# 4 Analysis of Statically Indeterminate Structures by the Direct Stiffness Method

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Module

# Lesson 29 The Direct Stiffness Method: Beams (Continued)

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# **Instructional Objectives**

After reading this chapter the student will be able to

- 1. Compute moments developed in the continuous beam due to support settlements.
- 2. Compute moments developed in statically indeterminate beams due to temperature changes.
- 3. Analyse continuous beam subjected to temperature changes and support settlements.

# 29.1 Introduction

In the last two lessons, the analysis of continuous beam by direct stiffness matrix method is discussed. It is assumed in the analysis that the supports are unyielding and the temperature is maintained constant. However, support settlements can never be prevented altogether and hence it is necessary to make provisions in design for future unequal vertical settlements of supports and probable rotations of fixed supports. The effect of temperature changes and support settlements can easily be incorporated in the direct stiffness method and is discussed in this lesson. Both temperature changes and support settlements induce fixed end actions in the restrained beams. These fixed end forces are handled in the same way as those due to loads on the members in the analysis. In other words, the global load vector is formulated by considering fixed end actions due to both support settlements and external loads. At the end, a few problems are solved to illustrate the procedure.

# 29.2 Support settlements

Consider continuous beam *ABC* as shown in Fig. 29.1a. Assume that the flexural rigidity of the continuous beam is constant throughout. Let the support *B* settles by an amount  $\Delta$  as shown in the figure. The fixed end actions due to loads are shown in Fig. 29.1b. The support settlements also induce fixed end actions and are shown in Fig. 29.1c. In Fig. 29.1d, the equivalent joint loads are shown. Since the beam is restrained against displacement in Fig. 29.1b and Fig. 29.1c, the displacements produced in the beam by the joint loads in Fig. 29.1d must be equal to the displacement produced in the beam by the actual loads in Fig. 29.1a. Thus to incorporate the effect of support settlement in the analysis it is required to modify the load vector by considering the negative of the fixed end actions acting on the restrained beam.





(b)





(d) Fig. 29.1

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## 29.3 Effect of temperature change

The effect of temperature on the statically indeterminate beams has already been discussed in lesson 9 of module 2 in connection with the flexibility matrix method. Consider the continuous beam *ABC* as shown in Fig. 29.2a, in which span *BC* is subjected to a differential temperature  $T_1$  at top and  $T_2$  at the bottom of the beam. Let temperature in span *AB* be constant. Let *d* be the depth of beam and *EI* be the flexural rigidity. As the cross section of the member remains plane after bending, the relative angle of rotation  $d\theta$  between two cross sections at a distance *dx* apart is given by

$$d\theta = \alpha \frac{(T_1 - T_2)}{d} dx$$
(29.1)

where  $\alpha$  is the co-efficient of the thermal expansion of the material. When beam is restrained, the temperature change induces fixed end moments in the beam as shown in Fig. 29.2b. The fixed end moments developed are,

$$M_1^T = -M_2^T = \alpha \ EI \ \frac{(T_1 - T_2)}{d}$$
 (29.2)

Corresponding to the above fixed end moments; the equivalent joint loads can easily be constructed. Also due to differential temperatures there will not be any vertical forces/reactions in the beam.



Fig. 29.2

#### Example 29.1

Calculate support reactions in the continuous beam *ABC* (vide Fig. 29.3a) having constant flexural rigidity *EI*, throughout due to vertical settlement of support *B*, by 5*mm* as shown in the figure. Assume  $E = 200 \ GPa$  and  $I = 4 \times 10^{-4} \ m^4$ .



### Fig. 29.3 Example 29.1

The continuous beam considered is divided into two beam elements. The numbering of the joints and members are shown in Fig. 29.3b. The possible global degrees of freedom are also shown in the figure. A typical beam element with two degrees of freedom at each node is also shown in the figure. For this problem, the unconstrained degrees of freedom are  $u_1$  and  $u_2$ . The fixed end actions due to support settlement are,

$$M_{AB}^{F} = \frac{6EI\Delta}{L^{2}} = 96 \text{ kN.m};$$
  $M_{BA}^{F} = 96 \text{ kN.m}$   
 $M_{BC}^{F} = -96 \text{ kN.m}$  ; $M_{CB}^{F} = -96 \text{ kN.m}$  (1)

The fixed-end moments due to support settlements are shown in Fig. 29.3c.

The equivalent joint loads due to support settlement are shown in Fig. 29.3d. In the next step, let us construct member stiffness matrix for each member.

<u>Member 1</u>: L = 5m, node points 1-2.

$$Global d.o.f \qquad 6 \qquad 5 \qquad 3 \qquad 1$$

$$[k'] = EI_{zz} \begin{bmatrix} 0.096 & 0.24 & -0.096 & 0.24 \\ 0.24 & 0.80 & -0.24 & 0.40 \\ -0.096 & -0.24 & 0.096 & -0.24 \\ 0.24 & 0.40 & -0.24 & 0.80 \end{bmatrix}$$

$$(2)$$

<u>Member 2</u>: L = 5m, node points 2-3.

$$Global \, d.o.f \qquad 3 \qquad 1 \qquad 4 \qquad 2$$

$$\begin{bmatrix} k^2 \end{bmatrix} = EI_{zz} \begin{bmatrix} 0.096 & 0.24 & -0.096 & 0.24 \\ 0.24 & 0.80 & -0.24 & 0.40 \\ -0.096 & -0.24 & 0.096 & -0.24 \\ 0.24 & 0.40 & -0.24 & 0.80 \end{bmatrix} 2$$
(3)

On the member stiffness matrix, the corresponding global degrees of freedom are indicated to facilitate assembling. The assembled global stiffness matrix is of order  $6 \times 6$ . Assembled stiffness matrix [*K*] is given by,

Thus the global load vector corresponding to unconstrained degrees of freedom is,

$$\{p_k\} = \begin{cases} p_1 \\ p_2 \end{cases} = \begin{cases} 0 \\ 96 \end{cases}$$
(5)

Thus the load displacement relation for the entire continuous beam is,

	0		1.6	0.4	0	-0.24	0.4	0.24	ſı	$\iota_1$	
	96		0.4	0.8	0.24	-0.24	0	0	u	$\iota_2$	
J	$p_3$		0	0.24	0.192	-0.096	-0.24	-0.096	Ju	<i>i</i> <sub>3</sub>	(6)
	$p_4$	$-LI_{zz}$	-0.24	-0.24	- 0.096	0.096	0	0	Ju	$\iota_4$	( )
	$p_5$		0.4	0	- 0.24	0	0.8	0.24	l	$\iota_5$	
	$p_6$		0.24	0	- 0.096	0	0.24	0.096	l	1 <sub>6</sub> ]	

Since,  $u_3 = u_4 = u_5 = u_6 = 0$  due to support conditions. We get,

$$\begin{cases} 0\\ 96 \end{cases} = EI_{zz} \begin{bmatrix} 1.6 & 0.4\\ 0.4 & 0.8 \end{bmatrix} \begin{cases} u_1\\ u_2 \end{cases}$$

Thus solving for unknowns  $u_1$  and  $u_2$ ,

$$\begin{cases} u_1 \\ u_2 \end{cases} = \frac{1}{1.12EI_{zz}} \begin{bmatrix} 0.8 & -0.4 \\ -0.4 & 1.6 \end{bmatrix} \begin{cases} 0 \\ 96 \end{cases}$$

$$=\frac{1}{EI_{zz}} \begin{cases} -34.285\\ 137.14 \end{cases} = \begin{cases} -0.429 \times 10^{-3}\\ 1.714 \times 10^{-3} \end{cases}$$

 $u_1 = -0.429 \times 10^{-3}$  radians;  $u_2 = 1.714 \times 10^{-3}$  radians (7)

Now, unknown joint loads are calculated by,

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$$\begin{cases} p_{3} \\ p_{4} \\ p_{5} \\ p_{6} \end{cases} = EI_{zz} \begin{bmatrix} 0 & 0.24 \\ -0.24 & -0.24 \\ 0.4 & 0 \\ 0.24 & 0 \end{bmatrix} \frac{1}{EI_{zz}} \begin{cases} -34.285 \\ 137.14 \end{cases}$$
(8)
$$= \begin{cases} 32.91 \\ -24.68 \\ -13.71 \\ -8.23 \end{cases}$$

Now the actual support reactions  $R_3$ ,  $R_4$ ,  $R_5$  and  $R_6$  must include the fixed end support reactions. Thus,

 $R_3 = -43.88 \text{ kN};$   $R_4 = 13.72 \text{ kN};$   $R_5 = 82.29 \text{ kN.m};$   $R_6 = 30.17 \text{ kN}$  (10)

#### Example 29.2

A continuous beam *ABCD* is carrying a uniformly distributed load of 5kN/m as shown in Fig. 29.4a. Compute reactions due to following support settlements.

Support B = 0.005 m vertically downwards.

Support C = 0.010 m vertically downwards.

Assume E = 200 GPa and  $I = 4 \times 10^{-4} m^4$ .



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#### Solution

The node and member numbering are shown in Fig. 29.4(b), wherein the continuous beam is divided into three beam elements. It is observed from the figure that the unconstrained degrees of freedom are  $u_1$  and  $u_2$ . The fixed end actions due to support settlements are shown in Fig. 29.4(c). and fixed end moments due to external loads are shown in Fig. 29.4(d). The equivalent joint loads due to support settlement and external loading are shown in Fig. 29.4(e). The fixed end actions due to support settlement are shown in Fig. 29.4(d).

 $M_A^F = -\frac{6EI}{L}(\psi)$  where  $\psi$  is the chord rotation and is taken + ve if the rotation is counterclockwise.

Substituting the appropriate values in the above equation,

$$M_{A}^{F} = -\frac{6 \times 200 \times 10^{9} \times 4 \times 10^{-4}}{5 \times 10^{3}} \left(-\frac{0.005}{5}\right) = 96 \text{ kN.m.}$$
$$M_{B}^{F} = 96 + 96 = 192 \text{ kN.m.}$$
$$M_{C}^{F} = 96 - 192 = -96 \text{ kN.m.}$$
$$M_{D}^{F} = -192 \text{ kN.m.}$$
(1)

The vertical reactions are calculated from equations of equilibrium. The fixed end actions due to external loading are,

$$M_{A}^{F} = \frac{w L^{2}}{12} = 10.42 \text{ kN.m.}$$

$$M_{B}^{F} = 10.42 - 10.42 = 0 \text{ kN.m.}$$

$$M_{C}^{F} = 0$$

$$M_{D}^{F} = -10.42 \text{ kN.m.}$$
(2)

In the next step, construct member stiffness matrix for each member.

<u>Member 1</u>, L = 5m, node points 1-2.

$$Global d.o.f \qquad 6 \qquad 5 \qquad 3 \qquad 1$$

$$\begin{bmatrix} k' \end{bmatrix} = EI_{zz} \begin{bmatrix} 0.096 & 0.24 & -0.096 & 0.24 \\ 0.24 & 0.80 & -0.24 & 0.40 \\ -0.096 & -0.24 & 0.096 & -0.24 \\ 0.24 & 0.40 & -0.24 & 0.80 \end{bmatrix} \qquad (3)$$

<u>Member 2</u>, L = 5m, node points 2-3.

$$\begin{bmatrix} Global \, d.o.f & 3 & 1 & 4 & 2 \\ 0.096 & 0.24 & -0.096 & 0.24 \\ 0.24 & 0.80 & -0.24 & 0.40 \\ -0.096 & -0.24 & 0.096 & -0.24 \\ 0.24 & 0.40 & -0.24 & 0.80 \end{bmatrix}$$
(4)

<u>Member 3</u>, L = 5m, node points 3-4.

$$Global d.o.f \qquad 4 \qquad 2 \qquad 8 \qquad 7$$

$$\begin{bmatrix} 0.096 & 0.24 & -0.096 & 0.24 \\ 0.24 & 0.80 & -0.24 & 0.40 \\ -0.096 & -0.24 & 0.096 & -0.24 \\ 0.24 & 0.40 & -0.24 & 0.80 \end{bmatrix}$$
(5)

On the member stiffness matrix, the corresponding global degrees of freedom are indicated to facilitate assembling. The assembled global stiffness matrix is of the order  $8 \times 8$ . Assembled stiffness matrix [*K*]is,

	1.60	0.40	0.0	-0.24	0.40	0.24	0	0	
	0.40	1.60	0.24	0	0	0	0.40	-0.24	
	0	0.24	0.192	- 0.096	-0.24	- 0.096	0	0	
$\begin{bmatrix} v \end{bmatrix} EI$	-0.24	0	- 0.096	0.192	0	0	0.24	- 0.096	(6)
$[\Lambda] = EI_{zz}$	0.40	0	-0.24	0	0.80	0.24	0	0	
	0.24	0	- 0.096	0	0.24	0.096	0	0	
	0	0.40	0	0.24	0	0	0.80	-0.24	
	0	-0.24	0	- 0.096	0	0	-0.24	0.096	

The global load vector corresponding to unconstrained degree of freedom is,

$$\{p_k\} = \begin{cases} p_1 \\ p_2 \end{cases} = \begin{cases} -192 \\ 96 \end{cases}$$
(7)

Writing the load displacement relation for the entire continuous beam,

[-192]		1.60	0.40	0.0	-0.24	0.40	0.375	0	0	$\left[ u_{1} \right]$
96		0.40	1.60	0.24	0	0	0	0.40	-0.24	<i>u</i> <sub>2</sub>
<i>p</i> <sub>3</sub>		0	0.24	0.192	- 0.096	- 0.24	- 0.096	0	0	<i>u</i> <sub>3</sub>
$p_4$	– FI	-0.24	0	- 0.096	0.192	0	0	0.24	- 0.096	$ u_4 $
$p_5$	$-LI_{zz}$	0.40	0	- 0.24	0	0.80	0.24	0	0	$u_5$
$p_6$		0.24	0	- 0.096	0	0.24	0.096	0	0	<i>u</i> <sub>6</sub>
<i>p</i> <sub>7</sub>		0	0.40	0	0.24	0	0	0.80	-0.24	<i>u</i> <sub>7</sub>
$p_8$		0	-0.24	0	- 0.096	0	0	-0.24	0.096	$\left[u_{8}\right]$

We know that  $u_3 = u_4 = u_5 = u_6 = u_7 = u_8 = 0$ . Thus solving for unknowns displacements  $u_1$  and  $u_2$  from equation,

$$\begin{cases} -192\\ 96 \end{cases} = EI_{zz} \begin{bmatrix} 1.60 & 0.40\\ 0.40 & 1.60 \end{bmatrix} \begin{cases} u_1\\ u_2 \end{cases}$$
(9)

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(8)

 $u_1 = -1.80 \times 10^{-3}$  radians;  $u_2 = 1.20 \times 10^{-3}$  radians (11)

The unknown joint loads are calculated as,

$$=\begin{cases} 23.04\\ 34.56\\ -57.60\\ -34.56\\ 38.40\\ -23.04 \end{cases}$$
(12)

Now the actual support reactions  $R_3, R_4, R_5, R_6, R_7$  and  $R_8$  must include the fixed end support reactions. Thus,

$$\begin{cases}
 R_3 \\
 R_4 \\
 R_5 \\
 R_6 \\
 R_7 \\
 R_8 \\
 P_8^F \\
 P_6^F \\
 P_7^F \\
 R_8 \\
 P_8^F \\
 P_8^F \\
 P_8^F \\
 P_8^F \\
 P_8 \\$$

# $R_6 = 16.34 \text{ kN};$ $R_7 = -164.02 \text{ kN.m};$ $R_8 = 66.26 \text{ kN}$

## Summary

The effect of temperature changes and support settlements can easily be incorporated in the direct stiffness method and is discussed in the present lesson. Both temperature changes and support settlements induce fixed end actions in the restrained beams. These fixed end forces are handled in the same way as those due to loads on the members in the analysis. In other words, the global load vector is formulated by considering fixed end actions due to both support settlements and external loads. At the end, a few problems are solved to illustrate the procedure.

(14)