

Lesson 14

1. What is a system of nonlinear equations?

A system of nonlinear equations in n unknowns $x_1, x_2, x_3, \dots, x_n$ is a series of n equations:

$$f_i(x_1, x_2, \dots, x_n) = 0, \quad i = 1, 2, \dots, n$$

A one point iteration method for this equation can be constructed by rewriting the system as:

$$x_i = \phi_i(x_1, x_2, \dots, x_n), \quad i = 1, 2, \dots, n$$

2. Can a system of nonlinear equations be solved iteratively?

A system of nonlinear equations can be solved iteratively. For example the one point scheme described above can be solved iteratively as:

$$x_i^{(k+1)} = \phi_i(x_1^{(k)}, x_2^{(k)}, \dots, x_n^{(k)}), \quad i = 1, 2, \dots, n$$

This can be restated in vector notation as:

$$\mathbf{x} = (x_1, x_2, \dots, x_n), \quad \boldsymbol{\phi}(\mathbf{x}) = (\phi_1(\mathbf{x}), \phi_2(\mathbf{x}), \dots, \phi_n(\mathbf{x}))$$

$$\mathbf{x}^{(k+1)} = \boldsymbol{\phi}(\mathbf{x}^{(k)}), \quad k = 0, 1, 2, \dots, n$$

3. What is the convergence criteria for systems of nonlinear equations?

In order to define the convergence criteria for a system of nonlinear equations it is necessary to consider the Jacobian of the system. For example, for the one point iterative scheme, the Jacobian is given by:

$$\mathbf{J} = \begin{bmatrix} \frac{\partial \phi_1}{\partial x_1} & \frac{\partial \phi_1}{\partial x_2} & \dots & \frac{\partial \phi_1}{\partial x_n} \\ \frac{\partial \phi_2}{\partial x_1} & \frac{\partial \phi_2}{\partial x_2} & \dots & \frac{\partial \phi_2}{\partial x_n} \\ \dots & \dots & \dots & \dots \\ \frac{\partial \phi_n}{\partial x_1} & \frac{\partial \phi_n}{\partial x_2} & \dots & \frac{\partial \phi_n}{\partial x_n} \end{bmatrix}$$

Each of the partial derivatives must exist in the region $x \in \mathfrak{R}$ where $\mathfrak{R} = \{\mathbf{x} : \|\mathbf{x} - \boldsymbol{\alpha}\| < \rho\}$ $\boldsymbol{\alpha}$ being the root of the system of nonlinear equations. The iteration will converge if for any value of the starting iterate $\mathbf{x}_0 \in \mathfrak{R}$, the following condition is satisfied in some matrix norm:

$$\|\mathbf{J}\| \leq m < 1, \quad \forall \mathbf{x} \in \mathfrak{R}$$

A necessary condition for this to happen is that the spectral radius of \mathbf{J} be less than for

all $\mathbf{x} \in \mathfrak{R}$

4. Why is it necessary to obtain numerical estimates of the partial derivatives in multi-dimensions?

For finding the roots of a system of nonlinear equations it is necessary to obtain the components of the Jacobian matrix, which involves evaluating partial derivatives of the function $\boldsymbol{\phi}(\mathbf{x}) = (\phi_1(\mathbf{x}), \phi_2(\mathbf{x}), \dots, \phi_n(\mathbf{x}))$. This can be done by estimating the derivative by a difference quotient, e.g.

$$\frac{\partial \phi_i(\mathbf{x})}{\partial x_j} \approx \frac{\phi_i(\mathbf{x} + h_j \mathbf{e}_j) - \phi_i(\mathbf{x})}{h_j}$$

where \mathbf{e}_j is the j^{th} unit vector and h_j is the j^{th} component of a n -dimensional parameter vector with components $h_j \neq 0$ for $j = 1, 2, \dots, n$.