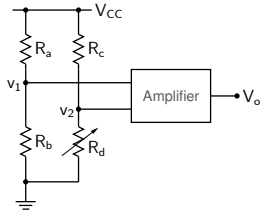
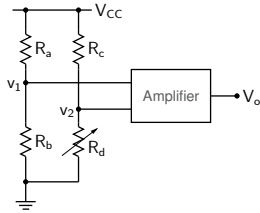


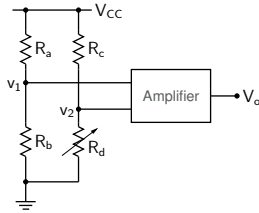
Common-mode and differential-mode voltages





Consider a bridge circuit for sensing temperature, pressure, etc., with $R_a = R_b = R_c = R$.

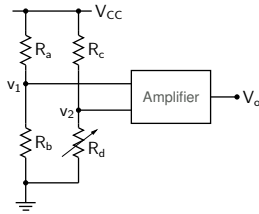
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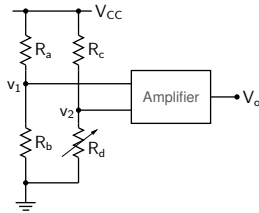


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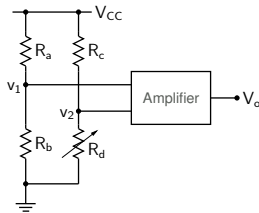
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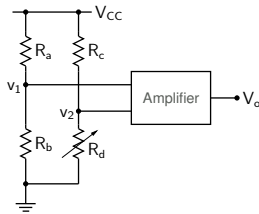
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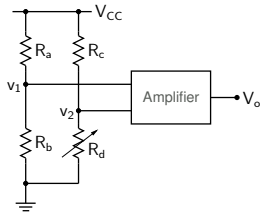
where $x = \Delta R/R$.

For example, with $V_{CC} = 15 \text{ V}$, $R = 1 \text{ k}$, $\Delta R = 0.01 \text{ k}$,

$$v_1 = 7.5 \text{ V},$$

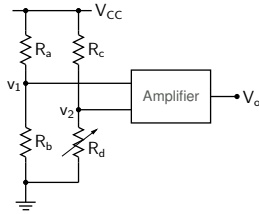
$$v_2 = 7.5 + 0.0375 \text{ V}.$$

Common-mode and differential-mode voltages



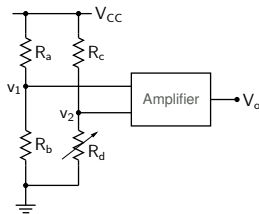
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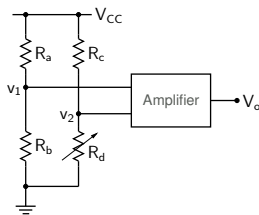
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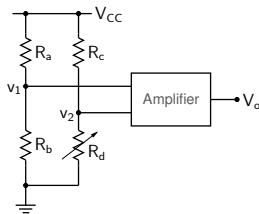
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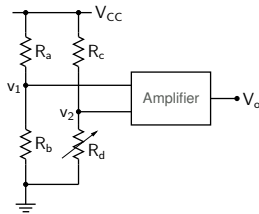
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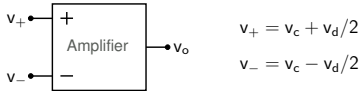
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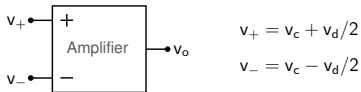
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Note that the common-mode voltage is quite large compared to the differential-mode voltage.

This is a common situation in transducer circuits.



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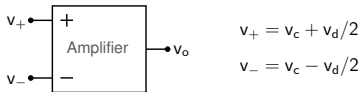
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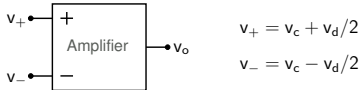
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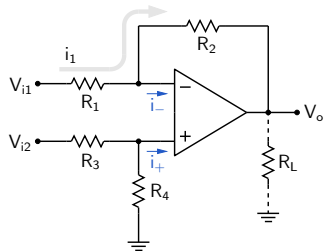
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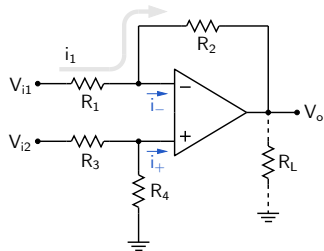
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For the 741 op-amp, the CMRR is 90 dB ($\simeq 30,000$), which may be considered to be infinite in many applications. In such cases, mismatch between circuit components will determine the overall common-mode rejection performance of the circuit.

Op-amp circuits (linear region)



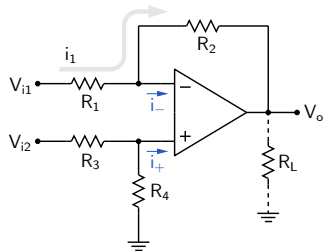
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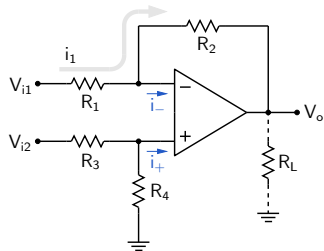


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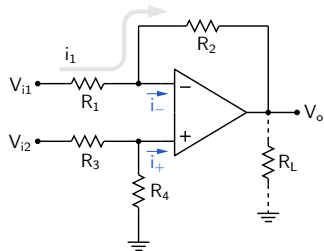
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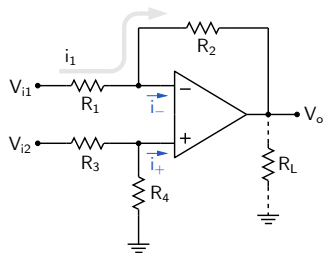
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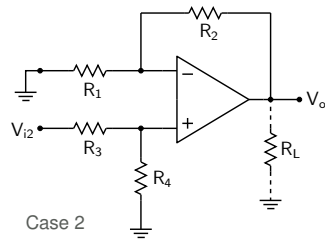
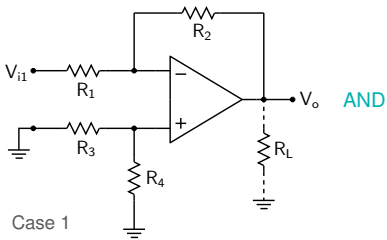
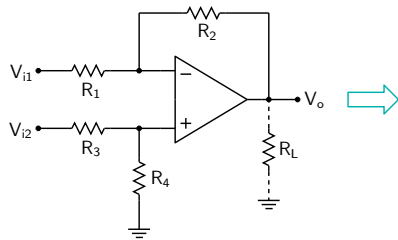
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The circuit is a "difference amplifier."

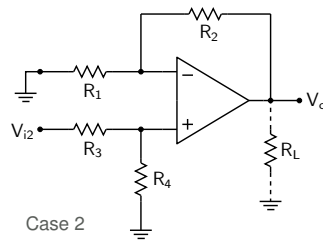
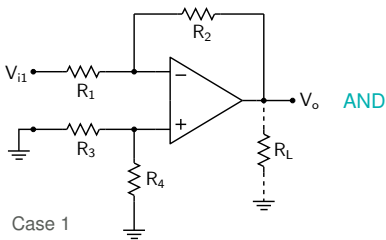
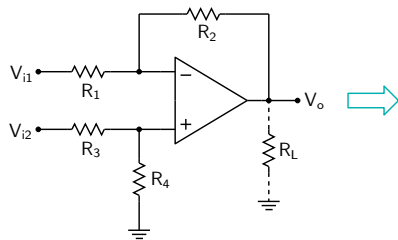
Difference amplifier



Method 2:

Since the op-amp is operating in the linear region, we can use superposition:

Difference amplifier



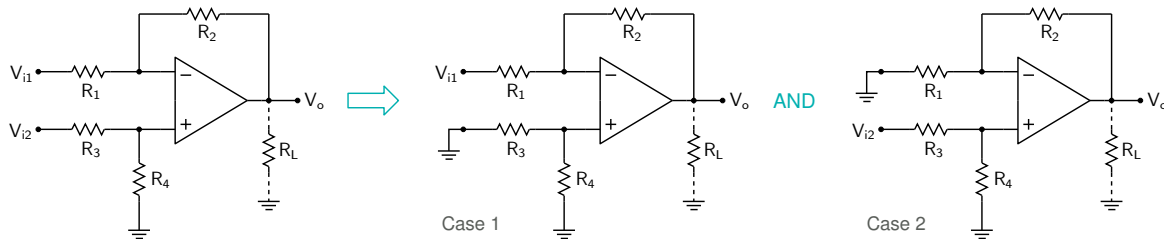
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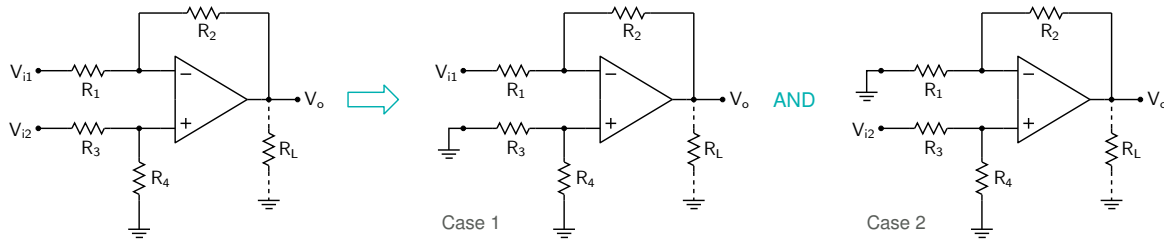
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Case 2: Non-inverting amplifier, with $V_i = \frac{R_4}{R_3 + R_4} V_{i2}$.

$$\rightarrow V_{o2} = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) V_{i2}.$$

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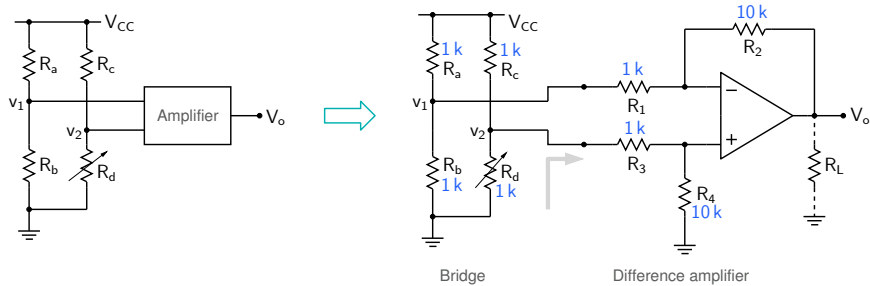
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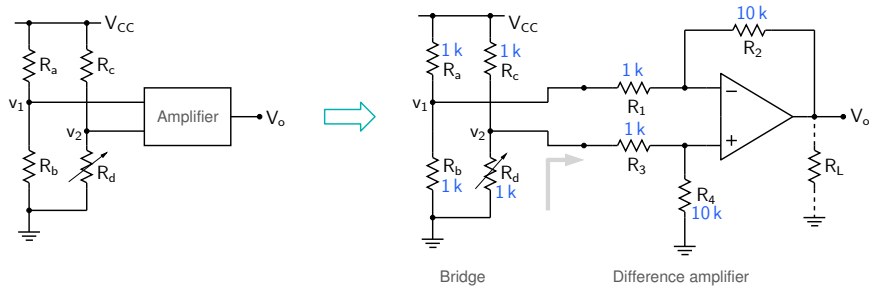
The net result is,

$$V_o = V_{o1} + V_{o2} = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) V_{i2} - \frac{R_2}{R_1} V_{i1} = \frac{R_2}{R_1} (V_{i2} - V_{i1}), \text{ if } \frac{R_4}{R_3} = \frac{R_2}{R_1}.$$

Difference amplifier

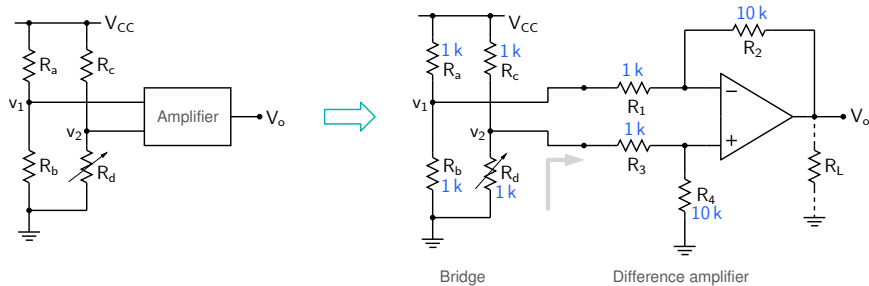


Difference amplifier



The resistance seen from v_2 is $(R_3 + R_4)$ which is small enough to cause v_2 to change.
This is not desirable.

Difference amplifier

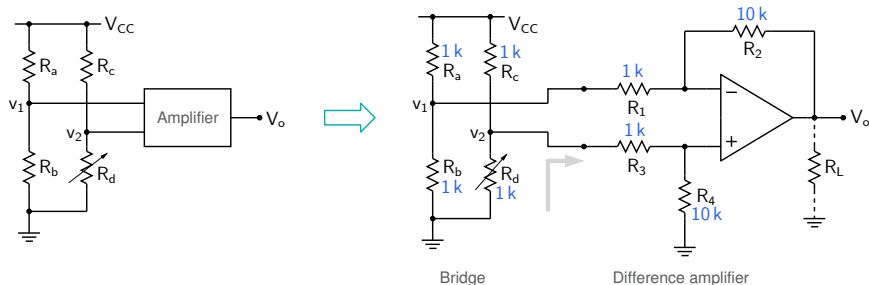


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→ need to improve the input resistance of the difference amplifier.

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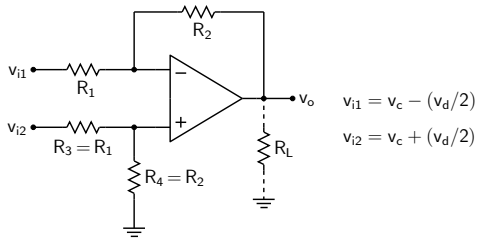
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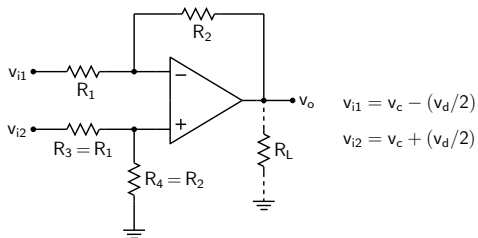
→ need to improve the input resistance of the difference amplifier.

We will discuss an improved difference amplifier later. Before we do that, let us discuss another problem with the above difference amplifier which can be important for some applications (next slide).

Difference amplifier



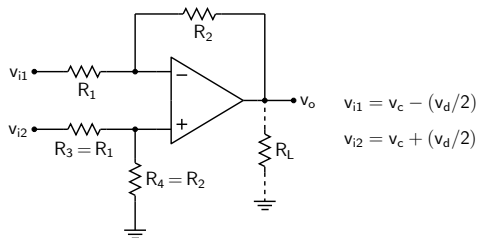
Difference amplifier



Consider the difference amplifier with $R_3 = R_1$, $R_4 = R_2 \rightarrow V_o = \frac{R_2}{R_1} (v_{i2} - v_{i1})$.

The output voltage depends only on the differential-mode signal $(v_{i2} - v_{i1})$,
i.e., A_c (common-mode gain) = 0.

Difference amplifier

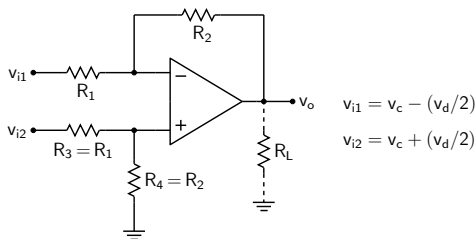


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In practice, R_3 and R_1 may not be exactly equal. Let $R_3 = R_1 + \Delta R$.

Difference amplifier



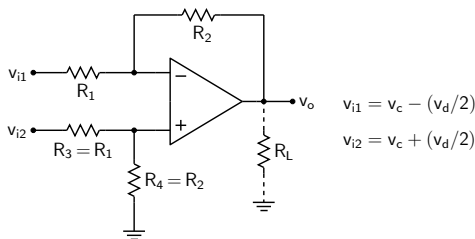
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In practice, R_3 and R_1 may not be exactly equal. Let $R_3 = R_1 + \Delta R$.

$$\begin{aligned}
 v_o &= \frac{R_4}{R_3 + R_4} \left(1 + \frac{R_2}{R_1} \right) v_{i2} - \frac{R_2}{R_1} v_{i1} = \frac{R_2}{R_1 + \Delta R + R_2} \left(1 + \frac{R_2}{R_1} \right) v_{i2} - \frac{R_2}{R_1} v_{i1} \\
 &\simeq \frac{R_2}{R_1} (v_d - x v_c), \text{ with } x = \frac{\Delta R}{R_1 + R_2} \quad (\text{show this})
 \end{aligned}$$

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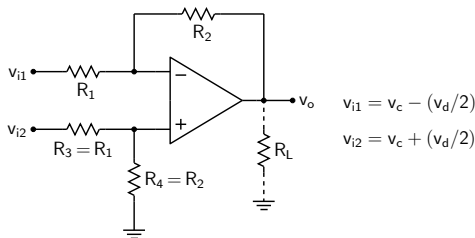
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In practice, R_3 and R_1 may not be exactly equal. Let $R_3 = R_1 + \Delta R$.

$$\begin{aligned}
 v_o &= \frac{R_4}{R_3 + R_4} \left(1 + \frac{R_2}{R_1} \right) v_{i2} - \frac{R_2}{R_1} v_{i1} = \frac{R_2}{R_1 + \Delta R + R_2} \left(1 + \frac{R_2}{R_1} \right) v_{i2} - \frac{R_2}{R_1} v_{i1} \\
 &\simeq \frac{R_2}{R_1} (v_d - x v_c), \text{ with } x = \frac{\Delta R}{R_1 + R_2} \quad (\text{show this})
 \end{aligned}$$

$$|A_c| = \frac{\Delta R}{R_1 + R_2} \frac{R_2}{R_1} \ll |A_d| = \frac{R_2}{R_1}.$$

Difference amplifier



Consider the difference amplifier with $R_3 = R_1$, $R_4 = R_2 \rightarrow V_o = \frac{R_2}{R_1} (v_{i2} - v_{i1})$.

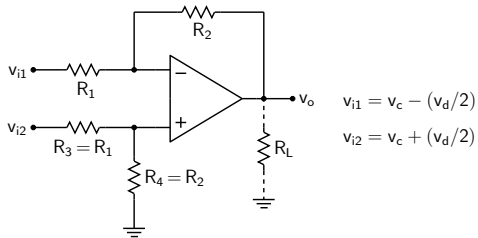
The output voltage depends only on the differential-mode signal $(v_{i2} - v_{i1})$,
i.e., A_c (common-mode gain) = 0.

In practice, R_3 and R_1 may not be exactly equal. Let $R_3 = R_1 + \Delta R$.

$$\begin{aligned}
 v_o &= \frac{R_4}{R_3 + R_4} \left(1 + \frac{R_2}{R_1} \right) v_{i2} - \frac{R_2}{R_1} v_{i1} = \frac{R_2}{R_1 + \Delta R + R_2} \left(1 + \frac{R_2}{R_1} \right) v_{i2} - \frac{R_2}{R_1} v_{i1} \\
 &\simeq \frac{R_2}{R_1} (v_d - x v_c), \text{ with } x = \frac{\Delta R}{R_1 + R_2} \quad (\text{show this})
 \end{aligned}$$

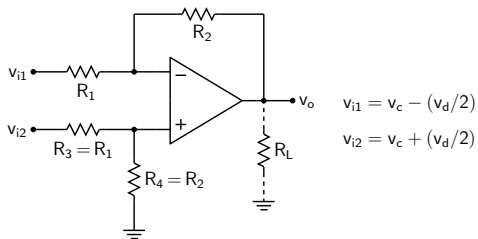
$|A_c| = \frac{\Delta R}{R_1 + R_2} \frac{R_2}{R_1} \ll |A_d| = \frac{R_2}{R_1}$. However, since v_c can be large compared to v_d , the effect of A_c cannot be ignored.

Difference amplifier



$$|A_c| = x \frac{R_2}{R_1}, |A_d| = \frac{R_2}{R_1}, \text{ where } x = \frac{\Delta R}{R_1 + R_2}.$$

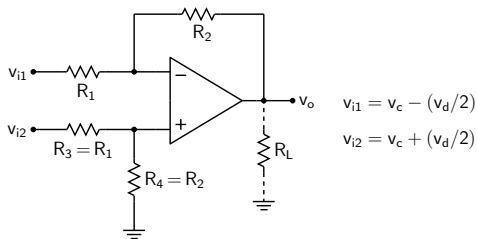
Difference amplifier



$$|A_c| = x \frac{R_2}{R_1}, |A_d| = \frac{R_2}{R_1}, \text{ where } x = \frac{\Delta R}{R_1 + R_2}.$$

In our earlier example, $v_c = 7.5 \text{ V}$, $v_d = 0.0375 \text{ V}$.

Difference amplifier



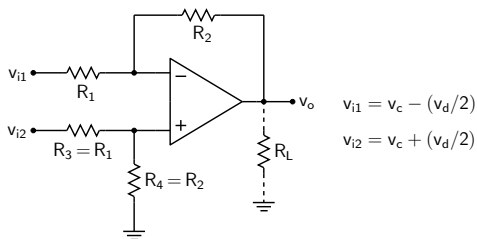
$$|A_c| = x \frac{R_2}{R_1}, |A_d| = \frac{R_2}{R_1}, \text{ where } x = \frac{\Delta R}{R_1 + R_2}.$$

In our earlier example, $v_c = 7.5 \text{ V}$, $v_d = 0.0375 \text{ V}$.

With $R_1 = 1 \text{ k}$, $R_2 = 10 \text{ k}$, $x = \frac{0.01 \text{ k}}{11 \text{ k}} = 0.00091 \rightarrow |A_c| = 0.00091 \frac{10 \text{ k}}{1 \text{ k}} = 0.0091$, $|A_d| = \frac{10 \text{ k}}{1 \text{ k}} = 10$.

$$|v_o^c| = |A_c v_c| = 0.0091 \times 7.5 = 0.068 \text{ V}.$$

Difference amplifier



$$|A_c| = x \frac{R_2}{R_1}, |A_d| = \frac{R_2}{R_1}, \text{ where } x = \frac{\Delta R}{R_1 + R_2}.$$

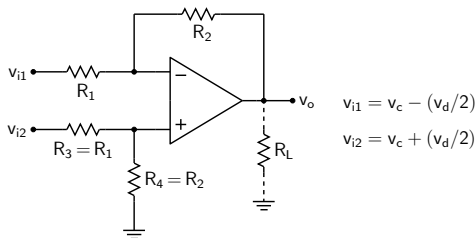
In our earlier example, $v_c = 7.5 \text{ V}$, $v_d = 0.0375 \text{ V}$.

$$\text{With } R_1 = 1 \text{ k}, R_2 = 10 \text{ k}, x = \frac{0.01 \text{ k}}{11 \text{ k}} = 0.00091 \rightarrow |A_c| = 0.00091 \frac{10 \text{ k}}{1 \text{ k}} = 0.0091, |A_d| = \frac{10 \text{ k}}{1 \text{ k}} = 10.$$

$$|v_o^c| = |A_c v_c| = 0.0091 \times 7.5 = 0.068 \text{ V}.$$

$$|v_o^d| = |A_d v_d| = 10 \times 0.0375 = 0.375 \text{ V}.$$

Difference amplifier



$$|A_c| = x \frac{R_2}{R_1}, |A_d| = \frac{R_2}{R_1}, \text{ where } x = \frac{\Delta R}{R_1 + R_2}.$$

In our earlier example, $v_c = 7.5 \text{ V}$, $v_d = 0.0375 \text{ V}$.

$$\text{With } R_1 = 1 \text{ k}, R_2 = 10 \text{ k}, x = \frac{0.01 \text{ k}}{11 \text{ k}} = 0.00091 \rightarrow |A_c| = 0.00091 \frac{10 \text{ k}}{1 \text{ k}} = 0.0091, |A_d| = \frac{10 \text{ k}}{1 \text{ k}} = 10.$$

$$|v_o^c| = |A_c v_c| = 0.0091 \times 7.5 = 0.068 \text{ V}.$$

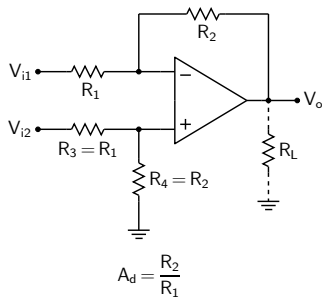
$$|v_o^d| = |A_d v_d| = 10 \times 0.0375 = 0.375 \text{ V}.$$

The (spurious) common-mode contribution is substantial.

If we measure v_o , we will conclude that $v_d = \frac{v_o}{A_d}$, but in reality, it would be different.

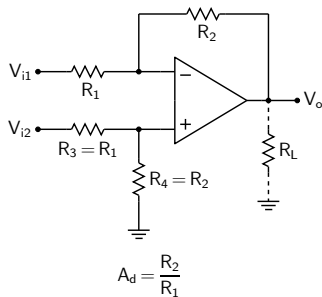
→ need a circuit which will drastically reduce the common-mode component at the output.

Difference amplifier: resistance mismatch



$$V_o = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) V_{i2} - \frac{R_2}{R_1} V_{i1}$$

Difference amplifier: resistance mismatch

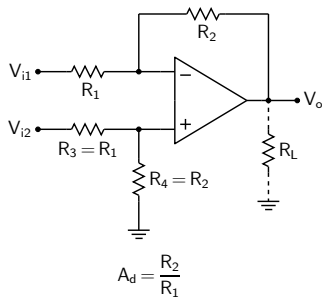


$$V_o = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) V_{i2} - \frac{R_2}{R_1} V_{i1}$$

$$\text{Let } V_{i1} = V_{i2} = V_c \rightarrow A_c = \frac{V_o}{V_c}.$$

$$A_c = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) - \frac{R_2}{R_1}$$

Difference amplifier: resistance mismatch

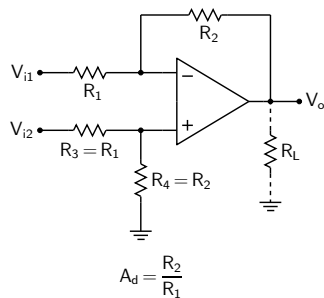


$$V_o = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) V_{i2} - \frac{R_2}{R_1} V_{i1}$$

$$\text{Let } V_{i1} = V_{i2} = V_c \rightarrow A_c = \frac{V_o}{V_c}.$$

$$\begin{aligned} A_c &= \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) - \frac{R_2}{R_1} \\ &= \frac{R_4}{R_3 + R_4} \left(1 - \frac{R_2}{R_1} \frac{R_3}{R_4}\right) \end{aligned}$$

Difference amplifier: resistance mismatch



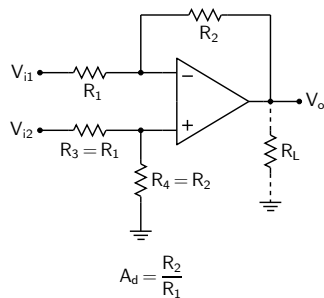
$$V_o = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) V_{i2} - \frac{R_2}{R_1} V_{i1}$$

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Assume ideal op-amp with $R_1 = R_1^0(1 + x_1)$, etc. 1 % resistor $\rightarrow x = 0.01$.

Difference amplifier: resistance mismatch



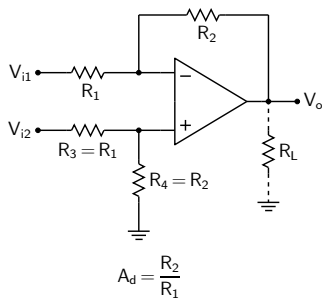
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Assume ideal op-amp with $R_1 = R_1^0(1 + x_1)$, etc. 1 % resistor $\rightarrow x = 0.01$.

$$\rightarrow A_c = \frac{R_4}{R_3 + R_4} \left(1 - \frac{R_2^0(1 + x_2)}{R_1^0(1 + x_1)} \times \frac{R_3^0(1 + x_3)}{R_4^0(1 + x_4)}\right).$$



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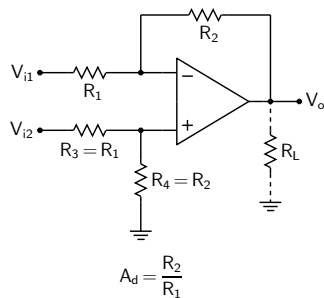
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Using $(1 + u_1)(1 + u_2) \approx 1 + u_1 + u_2$ if $|u_1| \ll 1$, $|u_2| \ll 1$,



$$V_o = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) V_{i2} - \frac{R_2}{R_1} V_{i1}$$

$$\text{Let } V_{i1} = V_{i2} = V_c \rightarrow A_c = \frac{V_o}{V_c}.$$

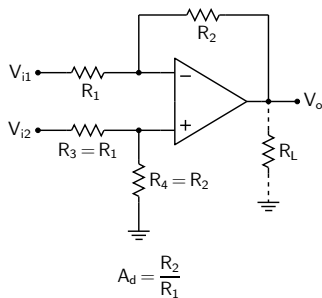
$$\begin{aligned} A_c &= \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) - \frac{R_2}{R_1} \\ &= \frac{R_4}{R_3 + R_4} \left(1 - \frac{R_2}{R_1} \frac{R_3}{R_4}\right) \end{aligned}$$

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Using $(1 + u_1)(1 + u_2) \approx 1 + u_1 + u_2$ if $|u_1| \ll 1$, $|u_2| \ll 1$,

$$\text{and } \frac{1}{1 + u} \approx 1 - u \text{ if } |u| \ll 1,$$



$$V_o = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) V_{i2} - \frac{R_2}{R_1} V_{i1}$$

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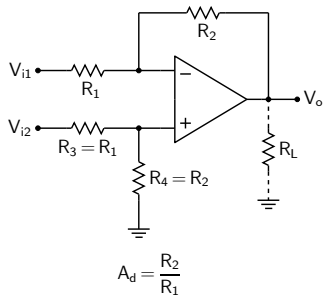
$$\rightarrow A_c = \frac{R_4}{R_3 + R_4} \left(1 - \frac{R_2^0(1 + x_2)}{R_1^0(1 + x_1)} \times \frac{R_3^0(1 + x_3)}{R_4^0(1 + x_4)}\right).$$

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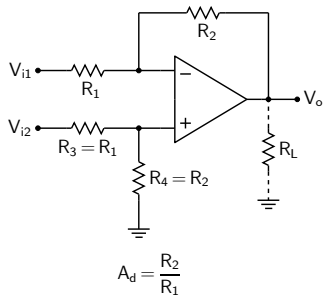
$$A_c = \frac{R_4}{R_3 + R_4} (x_1 - x_2 - x_3 + x_4).$$

Difference amplifier: resistance mismatch



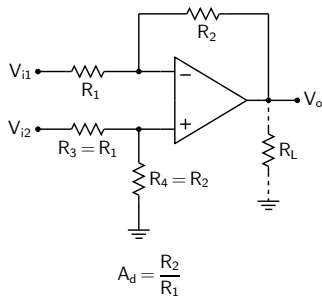
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Difference amplifier: resistance mismatch



$$A_c = \frac{R_4}{R_3 + R_4} (x_1 - x_2 - x_3 + x_4).$$

$$\frac{R_4}{R_3 + R_4} \approx \frac{R_4^0}{R_3^0 + R_4^0}.$$

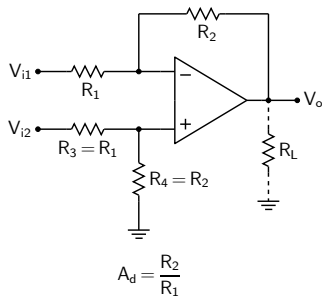


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$$\frac{R_4}{R_3 + R_4} \approx \frac{R_4^0}{R_3^0 + R_4^0}.$$

$$(1) R_1^0 = R_2^0 \text{ (i.e., } R_3^0 = R_4^0)$$

Difference amplifier: resistance mismatch



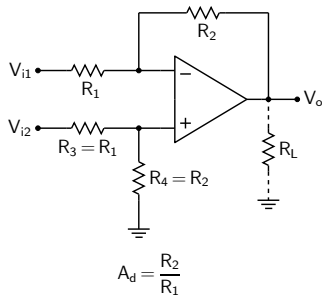
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$$(1) \quad R_1^0 = R_2^0 \text{ (i.e., } R_3^0 = R_4^0)$$

$$A_c = \frac{1}{2} (x_1 - x_2 - x_3 + x_4)$$

Difference amplifier: resistance mismatch

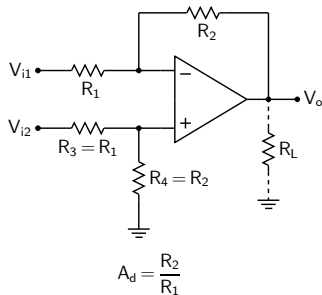


$$A_c = \frac{R_4}{R_3 + R_4} (x_1 - x_2 - x_3 + x_4).$$

$$\frac{R_4}{R_3 + R_4} \approx \frac{R_4^0}{R_3^0 + R_4^0}.$$

$$(1) R_1^0 = R_2^0 \text{ (i.e., } R_3^0 = R_4^0)$$

$$\begin{aligned} A_c &= \frac{1}{2} (x_1 - x_2 - x_3 + x_4) \\ &= \frac{1}{2} 4x = 2x \text{ (worst case)} \end{aligned}$$



$$A_c = \frac{R_4}{R_3 + R_4} (x_1 - x_2 - x_3 + x_4).$$

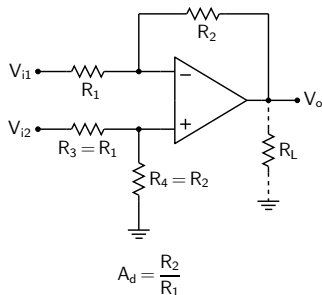
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$$(2) R_1^0 \ll R_2^0 \text{ (i.e., } R_3^0 \ll R_4^0)$$

Difference amplifier: resistance mismatch



$$A_c = \frac{R_4}{R_3 + R_4} (x_1 - x_2 - x_3 + x_4).$$

$$\frac{R_4}{R_3 + R_4} \approx \frac{R_4^0}{R_3^0 + R_4^0}.$$

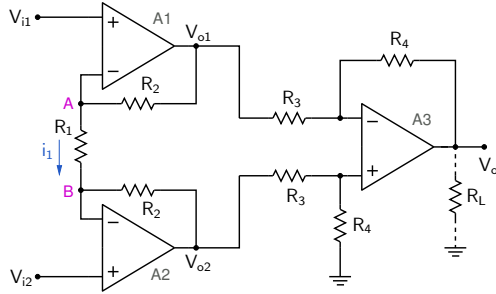
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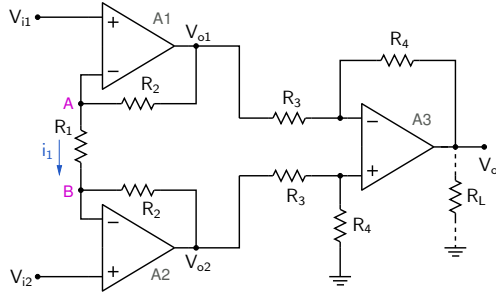
$$(2) R_1^0 \ll R_2^0 \text{ (i.e., } R_3^0 \ll R_4^0)$$

$$A_c = \frac{(R_4^0/R_3^0)}{1 + (R_4^0/R_3^0)} (x_1 - x_2 - x_3 + x_4) \approx 4x \text{ (worst case)}$$

Improved difference amplifier

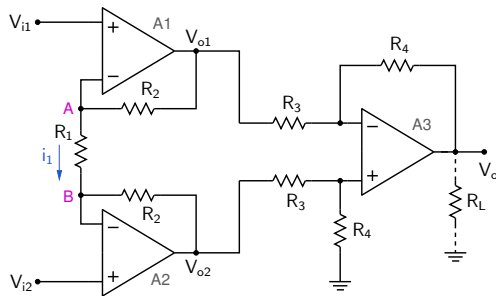


Improved difference amplifier



$$V_+ \approx V_- \rightarrow V_A = V_{i1}, V_B = V_{i2}, \rightarrow i_1 = \frac{1}{R_1} (V_{i1} - V_{i2}).$$

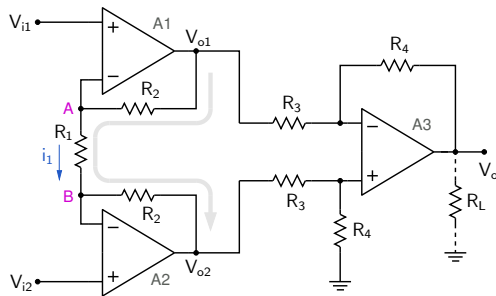
Improved difference amplifier



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Large input resistance of A1 and A2 \Rightarrow the current through the two resistors marked R_2 is also equal to i_1 .

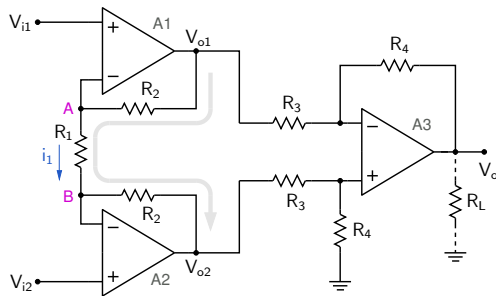
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Improved difference amplifier

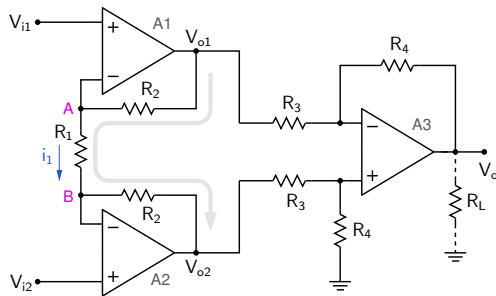


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Large input resistance of A1 and A2 \Rightarrow the current through the two resistors marked R_2 is also equal to i_1 .

$$V_{o1} - V_{o2} = i_1(R_1 + 2R_2) = \frac{1}{R_1} (V_{i1} - V_{i2}) (R_1 + 2R_2) = (V_{i1} - V_{i2}) \left(1 + \frac{2R_2}{R_1} \right).$$

Improved difference amplifier



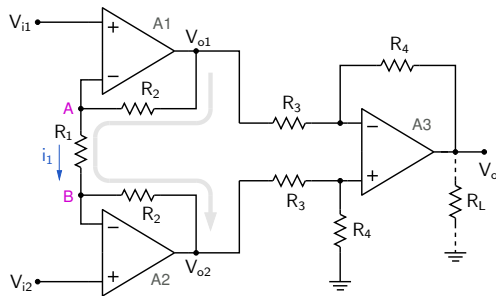
$$V_+ \approx V_- \rightarrow V_A = V_{i1}, V_B = V_{i2}, \rightarrow i_1 = \frac{1}{R_1} (V_{i1} - V_{i2}).$$

Large input resistance of A1 and A2 \Rightarrow the current through the two resistors marked R_2 is also equal to i_1 .

$$V_{o1} - V_{o2} = i_1(R_1 + 2R_2) = \frac{1}{R_1} (V_{i1} - V_{i2}) (R_1 + 2R_2) = (V_{i1} - V_{i2}) \left(1 + \frac{2R_2}{R_1}\right).$$

$$\text{Finally, } V_o = \frac{R_4}{R_3} (V_{o2} - V_{o1}) = \frac{R_4}{R_3} \left(1 + \frac{2R_2}{R_1}\right) (V_{i2} - V_{i1}).$$

Improved difference amplifier



$$V_+ \approx V_- \rightarrow V_A = V_{i1}, V_B = V_{i2}, \rightarrow i_1 = \frac{1}{R_1} (V_{i1} - V_{i2}).$$

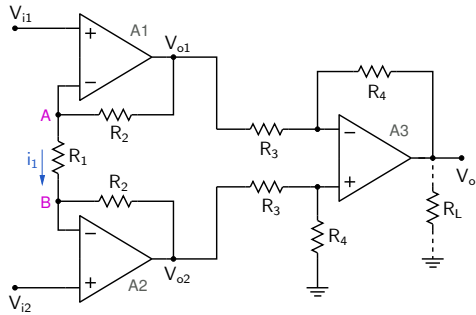
Large input resistance of A1 and A2 \Rightarrow the current through the two resistors marked R_2 is also equal to i_1 .

$$V_{o1} - V_{o2} = i_1(R_1 + 2R_2) = \frac{1}{R_1} (V_{i1} - V_{i2}) (R_1 + 2R_2) = (V_{i1} - V_{i2}) \left(1 + \frac{2R_2}{R_1}\right).$$

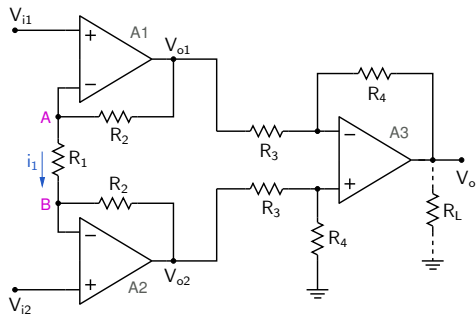
$$\text{Finally, } V_o = \frac{R_4}{R_3} (V_{o2} - V_{o1}) = \frac{R_4}{R_3} \left(1 + \frac{2R_2}{R_1}\right) (V_{i2} - V_{i1}).$$

This circuit is known as the “instrumentation amplifier.”

Instrumentation amplifier

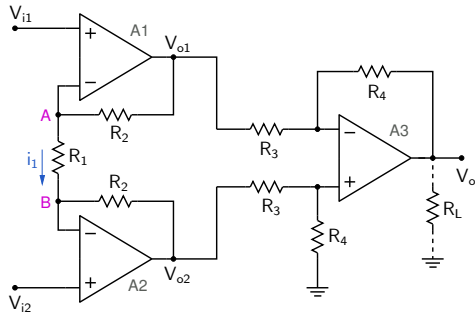


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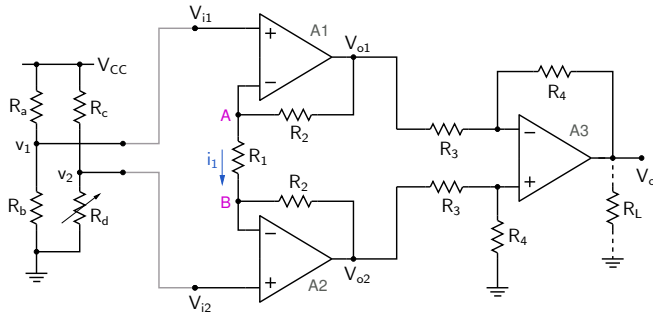
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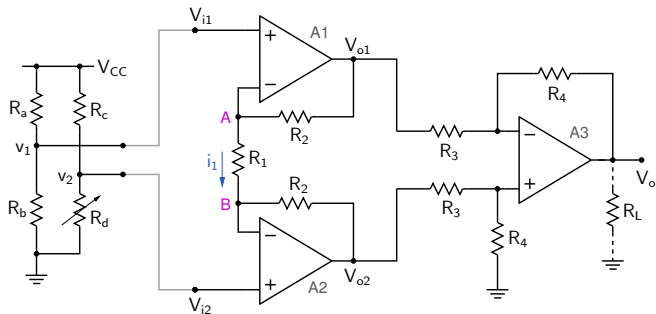


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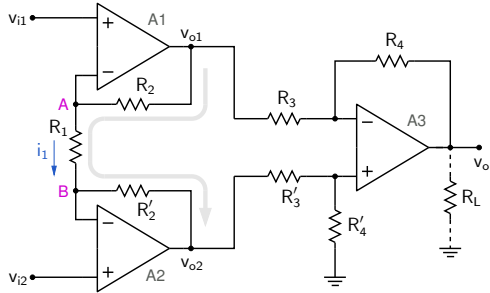


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As a result, the voltages v_1 and v_2 in the bridge circuit will remain essentially the same when the bridge circuit is connected to the instrumentation amplifier.

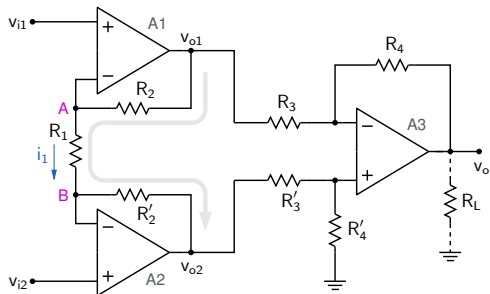
Instrumentation amplifier: common-mode rejection



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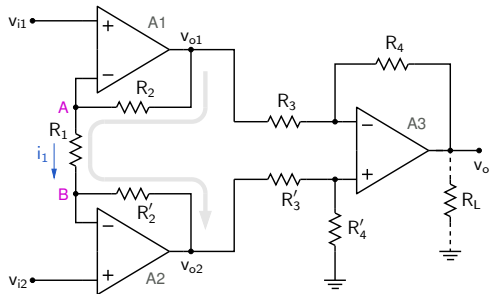


$$v_{i1} = v_c - (v_d/2)$$

$$v_{i2} = v_c + (v_d/2)$$

Note that v_{o1} serves as v_{i1} for the difference amplifier, and v_{o2} as v_{i2} . Let us find the differential-mode and common-mode components associated with v_{o1} and v_{o2} .

$$v'_{id} = v_{o2} - v_{o1}, \quad v'_{ic} = \frac{1}{2} (v_{o1} + v_{o2})$$



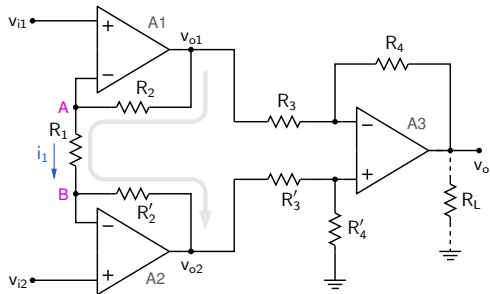
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$$v'_{id} = (R_2 + R'_2 + R_1) \frac{1}{R_1} \left[\left(v_c + \frac{v_d}{2} \right) - \left(v_c - \frac{v_d}{2} \right) \right] = \left(1 + \frac{R_2 + R'_2}{R_1} \right) v_d.$$



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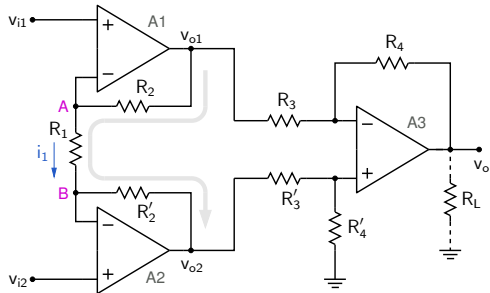
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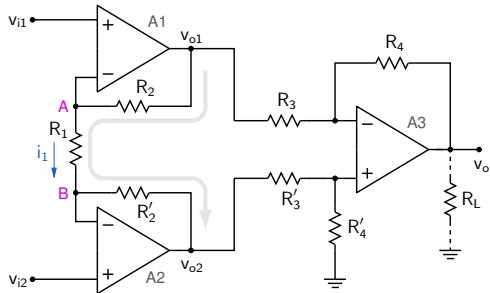
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→ v_d has got amplified but not v_c → overall improvement in CMRR.



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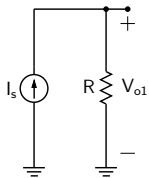
(Note that resistor mismatch in the second stage needs to be considered, but it will have a limited effect.)

Some circuits produce an output in the form of a current. It is convenient to convert this current into a voltage for further processing.

Current-to-voltage conversion

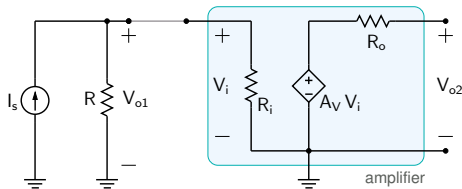
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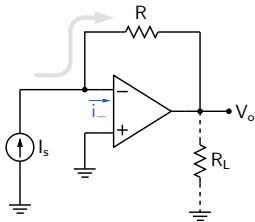
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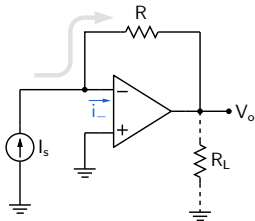


However, this simple approach will not work if the next stage in the circuit (such as an amplifier) has a finite R_i , since it will modify V_{o1} to $V_{o1} = I_s (R_i \parallel R)$, which is not desirable.

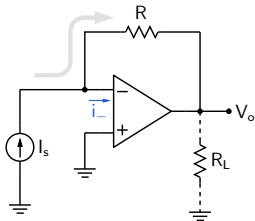
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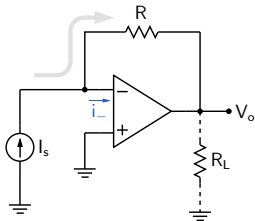


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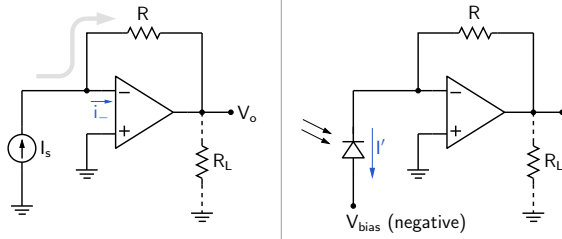
The output voltage is proportional to the source current, *irrespective* of the value of R_L , i.e., irrespective of the next stage.



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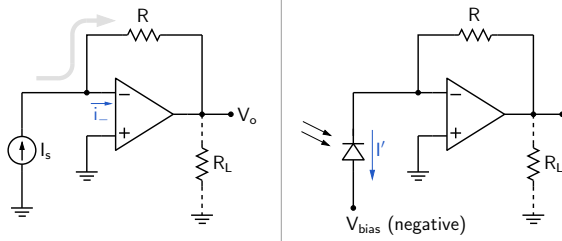
Example: a photocurrent detector.



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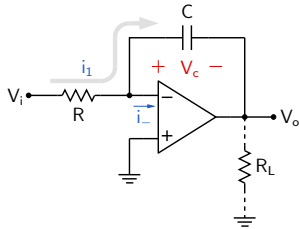
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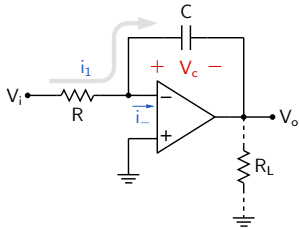
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$$V_o = I' R. \text{ (Note: The diode is under a reverse bias, with } V_n = 0 \text{ V and } V_p = V_{bias}.)$$

Op-amp circuits (linear region)

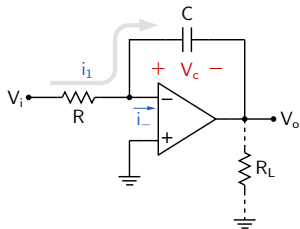


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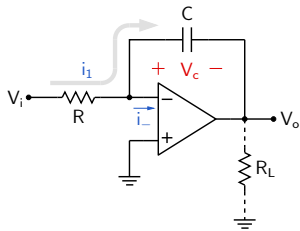


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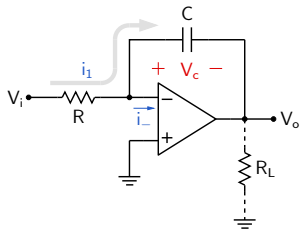
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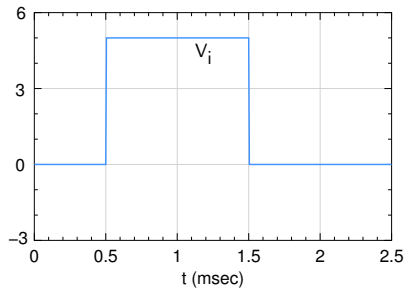
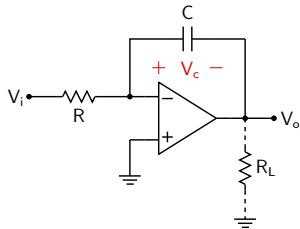
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$$V_o = -\frac{1}{RC} \int V_i dt$$

The circuit works as an integrator.

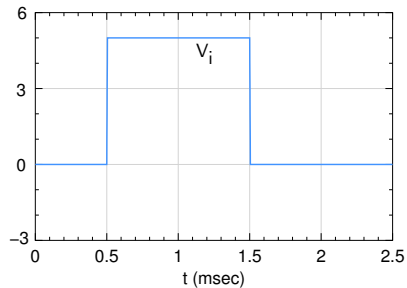
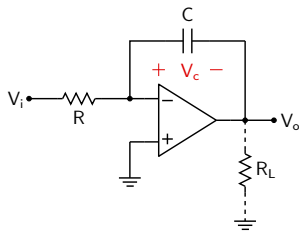
Integrator



Given: $R = 10 \text{ k}$, $C = 0.2 \mu\text{F}$.

If $V_o = 0 \text{ V}$ at $t = 0$, find $V_o(t)$ (Let $t_0 = 0.5 \text{ msec}$, $t_1 = 1.5 \text{ msec}$).

Integrator

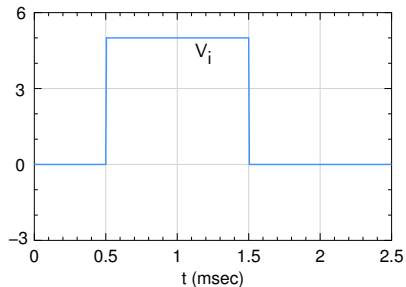
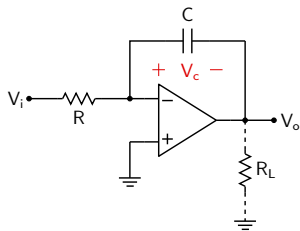


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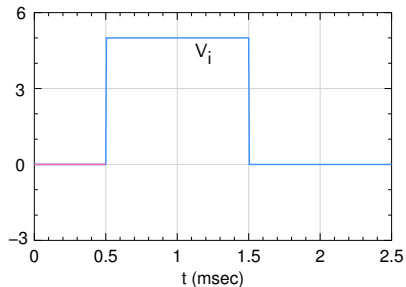
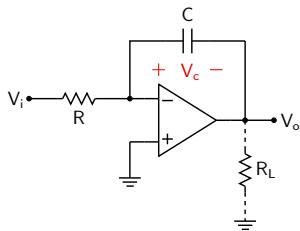
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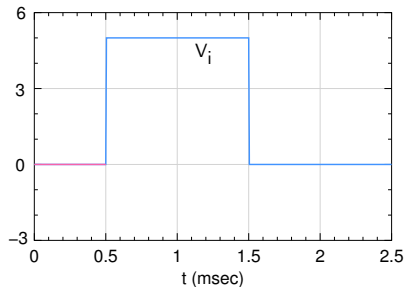
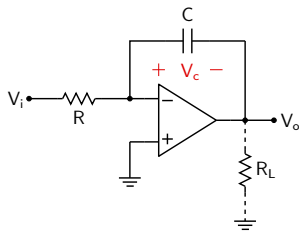
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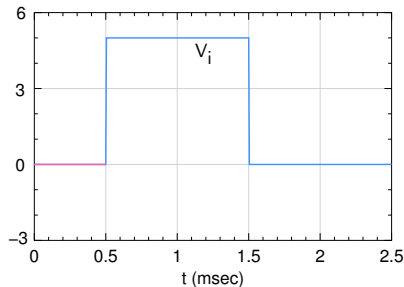
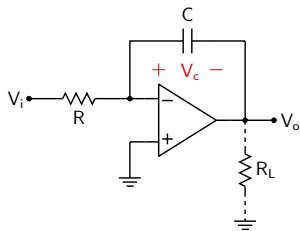
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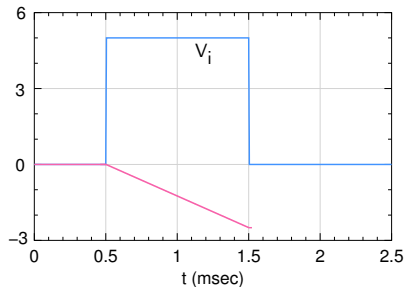
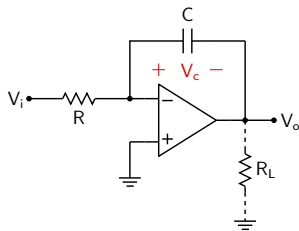
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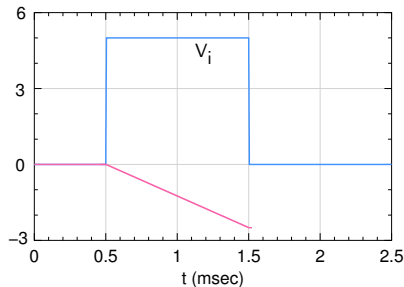
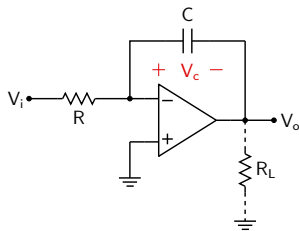
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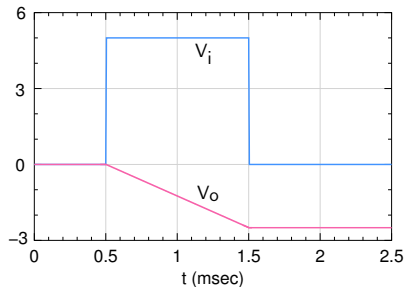
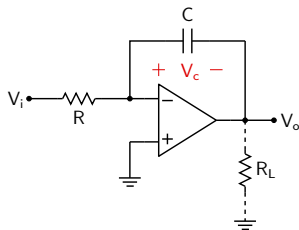
$$V_o = -\frac{1}{RC} \int V_i dt, \quad \tau \equiv RC = 2\text{ msec}.$$

* For $t < t_0$, $V_o(t) - V_o(0) = -\frac{1}{\tau} \int_0^t 0 dt' = 0 \rightarrow V_o(t) = V_o(0) = 0\text{ V}$

* For $t_0 < t < t_1$, $V_o(t) - V_o(t_0) = -\frac{1}{\tau} \int_{t_0}^t 5 dt' = -\frac{1}{\tau} 5(t - t_0) \rightarrow$ a straight line with a negative slope

$$\text{At } t = t_1, V(t_1) - V(t_0) = -\frac{1}{2\text{ msec}} 5\text{ V} \times 1\text{ msec} = -2.5\text{ V} \rightarrow V_o(t_1) = -2.5\text{ V}.$$

* For $t > t_1$, $V_o(t)$ remains constant since $V_i = 0\text{ V}$.



Given: $R = 10\text{ k}$, $C = 0.2\text{ }\mu\text{F}$.

If $V_o = 0\text{ V}$ at $t = 0$, find $V_o(t)$ (Let $t_0 = 0.5\text{ msec}$, $t_1 = 1.5\text{ msec}$).

$$V_o = -\frac{1}{RC} \int V_i dt, \quad \tau \equiv RC = 2\text{ msec}.$$

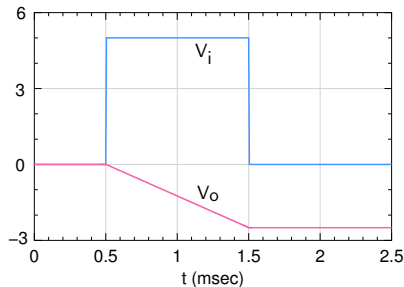
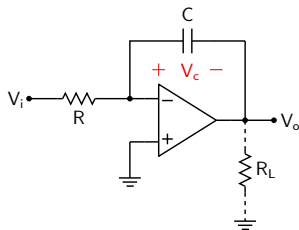
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Integrator



Given: $R = 10\text{ k}$, $C = 0.2\text{ }\mu\text{F}$.

If $V_o = 0\text{ V}$ at $t = 0$, find $V_o(t)$ (Let $t_0 = 0.5\text{ msec}$, $t_1 = 1.5\text{ msec}$).

$$V_o = -\frac{1}{RC} \int V_i dt, \quad \tau \equiv RC = 2\text{ msec}.$$

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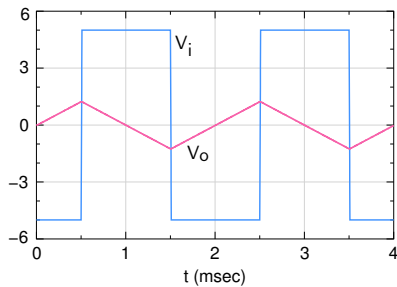
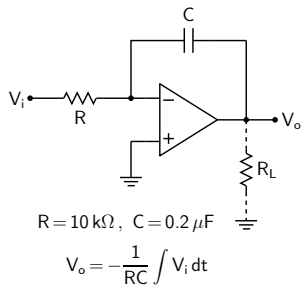
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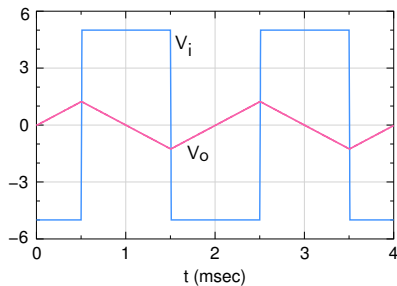
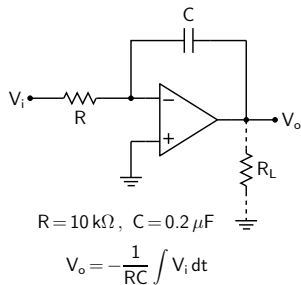
* For $t > t_1$, $V_o(t)$ remains constant since $V_i = 0\text{ V}$.

SEQUEL file: ee101_integrator_1.sqproj

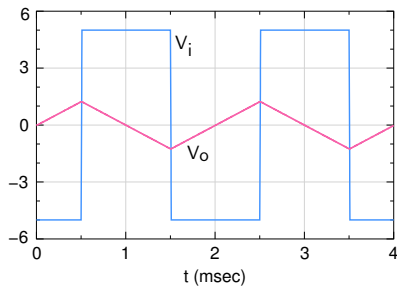
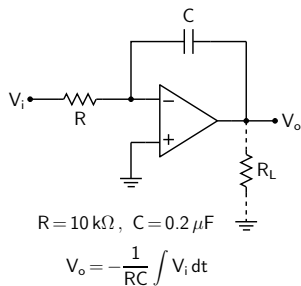
Integrator



- * An integrator can be used to convert a square wave to a triangle wave.



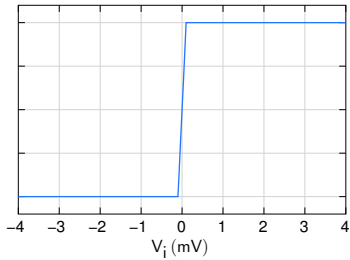
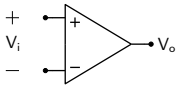
- * An integrator can be used to convert a square wave to a triangle wave.
- * In practice, the circuit needs a small modification, as discussed in the following.



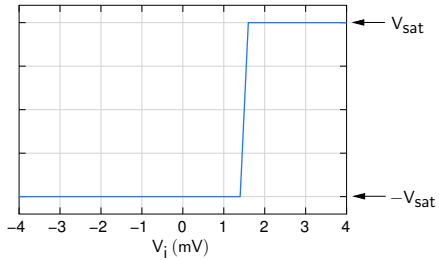
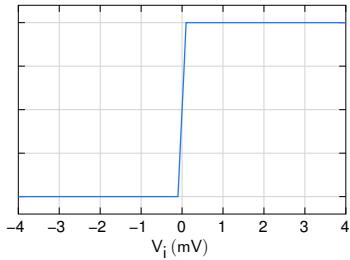
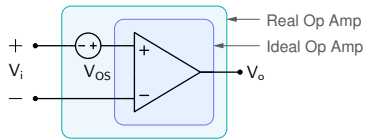
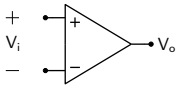
- * An integrator can be used to convert a square wave to a triangle wave.
- * In practice, the circuit needs a small modification, as discussed in the following.

SEQUEL file: ee101_integrator_2.sqproj

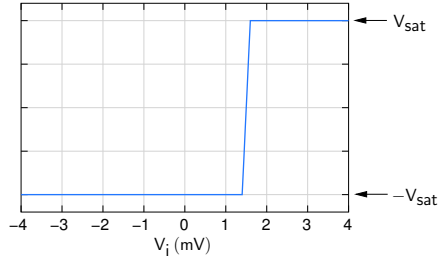
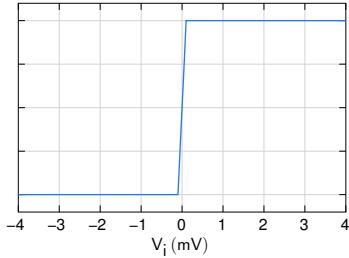
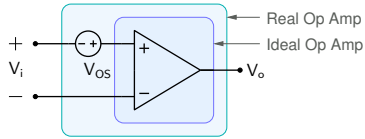
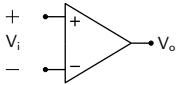
Practical op-amps: Offset voltage



Practical op-amps: Offset voltage

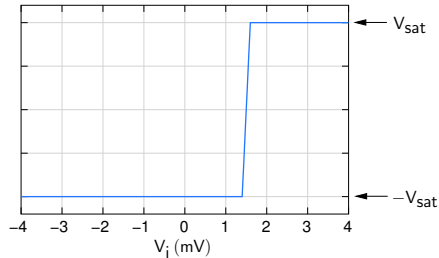
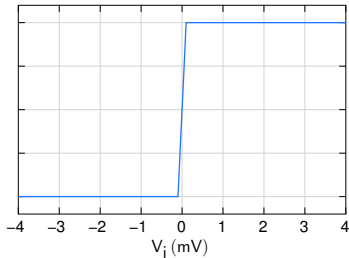
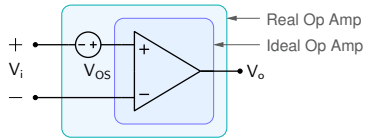
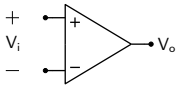


Practical op-amps: Offset voltage



For the real op-amp, $V_o = A_V((V_+ + V_{os}) - V_-)$.

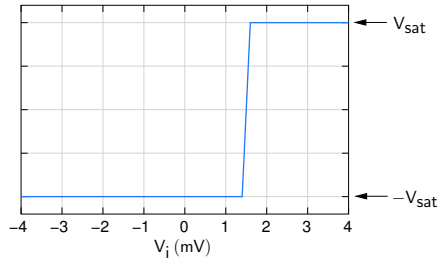
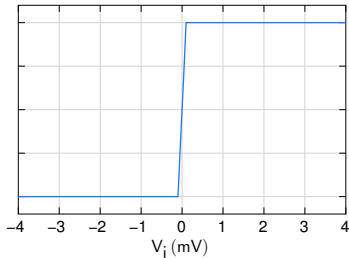
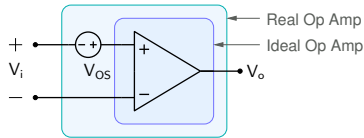
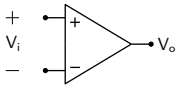
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For $V_o = 0$ V, $V_+ + V_{OS} - V_- = 0 \rightarrow V_i = V_+ - V_- = -V_{OS}$.

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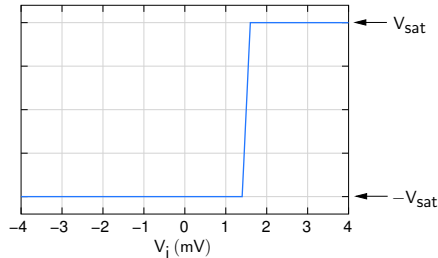
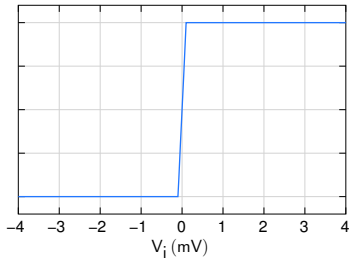
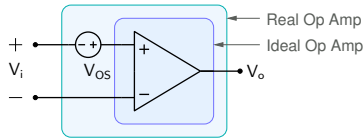
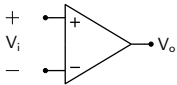


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V_o versus V_i curve gets shifted (Note: V_{OS} is negative in the above example).

Practical op-amps: Offset voltage



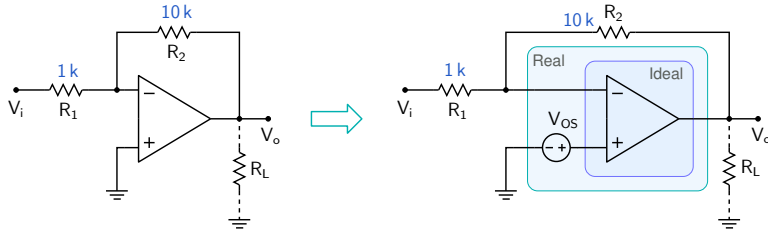
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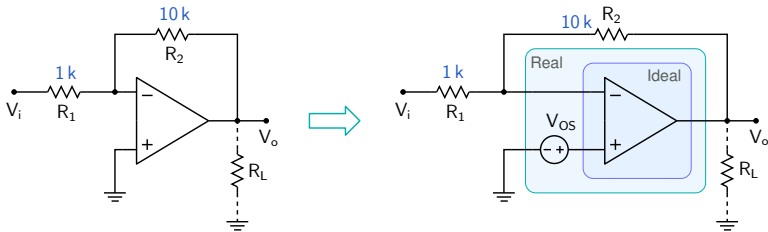
V_o versus V_i curve gets shifted (Note: V_{OS} is negative in the above example).

741: $-6 \text{ mV} < V_{OS} < 6 \text{ mV}$, OP-77: $-50 \mu\text{V} < V_{OS} < 50 \mu\text{V}$.

Effect of V_{OS} : inverting amplifier

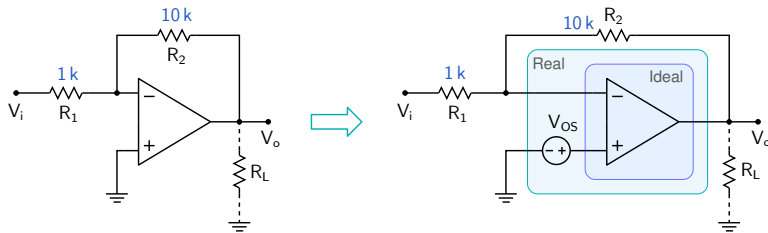


Effect of V_{OS} : inverting amplifier



By superposition, $V_o = -\frac{R_2}{R_1} V_i + V_{OS} \left(1 + \frac{R_2}{R_1}\right).$

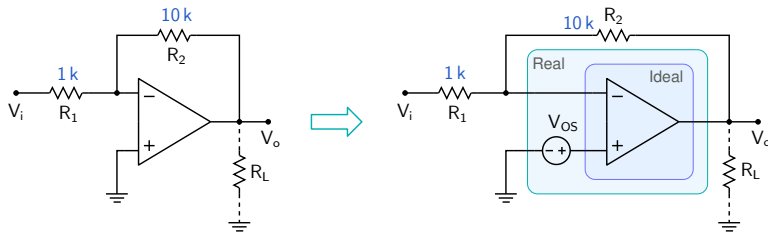
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Effect of V_{OS} : inverting amplifier

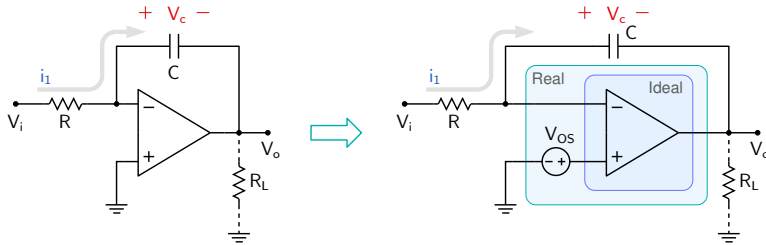


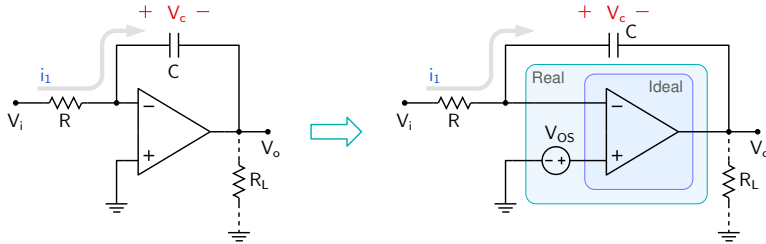
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i.e., a DC shift of 22 mV .

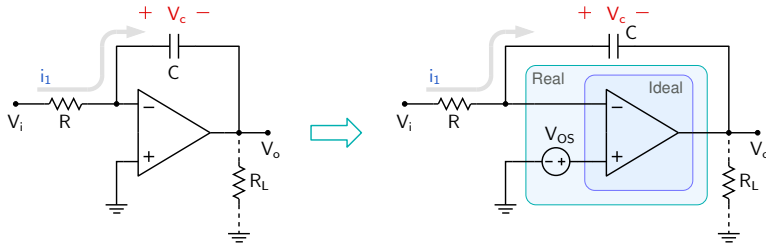
Effect of V_{OS} : integrator





$$V_- \approx V_+ = V_{OS} \rightarrow i_1 = \frac{1}{R}(V_i - V_{OS}) = C \frac{dV_c}{dt}.$$

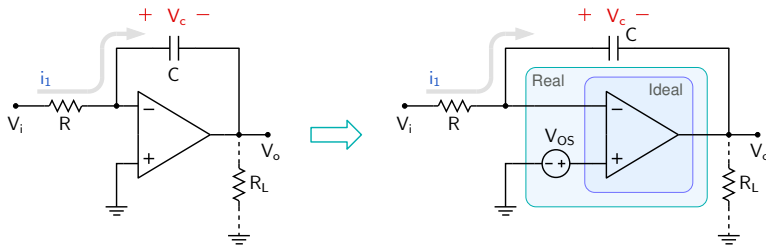
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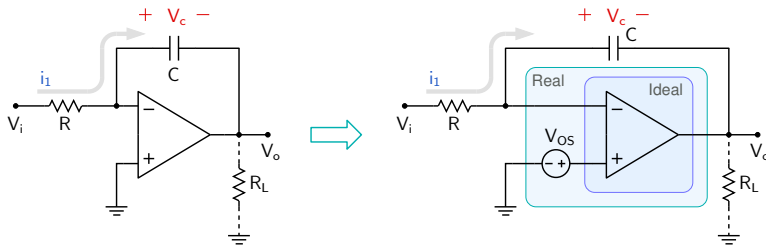


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Even with $V_i = 0$ V, V_c will keep rising or falling (depending on the sign of V_{OS}).

Eventually, the Op Amp will be driven into saturation.



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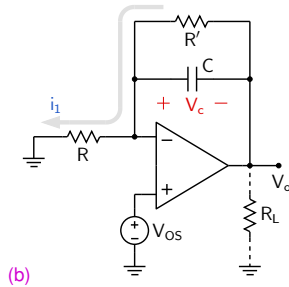
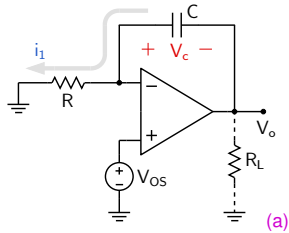
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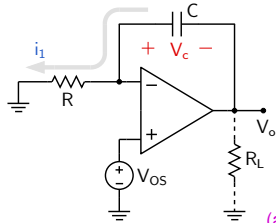
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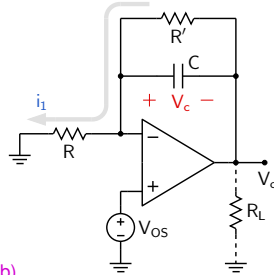
→ need to address this issue!

Effect of V_{OS} : integrator with $V_i = 0$





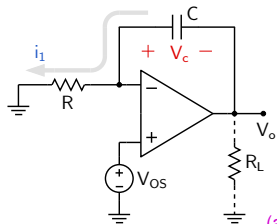
(a)



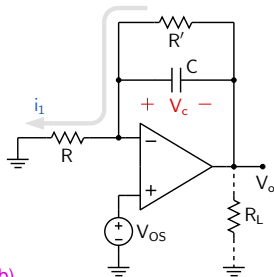
(b)

$$(a) \quad i_1 = \frac{V_{OS}}{R} = -C \frac{dV_c}{dt}$$

$$V_c = -\frac{1}{RC} \int V_{OS} dt \rightarrow \text{op-amp saturates.}$$



(a)



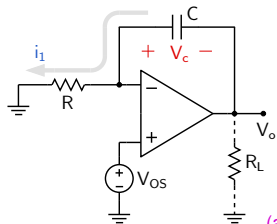
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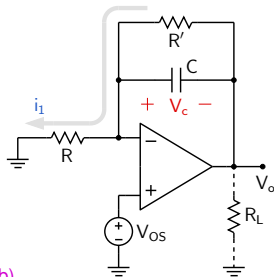
$$V_c = -\frac{1}{RC} \int V_{OS} dt \rightarrow \text{op-amp saturates.}$$

(b) There is a DC path for the current.

$$\rightarrow V_o = \left(1 + \frac{R'}{R}\right) V_{OS}.$$



(a)



(b)

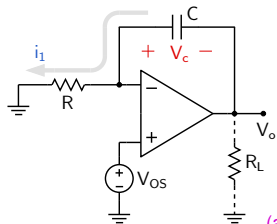
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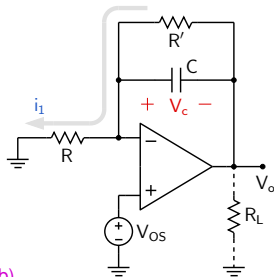
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R' should be small enough to have a negligible effect on V_o .



(a)



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$$(a) \quad i_1 = \frac{V_{OS}}{R} = -C \frac{dV_c}{dt}$$

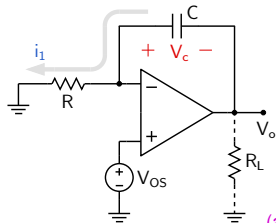
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(b) There is a DC path for the current.

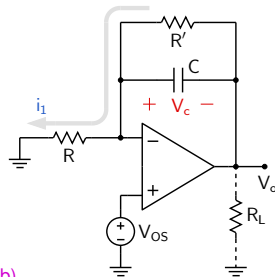
$$\rightarrow V_o = \left(1 + \frac{R'}{R}\right) V_{OS}.$$

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However, R' must be large enough to ensure that the circuit still functions as an integrator.



(a)



(b)

$$(a) \quad i_1 = \frac{V_{OS}}{R} = -C \frac{dV_c}{dt}$$

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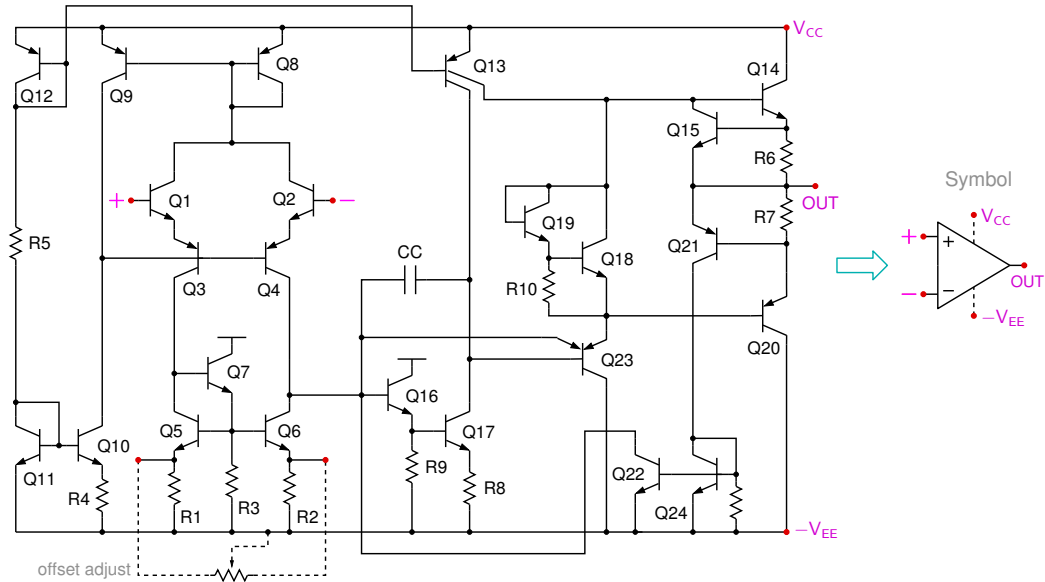
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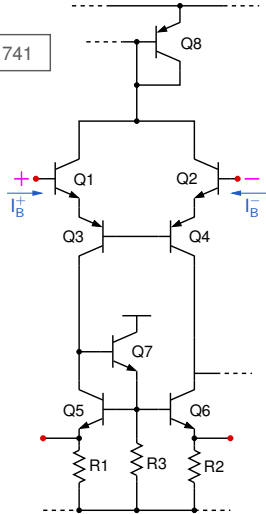
$\rightarrow R' \gg 1/\omega C$ at the frequency of interest.

Op-amp 741: offset null



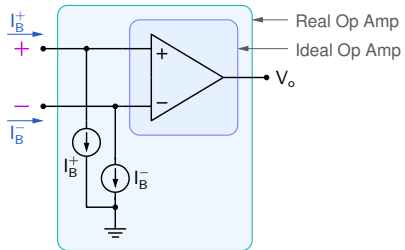
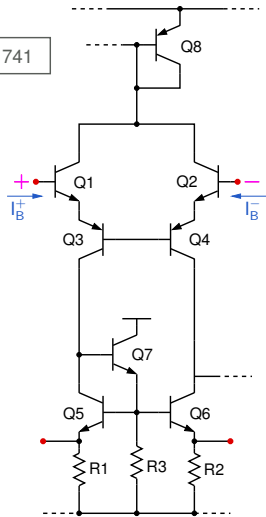
Input bias currents

741



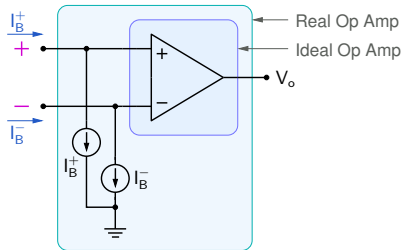
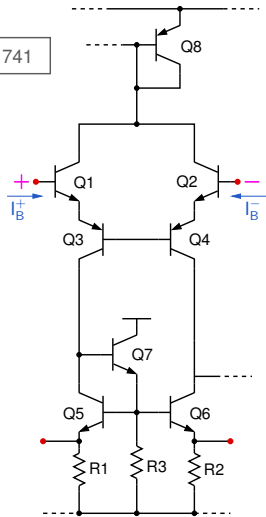
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741



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741



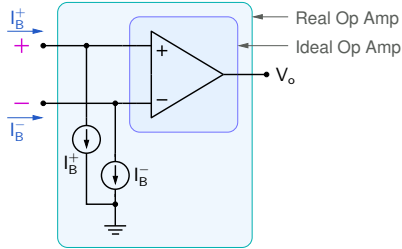
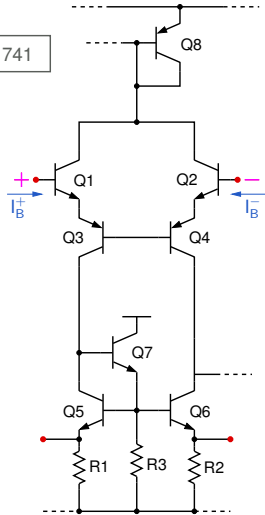
I_B^+ and I_B^- are generally not equal.

$|I_B^+ - I_B^-|$: "offset current" (I_{OS})

$(I_B^+ + I_B^-)/2$: "bias current" (I_B)

Input bias currents

741

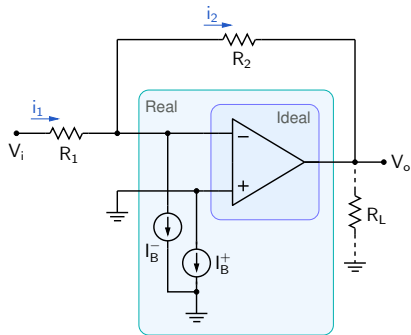


Typical values

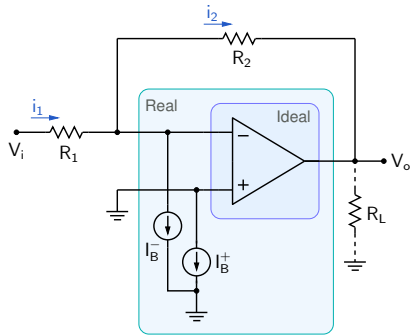
Op-Amp	I_B	I_{OS}	V_{OS}	Type
741	80 nA	20 nA	1 mV	BJT input
OP77	1.2 nA	0.3 nA	$10 \mu V$	BJT input
411	50 pA	25 pA	0.8 mV	FET input

I_B^+ and I_B^- are generally not equal.
 $|I_B^+ - I_B^-|$: "offset current" (I_{OS})
 $(I_B^+ + I_B^-)/2$: "bias current" (I_B)

Effect of bias currents: inverting amplifier

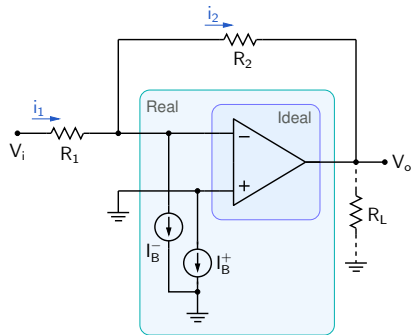


Effect of bias currents: inverting amplifier



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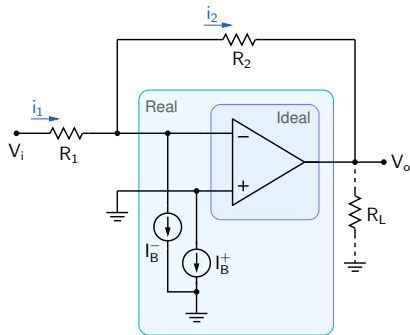
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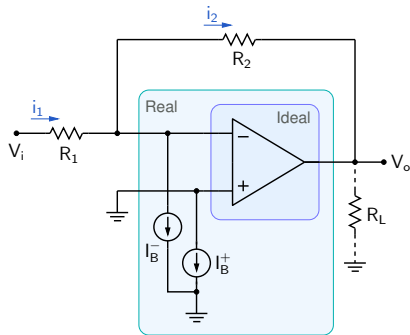


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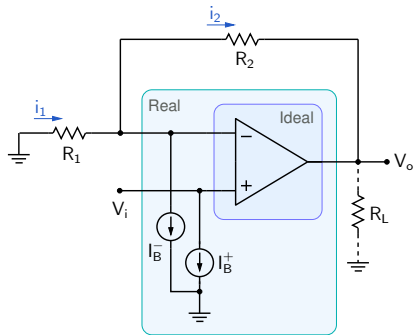
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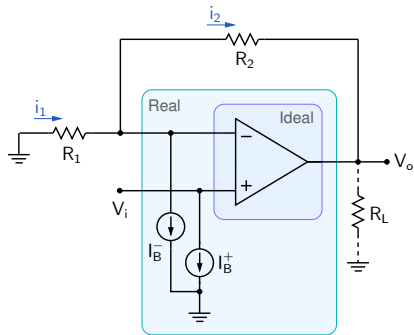
i.e., the bias current causes a DC shift in V_o .

$$\text{For } I_B^- = 80\text{ nA}, R_2 = 10\text{ k}, \Delta V_o = 0.8\text{ mV}.$$

Effect of bias currents: non-inverting amplifier

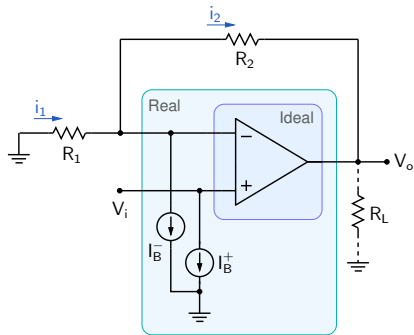


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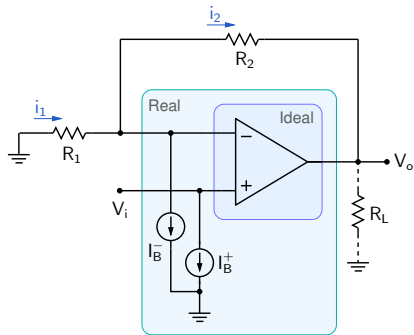
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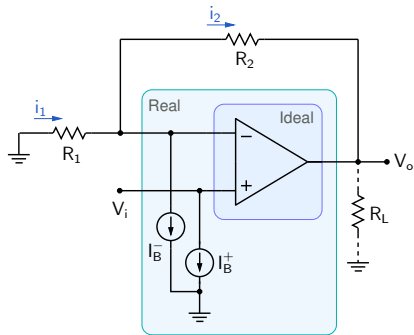


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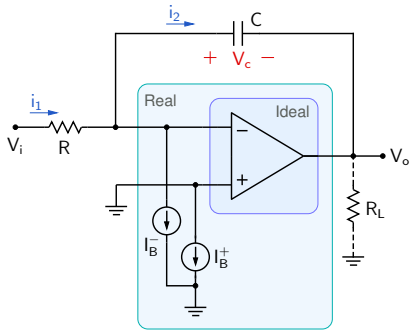
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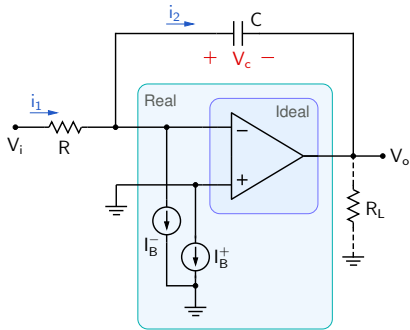
$$V_o = V_- - i_2 R_2 = V_i - \left(-\frac{V_i}{R_1} - I_B^- \right) R_2 = V_i \left(1 + \frac{R_2}{R_1} \right) + I_B^- R_2.$$

→ Again, a DC shift ΔV_o .

Effect of bias currents: integrator

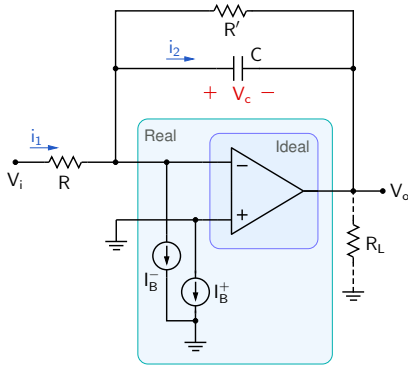


Effect of bias currents: integrator



Even with $V_i = 0 \text{ V}$, $V_c = \frac{1}{C} \int -I_B^- dt$ will drive the op-amp into saturation.

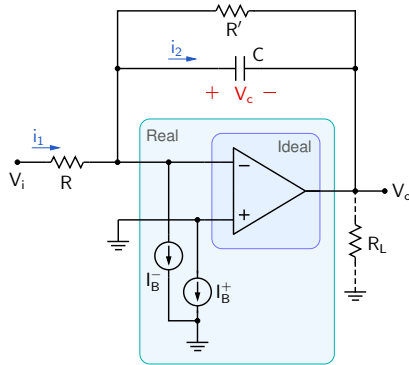
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Connecting R' across C provides a DC path for the current, and results in a DC shift $\Delta V_o = I_B^- R'$ at the output.

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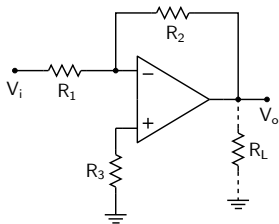
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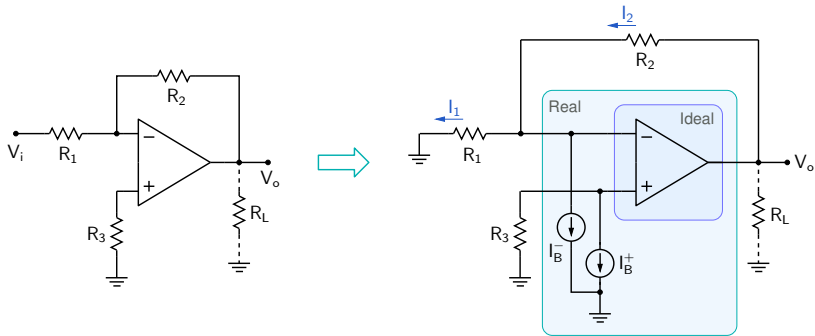
As we have discussed earlier, R' should be small enough to have a negligible effect on V_o .

However, R' must be large enough to ensure that the circuit still functions as an integrator.

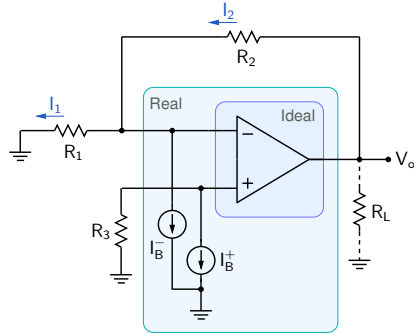
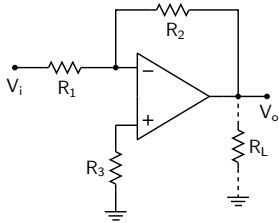
Effect of bias currents: inverting amplifier



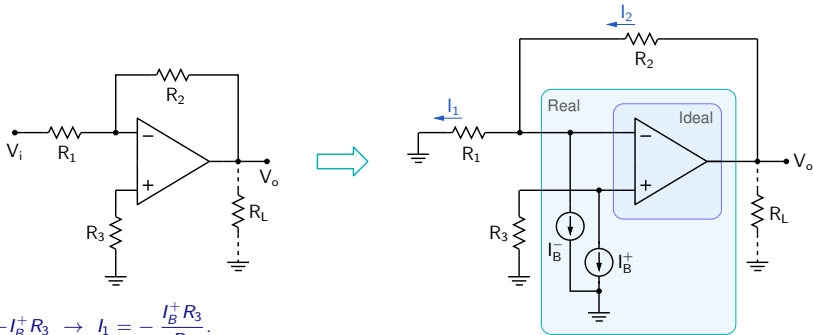
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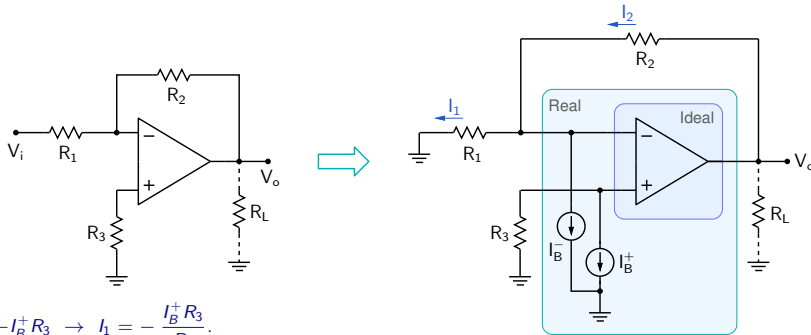


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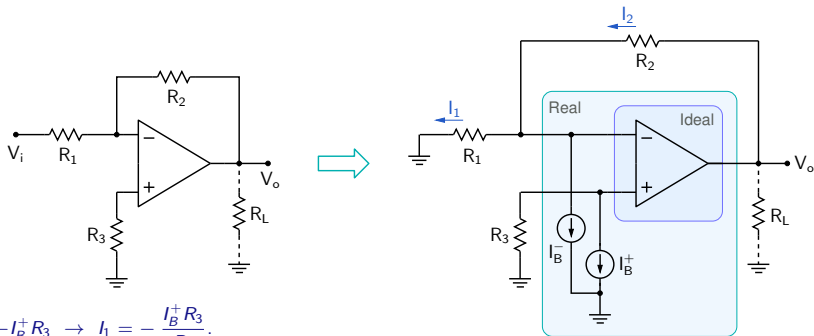
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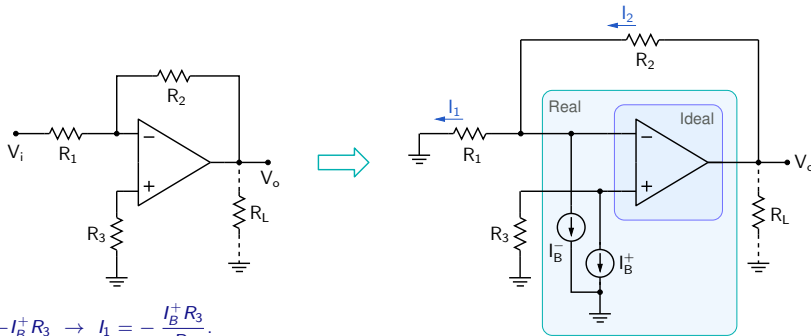


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$$V_o = -R_3 \left(1 + \frac{R_2}{R_1} \right) \left(I_B + \frac{I_{OS}}{2} \right) + R_2 \left(I_B - \frac{I_{OS}}{2} \right) = \left(1 + \frac{R_2}{R_1} \right) \left\{ [(R_1 \parallel R_2) - R_3] I_B - [(R_1 \parallel R_2) + R_3] \frac{I_{OS}}{2} \right\}$$



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The first term can be made zero if we select $R_3 = R_1 \parallel R_2$.

$\rightarrow V_o = -R_2 I_{OS}$ (Compare with $V_o = R_2 I_B^-$ when R_3 is not connected.)

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- * A DC shift is a matter of concern when the output is expected to be a DC (or slowly varying) quantity, e.g., a temperature sensor or a strain gauge circuit.

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- * The unit Bel turned out to be too large in practice \rightarrow deciBel (i.e., one tenth of a Bel).

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For example, if $P_1 = 20 \text{ W}$ and $P_{\text{ref}} = 1 \text{ W}$,

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- * The gain of a voltage-to-voltage amplifier is often expressed in dB. In that case, the ratio V_o^2/V_i^2 is considered (since $P \propto V^2$ or $P \propto I^2$ for a resistor).

$$A_V \text{ in dB} = 10 \log_{10} |V_o/V_i|^2 = 20 \log_{10} |V_o/V_i|,$$

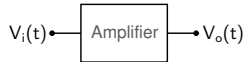
- * “dBm” is a related unit used to describe voltages with a reference of 1 mV.

$$\text{For example, } 2.2 \text{ V: } 20 \log_{10} \left(\frac{2.2 \text{ V}}{1 \text{ mV}} \right) = 6.85 \text{ dBm}.$$

Example



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Let \hat{V}_i and \hat{V}_o be the input and output amplitudes.

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Method 2:

$$A_V = 36.3 \text{ dB}$$

$$\rightarrow 20 \log_{10} A_V = 36.3 \rightarrow A_V = 65.$$

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Method 1:

$$\hat{V}_i = 20 \log_{10} \left(\frac{2.5 \text{ mV}}{1 \text{ mV}} \right) = 7.96 \text{ dBm}.$$

$$\begin{aligned} 20 \log_{10} \left(\frac{\hat{V}_o}{1 \text{ mV}} \right) &= 20 \log_{10} \left(\frac{A_V \hat{V}_i}{1 \text{ mV}} \right) \\ &= 20 \log_{10} A_V + 20 \log_{10} \left(\frac{\hat{V}_i}{1 \text{ mV}} \right) \end{aligned}$$

$$\hat{V}_o = 36.3 + 7.96 = 44.22 \text{ dBm}.$$

$$\text{Since } \hat{V}_o \text{ (dBm)} = 20 \log_{10} \left(\frac{\hat{V}_o}{1 \text{ mV}} \right),$$

$$\hat{V}_o = 10^x \times 1 \text{ mV}, \text{ where } x = \frac{1}{20} \hat{V}_o \text{ (in dBm)}$$

$$\rightarrow \hat{V}_o = 162.5 \text{ mV}.$$

Method 2:

$$A_V = 36.3 \text{ dB}$$

$$\rightarrow 20 \log_{10} A_V = 36.3 \rightarrow A_V = 65.$$

$$\hat{V}_o = A_V \times \hat{V}_i = 65 \times 2.5 \text{ mV} = 162.5 \text{ mV}.$$

Example



Let \hat{V}_i and \hat{V}_o be the input and output amplitudes.

If $\hat{V}_i = 2.5 \text{ mV}$ and $A_V = 36.3 \text{ dB}$, compute \hat{V}_o in dBm and mV.

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$$\hat{V}_i = 20 \log_{10} \left(\frac{2.5 \text{ mV}}{1 \text{ mV}} \right) = 7.96 \text{ dBm.}$$

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$$\hat{V}_o = A_V \times \hat{V}_i = 65 \times 2.5 \text{ mV} = 162.5 \text{ mV.}$$

$$\hat{V}_o \text{ in dBm} = 20 \log_{10} \left(\frac{162.5 \text{ mV}}{1 \text{ mV}} \right) = 44.2 \text{ dBm.}$$

- * When sound intensity is specified in dB, the reference pressure is $P_{\text{ref}} = 20 \mu\text{Pa}$ (our hearing threshold).
If the pressure corresponding to the sound being measured is P , we say that it is $20 \log(P/P_{\text{ref}})$ dB.

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- * Some interesting numbers:

mosquito 3 m away

0 dB

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whisper

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loud thunder	110 dB

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loud thunder	110 dB
loudest sound human ear can tolerate	120 dB

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windows break	163 dB

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- * Permissible day-time dB levels in India (from MoEF, Govt of India)

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Industrial area	75 dB
-----------------	-------

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Industrial area	75 dB
Commercial area	65 dB

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Industrial area	75 dB
Commercial area	65 dB
Residential area	55 dB

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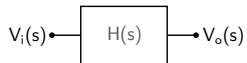
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loud thunder	110 dB
loudest sound human ear can tolerate	120 dB
windows break	163 dB

- * Permissible day-time dB levels in India (from MoEF, Govt of India)

Industrial area	75 dB
Commercial area	65 dB
Residential area	55 dB
Silence zone	50 dB

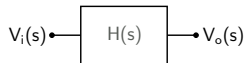




- * The transfer function of a circuit such as an amplifier or a filter is given by,

$$H(s) = V_o(s)/V_i(s), \quad s = j\omega.$$

$$\text{e.g., } H(s) = \frac{K}{1 + s\tau} = \frac{K}{1 + j\omega\tau}$$

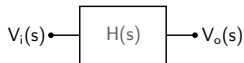


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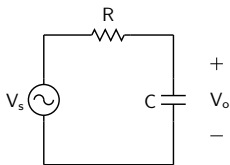
$$\text{e.g., } H(s) = \frac{K}{1 + s\tau} = \frac{K}{1 + j\omega\tau}$$

- * $H(j\omega)$ is a complex number, and a complete description of $H(j\omega)$ involves
 - (a) a plot of $|H(j\omega)|$ versus ω (Bode magnitude plot),
 - (b) a plot of $\angle H(j\omega)$ versus ω (Bode phase plot).



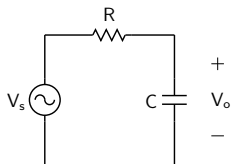
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- * Bode gave simple rules which allow construction of the above plots in an approximate (asymptotic) manner.

A simple transfer function



$$V_o = \frac{(1/sC)}{R + (1/sC)} V_s,$$
$$\rightarrow H(s) = \frac{1}{1+sRC} = \frac{1}{1 + (j\omega/\omega_0)},$$
$$\omega_0 = \frac{1}{RC}.$$

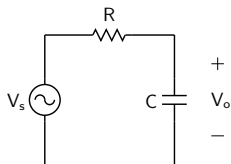
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* The circuit behaves like a low-pass filter.

A simple transfer function

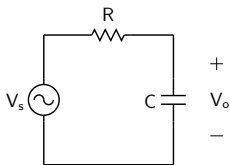


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For $\omega \ll \omega_0$, $\frac{\omega}{\omega_0} \ll 1$, $|H(j\omega)| \rightarrow 1$.

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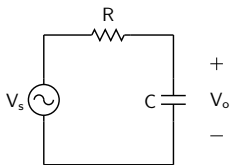
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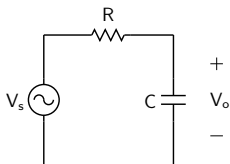
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$$|H(j\omega)| = \frac{1}{\sqrt{1 + (\omega/\omega_0)^2}}, \quad \angle H(j\omega) = -\tan^{-1} \left(\frac{\omega}{\omega_0} \right).$$

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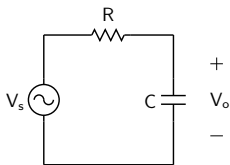
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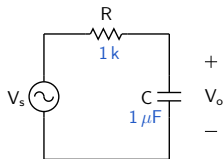
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- * We are generally interested in a large variation in ω (several orders), and its effect on $|H|$ and $\angle H$.
- * The magnitude ($|H|$) varies by orders of magnitude as well.
The phase ($\angle H$) varies from 0 (for $\omega \ll \omega_0$) to $-\pi/2$ (for $\omega \gg \omega_0$).

A simple transfer function: magnitude



$$V_o = \frac{(1/sC)}{R + (1/sC)} V_s,$$

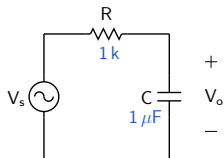
$$\rightarrow H(s) = \frac{1}{1+sRC} = \frac{1}{1+(j\omega/\omega_0)},$$

$$\omega_0 = \frac{1}{RC} = 10^3 \text{ rad/s}.$$

$$|H(j\omega)| = \frac{1}{\sqrt{1+(\omega/\omega_0)^2}}$$

$$\angle(H(j\omega)) = -\tan^{-1}\left(\frac{\omega}{\omega_0}\right)$$

A simple transfer function: magnitude



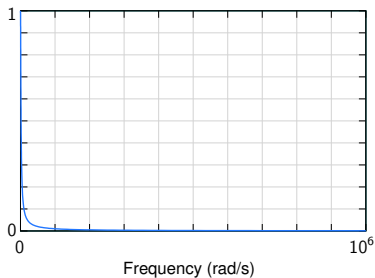
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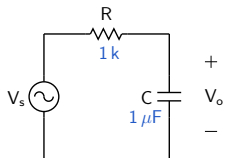
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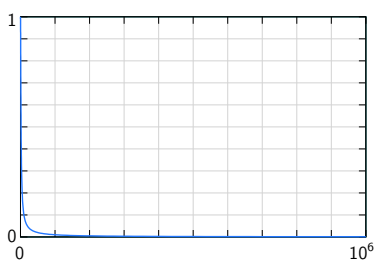
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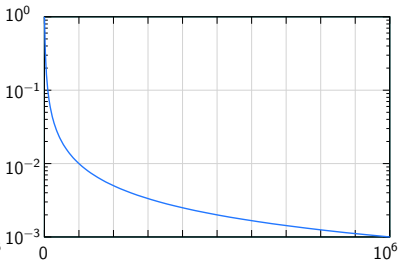
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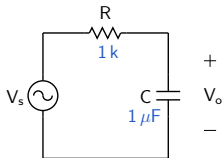


Frequency (rad/s)



Frequency (rad/s)

A simple transfer function: magnitude



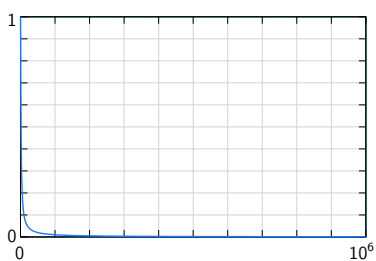
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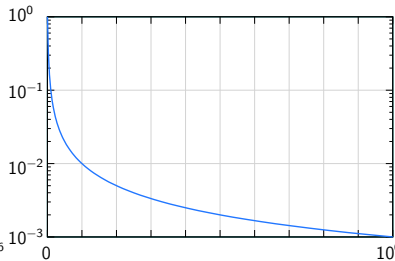
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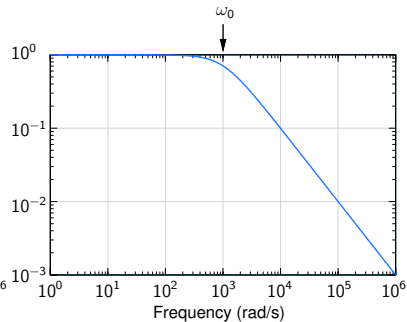
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Frequency (rad/s)

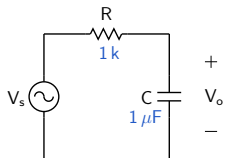


Frequency (rad/s)



Frequency (rad/s)

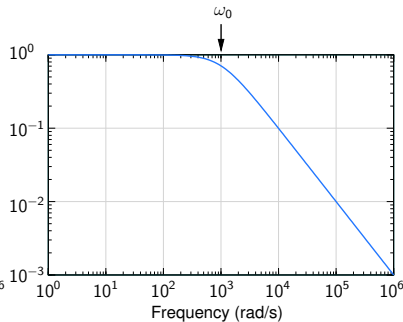
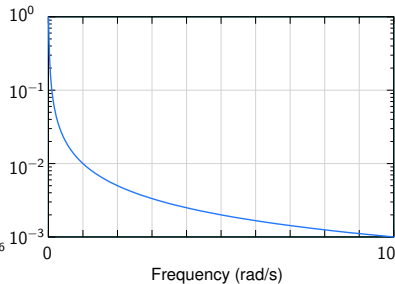
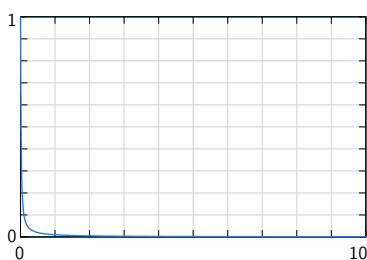
A simple transfer function: magnitude



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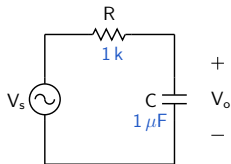
$$|H(j\omega)| = \frac{1}{\sqrt{1+(\omega/\omega_0)^2}}$$

$$\angle(H(j\omega)) = -\tan^{-1}\left(\frac{\omega}{\omega_0}\right)$$



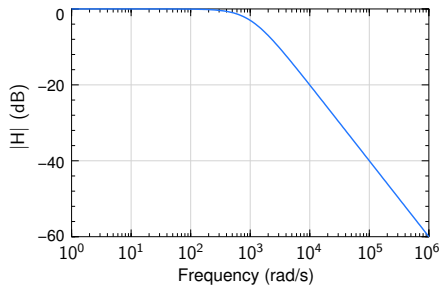
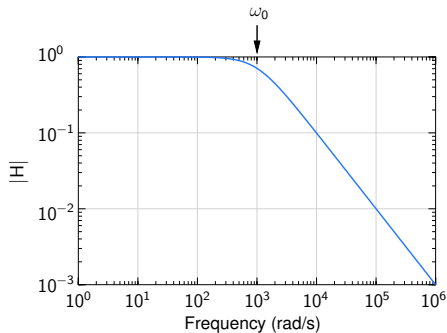
Since ω and $|H(j\omega)|$ vary by several orders of magnitude, a linear ω - or $|H|$ -axis is not appropriate $\rightarrow \log |H|$ is plotted against $\log \omega$.

A simple transfer function: magnitude

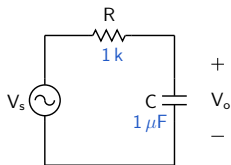


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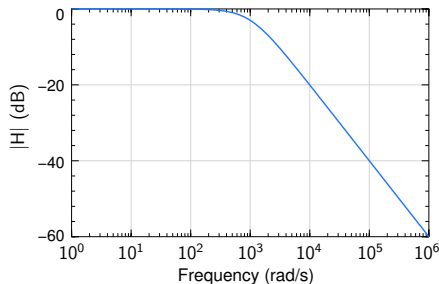
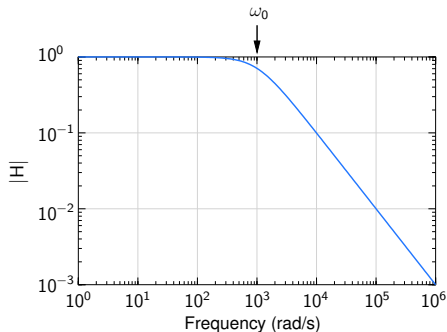


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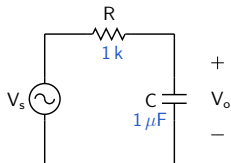
$$|H(j\omega)| = \frac{1}{\sqrt{1+(\omega/\omega_0)^2}}$$
$$\angle(H(j\omega)) = -\tan^{-1}\left(\frac{\omega}{\omega_0}\right)$$



Note that the *shape* of the plot does not change.

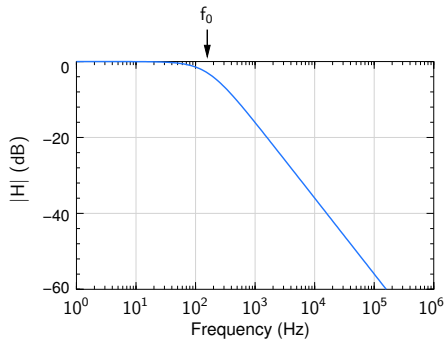
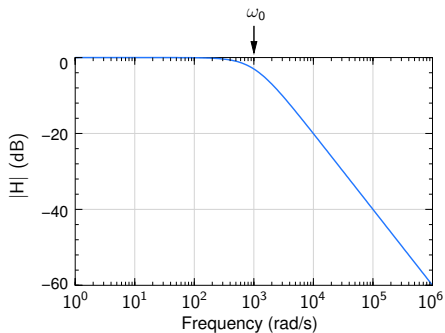
$|H| \text{ (dB)} = 20 \log |H|$ is simply a scaled version of $\log |H|$.

A simple transfer function: magnitude

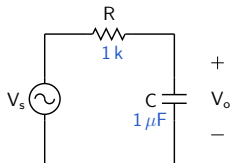


$$V_o = \frac{(1/sC)}{R + (1/sC)} V_s,$$
$$\rightarrow H(s) = \frac{1}{1 + sRC} = \frac{1}{1 + (j\omega/\omega_0)},$$
$$\omega_0 = \frac{1}{RC} = 10^3 \text{ rad/s}, f_0 = 159 \text{ Hz}.$$

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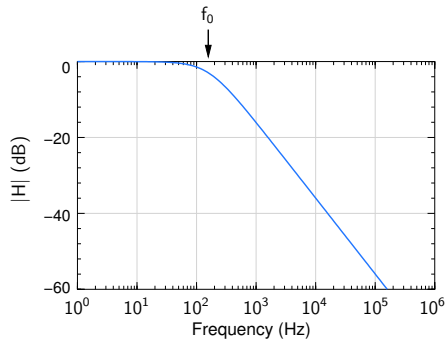
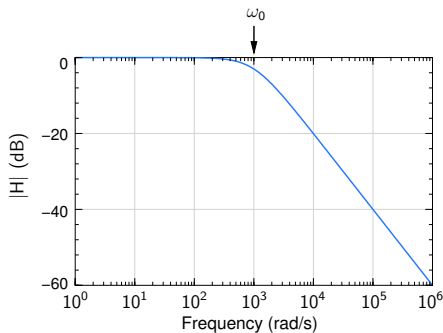


A simple transfer function: magnitude



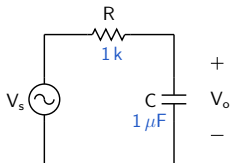
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Since $\omega = 2\pi f$, $\log \omega = \log(2\pi) + \log f$ which causes a shift in the x direction, but the *shape* of the plot does not change.

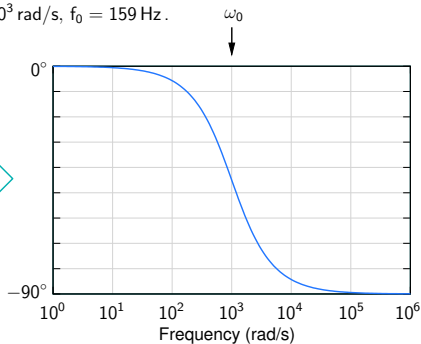
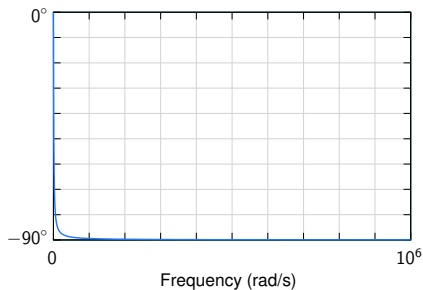
A simple transfer function: phase



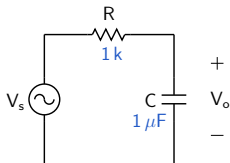
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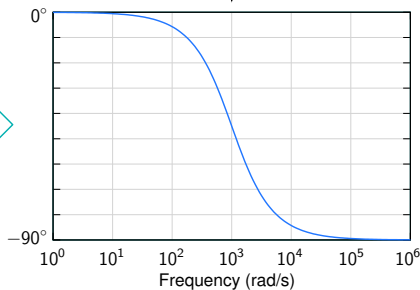
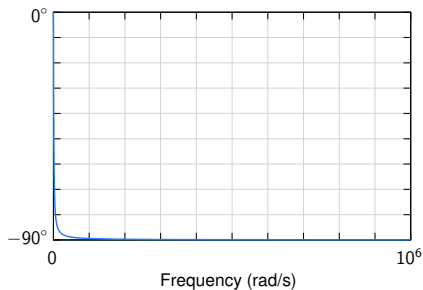
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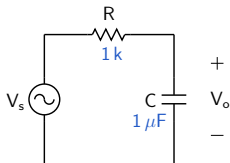
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- * Since $\angle H = -\tan^{-1}(\omega/\omega_0)$ varies in a limited range (0° to -90° in this example), a linear axis is appropriate for $\angle H$.

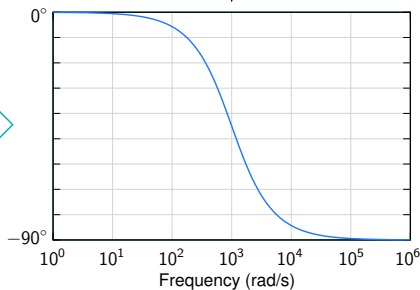
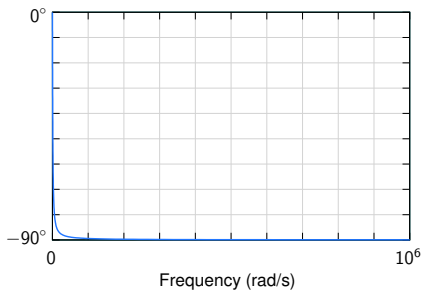
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- * Since $\angle H = -\tan^{-1}(\omega/\omega_0)$ varies in a limited range (0° to -90° in this example), a linear axis is appropriate for $\angle H$.
- * As in the magnitude plot, we use a log axis for ω , since we are interested in a wide range of ω .

Consider $H(s) = \frac{K (1 + s/z_1)(1 + s/z_2) \cdots (1 + s/z_M)}{(1 + s/p_1)(1 + s/p_2) \cdots (1 + s/p_N)}$.

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$-z_1, -z_2, \dots$ are called the “zeros” of $H(s)$.

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We will assume, for simplicity, that the zeros and poles are real and distinct.

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Construction of Bode plots involves

- (a) computing approximate contribution of each pole/zero as a function of ω .

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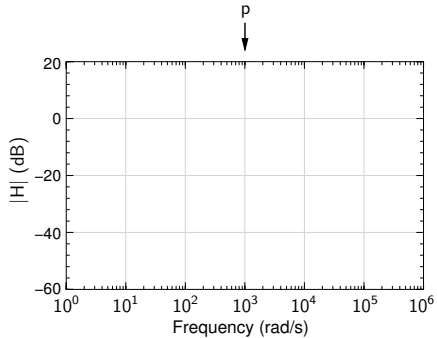
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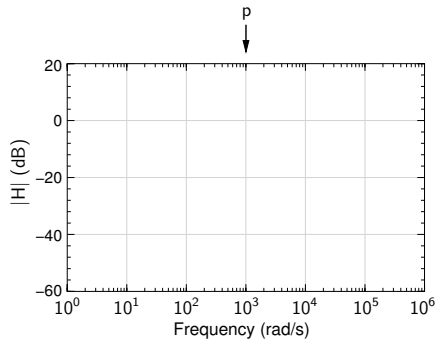
- (a) computing approximate contribution of each pole/zero as a function of ω .
- (b) combining the various contributions to obtain $|H|$ and $\angle H$ versus ω .

Contribution of a pole: magnitude



$$\text{Consider } H(s) = \frac{1}{1 + s/p} \rightarrow H(j\omega) = \frac{1}{1 + j(\omega/p)}, |H(j\omega)| = \frac{1}{\sqrt{1 + (\omega/p)^2}}.$$

In this example, $p = 10^3$ rad/s.

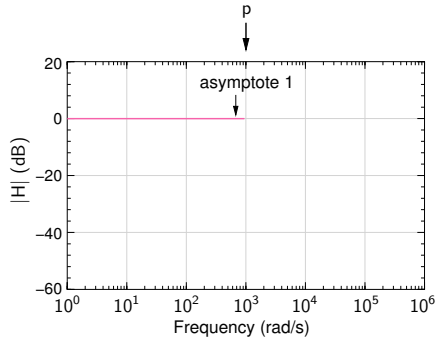


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$\omega \ll p$: $|H| \rightarrow 1$, $20 \log |H| = 0$ dB.



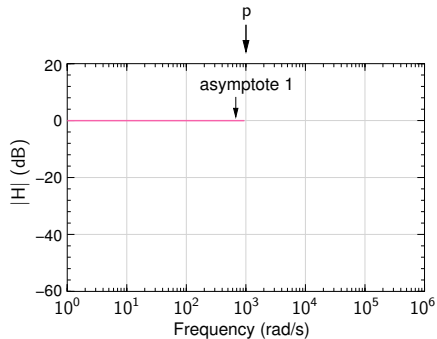
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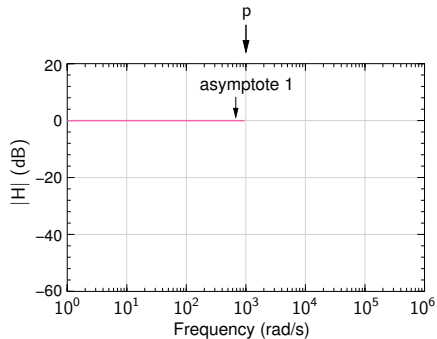
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Asymptote 2:

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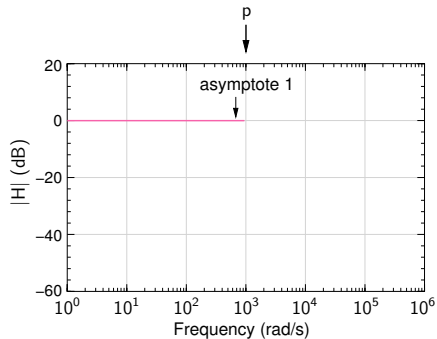
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Consider two values of ω : ω_1 and $10\omega_1$.

$$|H|_1 = 20 \log p - 20 \log \omega_1 \text{ (dB)}$$

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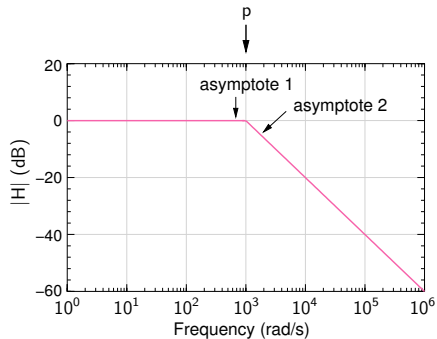
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$\rightarrow |H|$ versus ω has a slope of -20 dB/decade.



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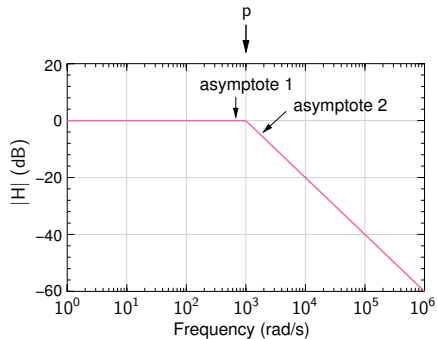
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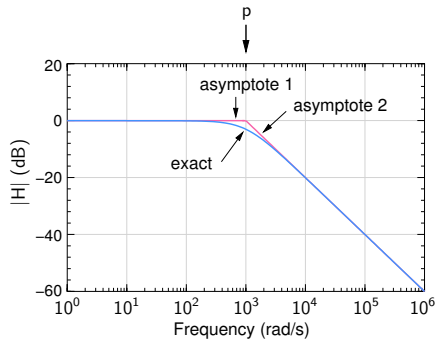
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Note that, at $\omega = p$, the actual value of $|H|$ is $1/\sqrt{2}$ (i.e., -3 dB).



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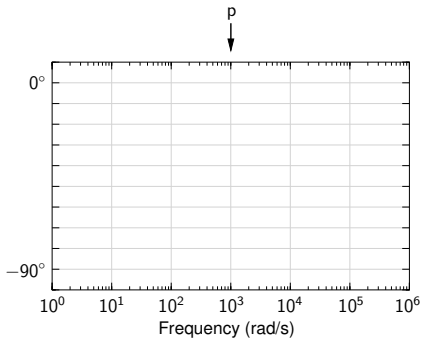
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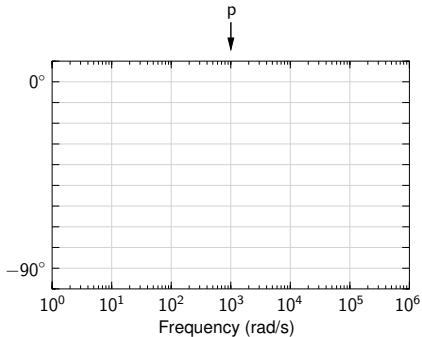
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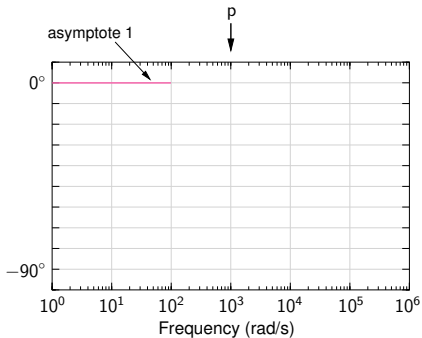


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$\omega \ll p$ (say, $\omega < p/10$): $H(s) \approx 1 \rightarrow \angle H = 0$.

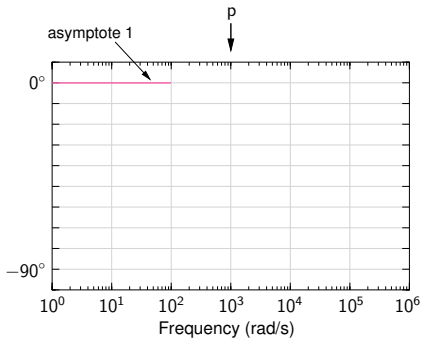


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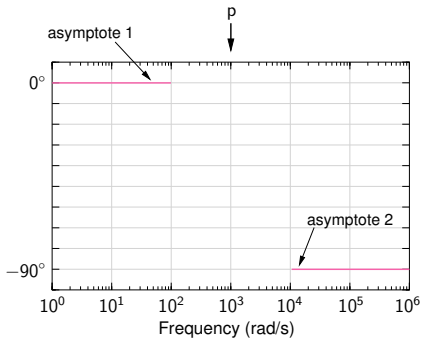
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Asymptote 2:

$\omega \gg p$ (say, $\omega > 10p$): $H(s) \approx \frac{1}{j(\omega/p)} \rightarrow \angle H = -\pi/2$.



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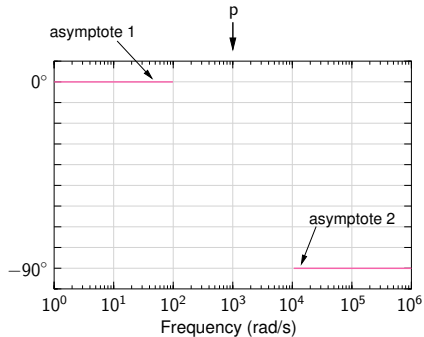
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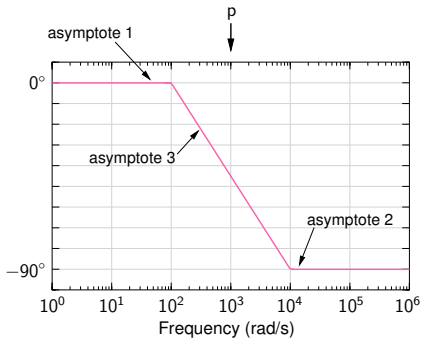
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For $p/10 < \omega < 10p$, $\angle H$ is assumed to vary linearly with $\log \omega$
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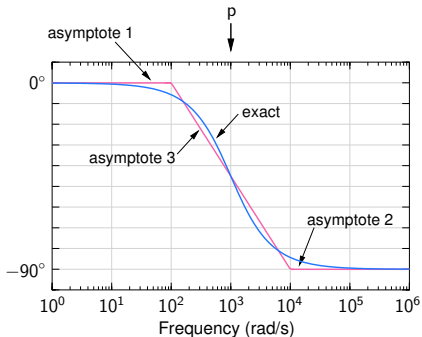
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$\omega \ll p$ (say, $\omega < p/10$): $H(s) \approx 1 \rightarrow \angle H = 0$.

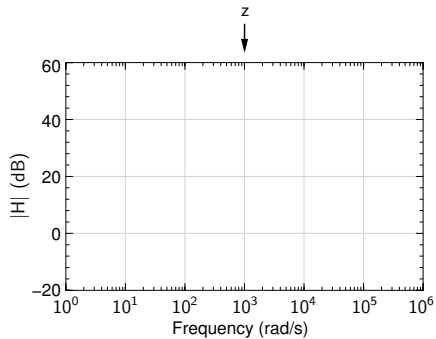
Asymptote 2:

$\omega \gg p$ (say, $\omega > 10p$): $H(s) \approx \frac{1}{j(\omega/p)} \rightarrow \angle H = -\pi/2$.

Asymptote 3:

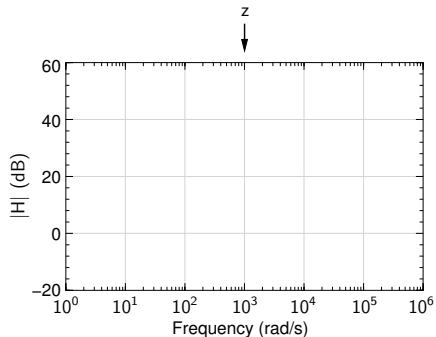
For $p/10 < \omega < 10p$, $\angle H$ is assumed to vary linearly with $\log \omega$
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Contribution of a zero: magnitude



Consider $H(s) = 1 + s/z \rightarrow H(j\omega) = 1 + j(\omega/z)$, $|H(j\omega)| = \sqrt{1 + (\omega/z)^2}$.

In this example, $z = 10^3$ rad/s.

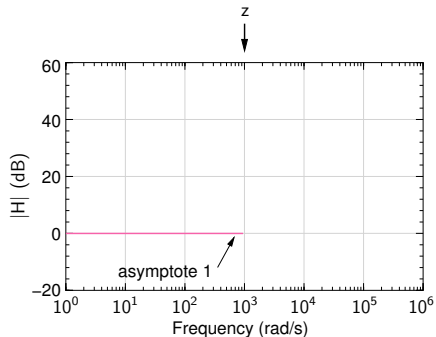


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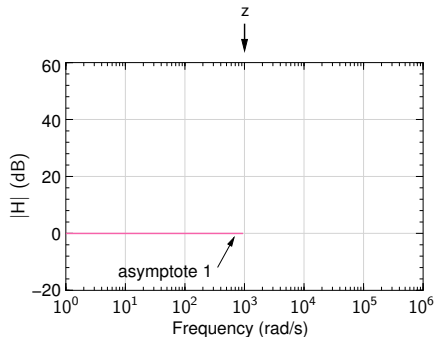


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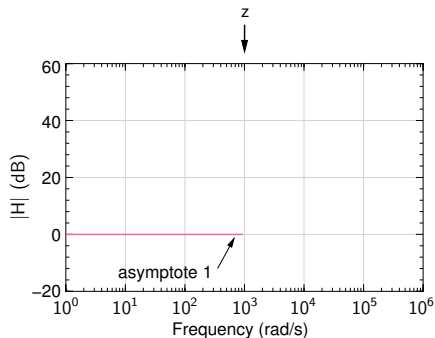
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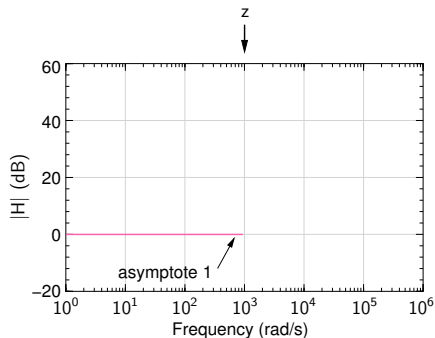
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$$|H|_1 = 20 \log \omega_1 - 20 \log z \text{ (dB)}$$

$$|H|_2 = 20 \log (10\omega_1) - 20 \log z \text{ (dB)}$$



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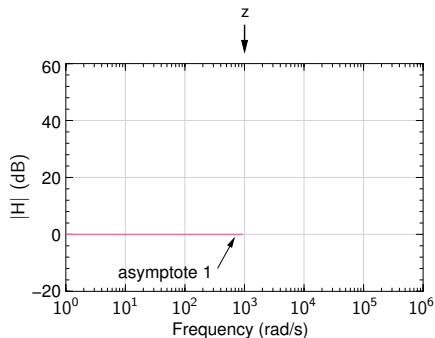
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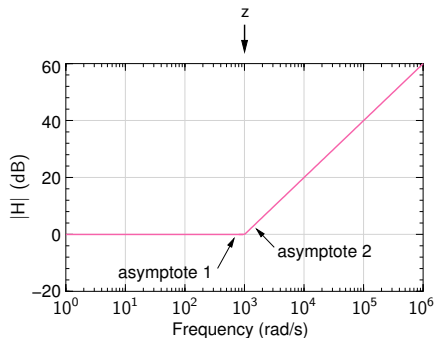
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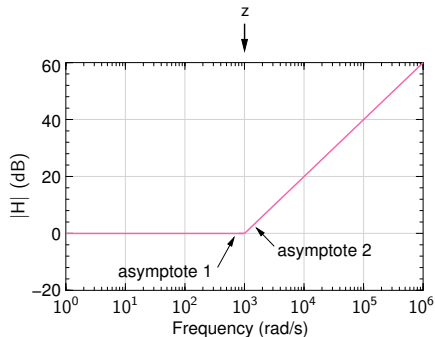
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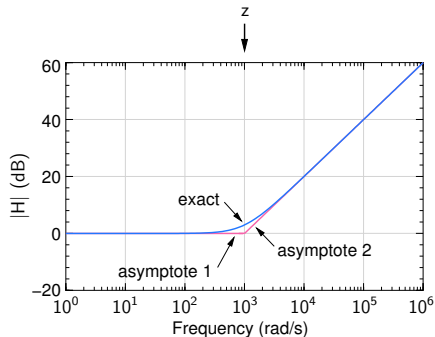
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Note that, at $\omega = z$, the actual value of $|H|$ is $\sqrt{2}$ (i.e., 3 dB).



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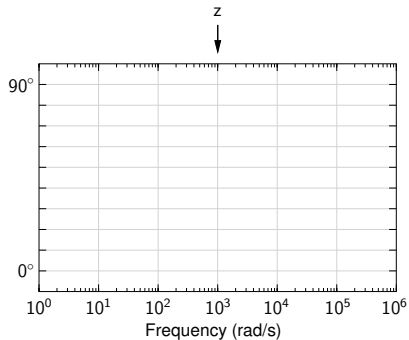
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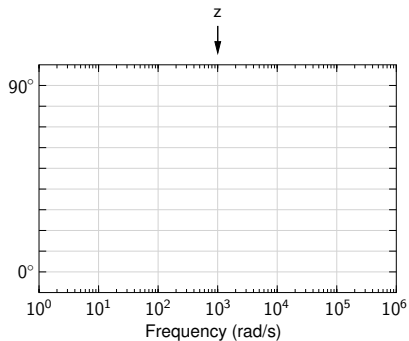
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Contribution of a zero: phase



Consider $H(s) = 1 + s/z = 1 + j(\omega/z) \rightarrow \angle H = \tan^{-1} \left(\frac{\omega}{z} \right)$

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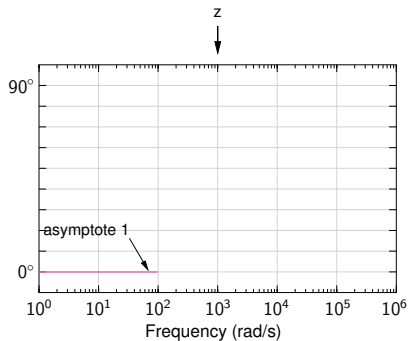
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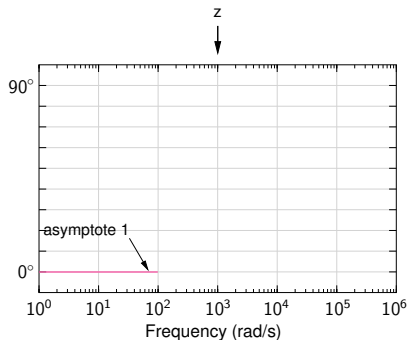


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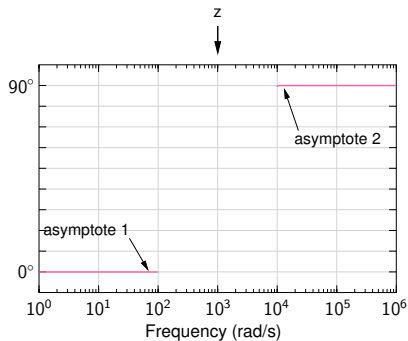
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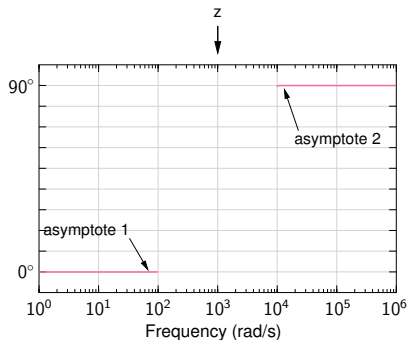
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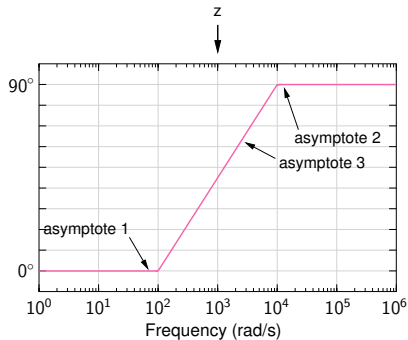
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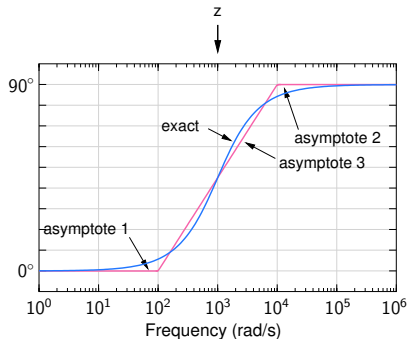
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$$\text{If } \omega \rightarrow 10\omega, \log \omega \rightarrow \log \omega + \log 10, |H| \rightarrow |H| + 20 \text{ (dB),}$$

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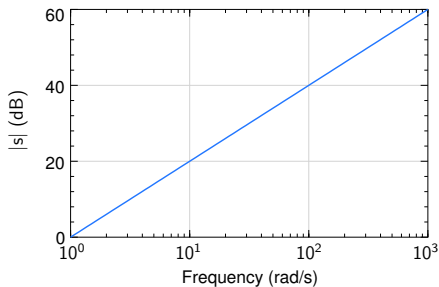
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Contribution of K (constant), s , and s^2



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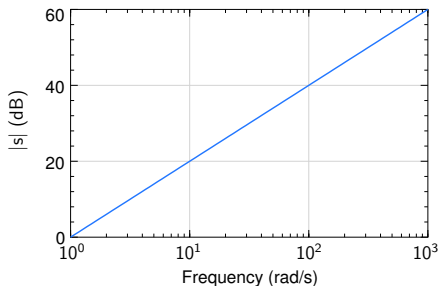
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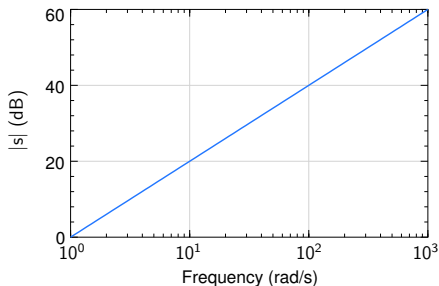
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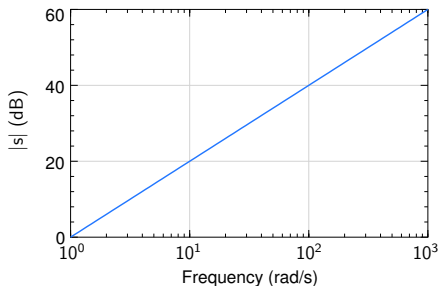
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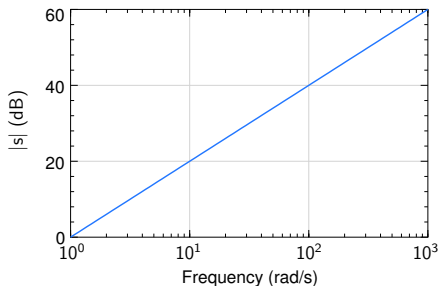
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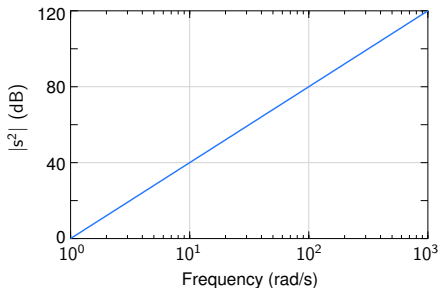
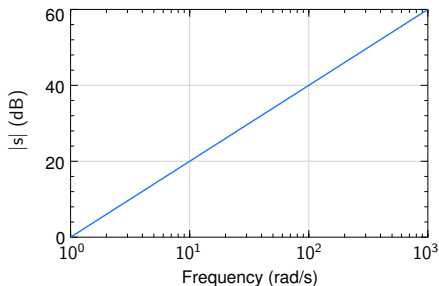
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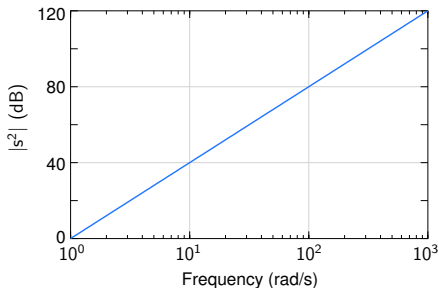
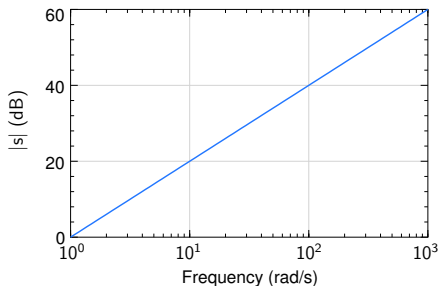
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$H_1(j\omega)$ and $H_2(j\omega)$ are complex numbers.

At a given ω , let $H_1 = K_1 \angle \alpha = K_1 e^{j\alpha}$, and $H_2 = K_2 \angle \beta = K_2 e^{j\beta}$.

Then, $H_1 H_2 = K_1 K_2 e^{j(\alpha+\beta)} = K_1 K_2 \angle (\alpha + \beta)$.

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In the Bode phase plot, the contributions due to H_1 and H_2 also get added.

The same reasoning applies to more than two terms as well.

Consider $H(s) = \frac{10 s}{(1 + s/10^2)(1 + s/10^5)}$.

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Let $H(s) = H_1(s) H_2(s) H_3(s) H_4(s)$, where

$$H_1(s) = 10,$$

$$H_2(s) = s,$$

$$H_3(s) = \frac{1}{1 + s/p_1}, p_1 = 10^2 \text{ rad/s},$$

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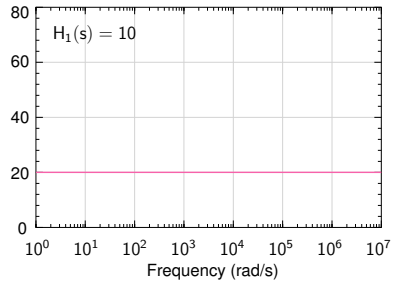
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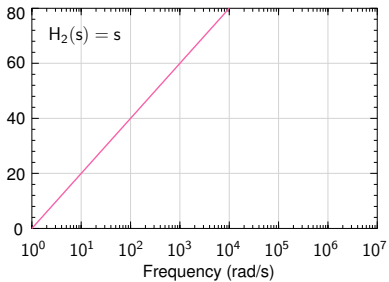
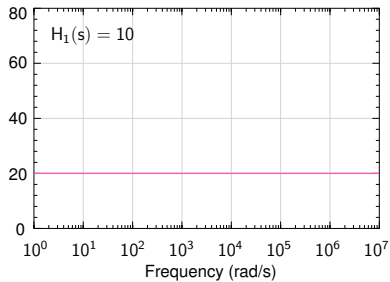
$$H_4(s) = \frac{1}{1 + s/p_2} , p_2 = 10^5 \text{ rad/s}.$$

We can now plot the magnitude and phase of H_1 , H_2 , H_3 , H_4 *individually* versus ω and then simply add them to obtain $|H|$ and $\angle H$.

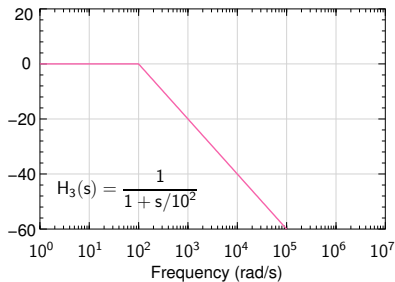
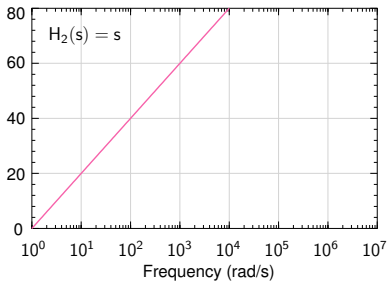
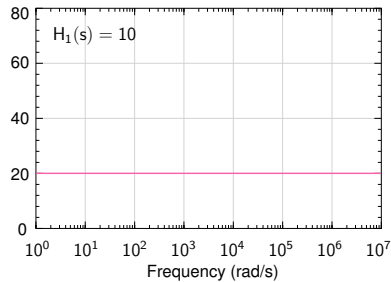
Magnitude plot ($|H|$ in dB)



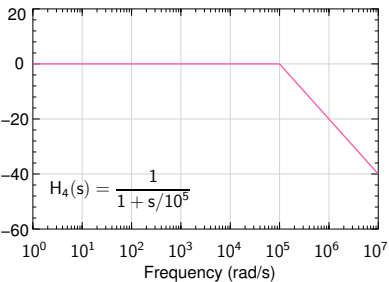
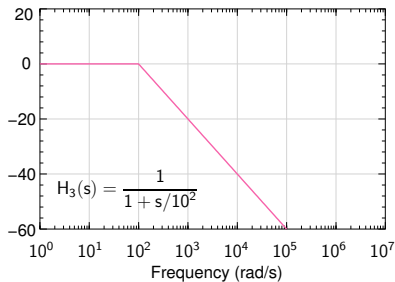
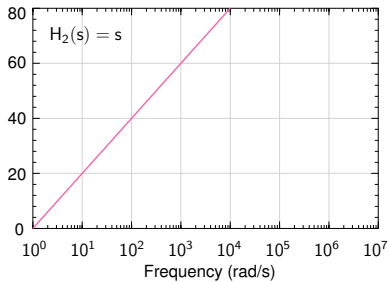
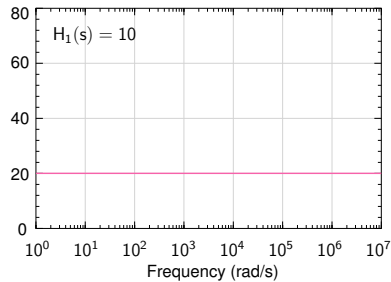
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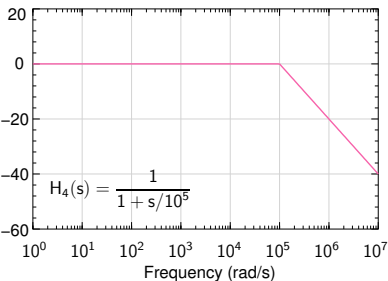
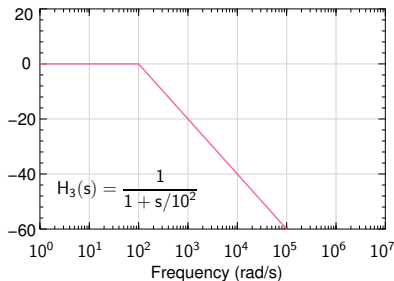
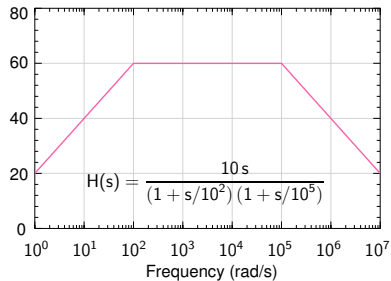
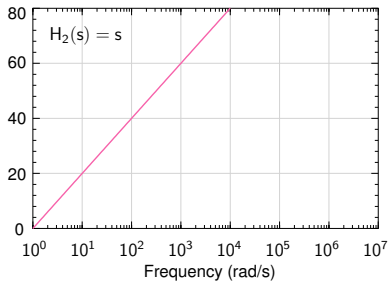
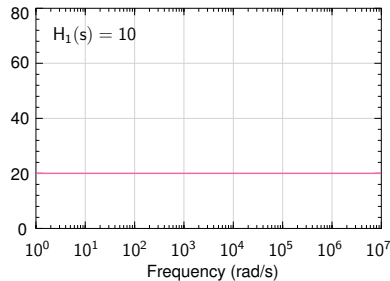
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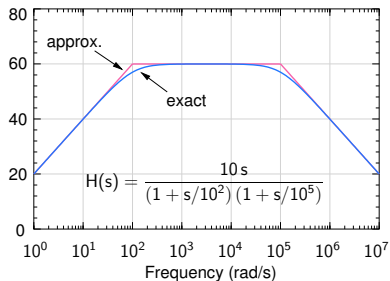
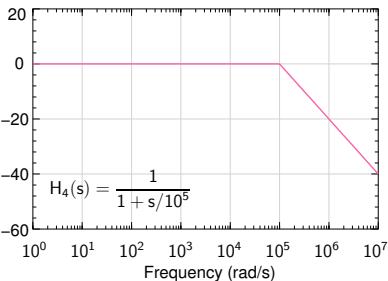
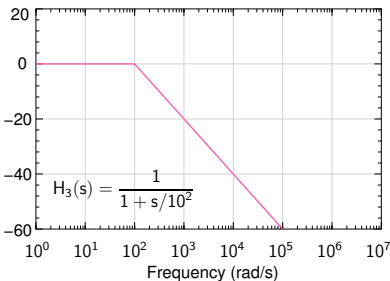
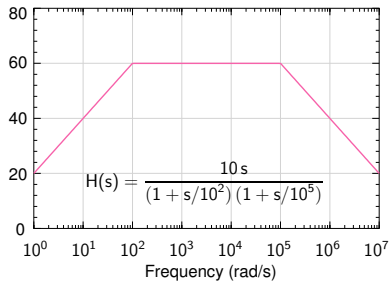
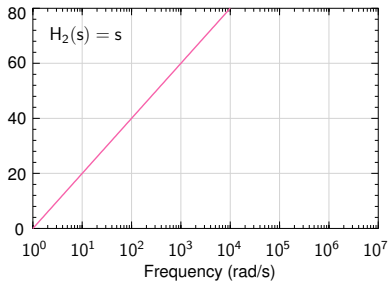
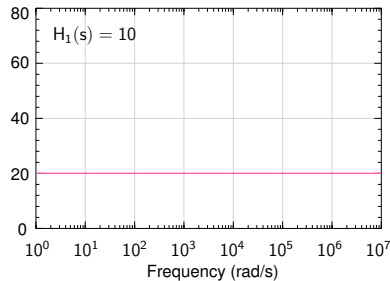
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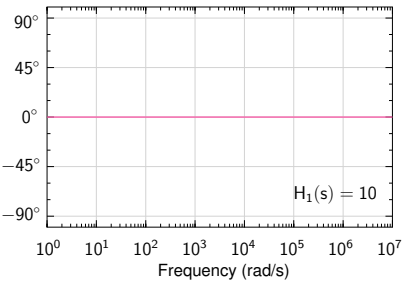
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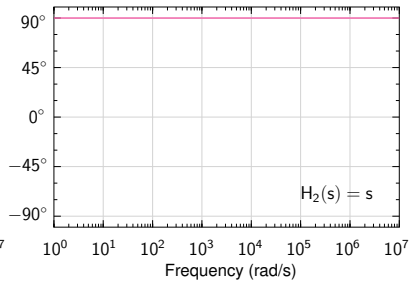
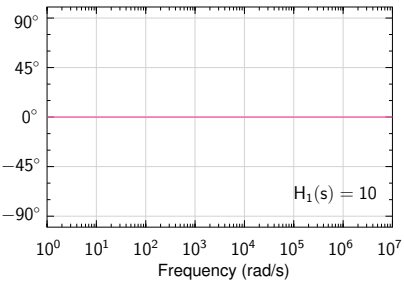
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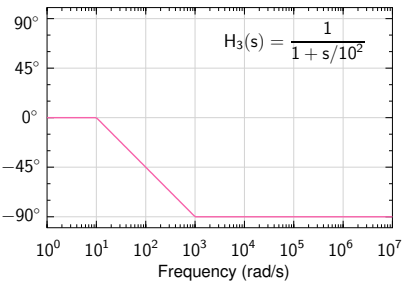
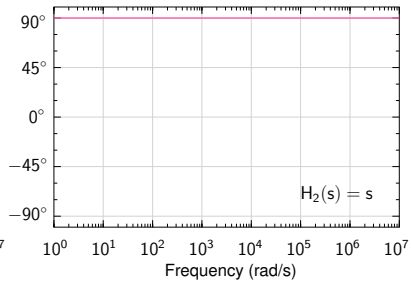
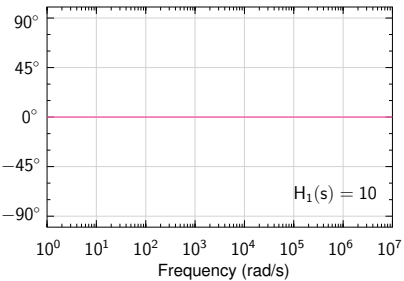
Phase plot



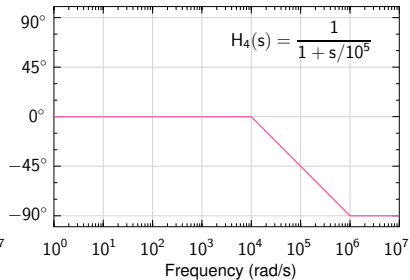
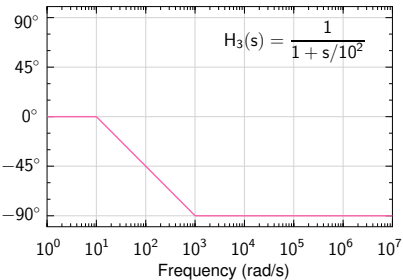
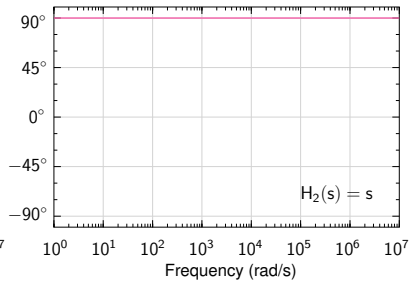
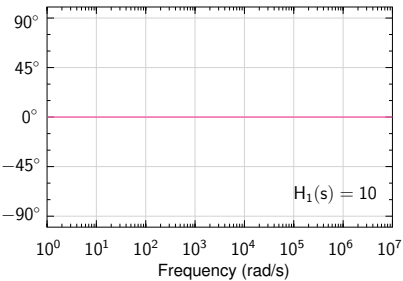
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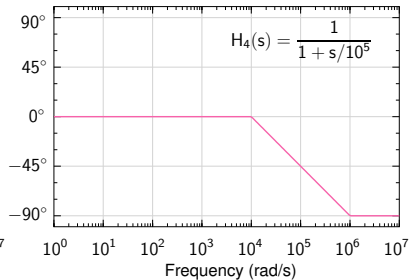
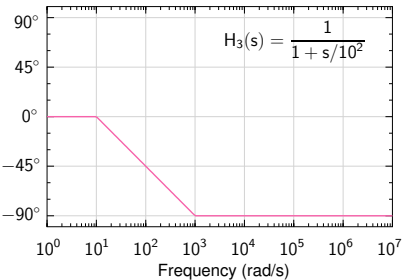
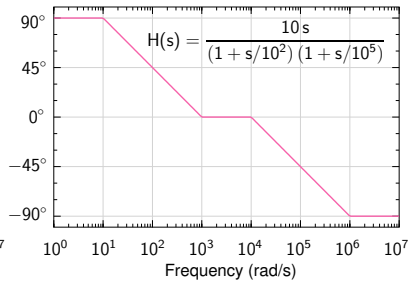
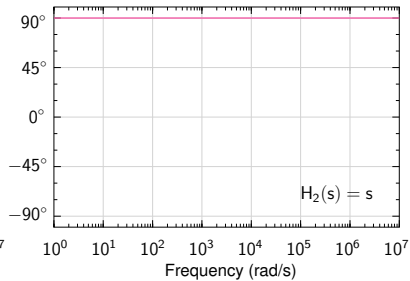
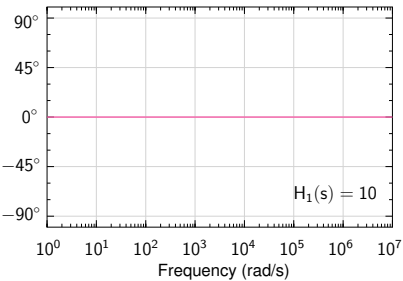
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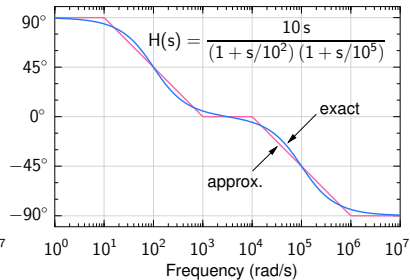
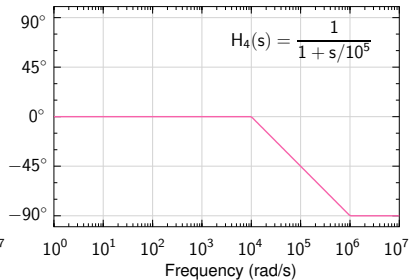
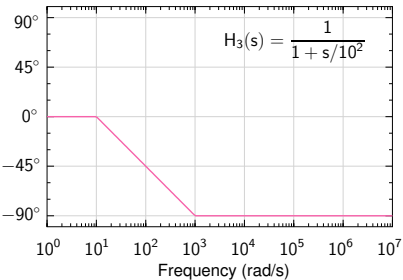
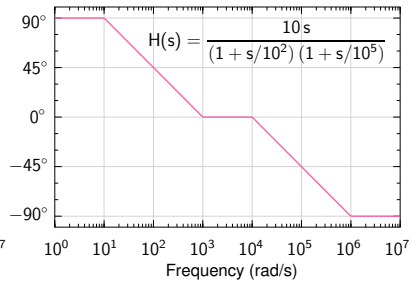
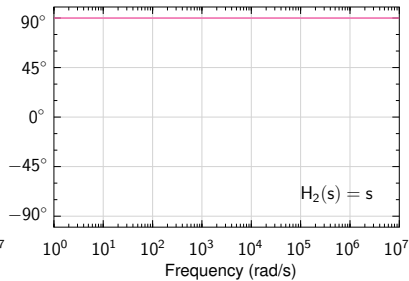
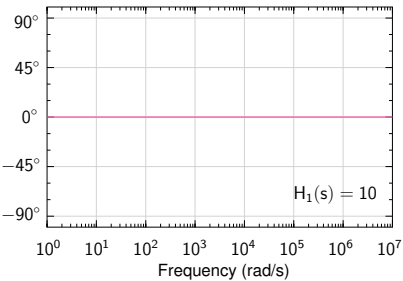
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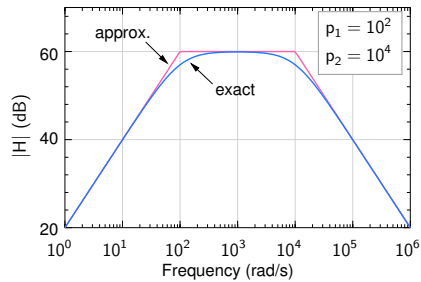
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- * When the poles and zeros are not sufficiently separated, the Bode approximation should be used only for a rough estimate, followed by a numerical calculation. However, even in such cases, it does give a good idea of the *asymptotic* magnitude and phase plots, which is valuable in amplifier design.

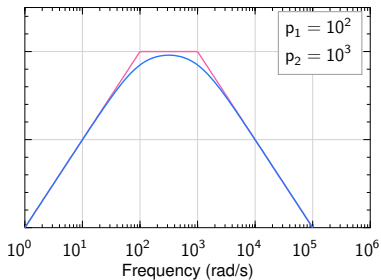
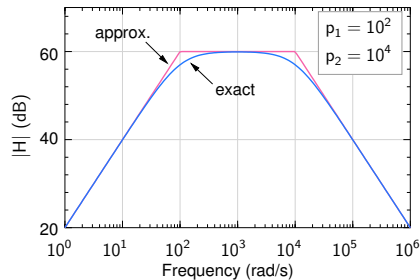
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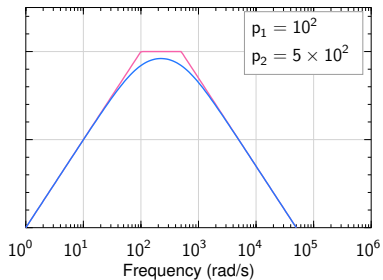
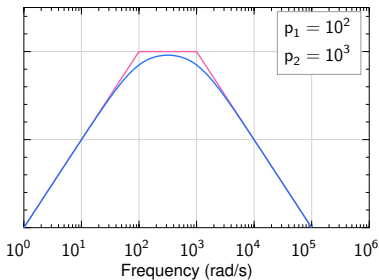
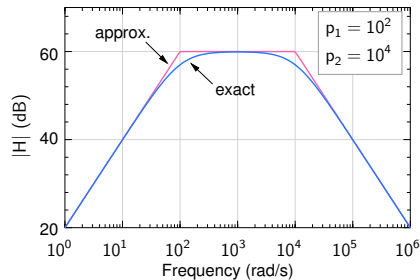
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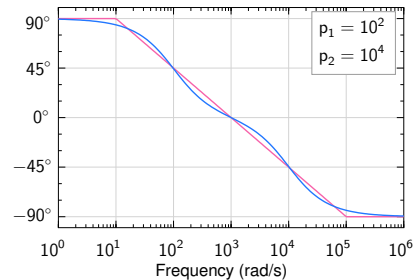
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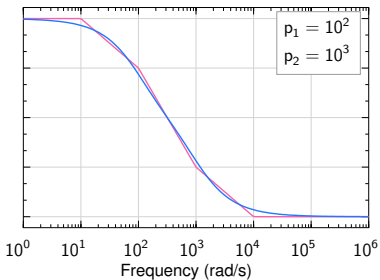
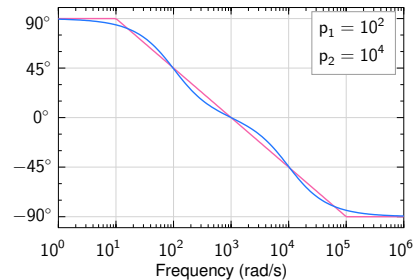
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