problem as a dynamic programming model



Design of Continuous Beam

 Consider a continuous beam having n spans with a set of loadings W₁, W₂,..., W_n



- > Beam rests on n+1 rigid supports
- Locations of the supports are assumed to be known



- Objective function: To minimize the sum of the cost of construction of all spans
- > Assumption: Simple plastic theory of beams is applicable
- > Let the reactant support moments be represented as m_1 , m_2 , ..., m_n
- Complete bending moment distribution can be determined once these support moments are known
- Plastic limit moment for each span and also the cross section of the span can be designed using these support moments



- > Bending moment at the center of the *i*th span is $-W_iL_i/4$
- Thus, the largest bending moment in the *ith* span can be computed as

$$M_{i} = \max\left\{ |m_{i-1}|, |m_{i}|, \left|\frac{m_{i-1} + m_{i}}{2} - \frac{W_{i}L_{i}}{4}\right| \right\} \qquad \text{for } i = 1, 2, \dots n$$

- Limit moment for the *ith* span, *m_lim_i* should be greater than or equal to *M_i* for a beam of uniform cross section
- Thus, the cross section of the beam should be selected such that it has the required limit moment



- > The cost of the beam depends on the cross section
- > And cross section in turn depends on the limit moment
- Thus, cost of the beam can be expressed as a function of the limit moments
- > Let X represents the vector of limit moments



- > The sum of the cost of construction of all spans of the beam is $\sum_{i=1}^{n} C_i(X)$
- > Then, the optimization problem is to find X to

Minimize $\sum_{i=1}^{n} C_i(X)$

satisfying the constraints .

 $m_{\rm lim}_i \ge M_i$ for i = 1, 2, ..., n

This problem has a serial structure and can be solved using dynamic programming



Thank You

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