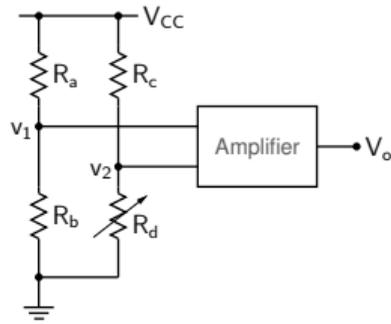
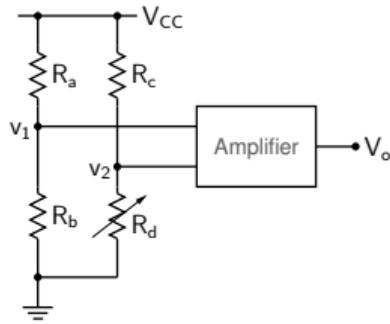


## Common-mode and differential-mode voltages



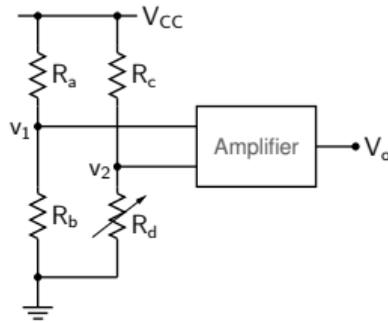
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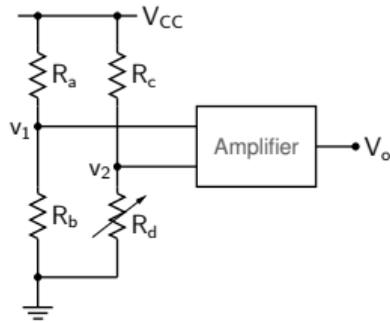
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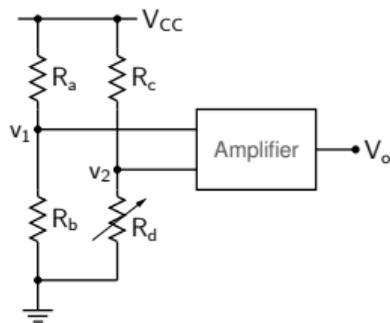


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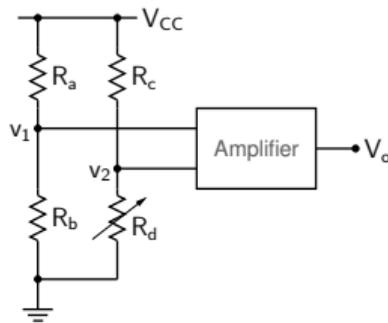
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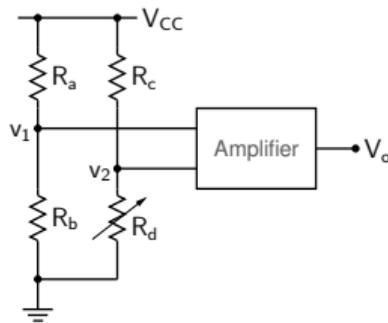
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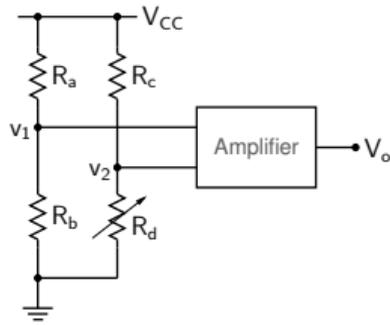
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For example, with  $V_{CC} = 15 V$ ,  $R = 1 k$ ,  $\Delta R = 0.01 k$ ,

$$v_1 = 7.5 V ,$$

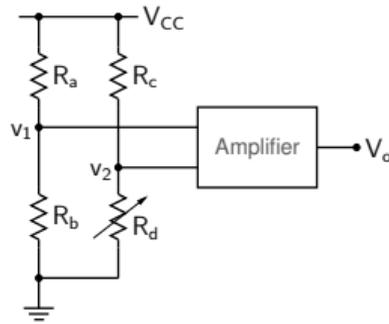
$$v_2 = 7.5 + 0.0375 V .$$

## Common-mode and differential-mode voltages



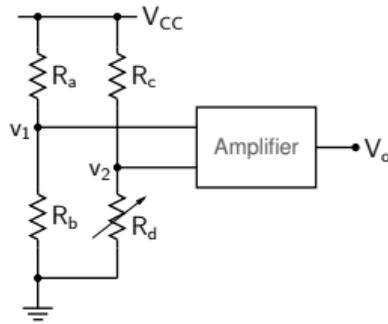
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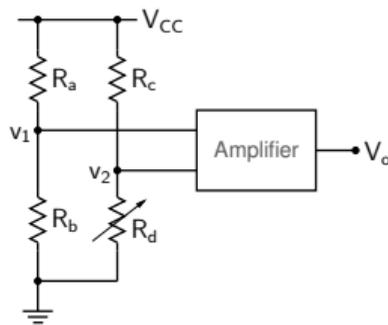
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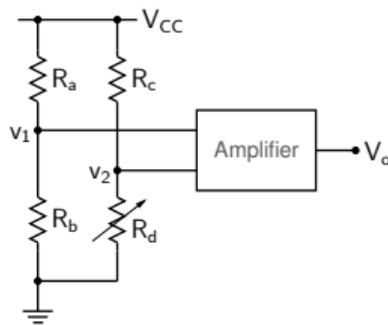
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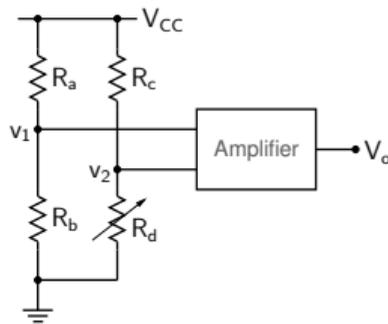
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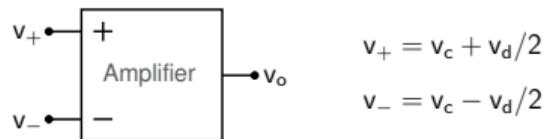
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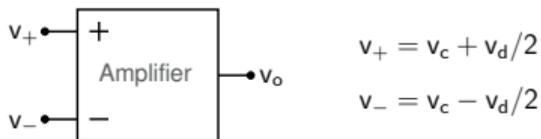
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Note that the common-mode voltage is quite large compared to the differential-mode voltage.

This is a common situation in transducer circuits.



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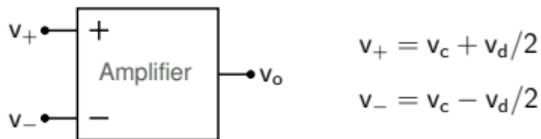
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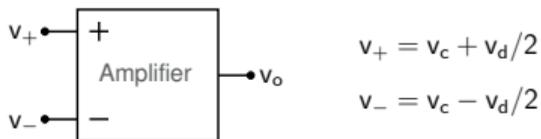
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The ability of an amplifier to *reject* the common-mode signal is given by the

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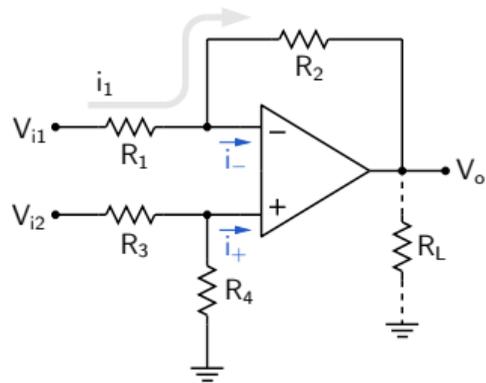
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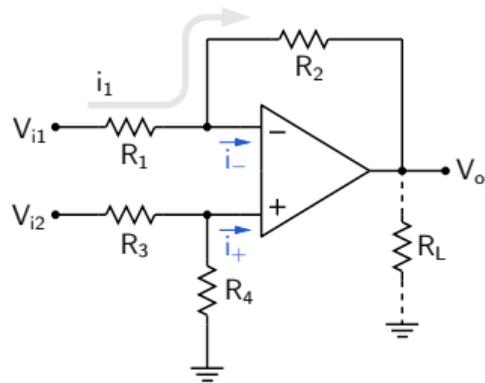
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For the 741 op-amp, the CMRR is 90 dB ( $\simeq 30,000$ ), which may be considered to be infinite in many applications. In such cases, mismatch between circuit components will determine the overall common-mode rejection performance of the circuit.

## Op-amp circuits (linear region)



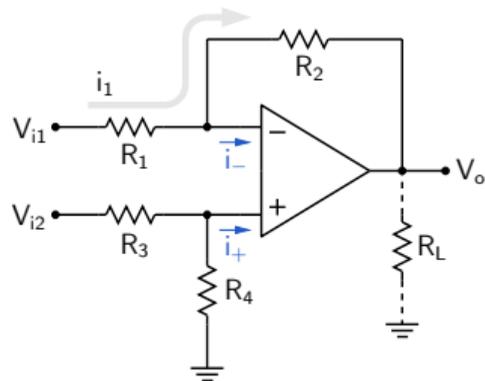
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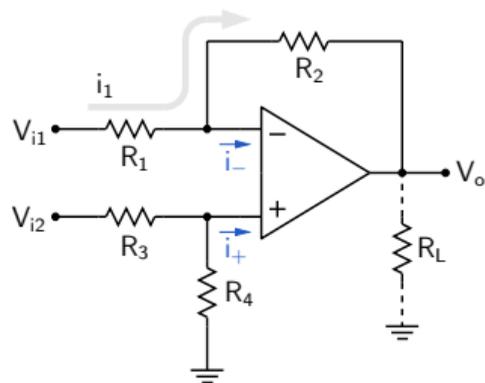


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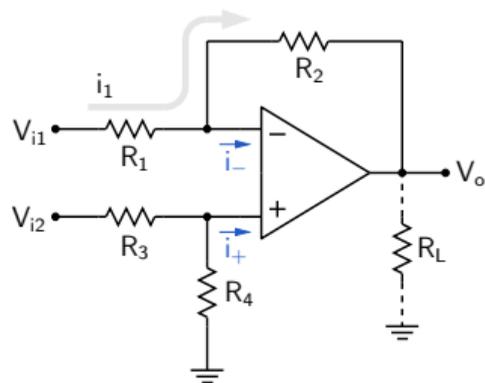
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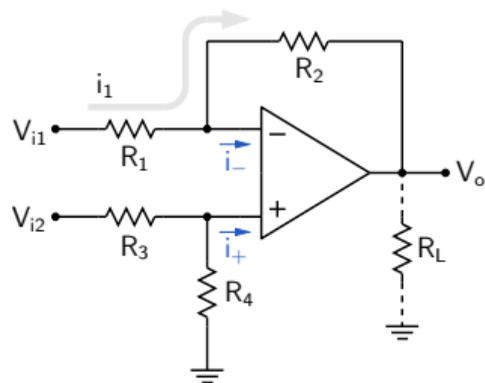
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Substituting for  $V_+$  and selecting  $\frac{R_4}{R_3} = \frac{R_2}{R_1}$ , we get (show this)

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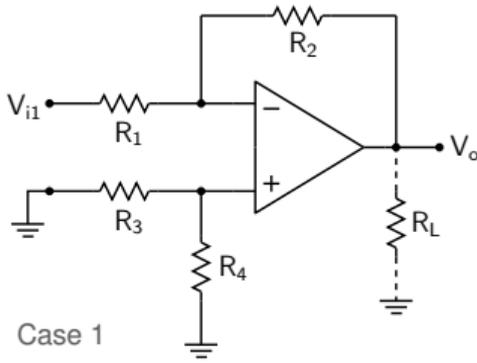
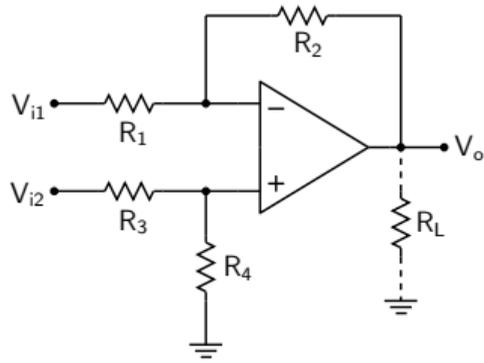
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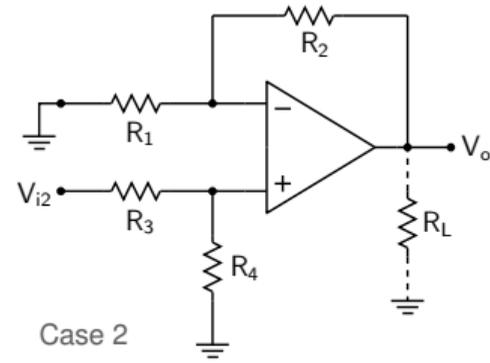
$$V_o = \frac{R_2}{R_1} (V_{i2} - V_{i1}).$$

The circuit is a "difference amplifier."

# Difference amplifier



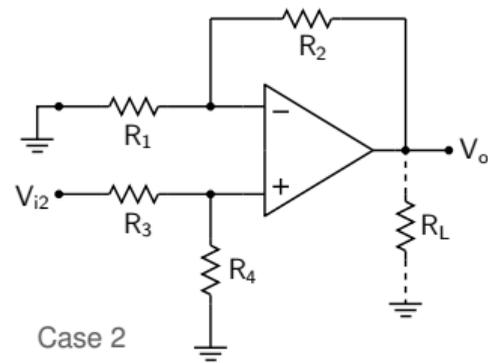
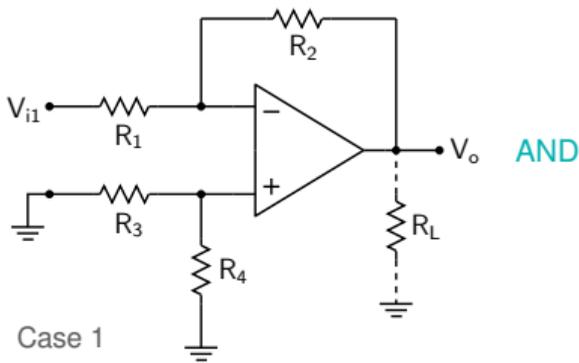
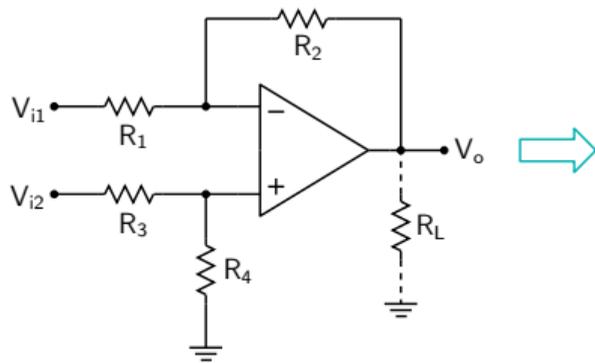
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Since the op-amp is operating in the linear region, we can use superposition:

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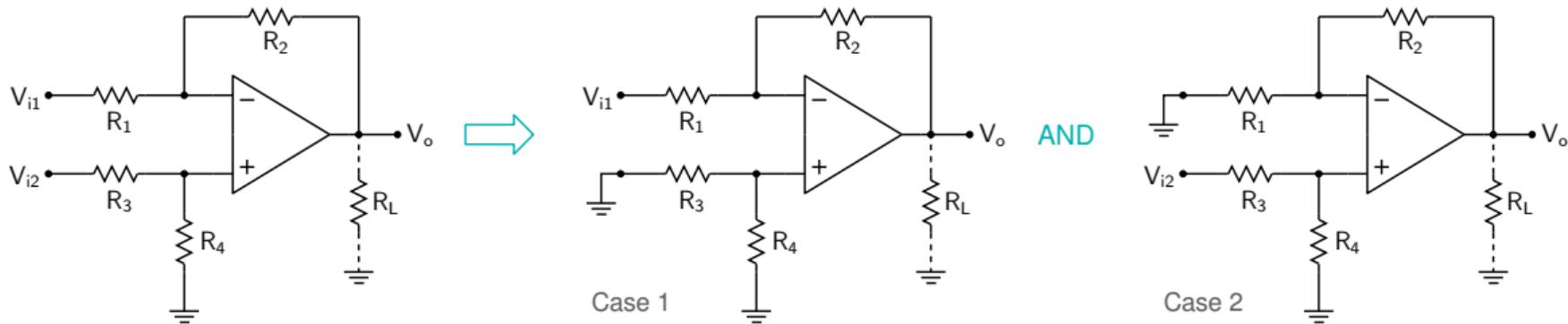
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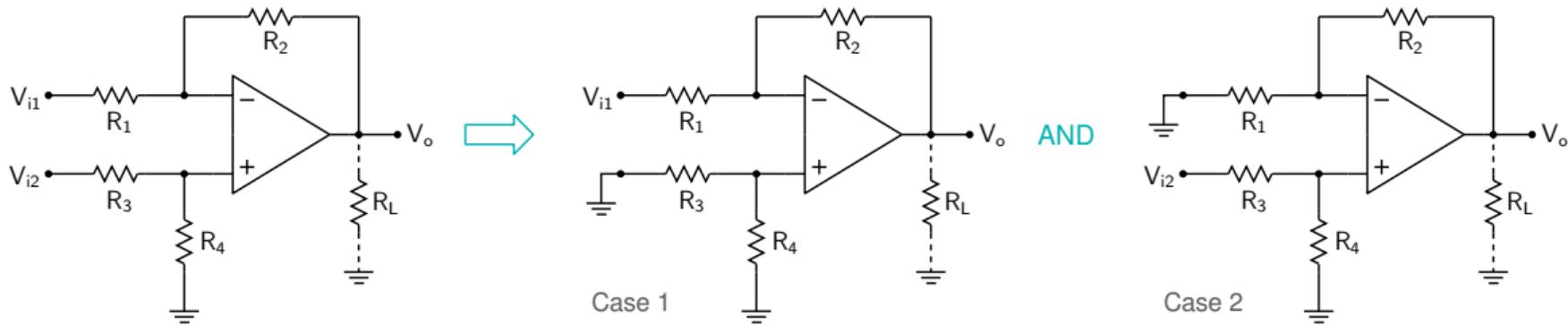
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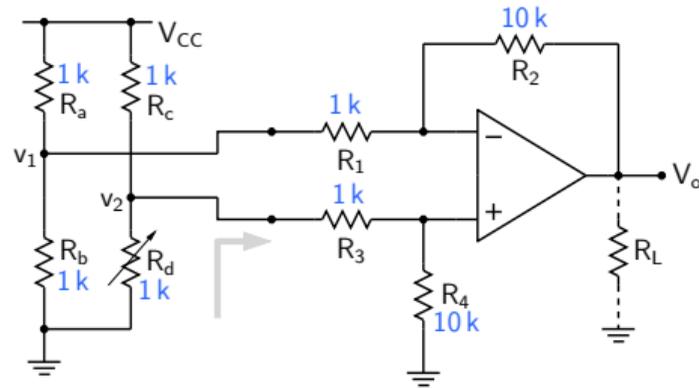
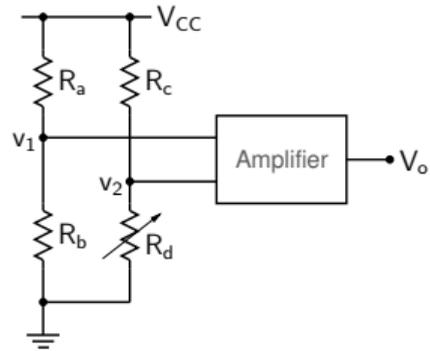
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The net result is,

$$V_o = V_{o1} + V_{o2} = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) V_{i2} - \frac{R_2}{R_1} V_{i1} = \frac{R_2}{R_1} (V_{i2} - V_{i1}), \text{ if } \frac{R_4}{R_3} = \frac{R_2}{R_1}.$$

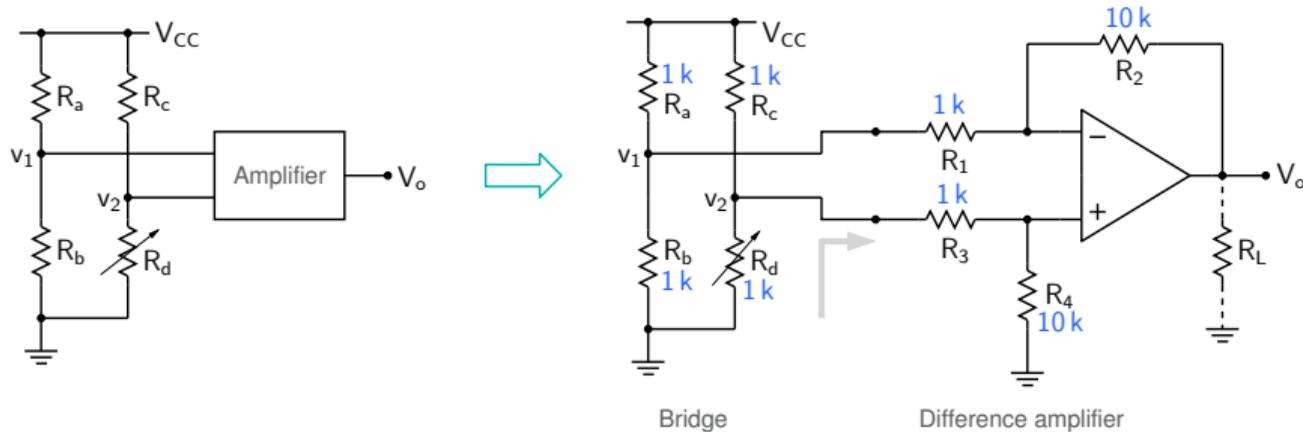
# Difference amplifier



Bridge

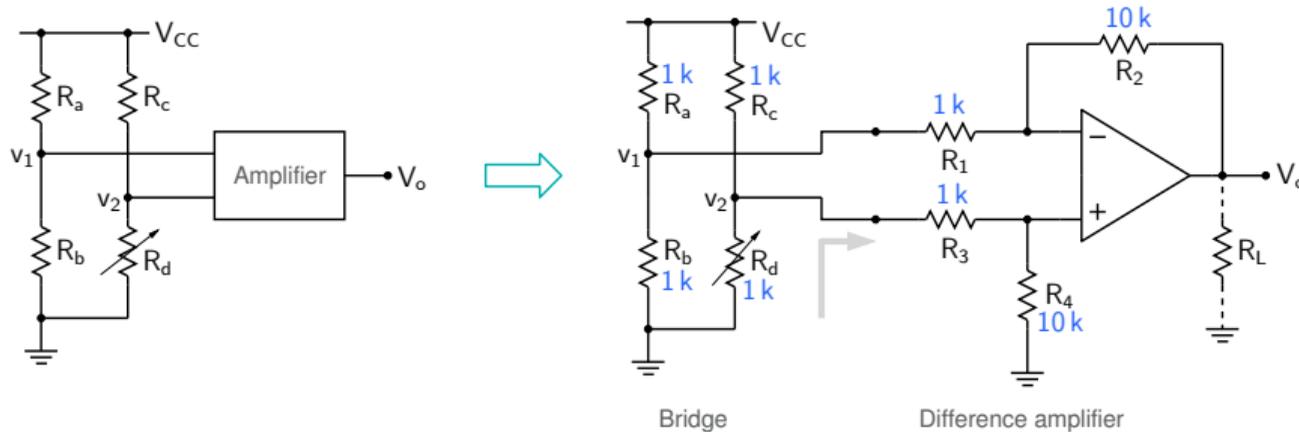
Difference amplifier

# Difference amplifier



The resistance seen from  $v_2$  is  $(R_3 + R_4)$  which is small enough to cause  $v_2$  to change.  
This is not desirable.

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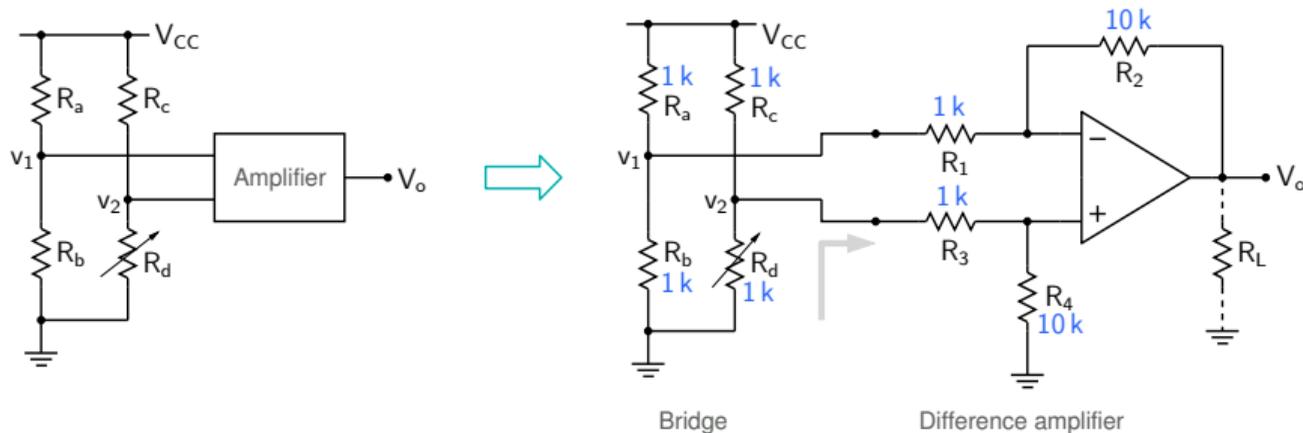


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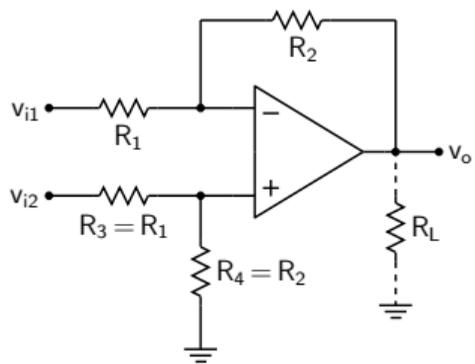


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We will discuss an improved difference amplifier later. Before we do that, let us discuss another problem with the above difference amplifier which can be important for some applications (next slide).

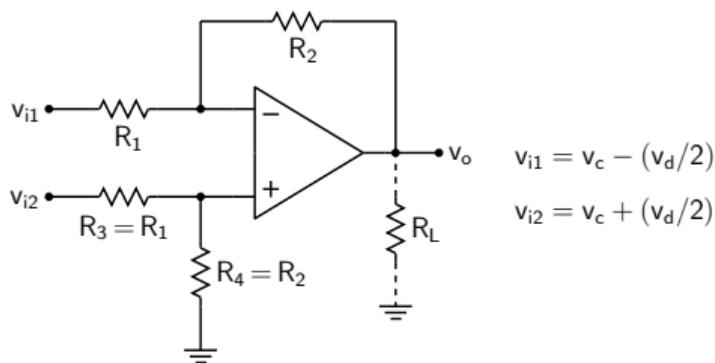
## Difference amplifier



$$v_{i1} = v_c - (v_d/2)$$

$$v_{i2} = v_c + (v_d/2)$$

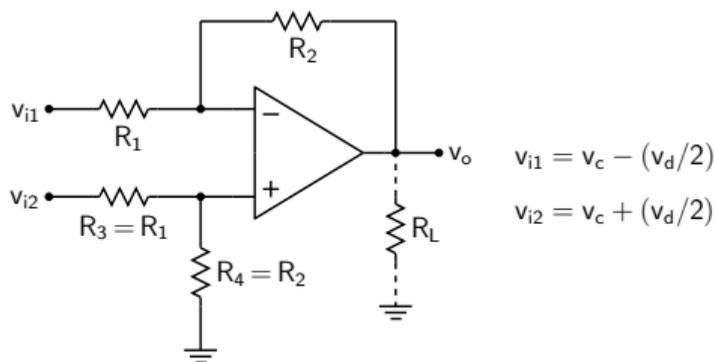
## Difference amplifier



Consider the difference amplifier with  $R_3 = R_1$ ,  $R_4 = R_2 \rightarrow V_o = \frac{R_2}{R_1} (v_{i2} - v_{i1})$ .

The output voltage depends only on the differential-mode signal  $(v_{i2} - v_{i1})$ ,  
i.e.,  $A_c$  (common-mode gain) = 0.

## Difference amplifier

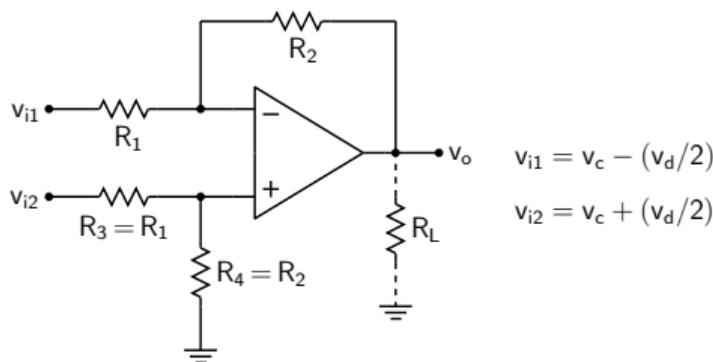


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In practice,  $R_3$  and  $R_1$  may not be exactly equal. Let  $R_3 = R_1 + \Delta R$ .

## Difference amplifier

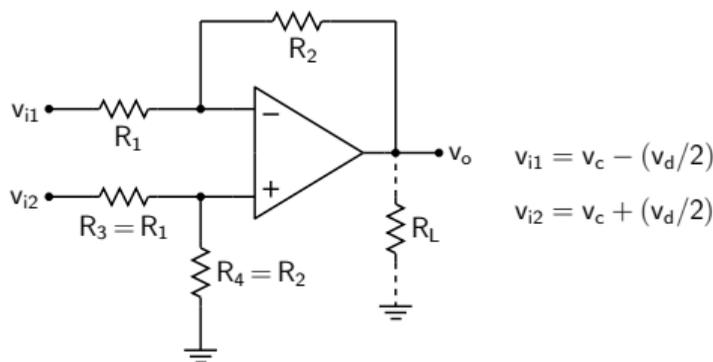


Consider the difference amplifier with  $R_3 = R_1$ ,  $R_4 = R_2 \rightarrow V_o = \frac{R_2}{R_1} (v_{i2} - v_{i1})$ .

The output voltage depends only on the differential-mode signal  $(v_{i2} - v_{i1})$ ,  
i.e.,  $A_c$  (common-mode gain) = 0.

In practice,  $R_3$  and  $R_1$  may not be exactly equal. Let  $R_3 = R_1 + \Delta R$ .

$$v_o = \frac{R_4}{R_3 + R_4} \left(1 + \frac{R_2}{R_1}\right) v_{i2} - \frac{R_2}{R_1} v_{i1} = \frac{R_2}{R_1 + \Delta R + R_2} \left(1 + \frac{R_2}{R_1}\right) v_{i2} - \frac{R_2}{R_1} v_{i1}$$
$$\simeq \frac{R_2}{R_1} (v_d - x v_c), \text{ with } x = \frac{\Delta R}{R_1 + R_2} \quad (\text{show this})$$



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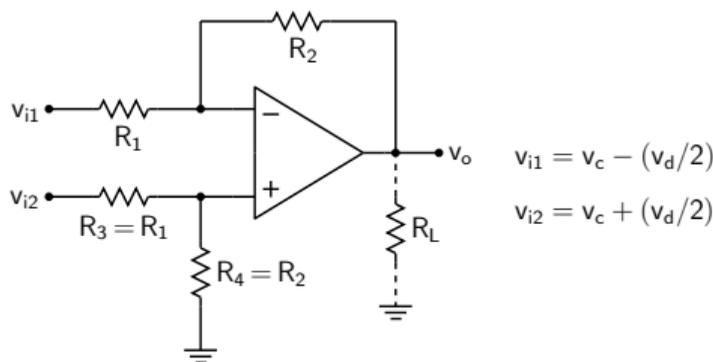
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$$\simeq \frac{R_2}{R_1} (v_d - x v_c), \text{ with } x = \frac{\Delta R}{R_1 + R_2} \quad (\text{show this})$$

$$|A_c| = \frac{\Delta R}{R_1 + R_2} \frac{R_2}{R_1} \ll |A_d| = \frac{R_2}{R_1}.$$



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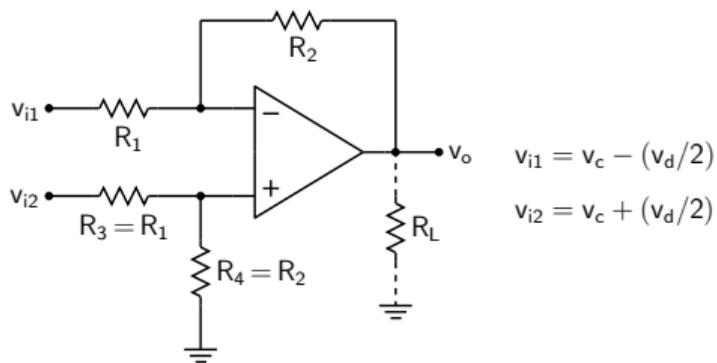
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$$\simeq \frac{R_2}{R_1} (v_d - x v_c), \text{ with } x = \frac{\Delta R}{R_1 + R_2} \quad (\text{show this})$$

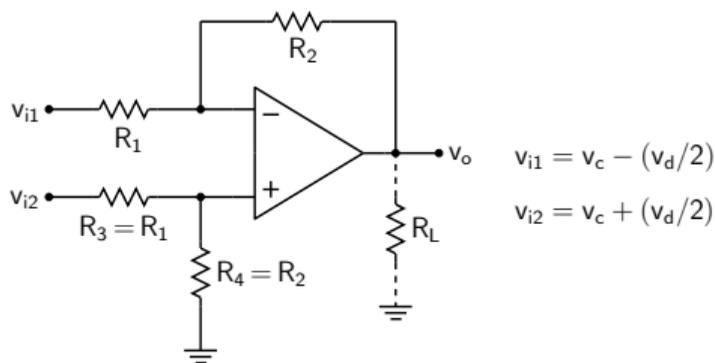
$|A_c| = \frac{\Delta R}{R_1 + R_2} \frac{R_2}{R_1} \ll |A_d| = \frac{R_2}{R_1}$ . However, since  $v_c$  can be large compared to  $v_d$ , the effect of  $A_c$  cannot be ignored.

## Difference amplifier



$$|A_c| = x \frac{R_2}{R_1}, |A_d| = \frac{R_2}{R_1}, \text{ where } x = \frac{\Delta R}{R_1 + R_2}.$$

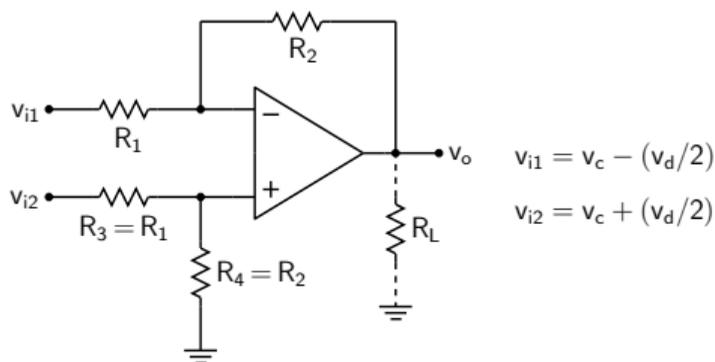
## Difference amplifier



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In our earlier example,  $v_c = 7.5 \text{ V}$ ,  $v_d = 0.0375 \text{ V}$ .

## Difference amplifier



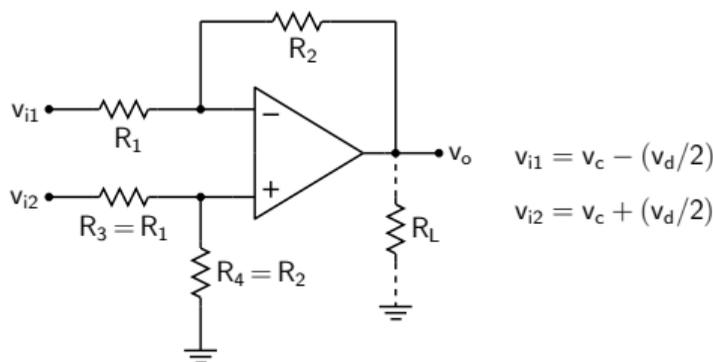
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$$\text{With } R_1 = 1 \text{ k}, R_2 = 10 \text{ k}, x = \frac{0.01 \text{ k}}{11 \text{ k}} = 0.00091 \rightarrow |A_c| = 0.00091 \frac{10 \text{ k}}{1 \text{ k}} = 0.0091, |A_d| = \frac{10 \text{ k}}{1 \text{ k}} = 10.$$

$$|v_o^c| = |A_c v_c| = 0.0091 \times 7.5 = 0.068 \text{ V}.$$

## Difference amplifier



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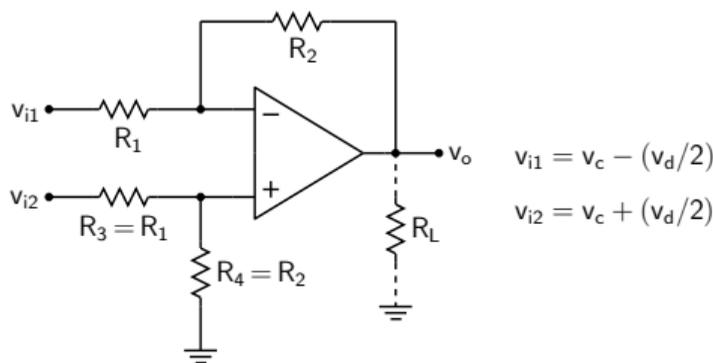
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$$|v_o^c| = |A_c v_c| = 0.0091 \times 7.5 = 0.068 \text{ V}.$$

$$|v_o^d| = |A_d v_d| = 10 \times 0.0375 = 0.375 \text{ V}.$$

## Difference amplifier



$$|A_c| = x \frac{R_2}{R_1}, |A_d| = \frac{R_2}{R_1}, \text{ where } x = \frac{\Delta R}{R_1 + R_2}.$$

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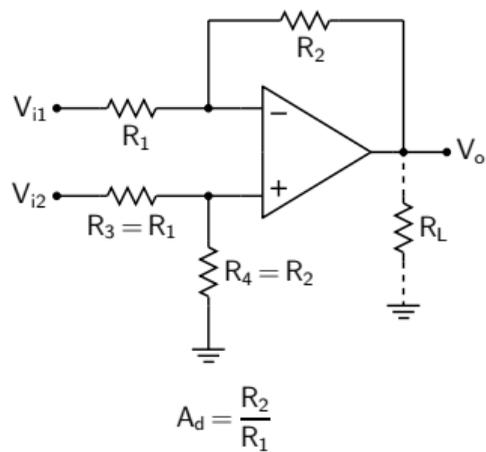
$$|v_o^d| = |A_d v_d| = 10 \times 0.0375 = 0.375 \text{ V}.$$

The (spurious) common-mode contribution is substantial.

If we measure  $v_o$ , we will conclude that  $v_d = \frac{v_o}{A_d}$ , but in reality, it would be different.

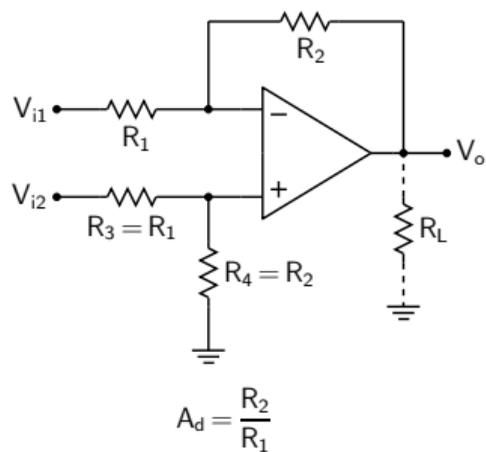
→ need a circuit which will drastically reduce the common-mode component at the output.

## Difference amplifier: resistance mismatch



$$V_o = \left(1 + \frac{R_2}{R_1}\right) \left(\frac{R_4}{R_3 + R_4}\right) V_{i2} - \frac{R_2}{R_1} V_{i1}$$

## Difference amplifier: resistance mismatch

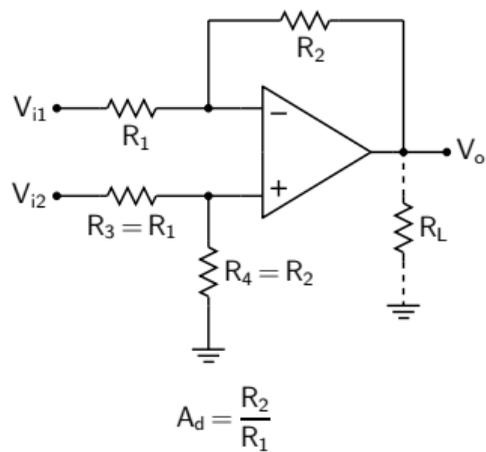


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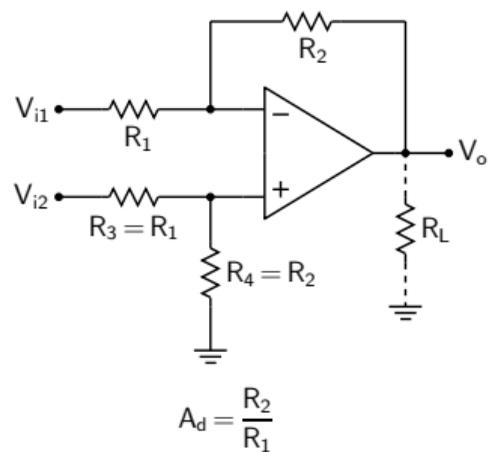


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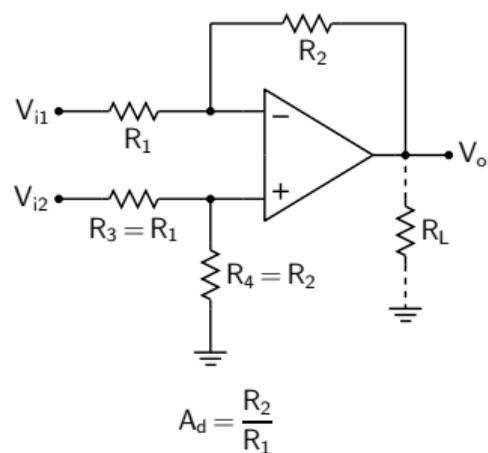


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Assume ideal op-amp with  $R_1 = R_1^0(1 + x_1)$ , etc. 1% resistor  $\rightarrow x = 0.01$ .



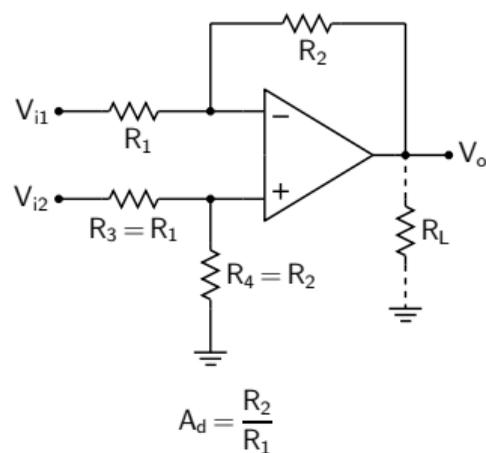
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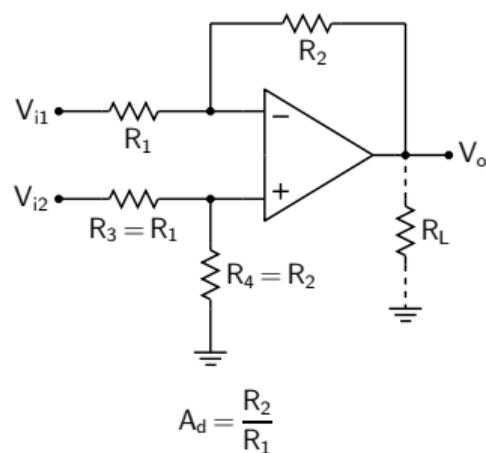
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Using  $(1 + u_1)(1 + u_2) \approx 1 + u_1 + u_2$  if  $|u_1| \ll 1$ ,  $|u_2| \ll 1$ ,



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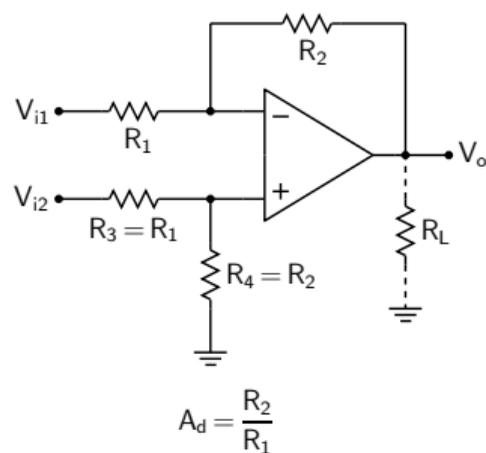
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and  $\frac{1}{1 + u} \approx 1 - u$  if  $|u| \ll 1$ ,



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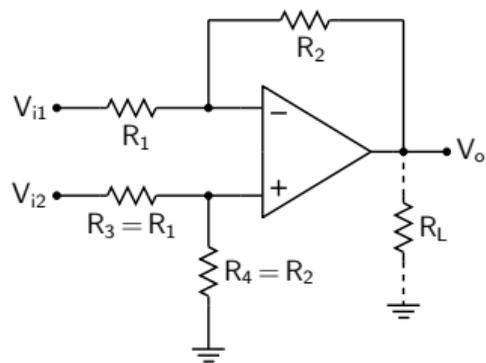
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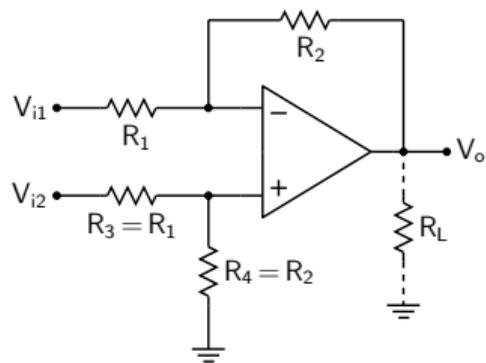
## Difference amplifier: resistance mismatch



$$A_d = \frac{R_2}{R_1}$$

$$A_c = \frac{R_4}{R_3 + R_4} (x_1 - x_2 - x_3 + x_4).$$

## Difference amplifier: resistance mismatch

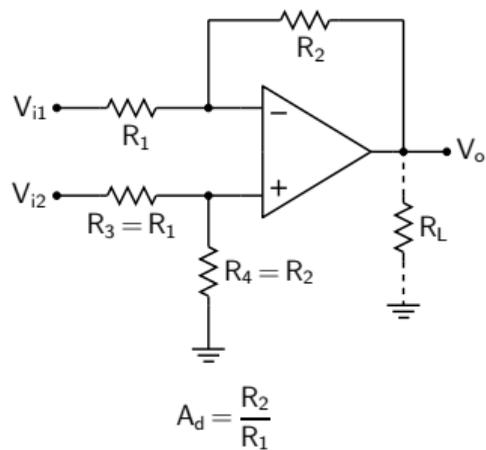


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$$\frac{R_4}{R_3 + R_4} \approx \frac{R_4^0}{R_3^0 + R_4^0}.$$

## Difference amplifier: resistance mismatch

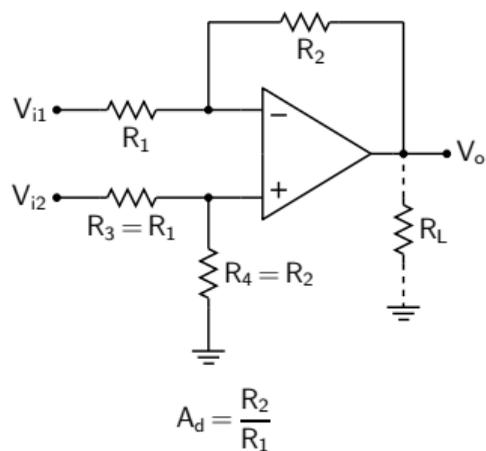


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$$(1) R_1^0 = R_2^0 \text{ (i.e., } R_3^0 = R_4^0)$$

## Difference amplifier: resistance mismatch



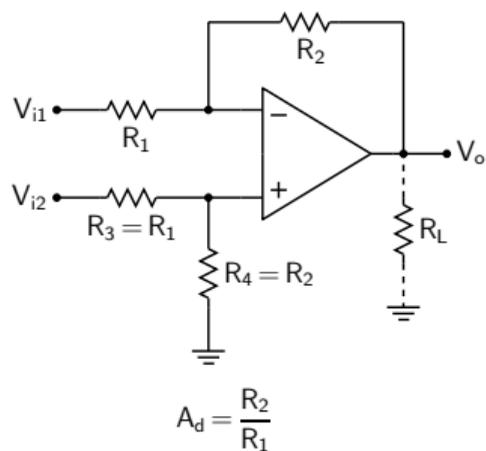
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## Difference amplifier: resistance mismatch



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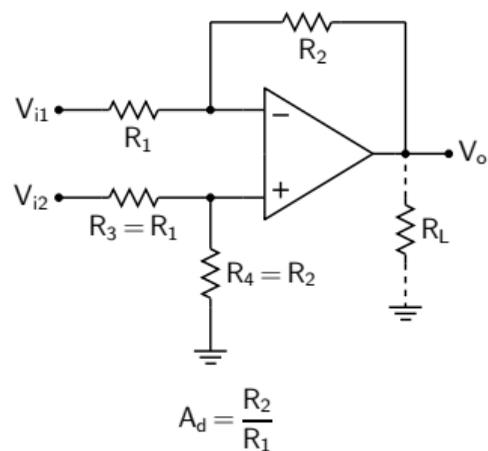
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$$= \frac{1}{2} 4x = 2x \text{ (worst case)}$$

## Difference amplifier: resistance mismatch



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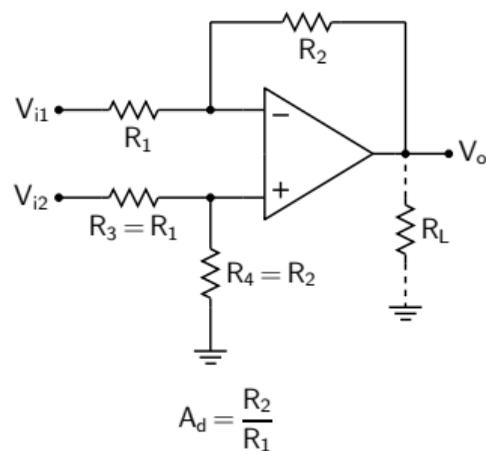
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(2)  $R_1^0 \ll R_2^0$  (i.e.,  $R_3^0 \ll R_4^0$ )

## Difference amplifier: resistance mismatch



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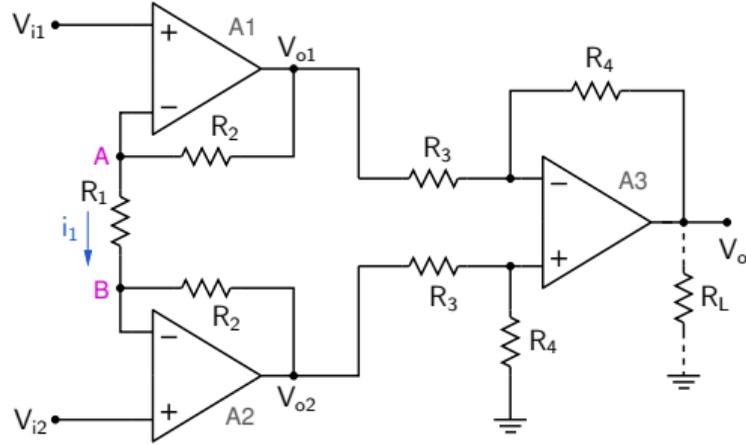
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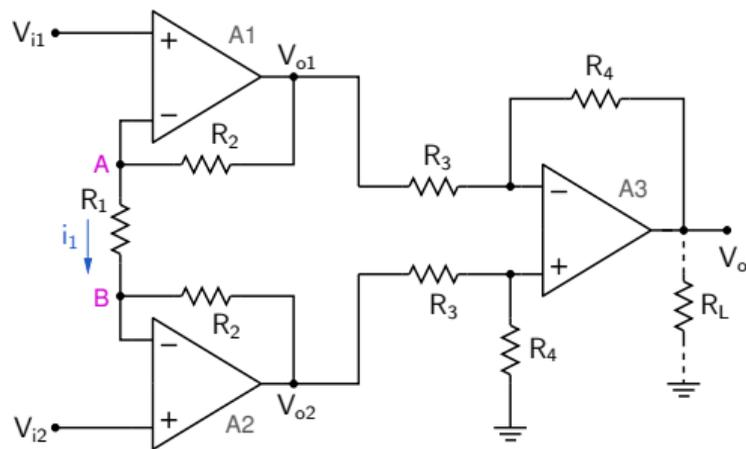
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$$A_c = \frac{(R_4^0/R_3^0)}{1 + (R_4^0/R_3^0)} (x_1 - x_2 - x_3 + x_4) \approx 4x \text{ (worst case)}$$

# Improved difference amplifier

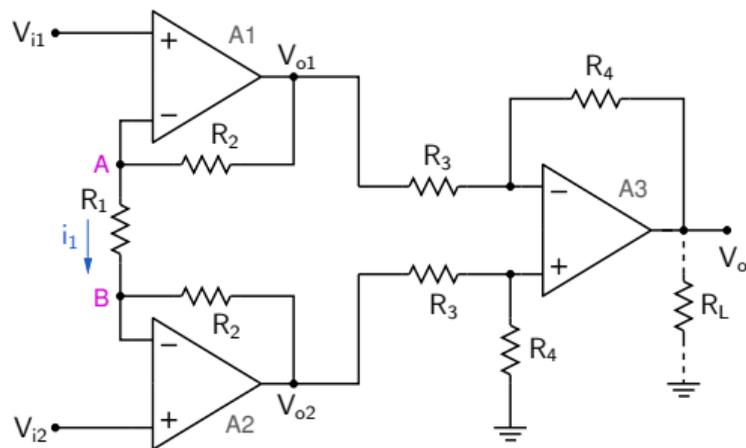


## Improved difference amplifier



$$V_+ \approx V_- \rightarrow V_A = V_{i1}, V_B = V_{i2}, \rightarrow i_1 = \frac{1}{R_1} (V_{i1} - V_{i2}).$$

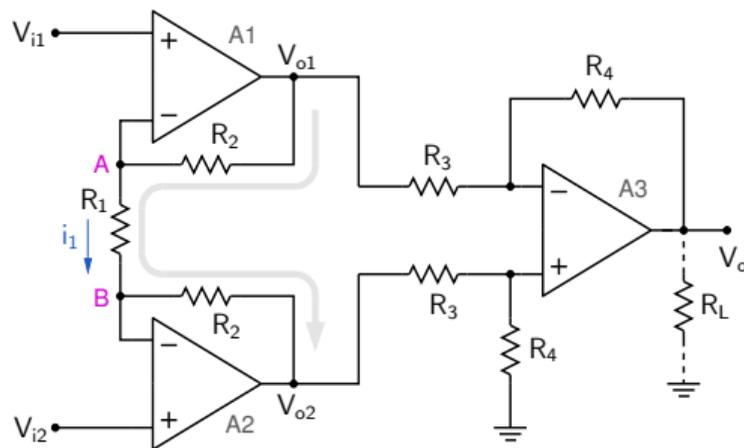
## Improved difference amplifier



$$V_+ \approx V_- \rightarrow V_A = V_{i1}, V_B = V_{i2}, \rightarrow i_1 = \frac{1}{R_1} (V_{i1} - V_{i2}).$$

Large input resistance of A1 and A2  $\Rightarrow$  the current through the two resistors marked  $R_2$  is also equal to  $i_1$ .

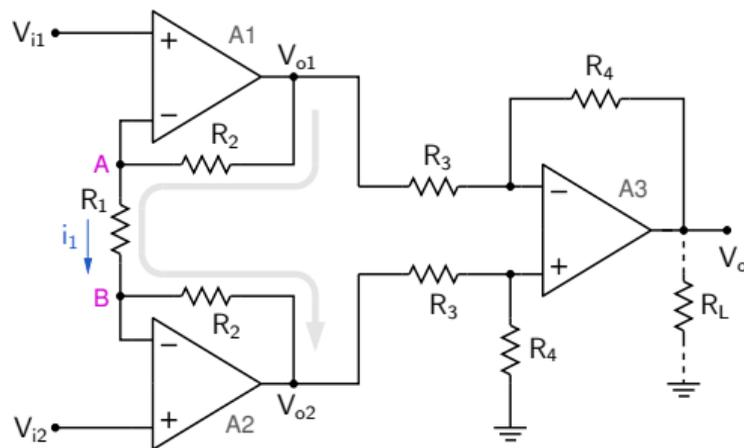
## Improved difference amplifier



$$V_+ \approx V_- \rightarrow V_A = V_{i1}, V_B = V_{i2}, \rightarrow i_1 = \frac{1}{R_1} (V_{i1} - V_{i2}).$$

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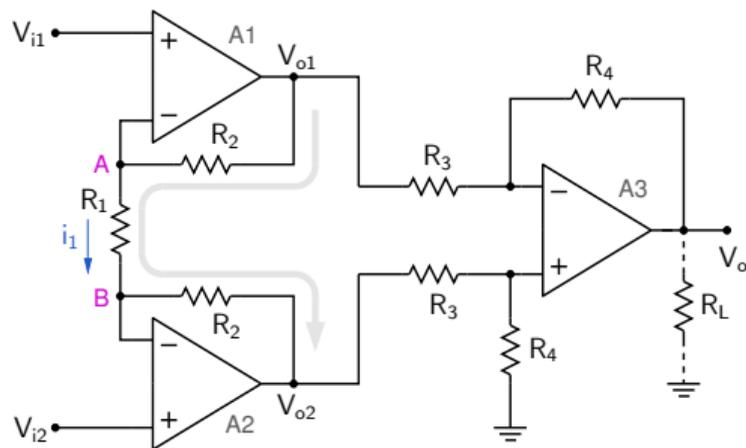


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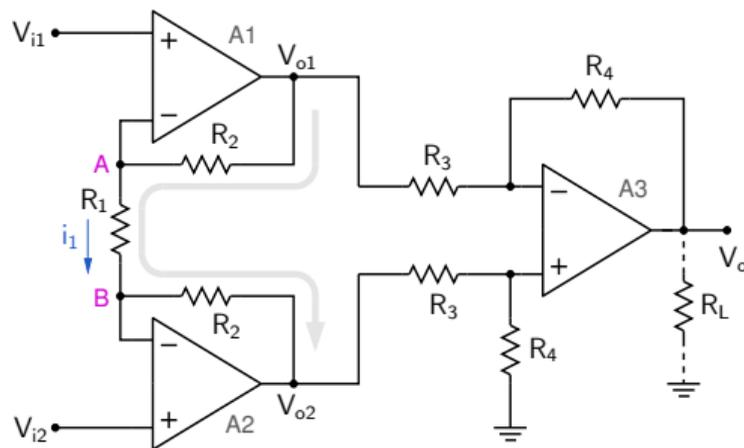


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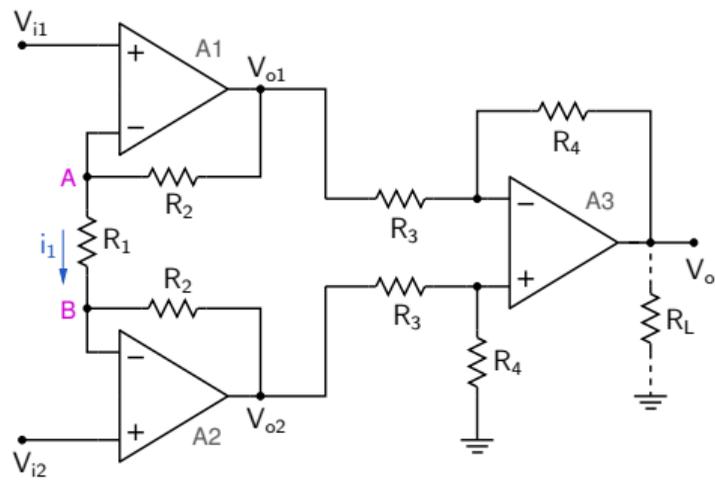
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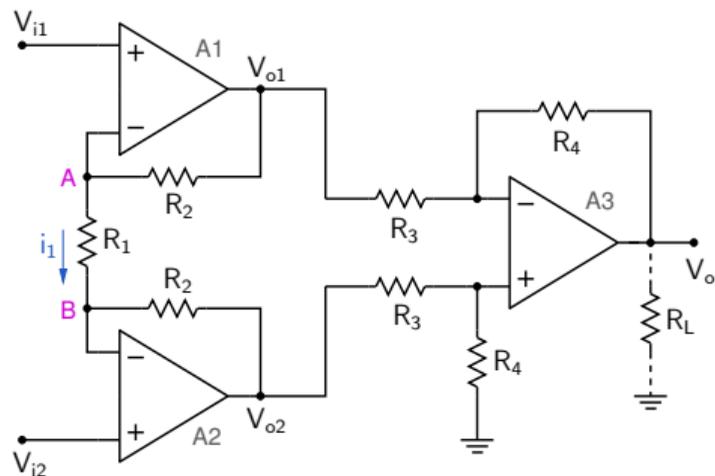
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This circuit is known as the "instrumentation amplifier."

# Instrumentation amplifier

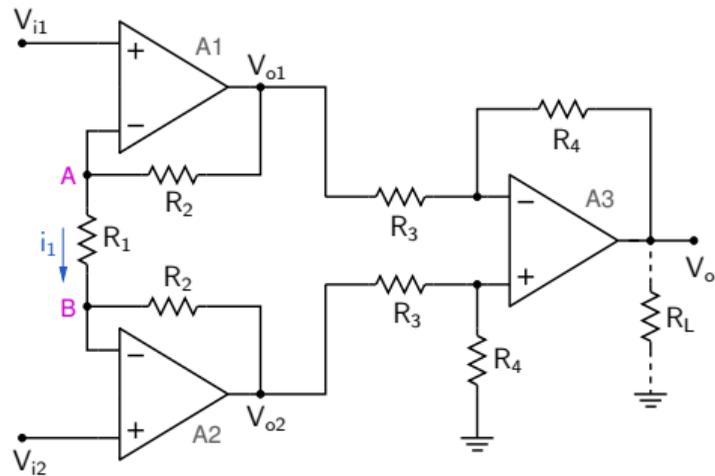


## Instrumentation amplifier



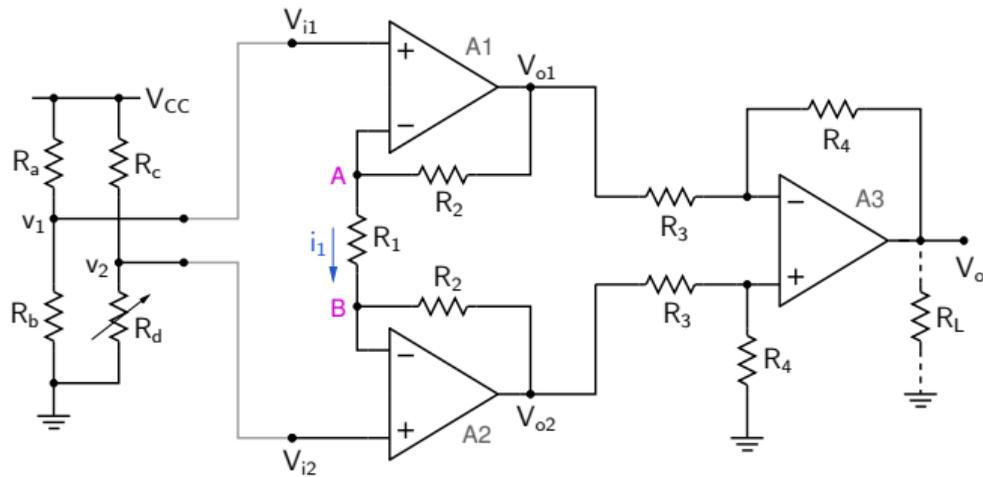
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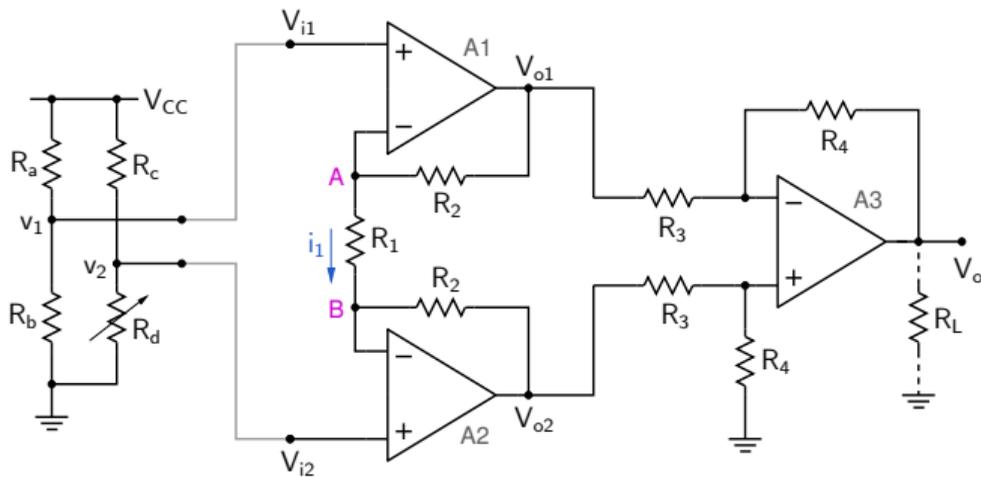
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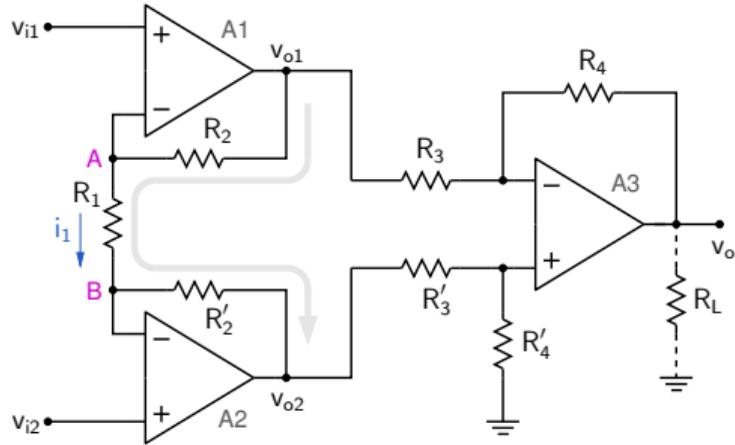


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As a result, the voltages  $v_1$  and  $v_2$  in the bridge circuit will remain essentially the same when the bridge circuit is connected to the instrumentation amplifier.

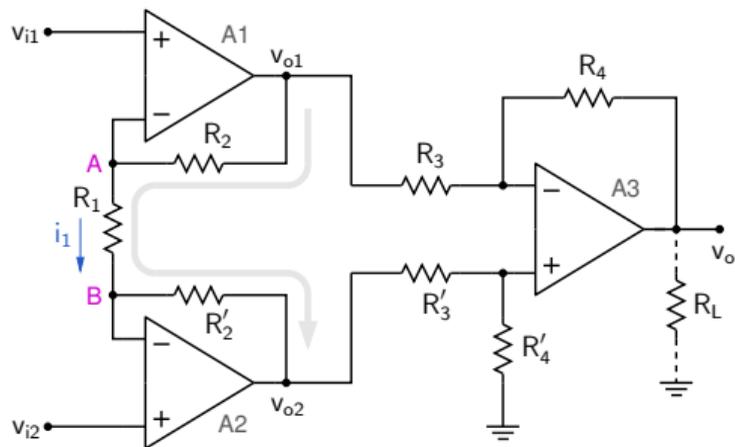
## Instrumentation amplifier: common-mode rejection



$$v_{i1} = v_c - (v_d/2)$$

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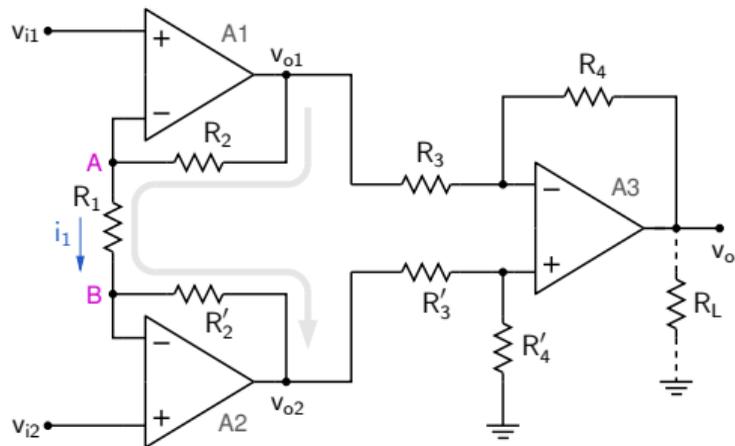
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Note that  $v_{o1}$  serves as  $v_{i1}$  for the difference amplifier, and  $v_{o2}$  as  $v_{i2}$ . Let us find the differential-mode and common-mode components associated with  $v_{o1}$  and  $v_{o2}$ .

$$v'_{id} = v_{o2} - v_{o1}, \quad v'_{ic} = \frac{1}{2} (v_{o1} + v_{o2})$$

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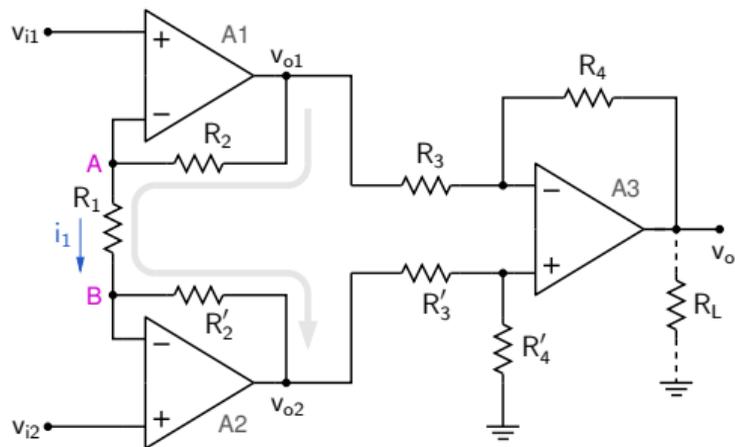
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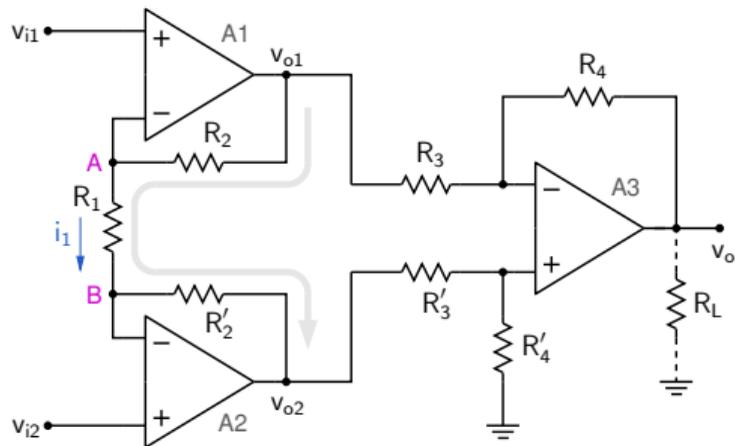
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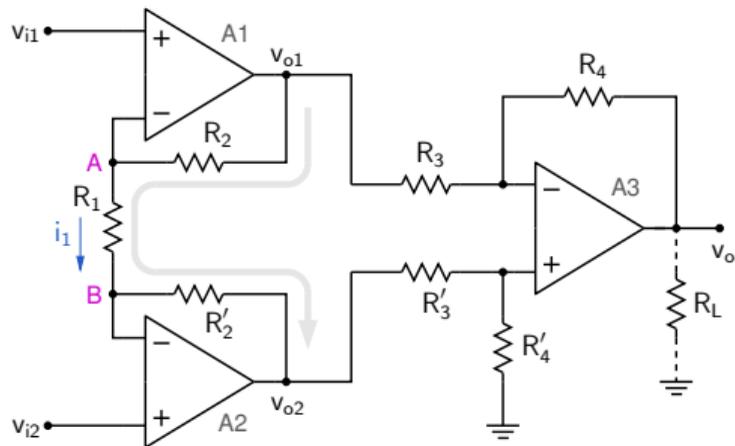
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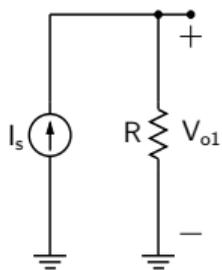
(Note that resistor mismatch in the second stage needs to be considered, but it will have a limited effect.)

Some circuits produce an output in the form of a current. It is convenient to convert this current into a voltage for further processing.

## Current-to-voltage conversion

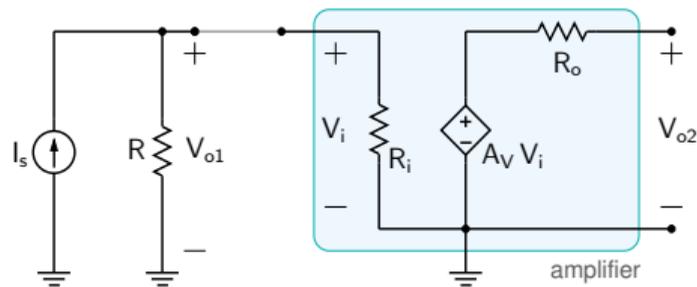
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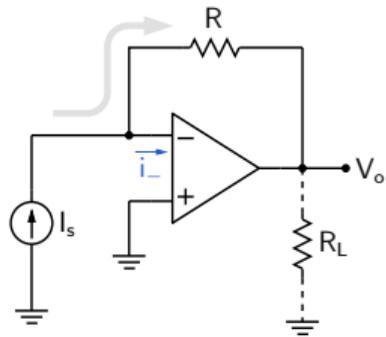
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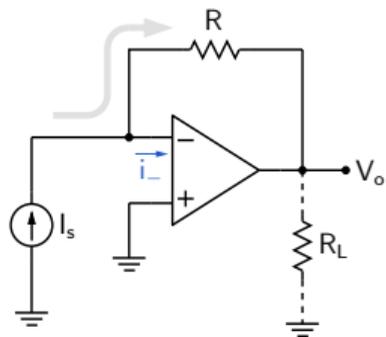


However, this simple approach will not work if the next stage in the circuit (such as an amplifier) has a finite  $R_i$ , since it will modify  $V_{o1}$  to  $V_{o1} = I_s (R_i \parallel R)$ , which is not desirable.

## Current-to-voltage conversion

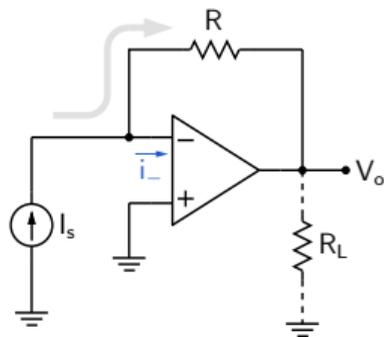


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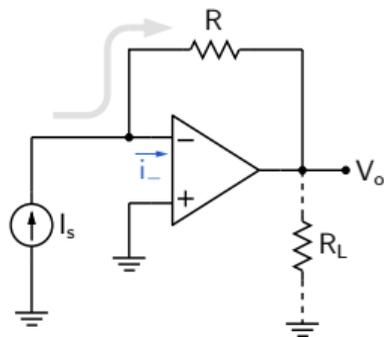
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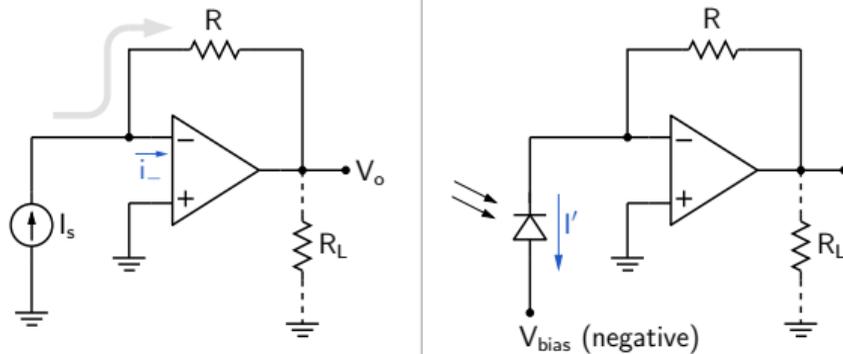


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Example: a photocurrent detector.

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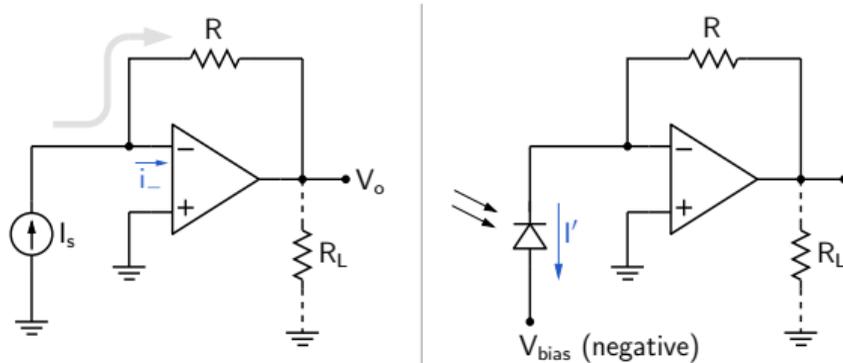


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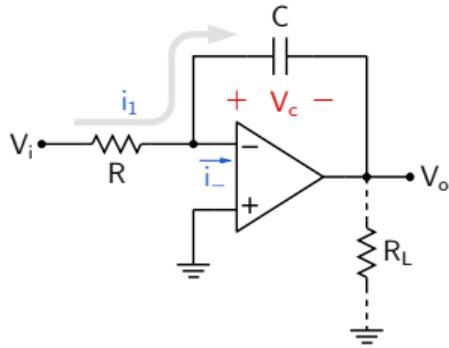
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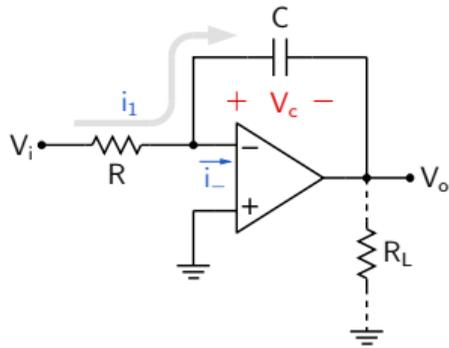
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$$V_o = I' R. \text{ (Note: The diode is under a reverse bias, with } V_n = 0 \text{ V and } V_p = V_{\text{bias}}.)$$

## Op-amp circuits (linear region)

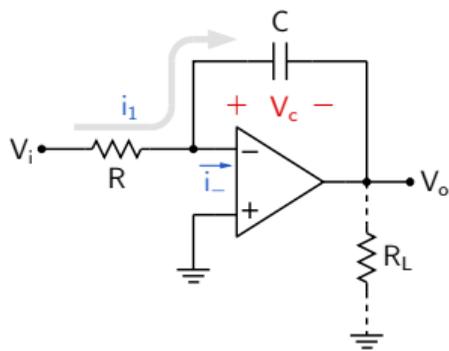


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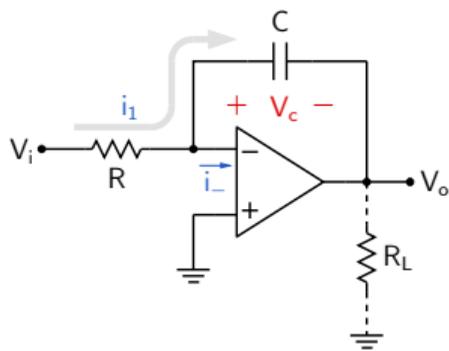


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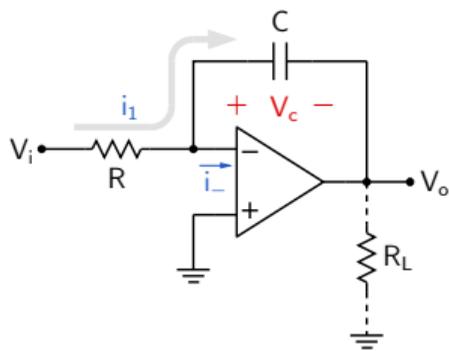
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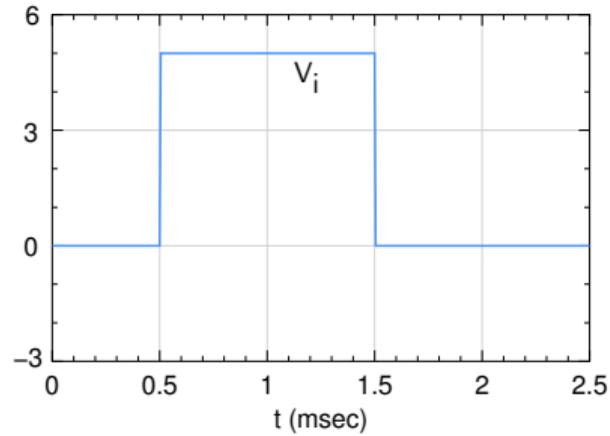
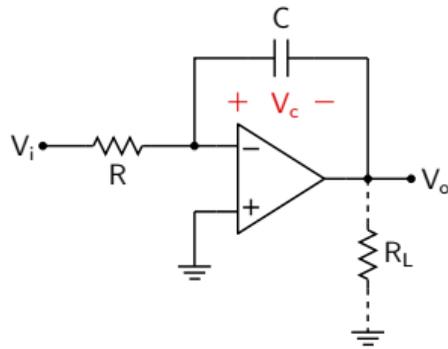
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$$V_o = -\frac{1}{RC} \int V_i dt$$

The circuit works as an integrator.

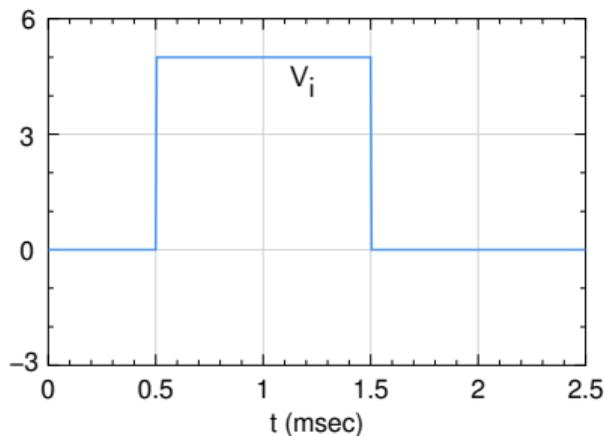
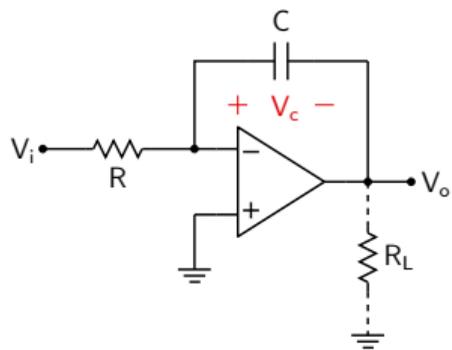
# Integrator



Given:  $R = 10\text{ k}$ ,  $C = 0.2\ \mu\text{F}$ .

If  $V_o = 0\text{ V}$  at  $t = 0$ , find  $V_o(t)$  (Let  $t_0 = 0.5\text{ msec}$ ,  $t_1 = 1.5\text{ msec}$ ).

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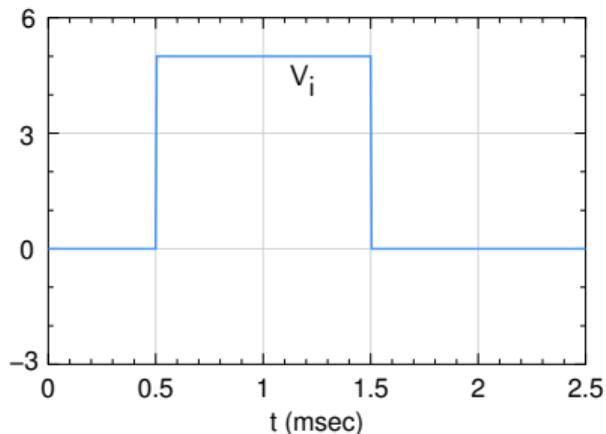
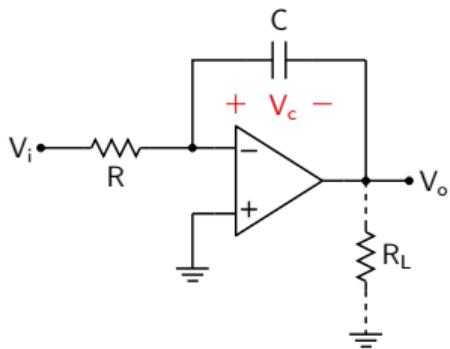


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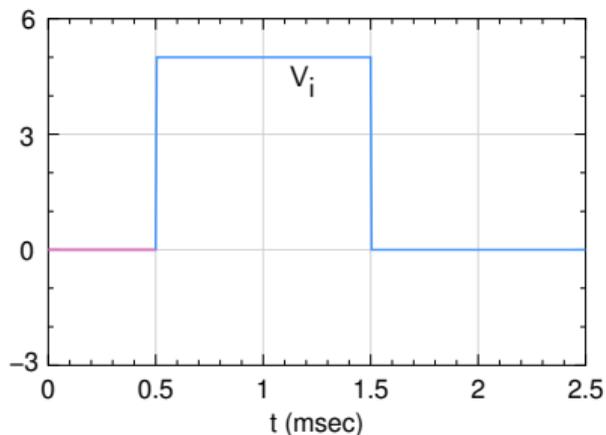
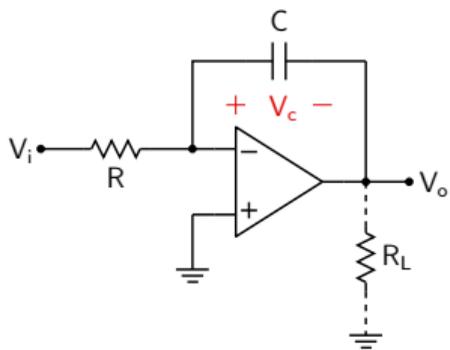
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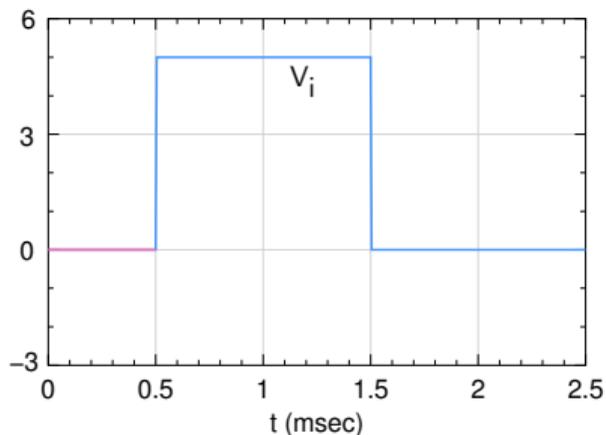
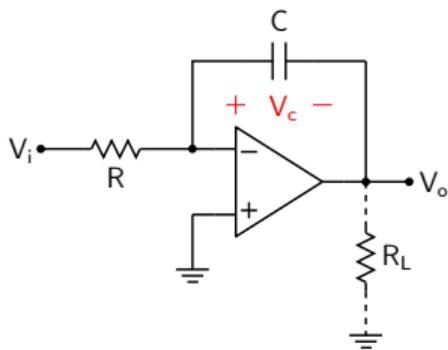
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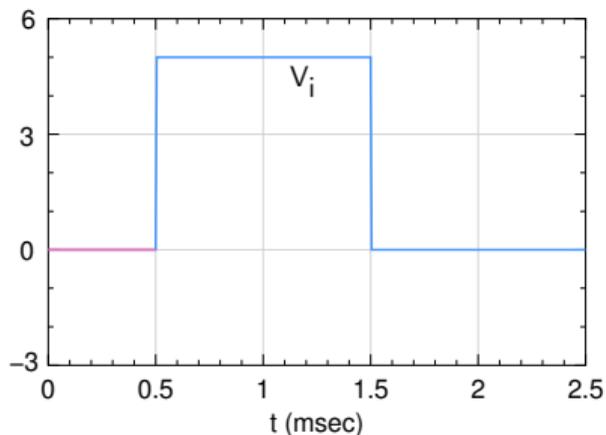
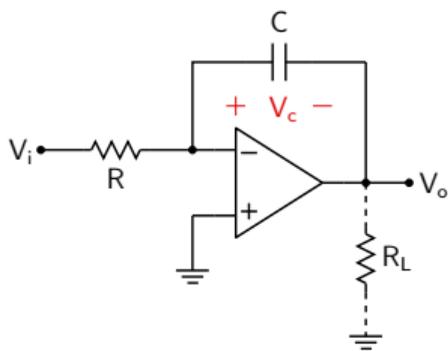
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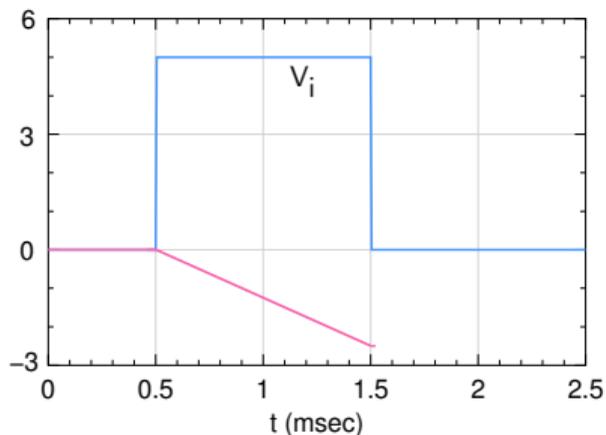
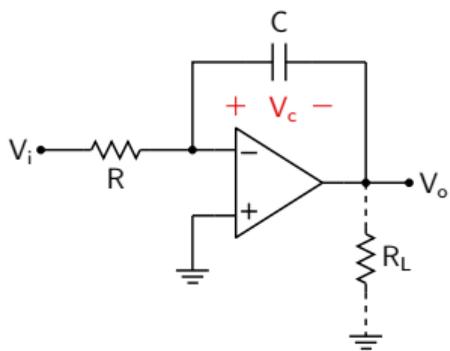
$$V_o = -\frac{1}{RC} \int V_i dt, \quad \tau \equiv RC = 2\text{ msec}.$$

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At  $t = t_1$ ,  $V(t_1) - V(t_0) = -\frac{1}{2\text{ msec}} 5\text{ V} \times 1\text{ msec} = -2.5\text{ V} \rightarrow V_o(t_1) = -2.5\text{ V}$ .

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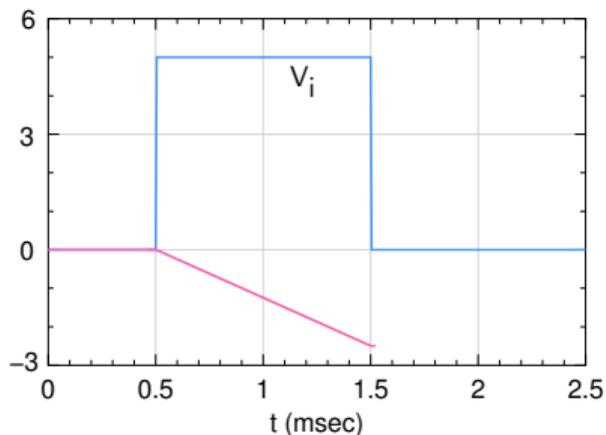
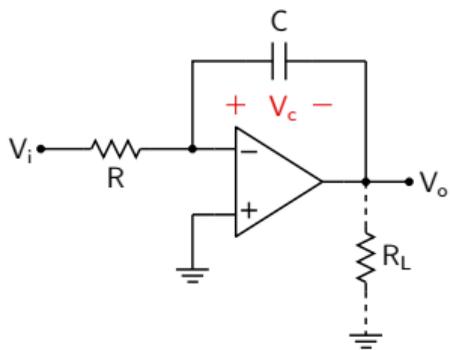
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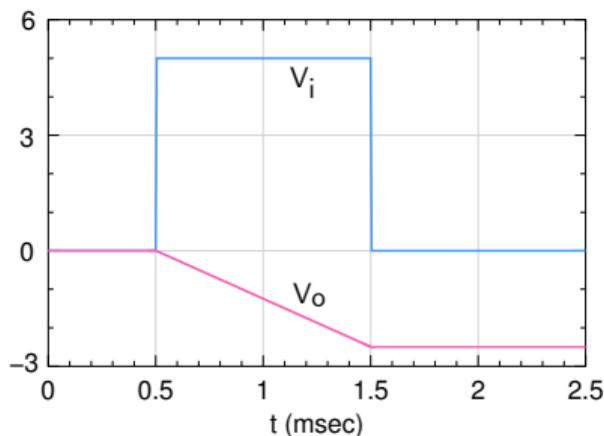
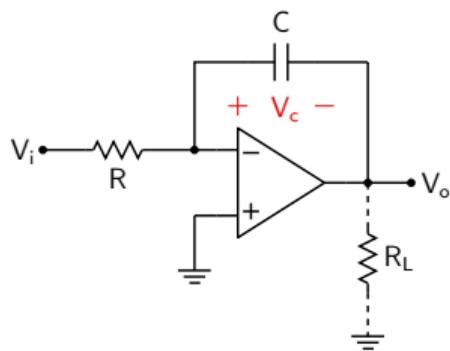
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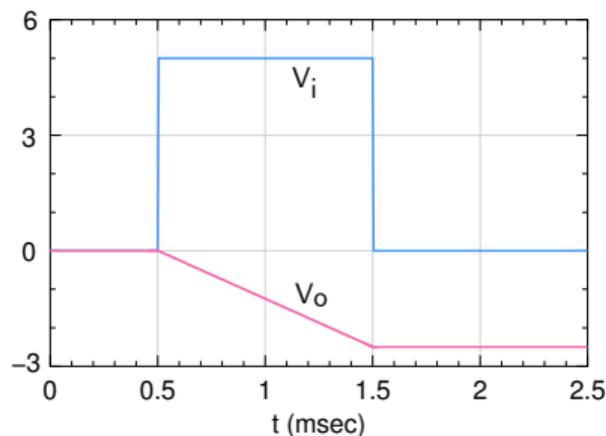
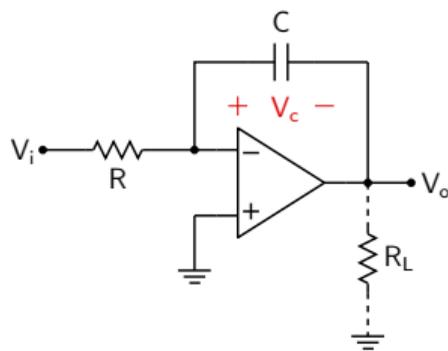
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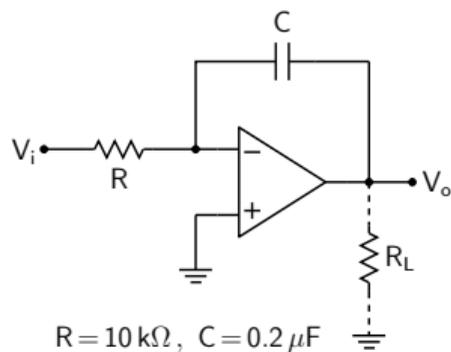
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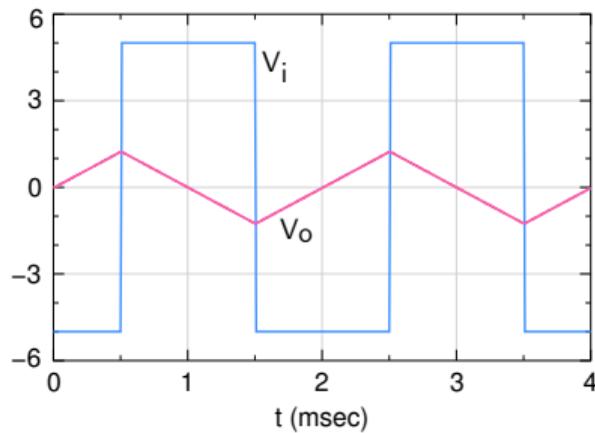
SEQUEL file: ee101\_integrator\_1.sqproj

# Integrator

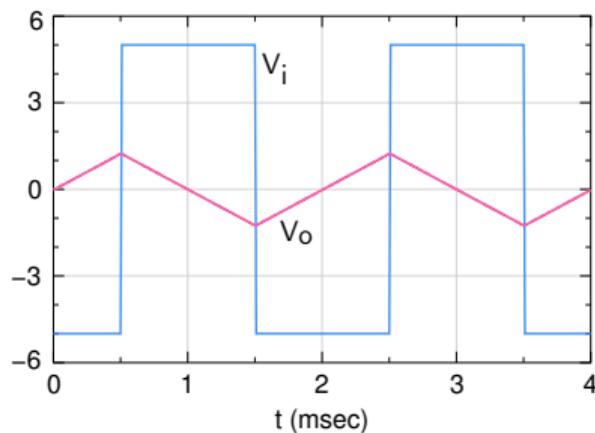
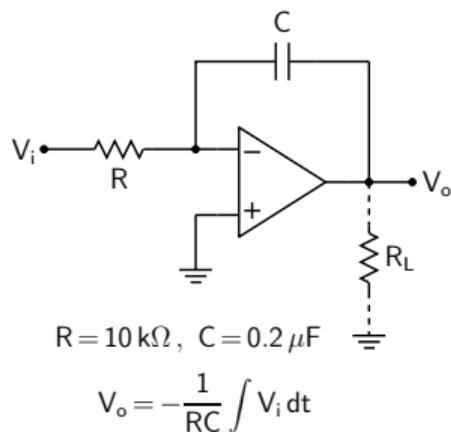


$$R = 10 \text{ k}\Omega, C = 0.2 \mu\text{F}$$

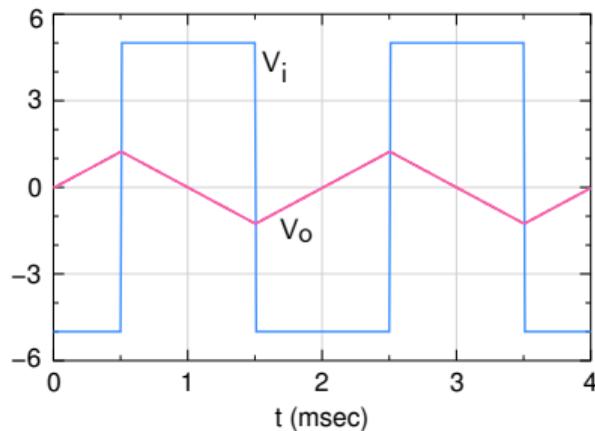
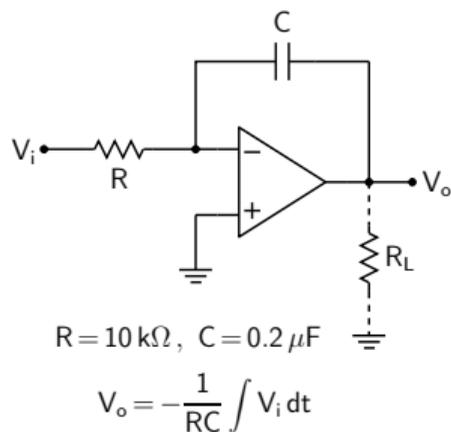
$$V_o = -\frac{1}{RC} \int V_i dt$$



- \* An integrator can be used to convert a square wave to a triangle wave.



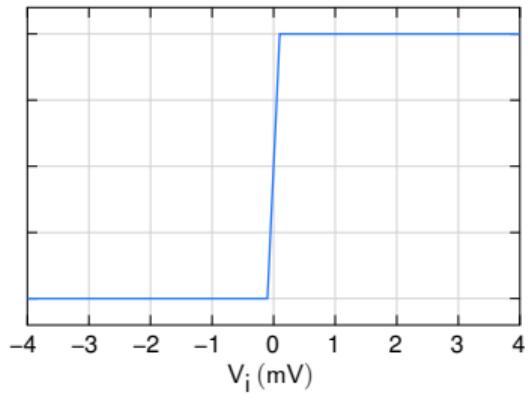
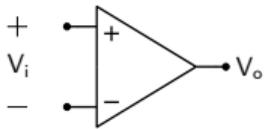
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- \* In practice, the circuit needs a small modification, as discussed in the following.



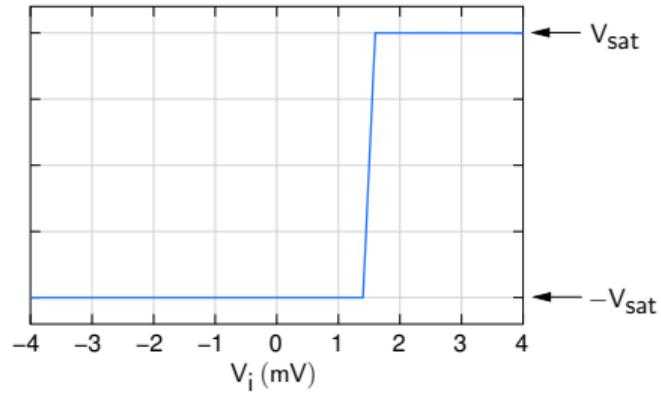
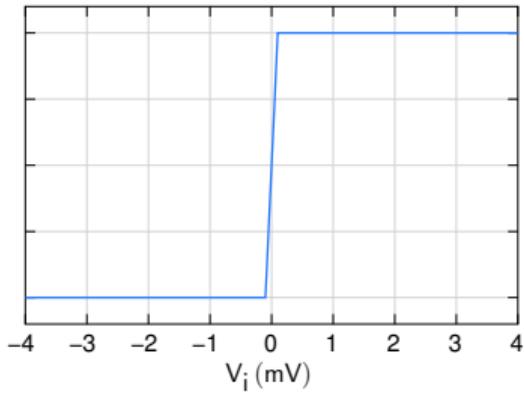
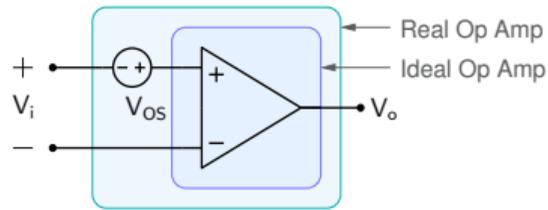
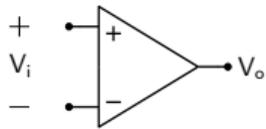
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SEQUEL file: ee101\_integrator\_2.sqproj

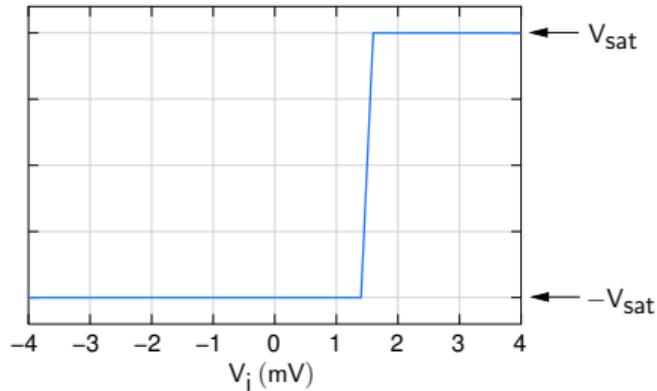
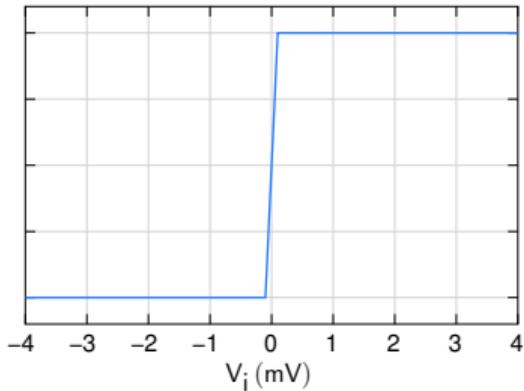
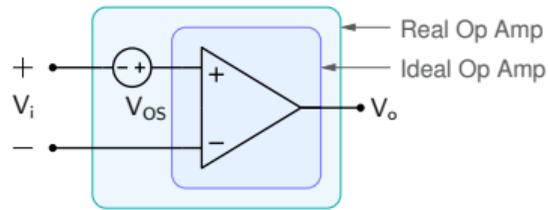
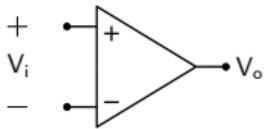
# Practical op-amps: Offset voltage



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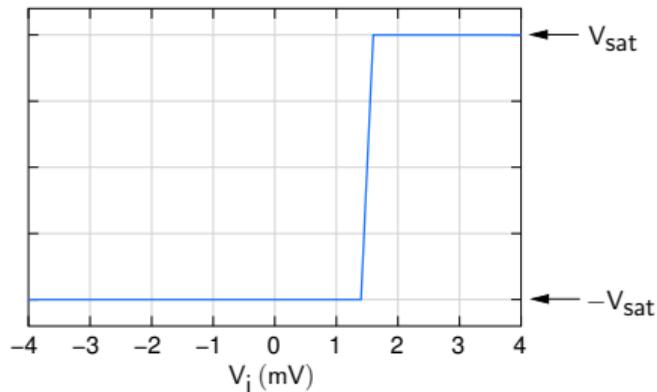
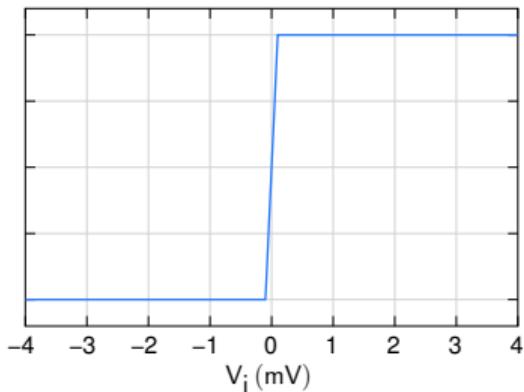
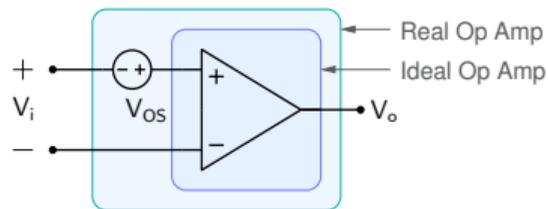
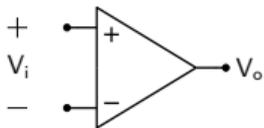


## Practical op-amps: Offset voltage



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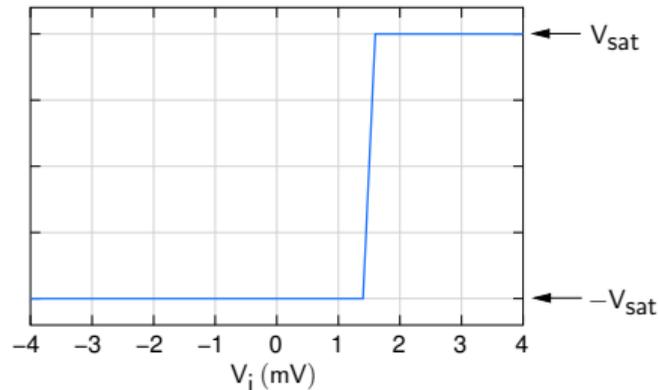
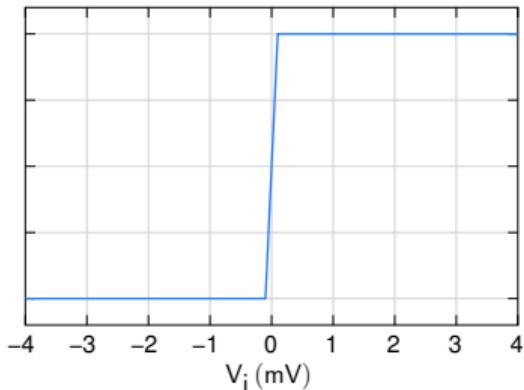
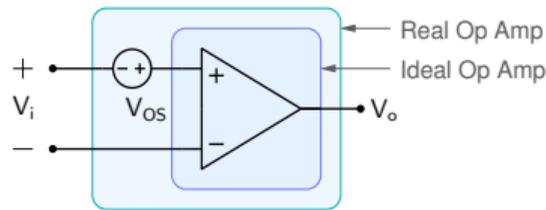
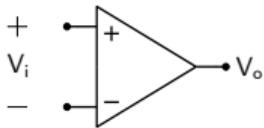
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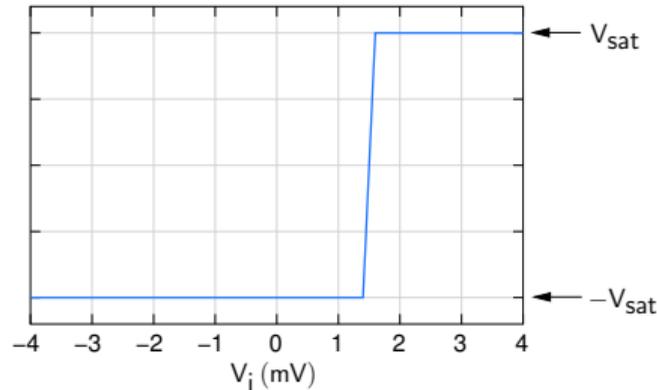
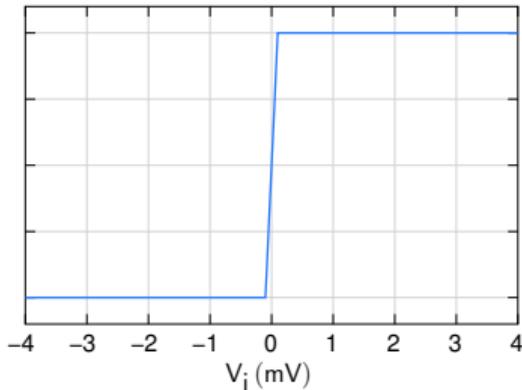
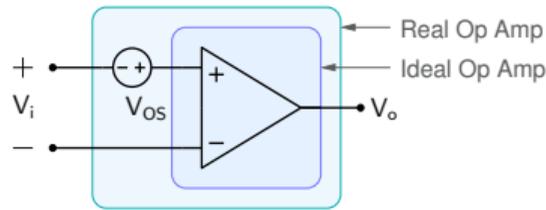
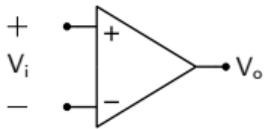


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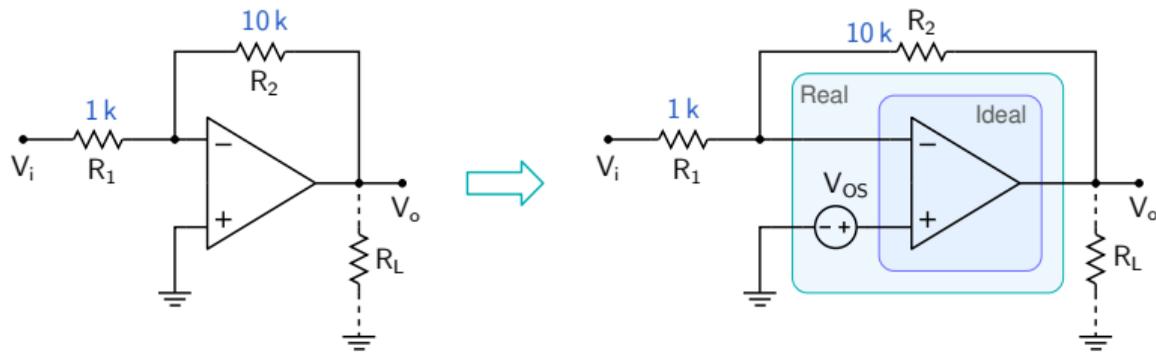
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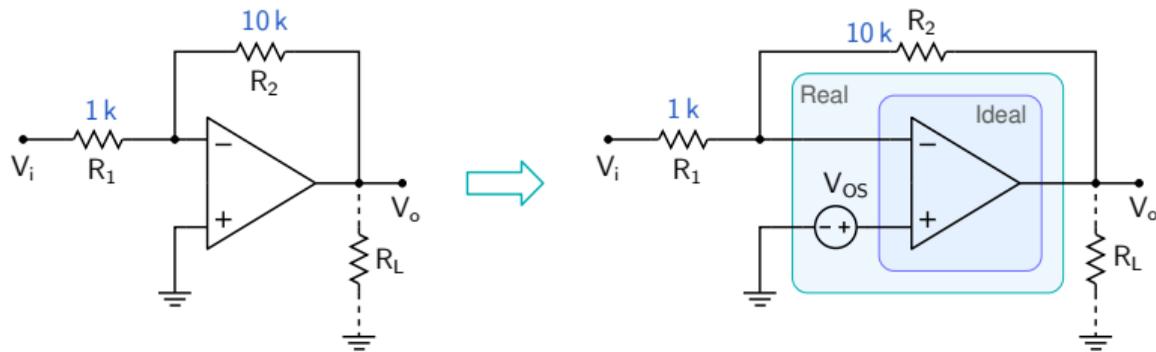
$V_o$  versus  $V_i$  curve gets shifted (Note:  $V_{OS}$  is negative in the above example).

741:  $-6$  mV  $< V_{OS} < 6$  mV, OP-77:  $-50$   $\mu$ V  $< V_{OS} < 50$   $\mu$ V.

## Effect of $V_{OS}$ : inverting amplifier

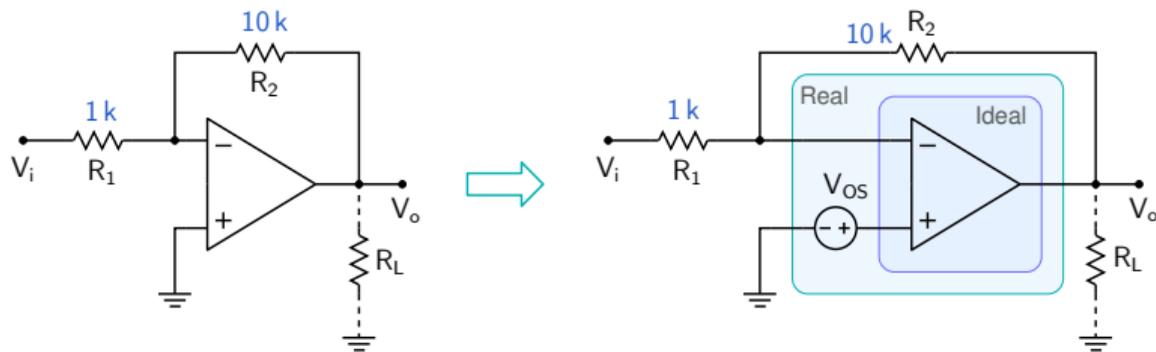


## Effect of $V_{OS}$ : inverting amplifier



By superposition, 
$$V_o = -\frac{R_2}{R_1} V_i + V_{OS} \left(1 + \frac{R_2}{R_1}\right).$$

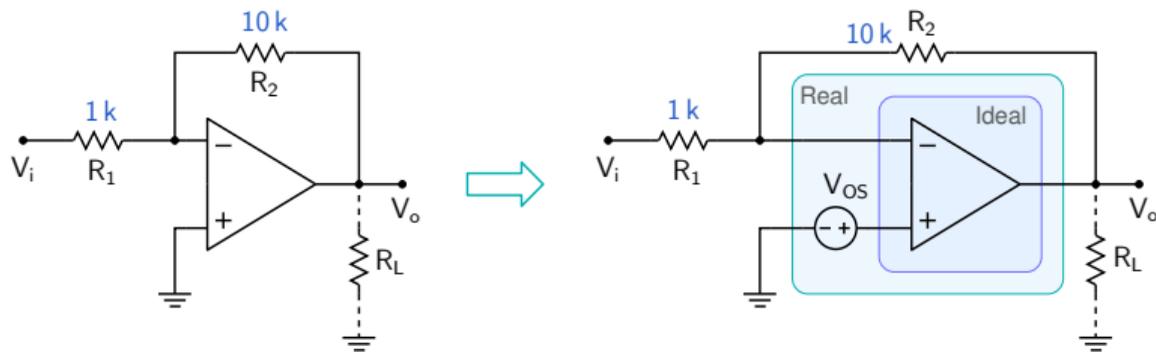
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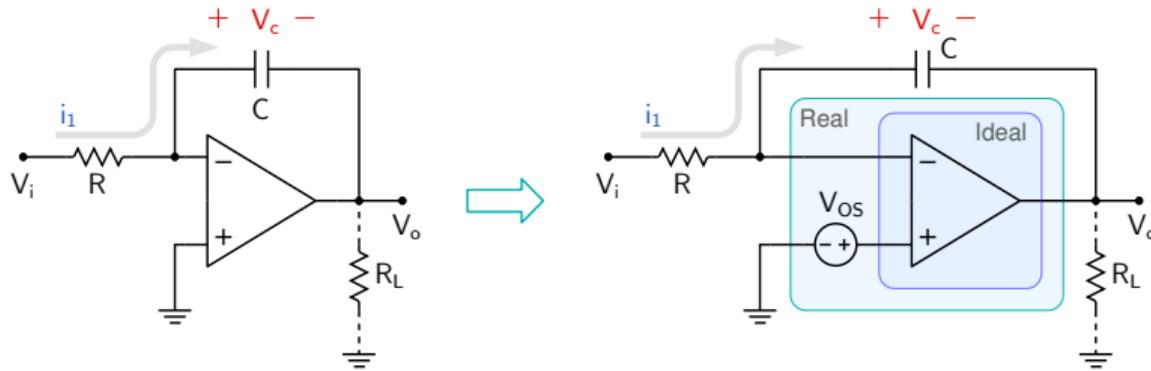


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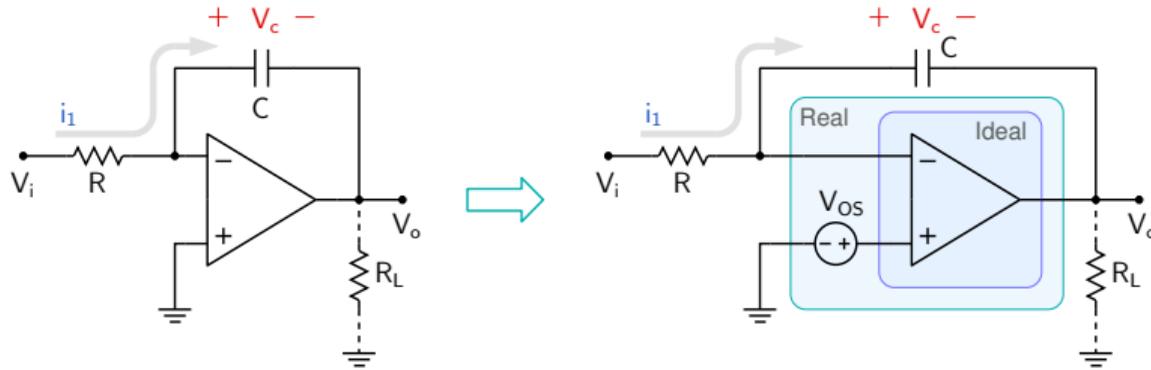
For  $V_{OS} = 2\text{ mV}$ , the contribution from  $V_{OS}$  to  $V_o$  is  $22\text{ mV}$ ,

i.e., a DC shift of  $22\text{ mV}$ .

## Effect of $V_{OS}$ : integrator

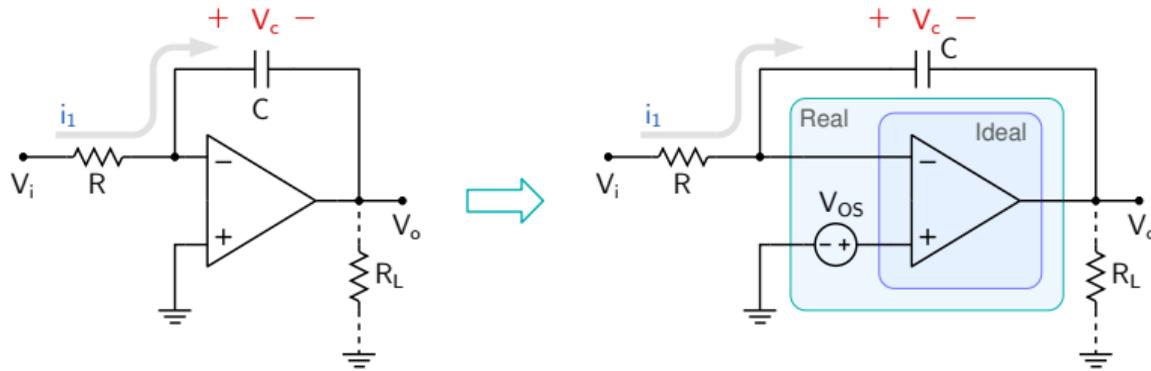


## Effect of $V_{OS}$ : integrator



$$V_- \approx V_+ = V_{OS} \rightarrow i_1 = \frac{1}{R}(V_i - V_{OS}) = C \frac{dV_c}{dt}.$$

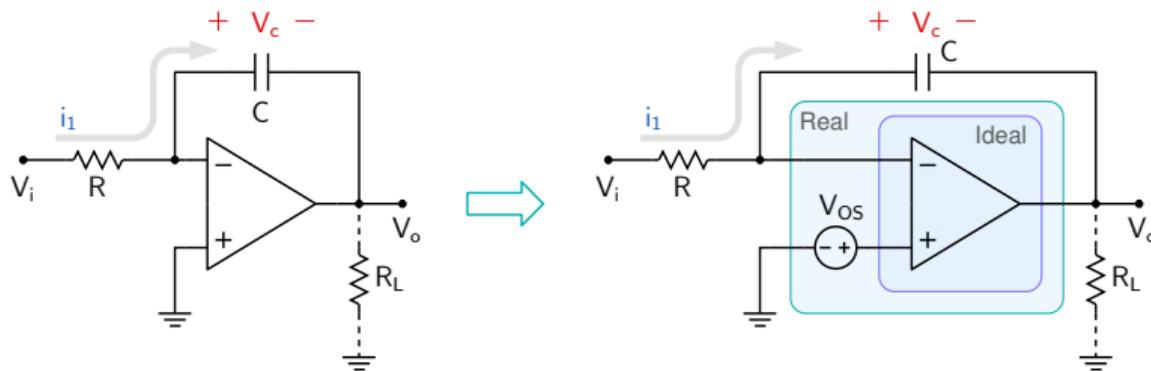
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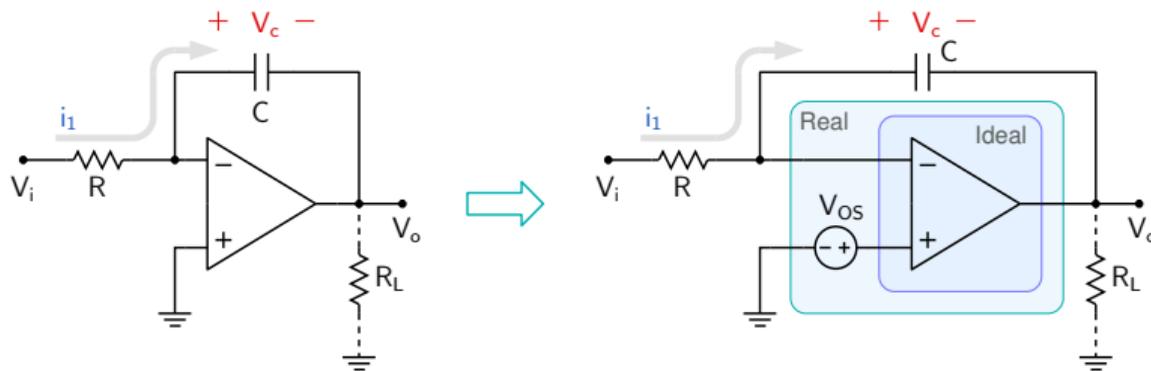
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Eventually, the Op Amp will be driven into saturation.

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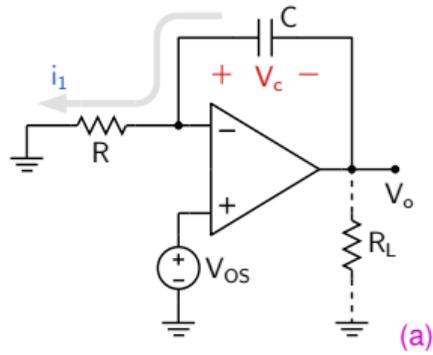
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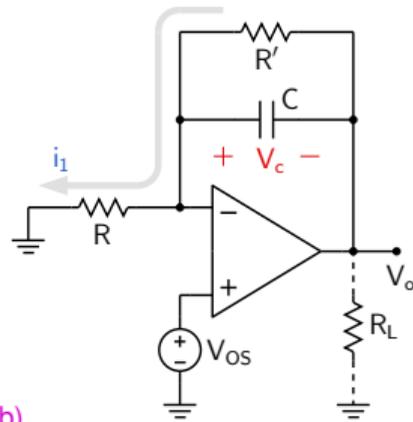
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→ need to address this issue!

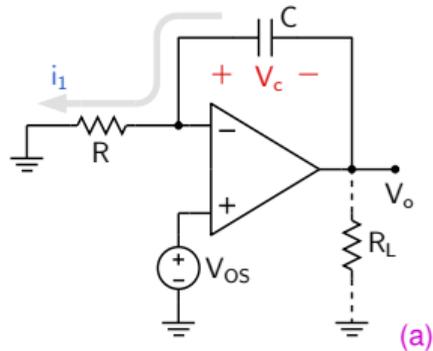
# Effect of $V_{OS}$ : integrator with $V_i = 0$



(a)

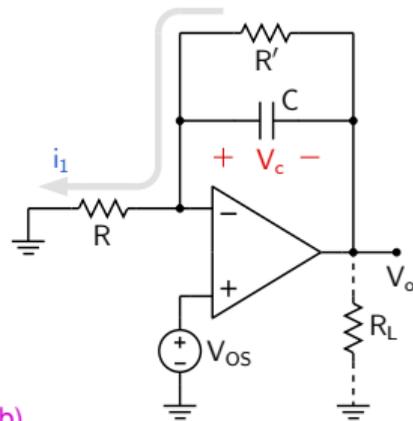


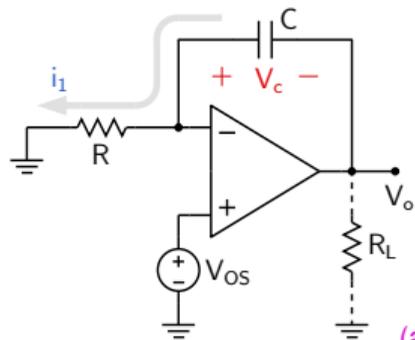
(b)



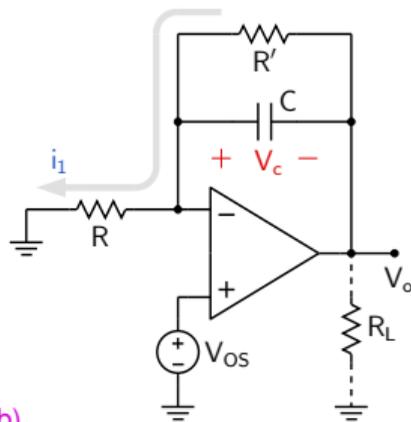
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$$V_c = -\frac{1}{RC} \int V_{OS} dt \rightarrow \text{op-amp saturates.}$$





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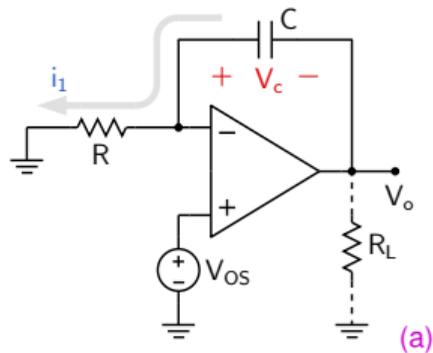
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(b) There is a DC path for the current.

$$\rightarrow V_o = \left(1 + \frac{R'}{R}\right) V_{OS}.$$



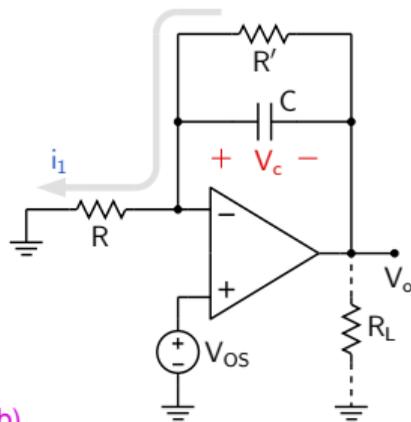
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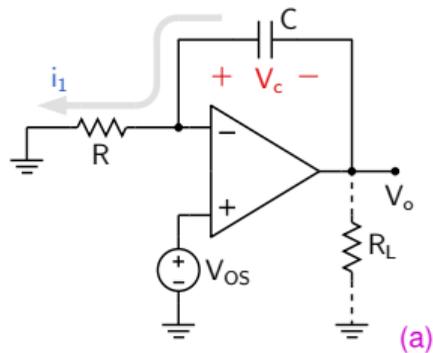
$$V_c = -\frac{1}{RC} \int V_{OS} dt \rightarrow \text{op-amp saturates.}$$

(b) There is a DC path for the current.

$$\rightarrow V_o = \left(1 + \frac{R'}{R}\right) V_{OS}.$$

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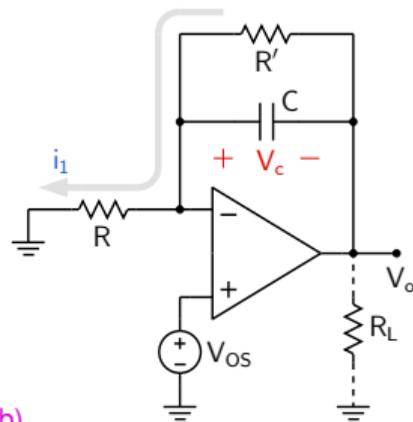


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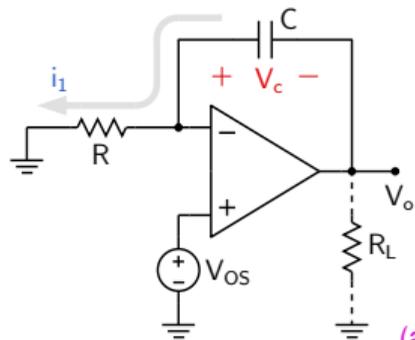
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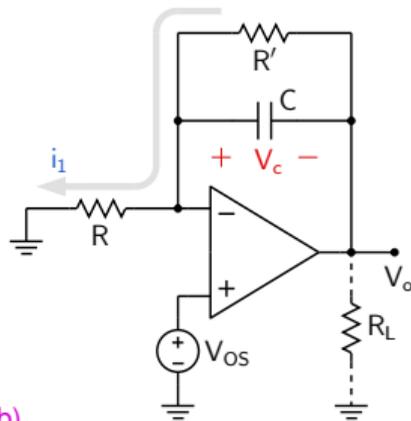


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However,  $R'$  must be large enough to ensure that the circuit still functions as an integrator.



(a)



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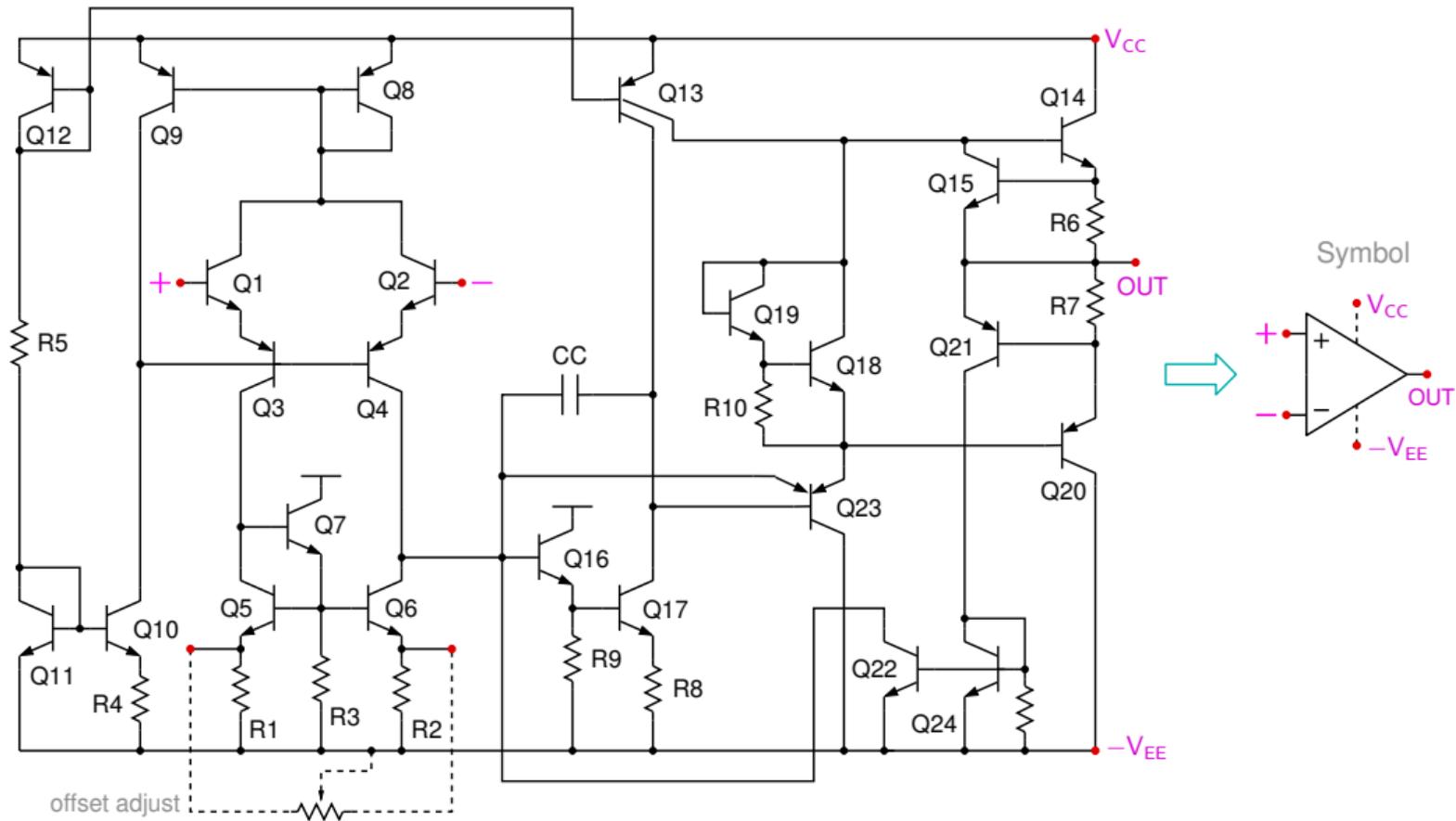
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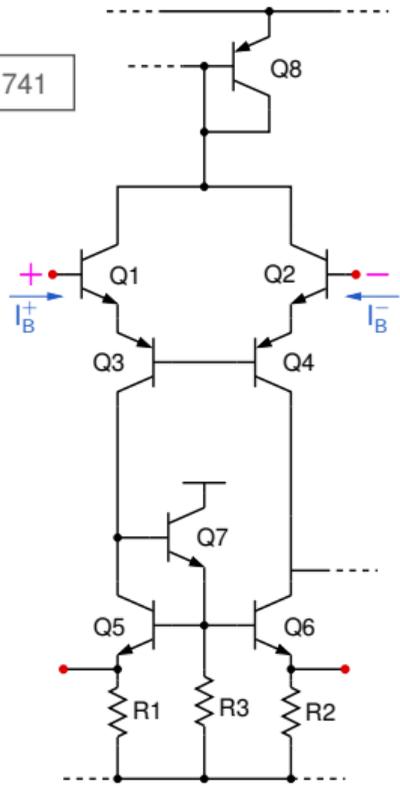
$\rightarrow R' \gg 1/\omega C$  at the frequency of interest.

# Op-amp 741: offset null



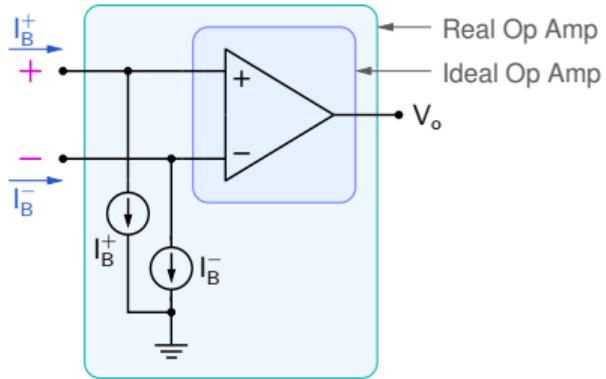
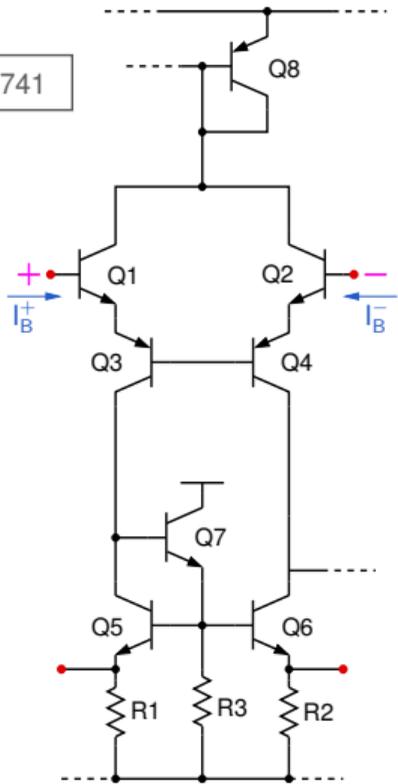
# Input bias currents

741

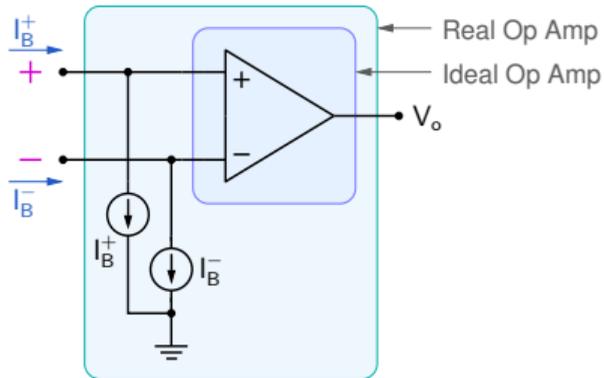
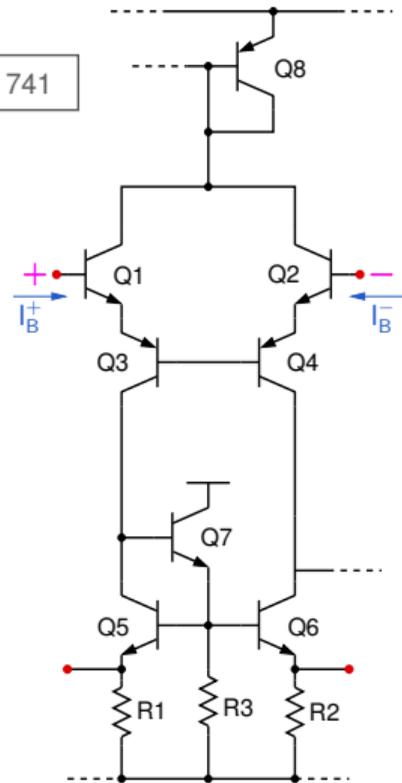


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741

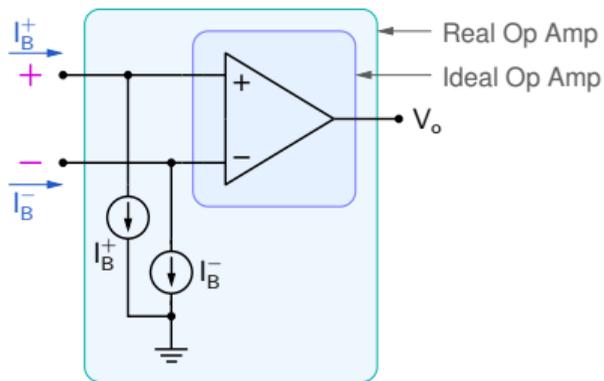
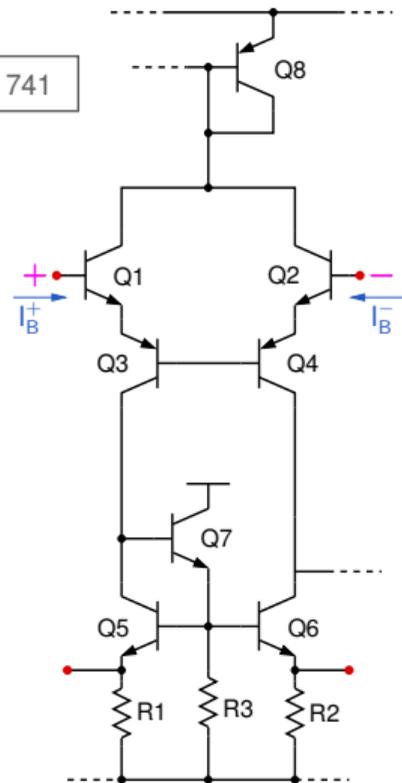


# Input bias currents



$I_B^+$  and  $I_B^-$  are generally not equal.  
 $|I_B^+ - I_B^-|$  : "offset current" ( $I_{OS}$ )  
 $(I_B^+ + I_B^-)/2$  : "bias current" ( $I_B$ )

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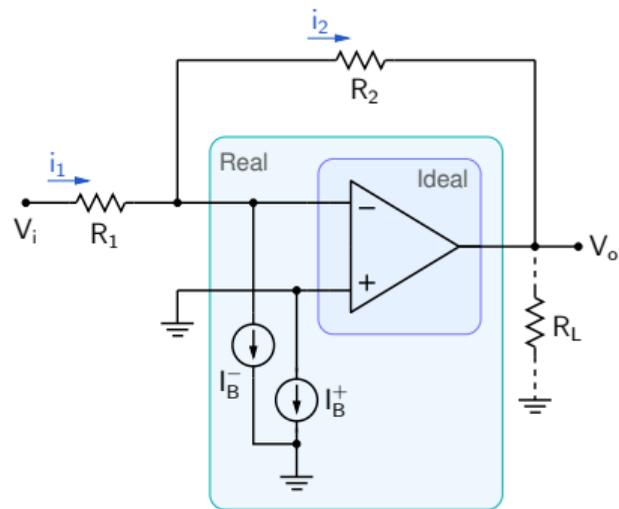


Typical values

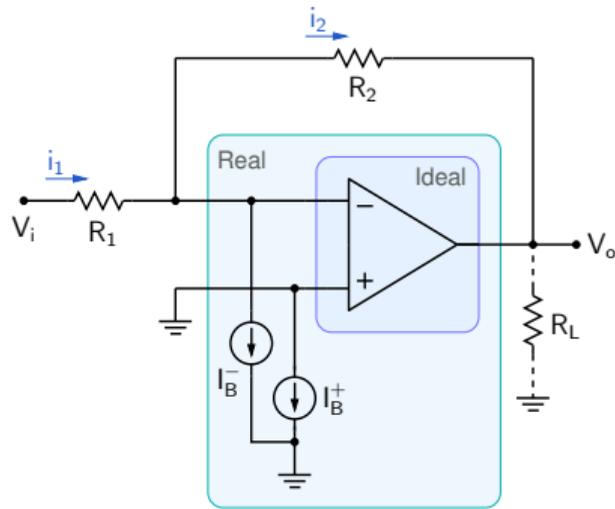
Op-Amp	$I_B$	$I_{OS}$	$V_{OS}$	Type
741	80 nA	20 nA	1 mV	BJT input
OP77	1.2 nA	0.3 nA	$10 \mu V$	BJT input
411	50 pA	25 pA	0.8 mV	FET input

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## Effect of bias currents: inverting amplifier

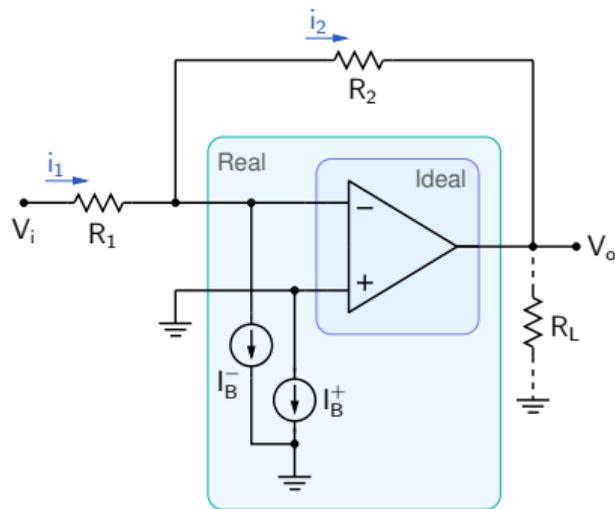


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Assume that the op-amp is ideal in other respects (including  $V_{OS} = 0\text{ V}$ ).

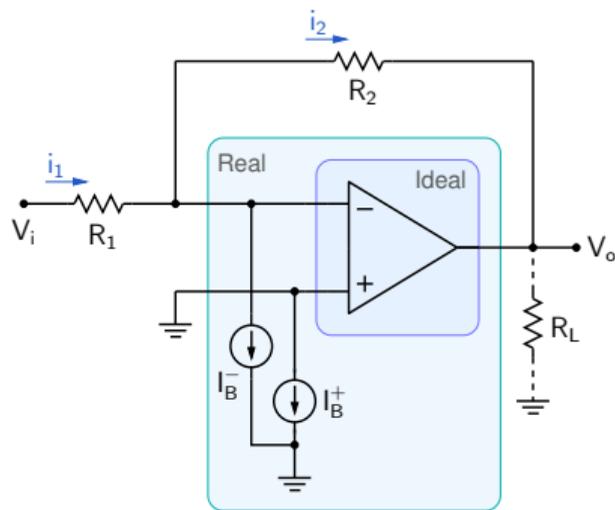
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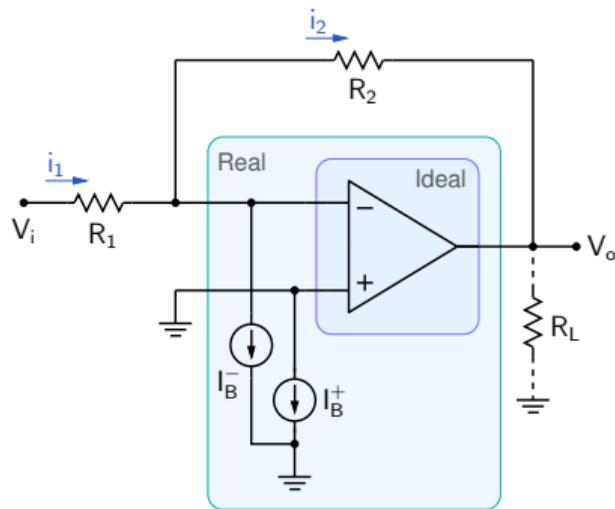


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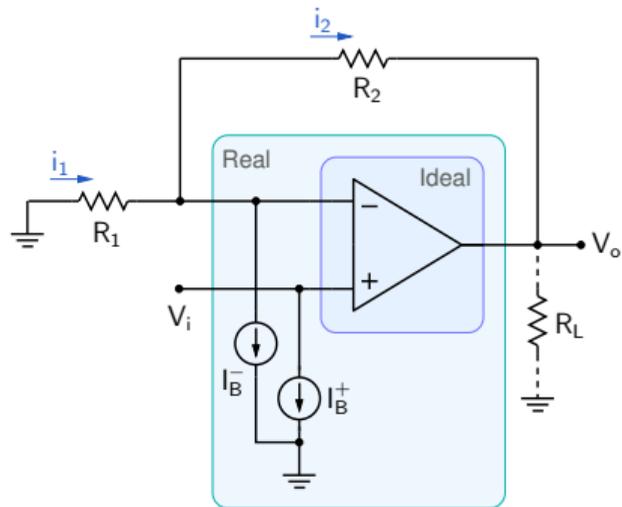
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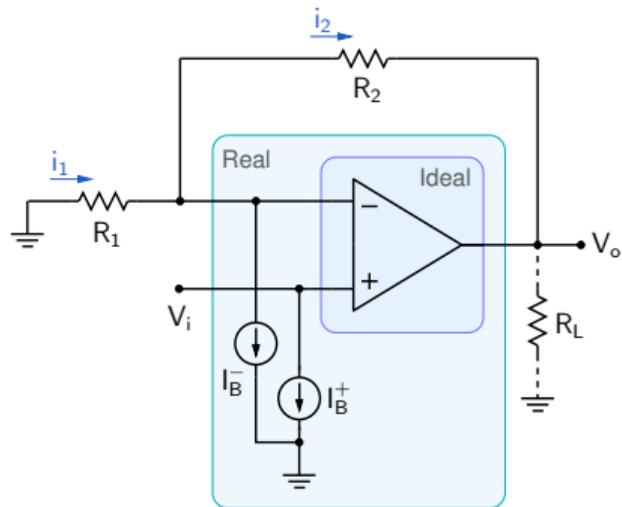
i.e., the bias current causes a DC shift in  $V_o$ .

$$\text{For } I_B^- = 80\text{ nA}, R_2 = 10\text{ k}, \Delta V_o = 0.8\text{ mV}.$$

## Effect of bias currents: non-inverting amplifier

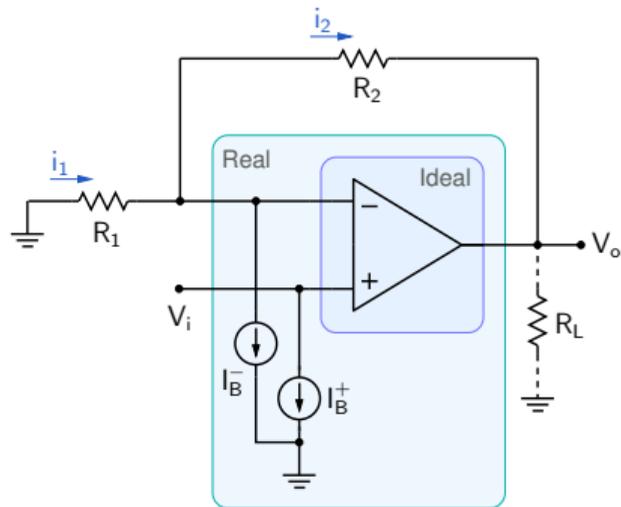


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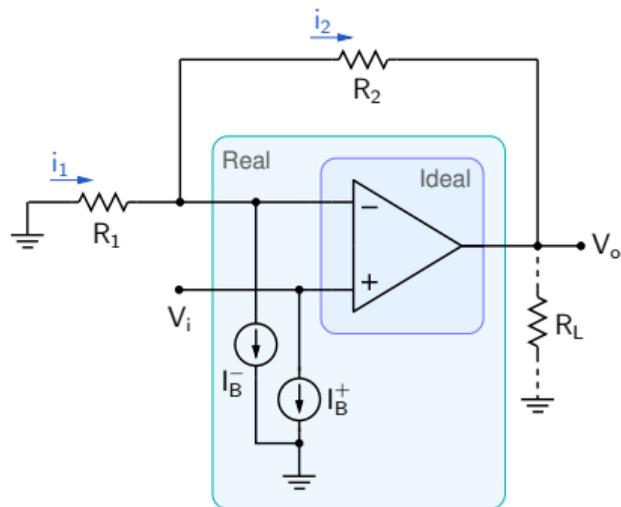
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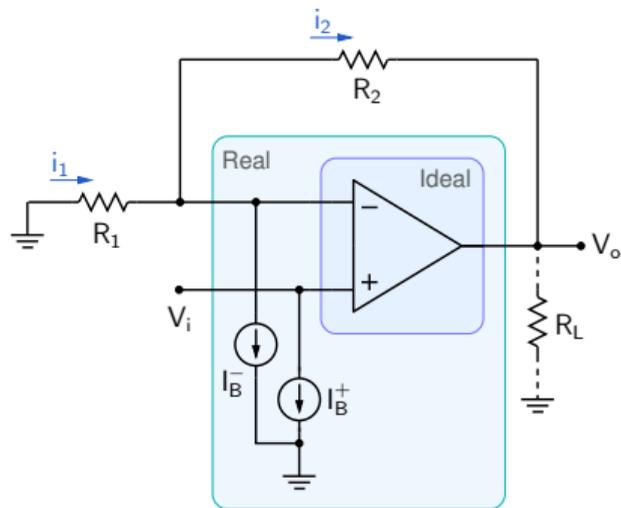


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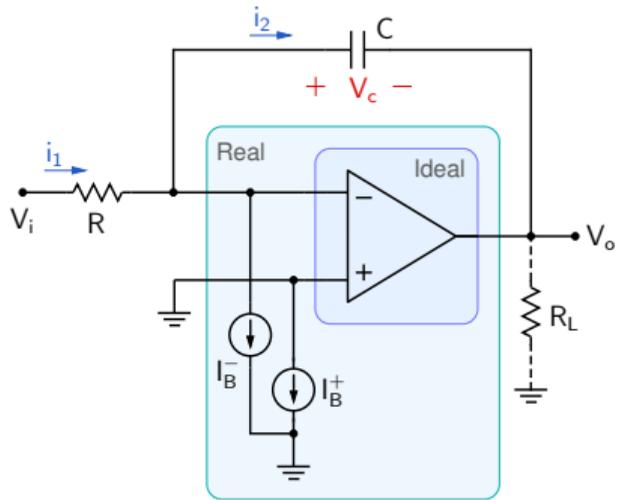
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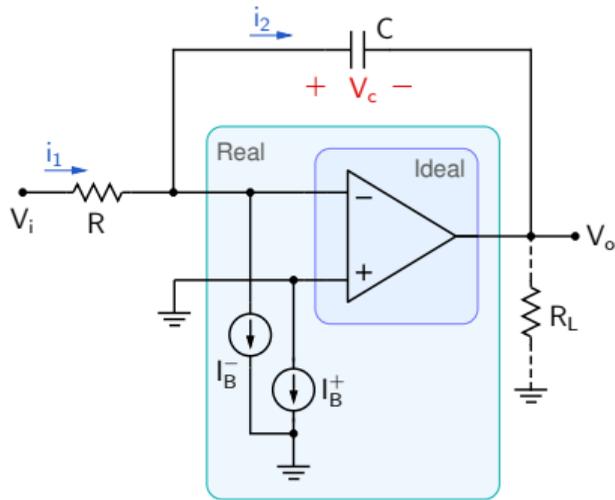
$$V_o = V_- - i_2 R_2 = V_i - \left(-\frac{V_i}{R_1} - I_B^-\right) R_2 = V_i \left(1 + \frac{R_2}{R_1}\right) + I_B^- R_2.$$

→ Again, a DC shift  $\Delta V_o$ .

## Effect of bias currents: integrator

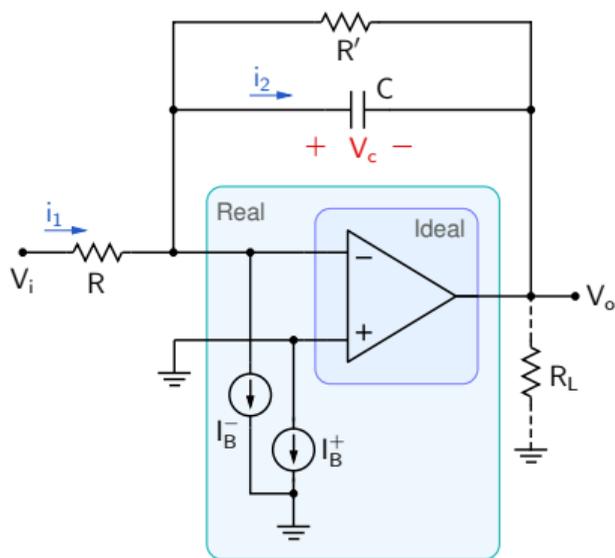


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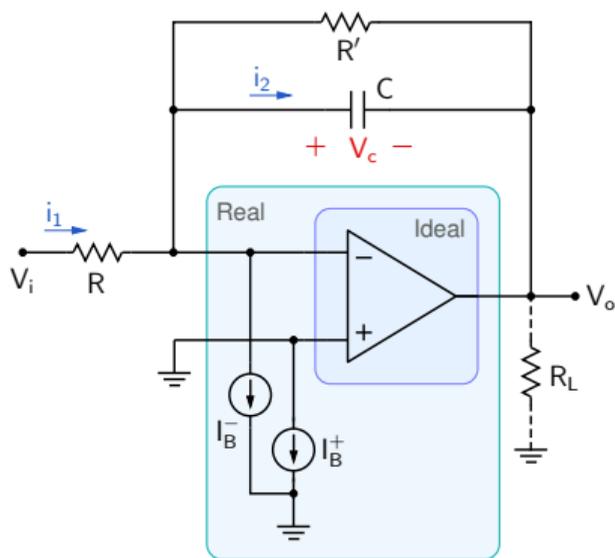
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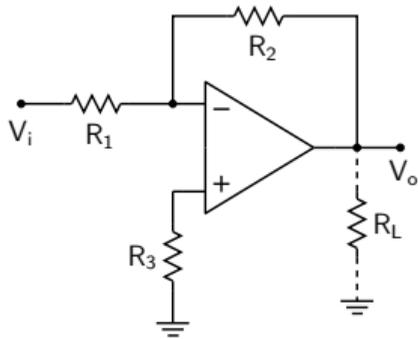
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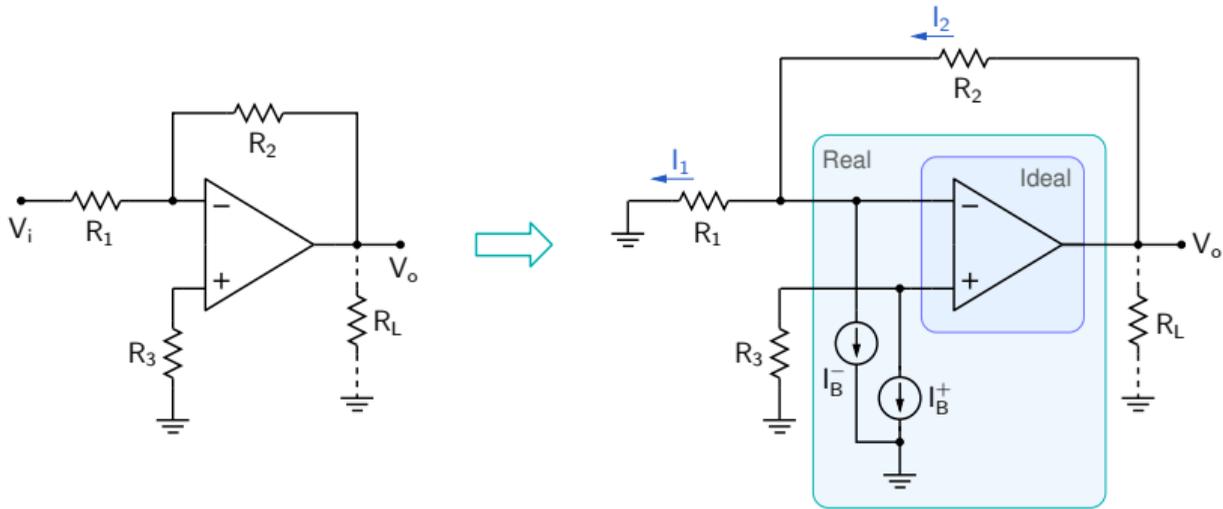
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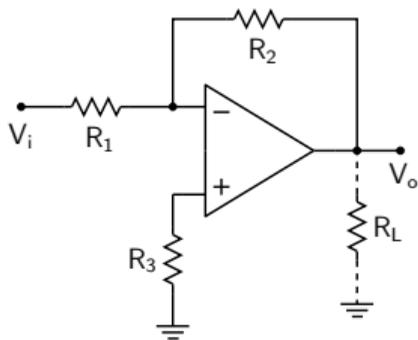
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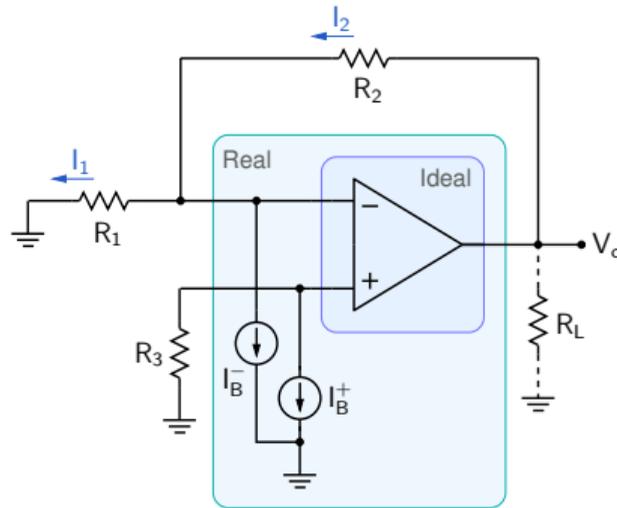
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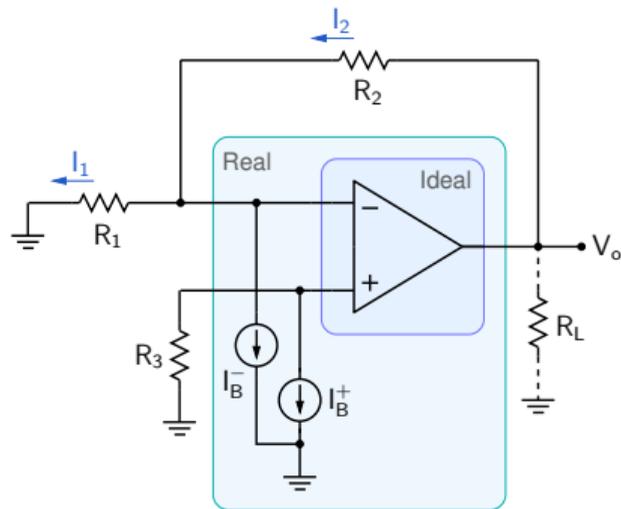
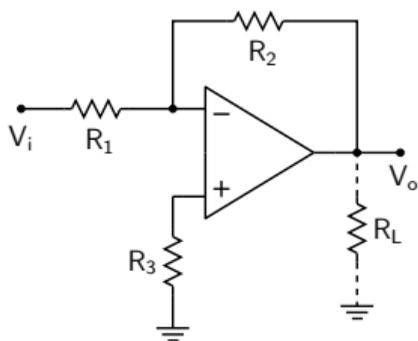


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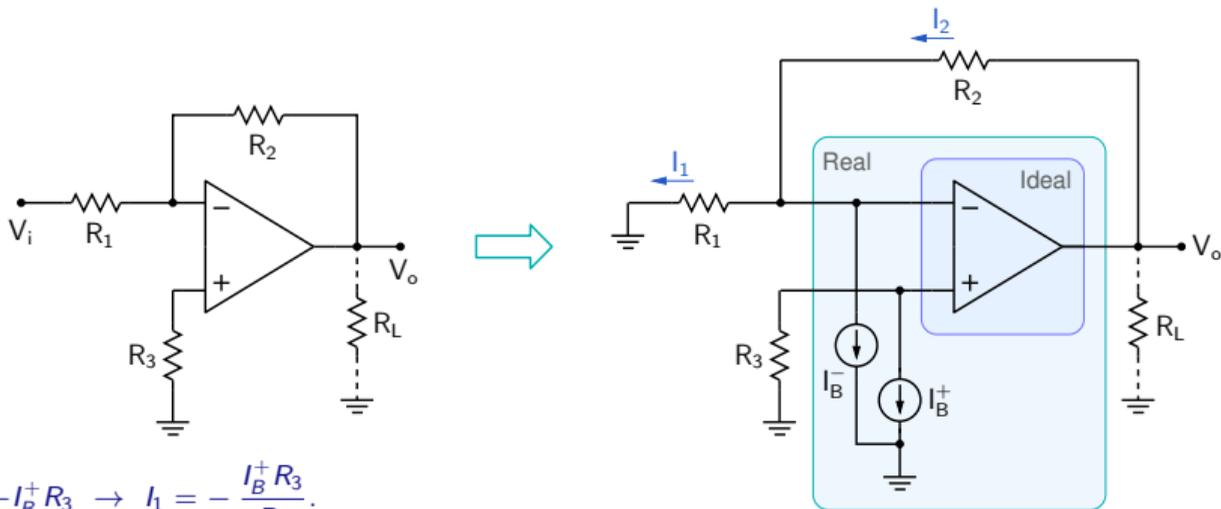




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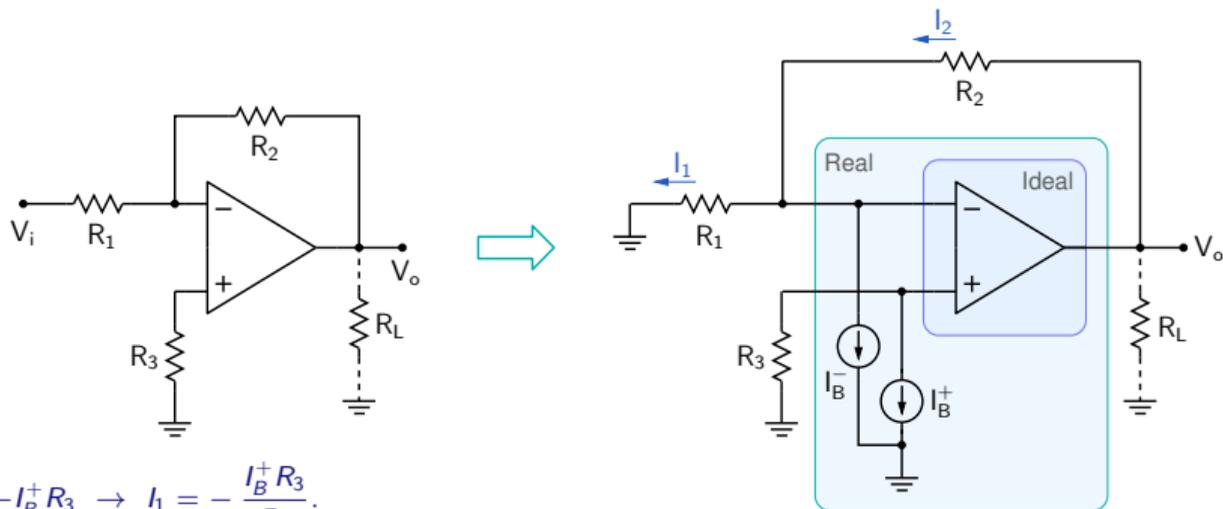


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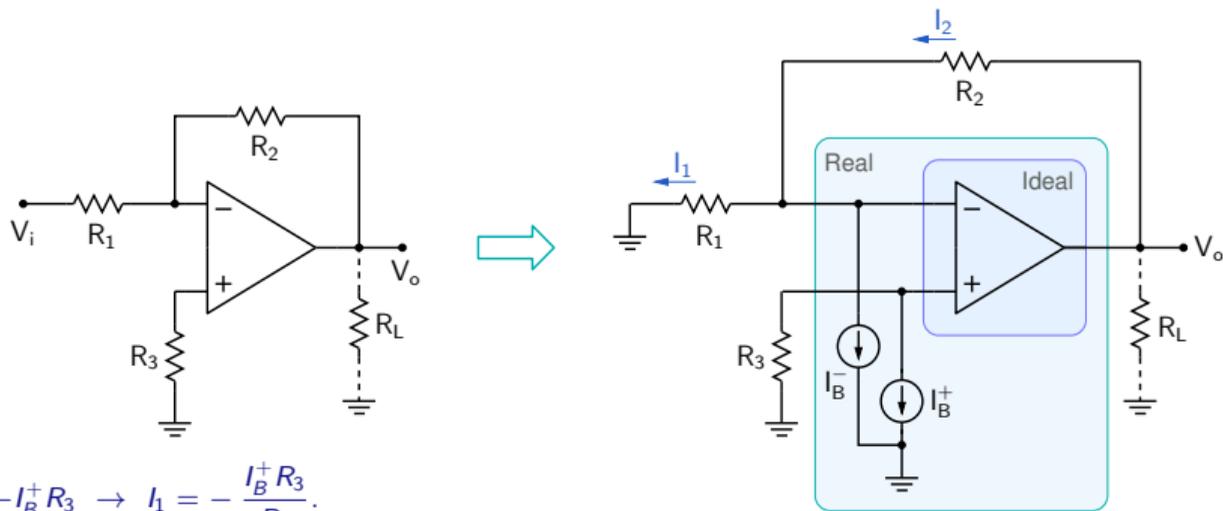
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The first term can be made zero if we select  $R_3 = R_1 \parallel R_2$ .

$\rightarrow V_o = -R_2 I_{OS}$  (Compare with  $V_o = R_2 I_B^-$  when  $R_3$  is not connected.)

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- \* A DC shift is a matter of concern when the output is expected to be a DC (or slowly varying) quantity, e.g., a temperature sensor or a strain gauge circuit.

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- \* The unit Bel turned out to be too large in practice  $\rightarrow$  deciBel (i.e., one tenth of a Bel).

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For example, if  $P_1 = 20 \text{ W}$  and  $P_{\text{ref}} = 1 \text{ W}$ ,

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- \* The gain of a voltage-to-voltage amplifier is often expressed in dB. In that case, the ratio  $V_o^2/V_i^2$  is considered (since  $P \propto V^2$  or  $P \propto I^2$  for a resistor).

$$A_V \text{ in dB} = 10 \log_{10} |V_o/V_i|^2 = 20 \log_{10} |V_o/V_i|,$$

- \* “dBm” is a related unit used to describe voltages with a reference of 1 mV.

$$\text{For example, } 2.2 \text{ V: } 20 \log_{10} \left( \frac{2.2 \text{ V}}{1 \text{ mV}} \right) = 6.85 \text{ dBm}.$$



## Example



## Example



Let  $\hat{V}_i$  and  $\hat{V}_o$  be the input and output amplitudes.

If  $\hat{V}_i = 2.5$  mV and  $A_V = 36.3$  dB, compute  $\hat{V}_o$  in dBm and mV.

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### Method 2:

$$A_V = 36.3 \text{ dB}$$

$$\rightarrow 20 \log_{10} A_V = 36.3 \rightarrow A_V = 65.$$

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$$\widehat{V}_o = A_V \times \widehat{V}_i = 65 \times 2.5 \text{ mV} = 162.5 \text{ mV.}$$

## Example



Let  $\widehat{V}_i$  and  $\widehat{V}_o$  be the input and output amplitudes.

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$$A_V = 36.3 \text{ dB}$$

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$$\widehat{V}_o = A_V \times \widehat{V}_i = 65 \times 2.5 \text{ mV} = 162.5 \text{ mV.}$$

$$\widehat{V}_o \text{ in dBm} = 20 \log_{10} \left( \frac{162.5 \text{ mV}}{1 \text{ mV}} \right) = 44.2 \text{ dBm.}$$

- \* When sound intensity is specified in dB, the reference pressure is  $P_{\text{ref}} = 20 \mu\text{Pa}$  (our hearing threshold). If the pressure corresponding to the sound being measured is  $P$ , we say that it is  $20 \log(P/P_{\text{ref}})$  dB.

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0 dB

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whisper

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Industrial area	75 dB
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Industrial area	75 dB
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Industrial area	75 dB
Commercial area	65 dB
Residential area	55 dB

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Industrial area	75 dB
Commercial area	65 dB
Residential area	55 dB
Silence zone	50 dB





- \* The transfer function of a circuit such as an amplifier or a filter is given by,

$$H(s) = V_o(s)/V_i(s), \quad s = j\omega.$$

$$\text{e.g., } H(s) = \frac{K}{1 + s\tau} = \frac{K}{1 + j\omega\tau}$$



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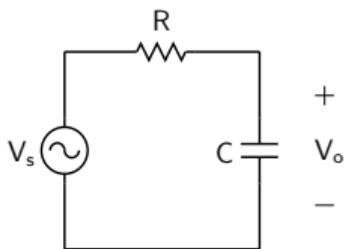
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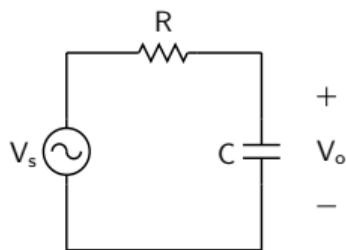
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- \* Bode gave simple rules which allow construction of the above plots in an approximate (asymptotic) manner.

## A simple transfer function



$$V_o = \frac{(1/sC)}{R + (1/sC)} V_s,$$
$$\rightarrow H(s) = \frac{1}{1+sRC} = \frac{1}{1 + (j\omega/\omega_0)},$$
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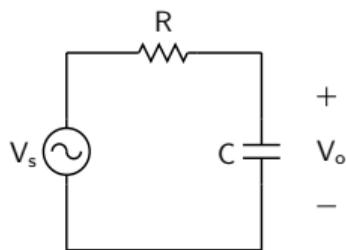
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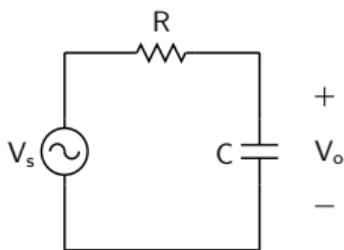


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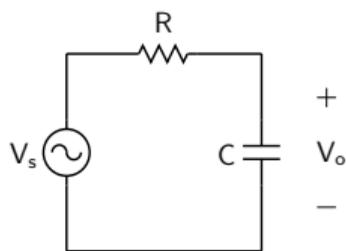
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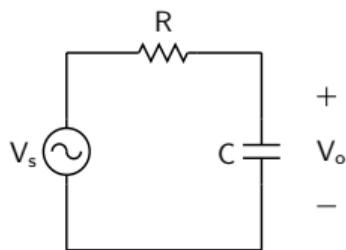
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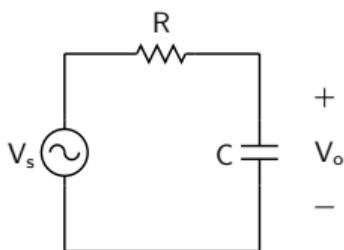
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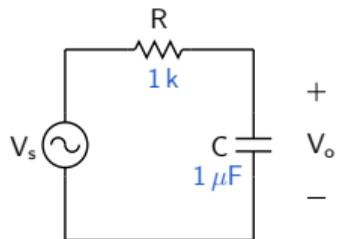
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- \* We are generally interested in a large variation in  $\omega$  (several orders), and its effect on  $|H|$  and  $\angle H$ .
- \* The magnitude ( $|H|$ ) varies by orders of magnitude as well.  
The phase ( $\angle H$ ) varies from 0 (for  $\omega \ll \omega_0$ ) to  $-\pi/2$  (for  $\omega \gg \omega_0$ ).

## A simple transfer function: magnitude



$$V_o = \frac{(1/sC)}{R + (1/sC)} V_s,$$

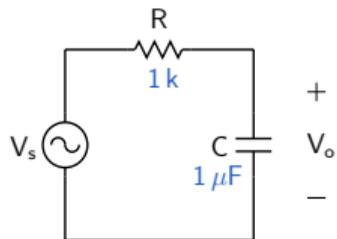
$$\rightarrow H(s) = \frac{1}{1+sRC} = \frac{1}{1+(j\omega/\omega_0)},$$

$$\omega_0 = \frac{1}{RC} = 10^3 \text{ rad/s}.$$

$$|H(j\omega)| = \frac{1}{\sqrt{1+(\omega/\omega_0)^2}}$$

$$\angle(H(j\omega)) = -\tan^{-1}\left(\frac{\omega}{\omega_0}\right)$$

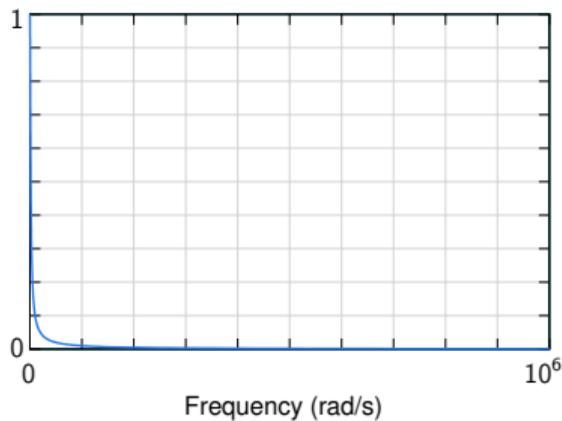
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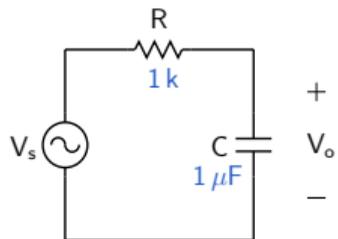
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$$\rightarrow H(s) = \frac{1}{1+sRC} = \frac{1}{1+(j\omega/\omega_0)},$$
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$$|H(j\omega)| = \frac{1}{\sqrt{1+(\omega/\omega_0)^2}}$$

$$\angle(H(j\omega)) = -\tan^{-1}\left(\frac{\omega}{\omega_0}\right)$$



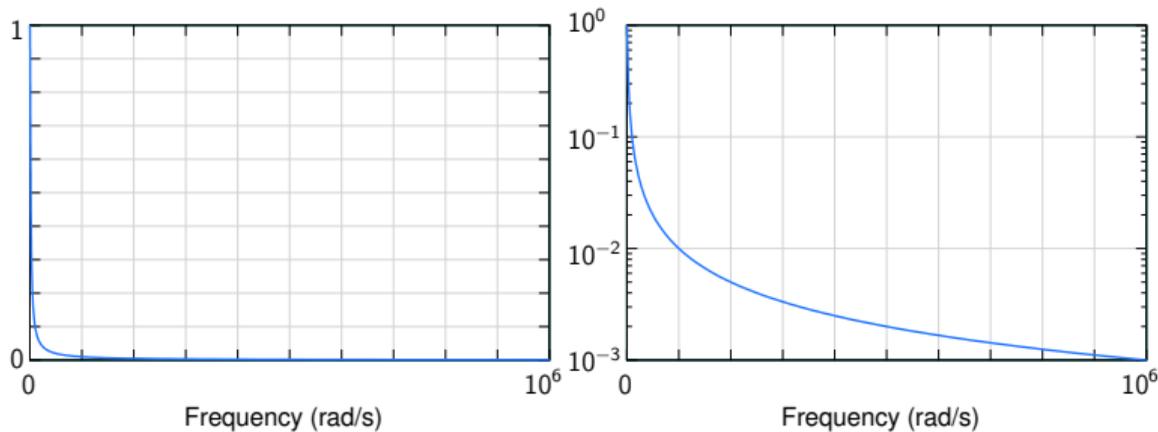
## A simple transfer function: magnitude



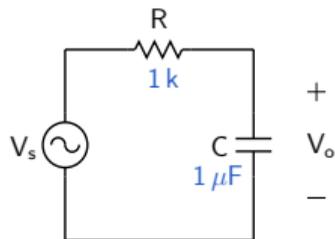
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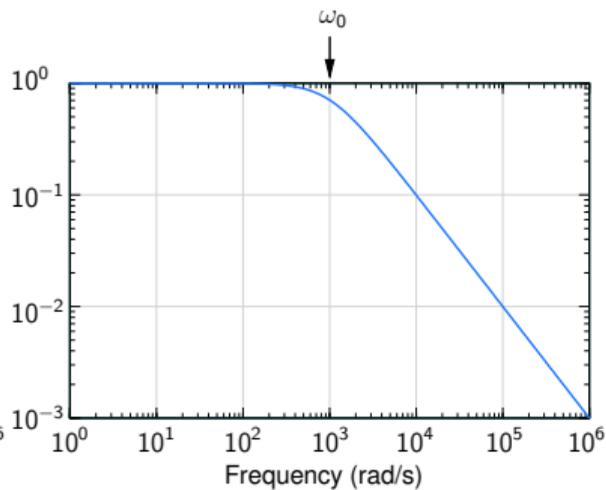
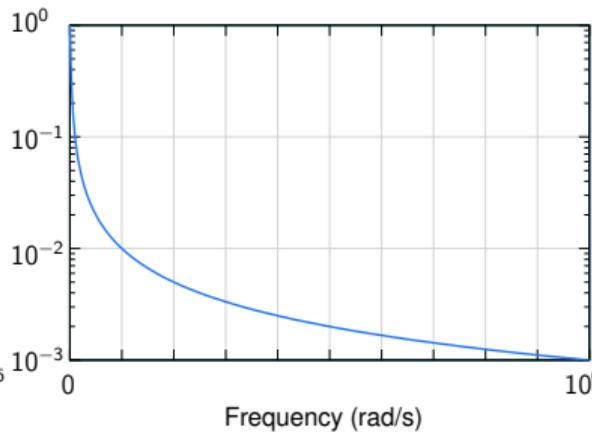
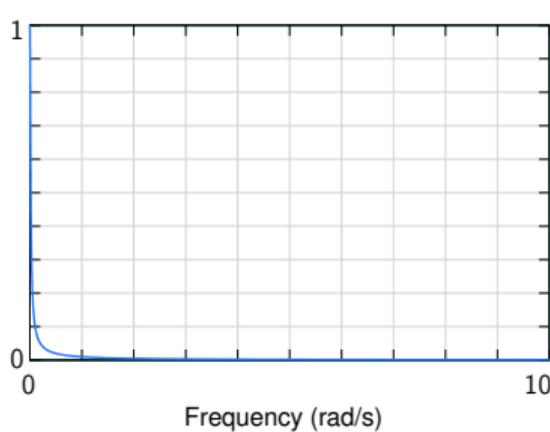
# A simple transfer function: magnitude



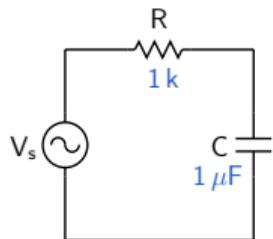
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$$\angle(H(j\omega)) = -\tan^{-1}\left(\frac{\omega}{\omega_0}\right)$$



## A simple transfer function: magnitude



+  
V<sub>o</sub>  
-

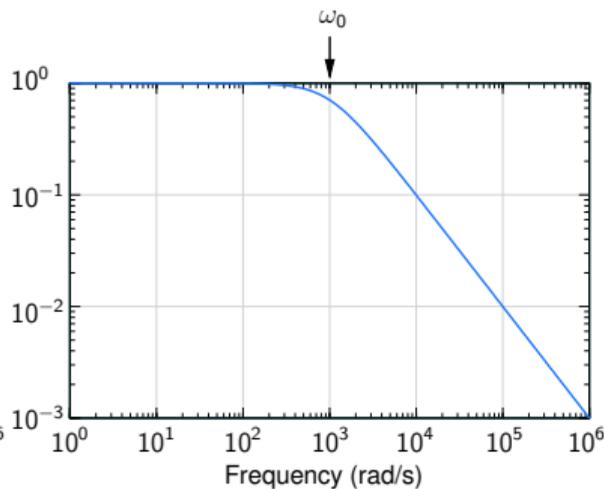
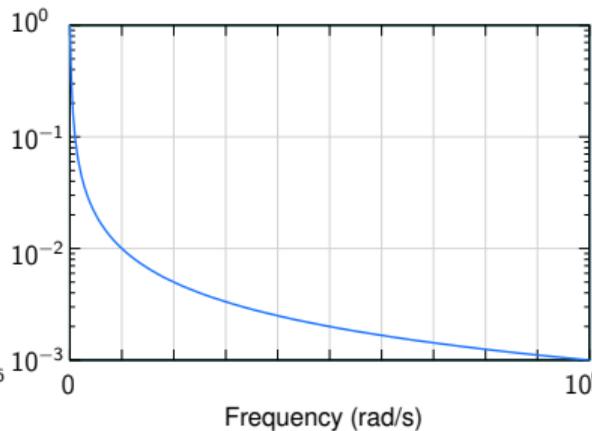
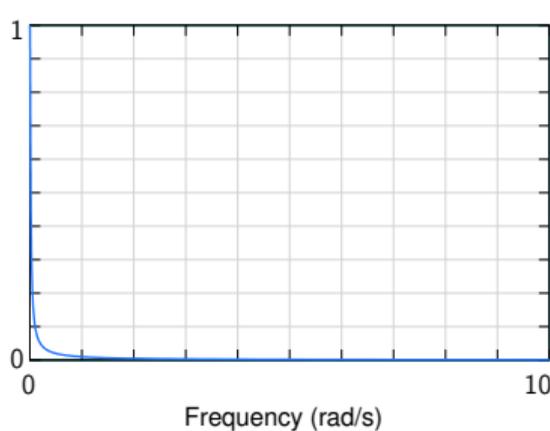
$$V_o = \frac{(1/sC)}{R + (1/sC)} V_s,$$

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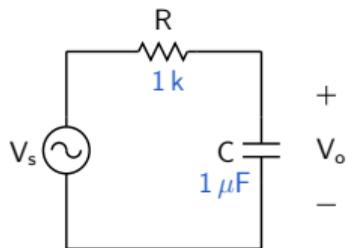
$$|H(j\omega)| = \frac{1}{\sqrt{1 + (\omega/\omega_0)^2}}$$

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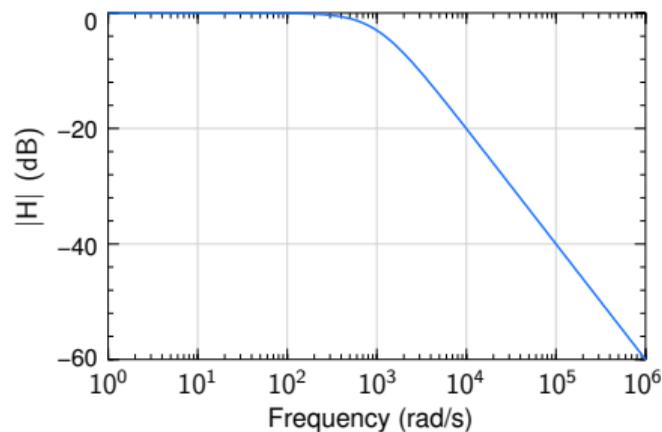
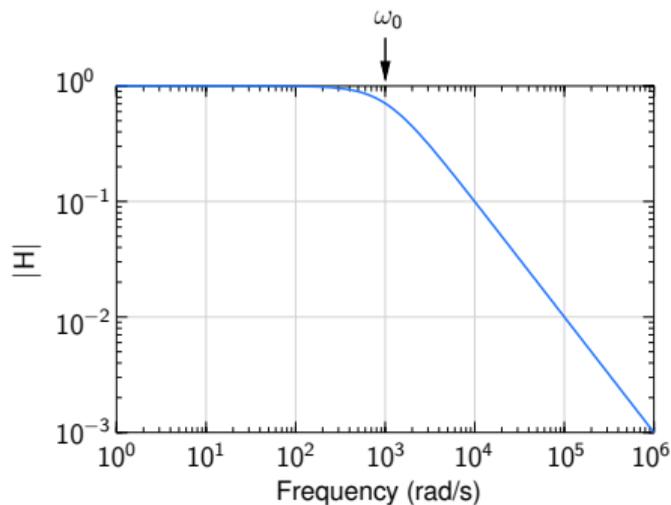
Since  $\omega$  and  $|H(j\omega)|$  vary by several orders of magnitude, a linear  $\omega$ - or  $|H|$ -axis is not appropriate  $\rightarrow \log |H|$  is plotted against  $\log \omega$ .

## A simple transfer function: magnitude

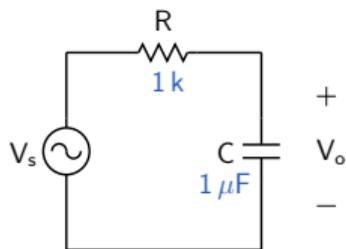


$$V_o = \frac{(1/sC)}{R + (1/sC)} V_s,$$
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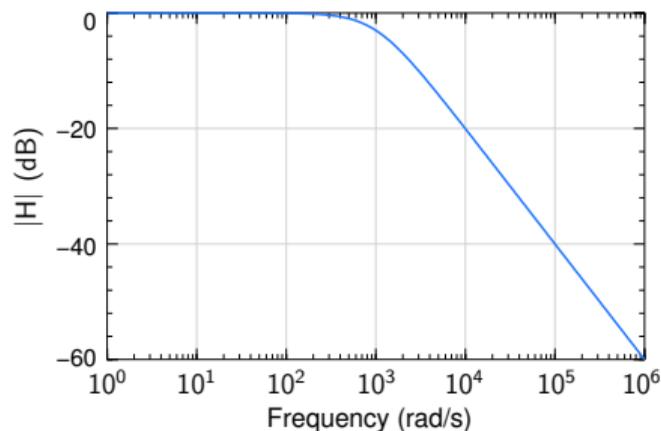
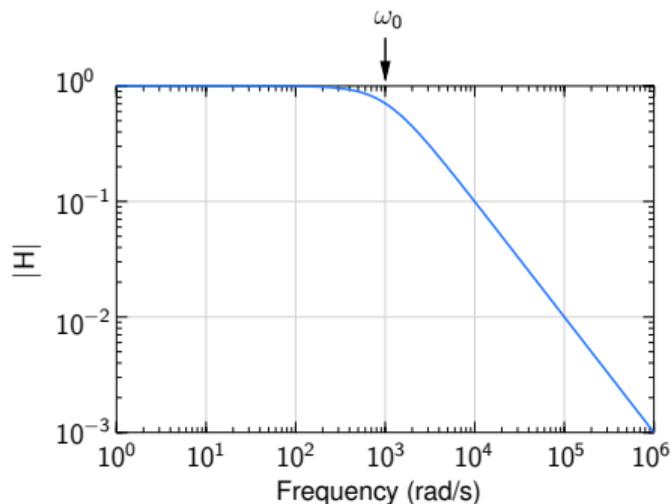


## A simple transfer function: magnitude



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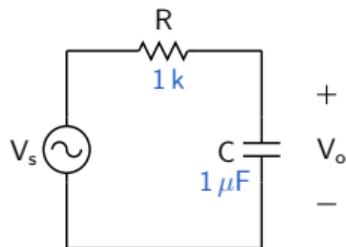
$$|H(j\omega)| = \frac{1}{\sqrt{1 + (\omega/\omega_0)^2}}$$
$$\angle(H(j\omega)) = -\tan^{-1}\left(\frac{\omega}{\omega_0}\right)$$



Note that the *shape* of the plot does not change.

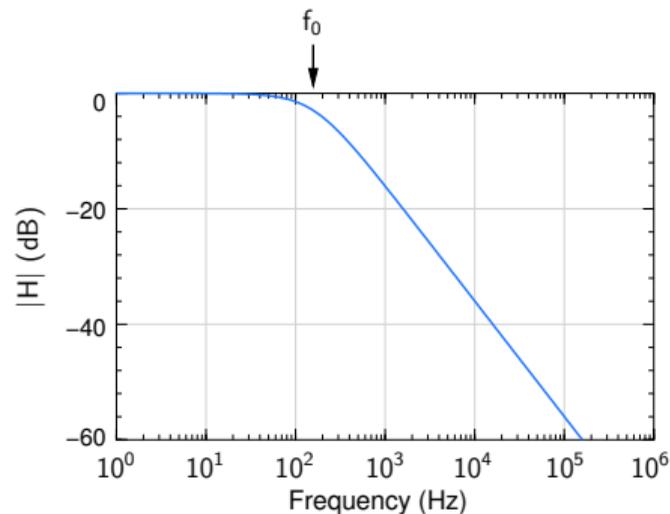
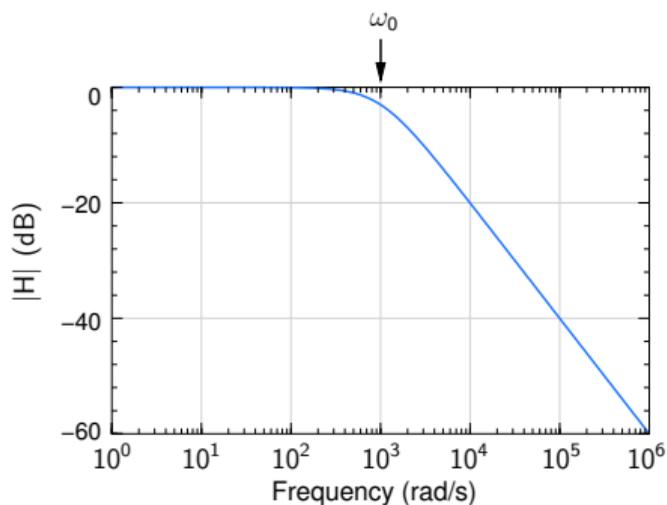
$|H|$  (dB) =  $20 \log |H|$  is simply a scaled version of  $\log |H|$ .

# A simple transfer function: magnitude

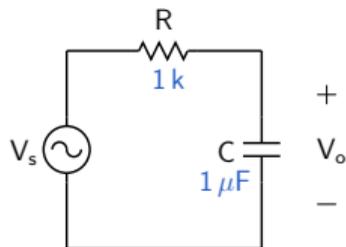


$$V_o = \frac{(1/sC)}{R + (1/sC)} V_s,$$
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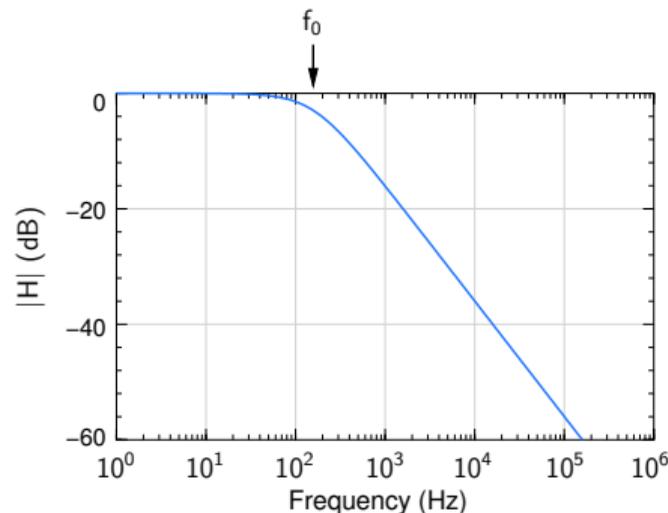
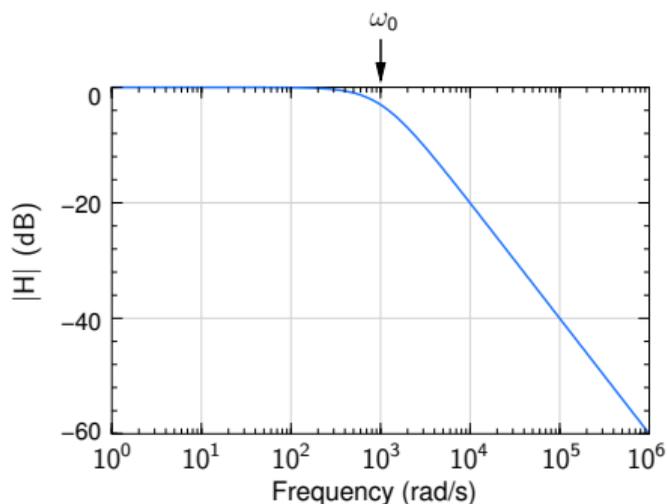


## A simple transfer function: magnitude



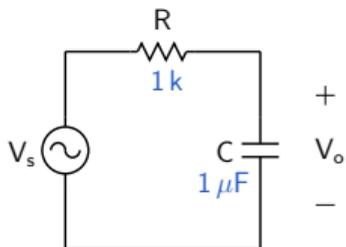
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$$|H(j\omega)| = \frac{1}{\sqrt{1 + (\omega/\omega_0)^2}}$$
$$\angle(H(j\omega)) = -\tan^{-1}\left(\frac{\omega}{\omega_0}\right)$$



Since  $\omega = 2\pi f$ ,  $\log \omega = \log(2\pi) + \log f$  which causes a shift in the  $x$  direction, but the *shape* of the plot does not change.

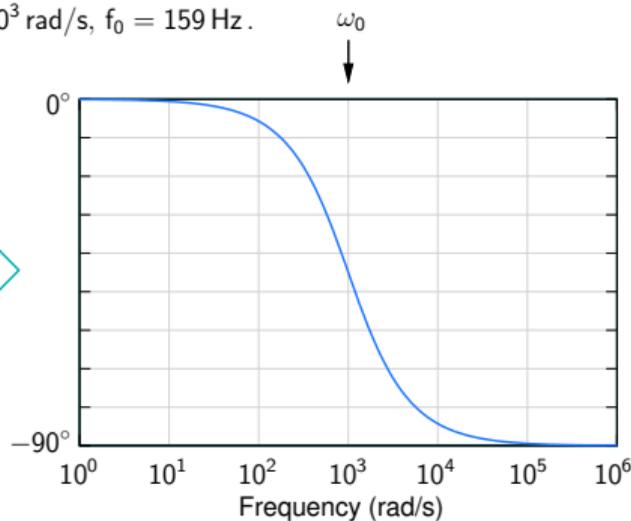
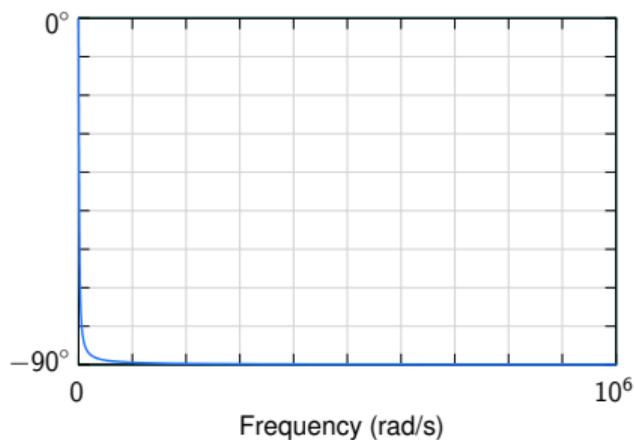
## A simple transfer function: phase



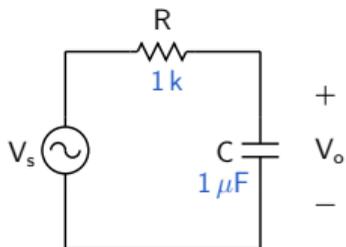
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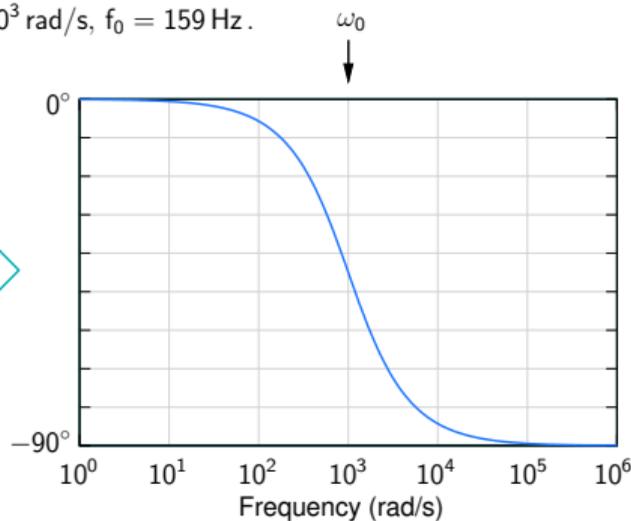
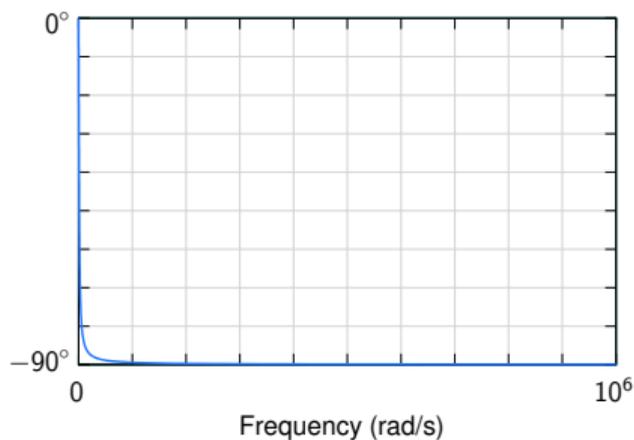
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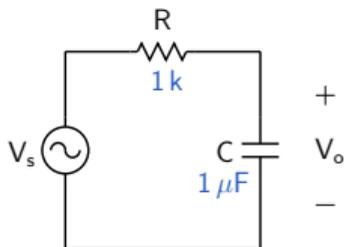
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- \* Since  $\angle H = -\tan^{-1}(\omega/\omega_0)$  varies in a limited range ( $0^\circ$  to  $-90^\circ$  in this example), a linear axis is appropriate for  $\angle H$ .

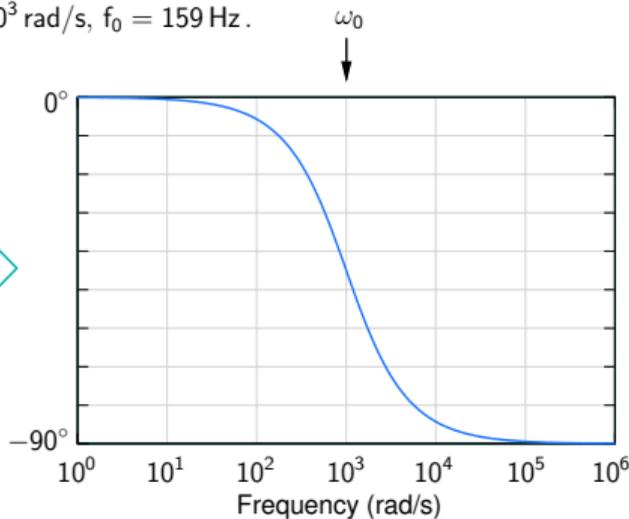
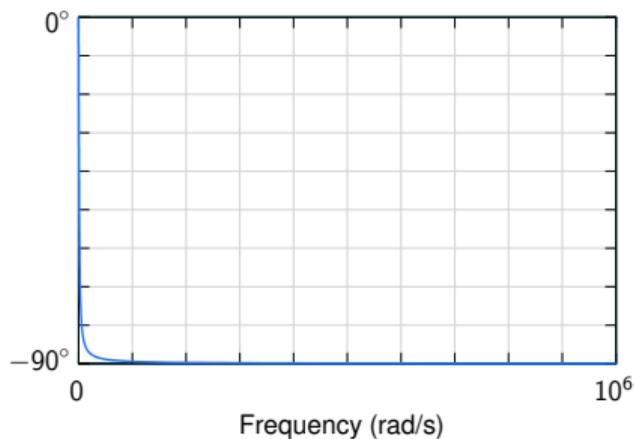
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- \* As in the magnitude plot, we use a log axis for  $\omega$ , since we are interested in a wide range of  $\omega$ .

Consider  $H(s) = \frac{K(1 + s/z_1)(1 + s/z_2) \cdots (1 + s/z_M)}{(1 + s/p_1)(1 + s/p_2) \cdots (1 + s/p_N)}$ .

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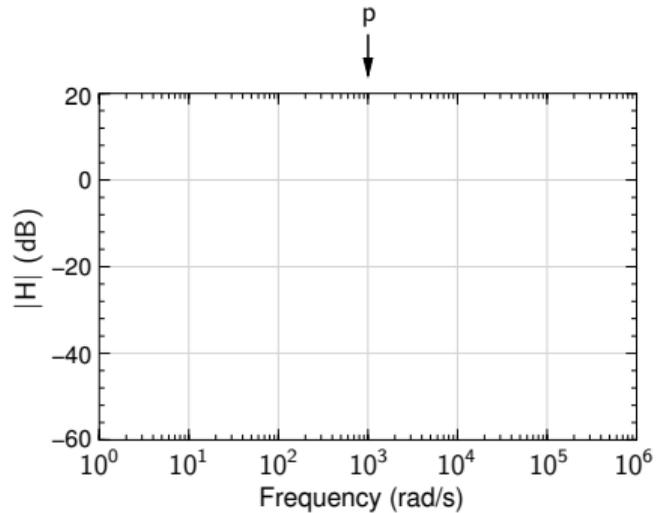
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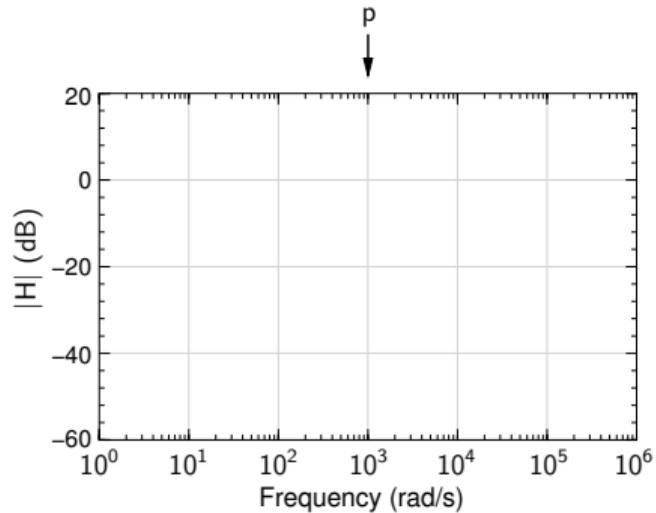
Construction of Bode plots involves

- (a) computing approximate contribution of each pole/zero as a function of  $\omega$ .
- (b) combining the various contributions to obtain  $|H|$  and  $\angle H$  versus  $\omega$ .



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In this example,  $p = 10^3$  rad/s.

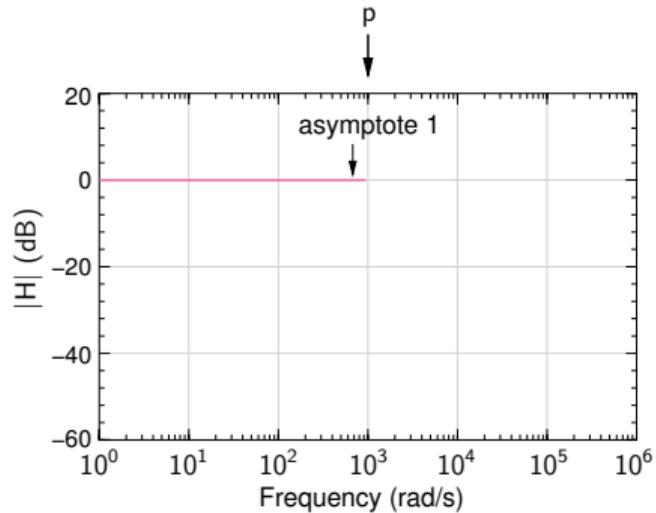


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$$\omega \ll p: |H| \rightarrow 1, 20 \log |H| = 0 \text{ dB.}$$

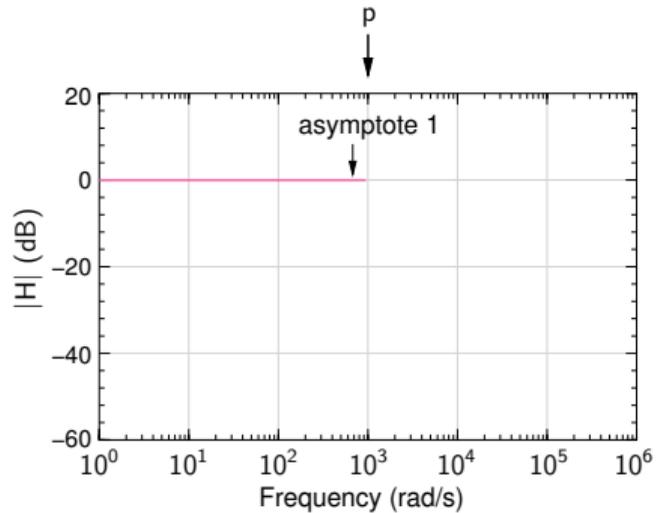


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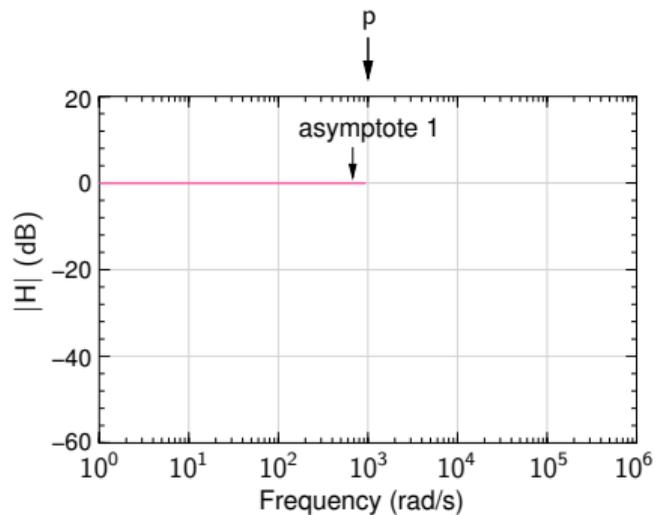
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**Asymptote 1:**

$$\omega \ll p: |H| \rightarrow 1, 20 \log |H| = 0 \text{ dB.}$$

**Asymptote 2:**

$$\omega \gg p: |H| \rightarrow \frac{1}{\omega/p} = \frac{p}{\omega} \rightarrow |H| = 20 \log p - 20 \log \omega \text{ (dB)}$$



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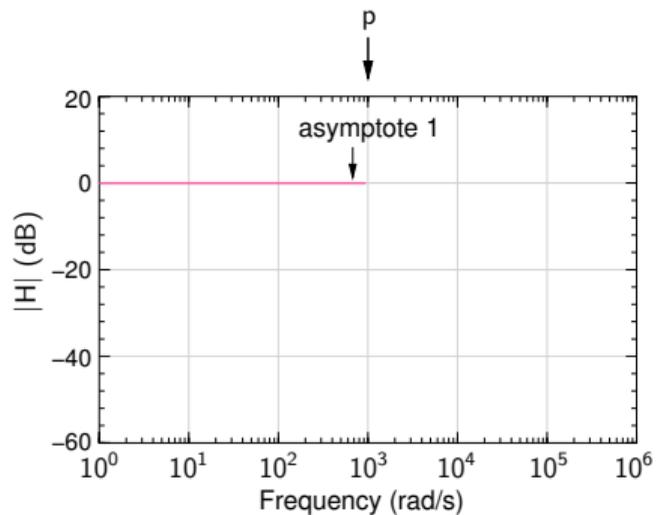
### Asymptote 2:

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Consider two values of  $\omega$ :  $\omega_1$  and  $10\omega_1$ .

$$|H|_1 = 20 \log p - 20 \log \omega_1 \text{ (dB)}$$

$$|H|_2 = 20 \log p - 20 \log (10\omega_1) \text{ (dB)}$$



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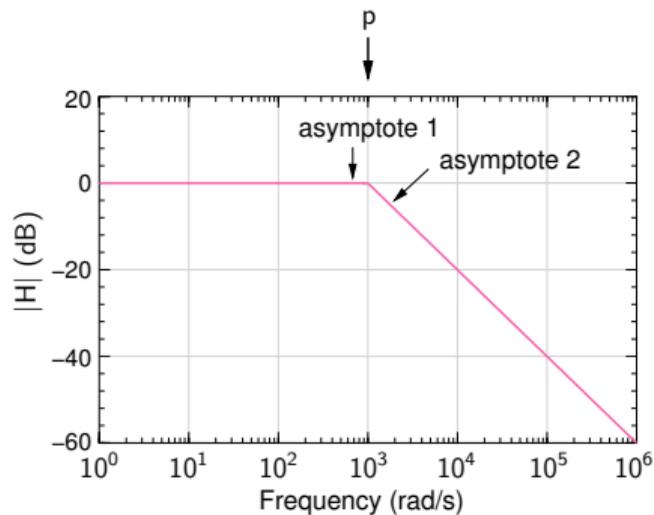
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$\rightarrow |H|$  versus  $\omega$  has a slope of  $-20$  dB/decade.



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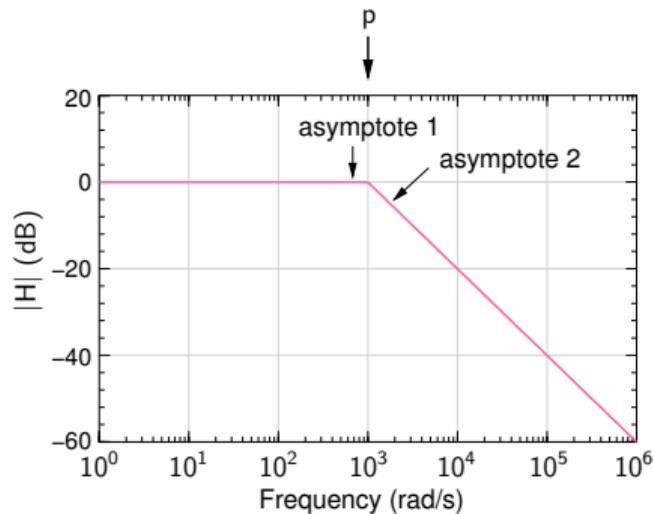
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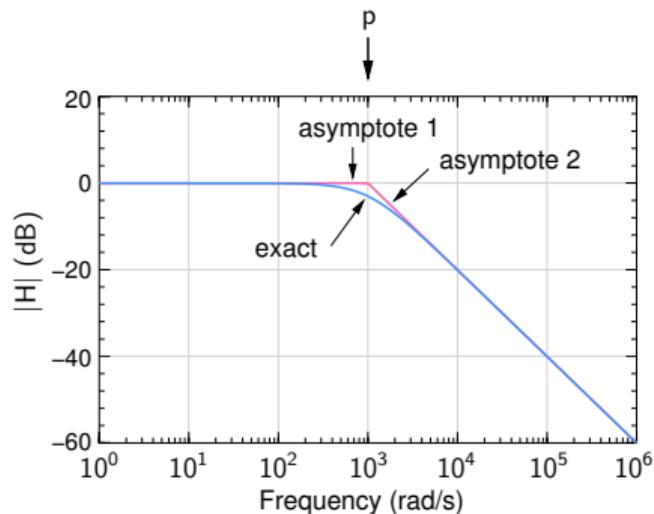
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In this example,  $p = 10^3$  rad/s.

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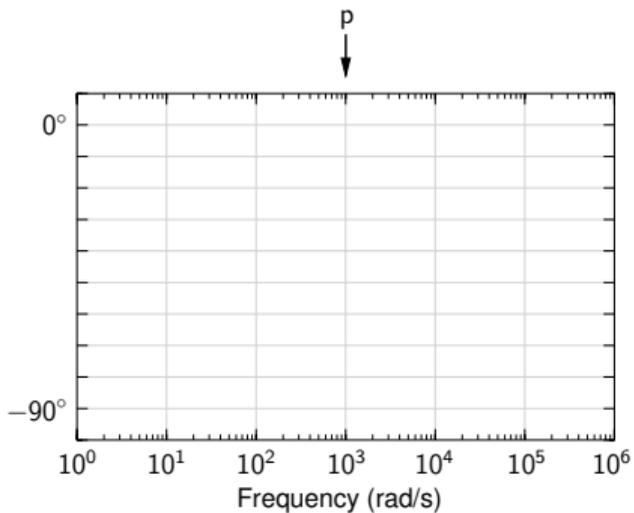
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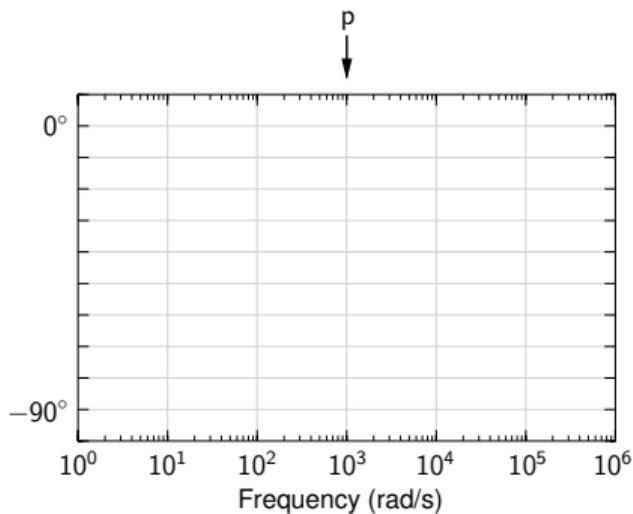
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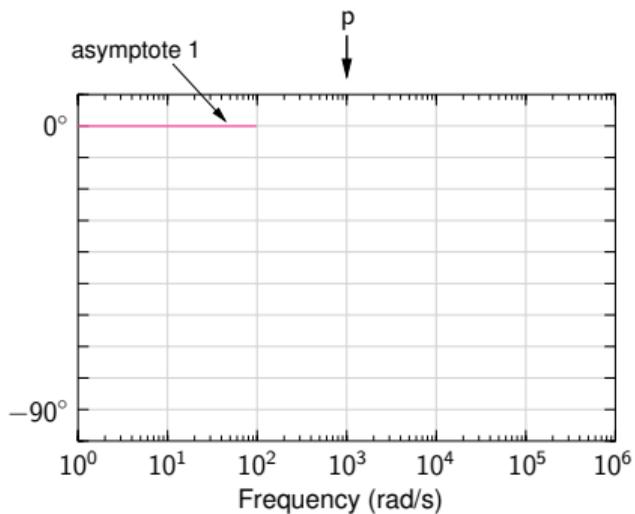


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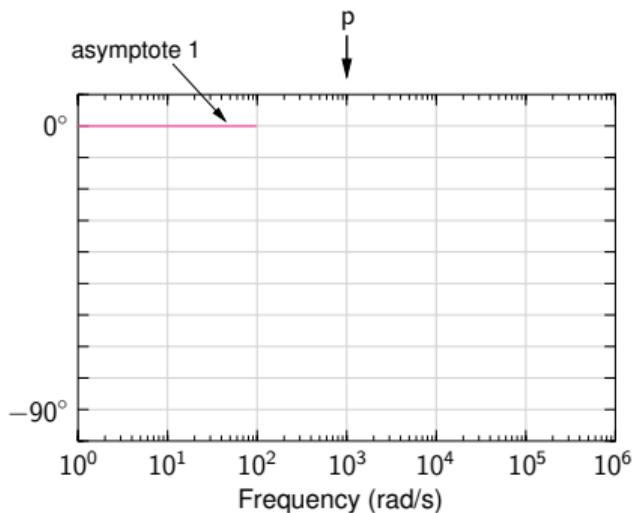


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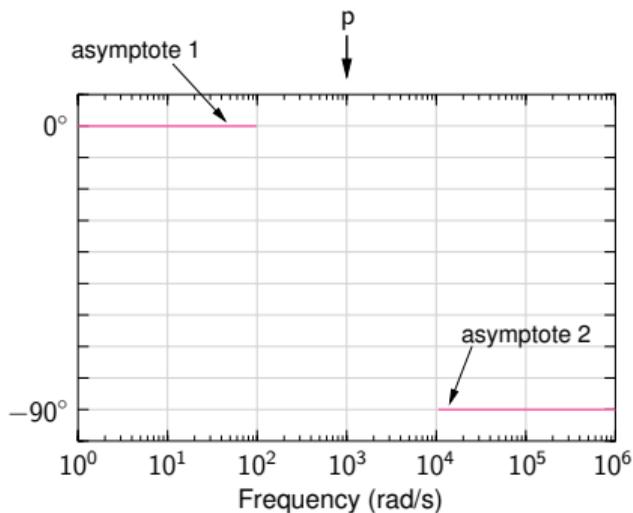
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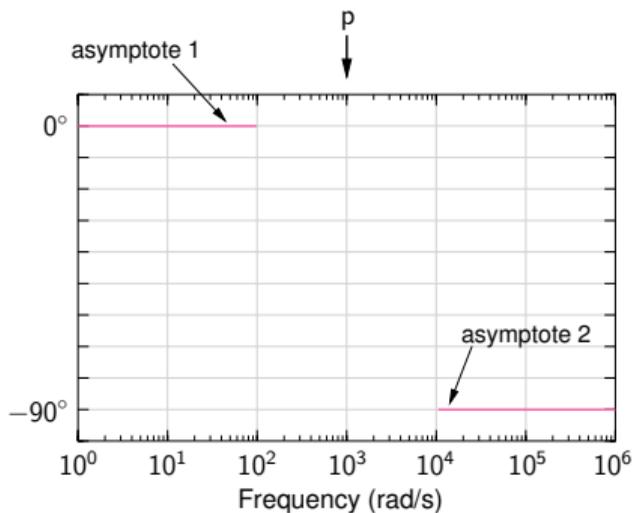
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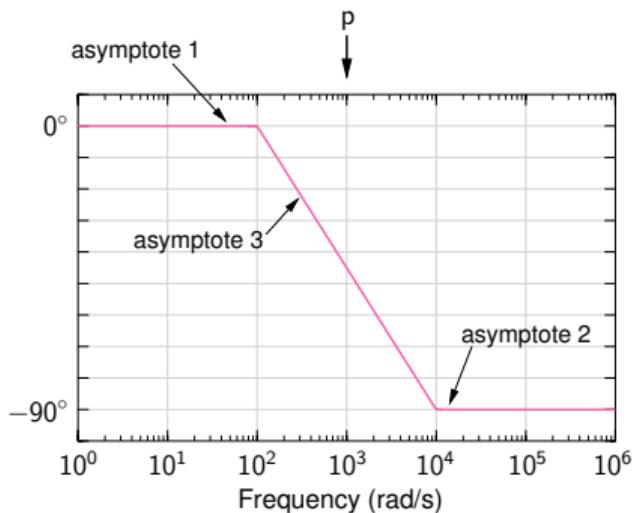
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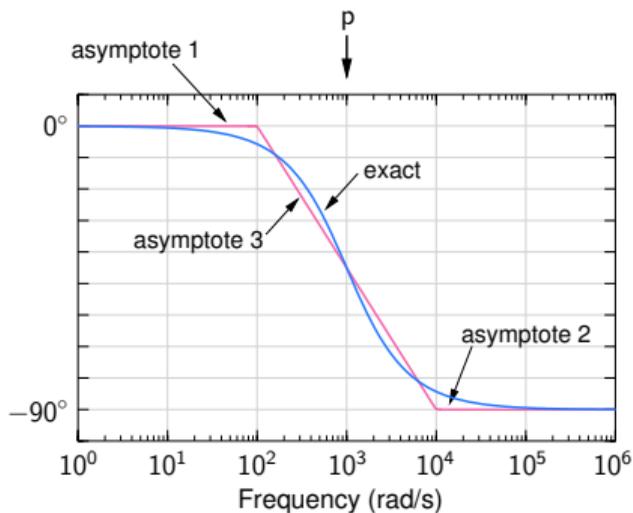
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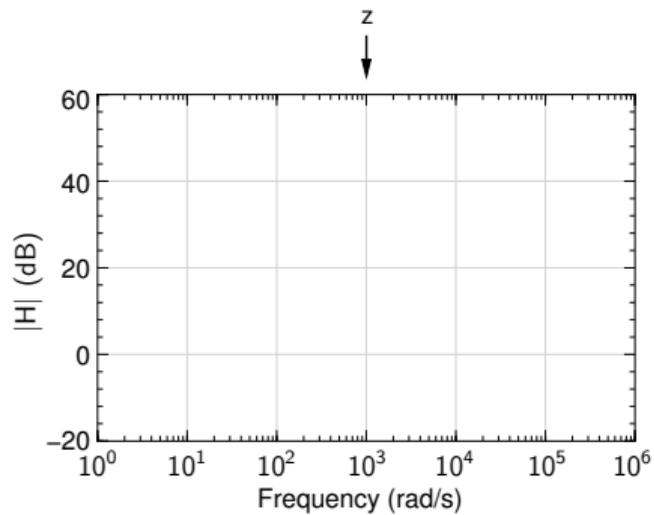
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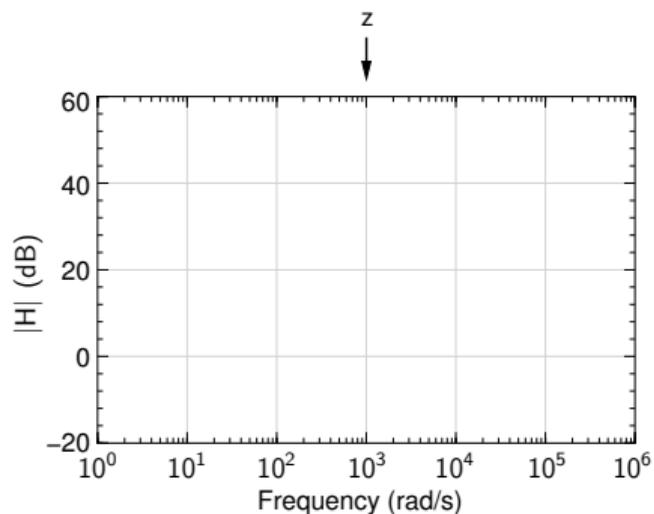
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In this example,  $z = 10^3$  rad/s.

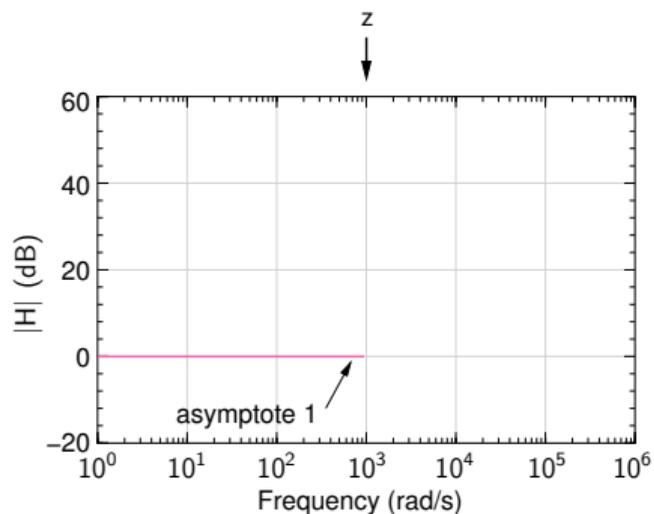


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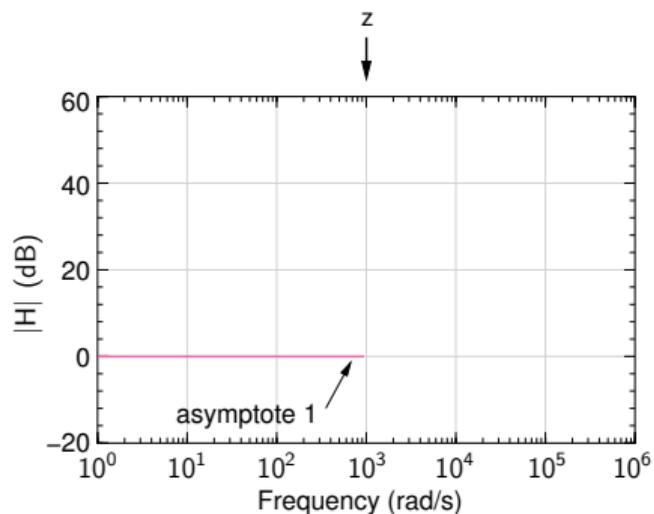


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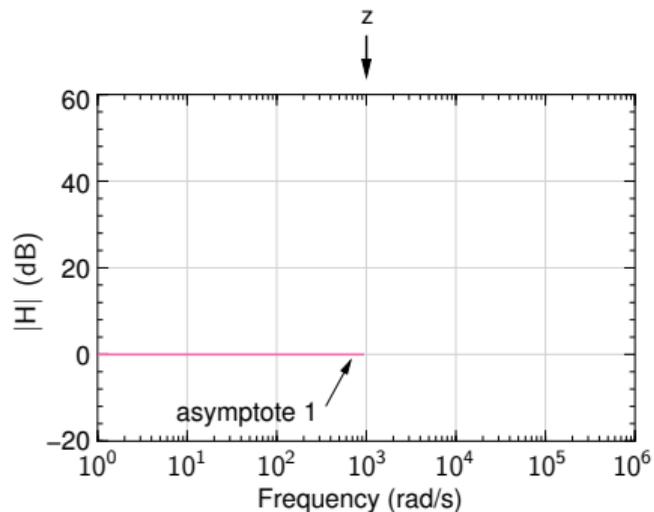
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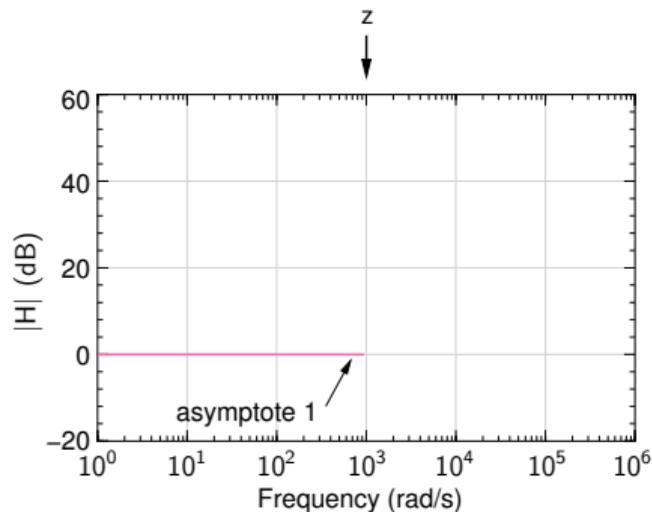
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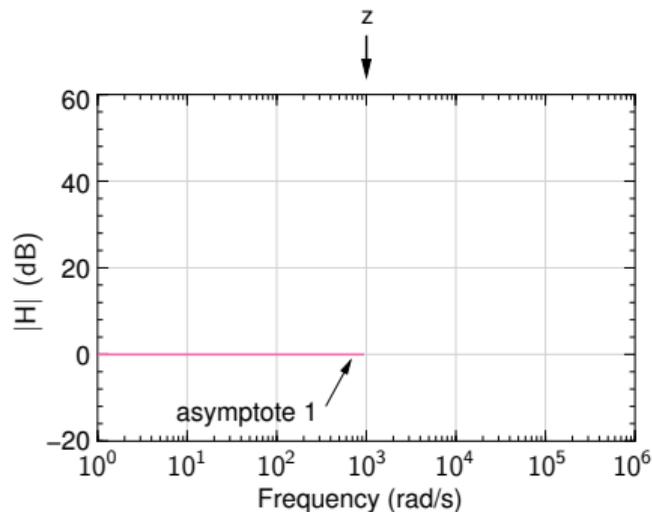
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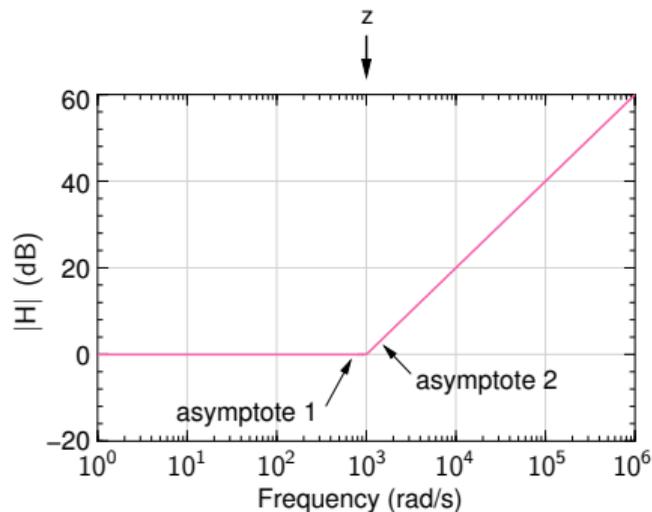
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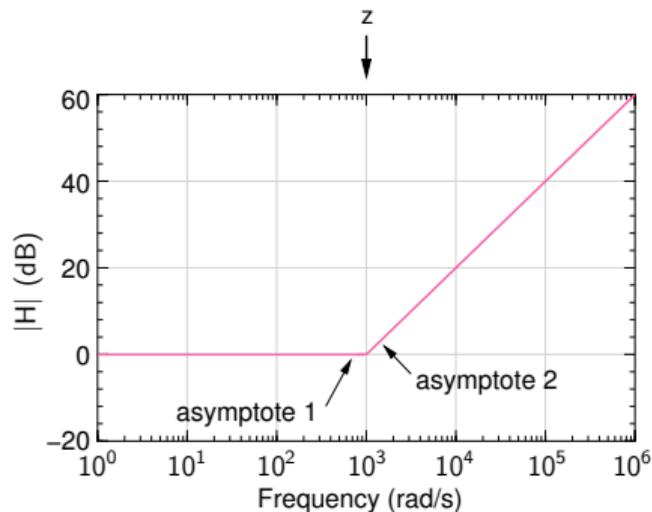
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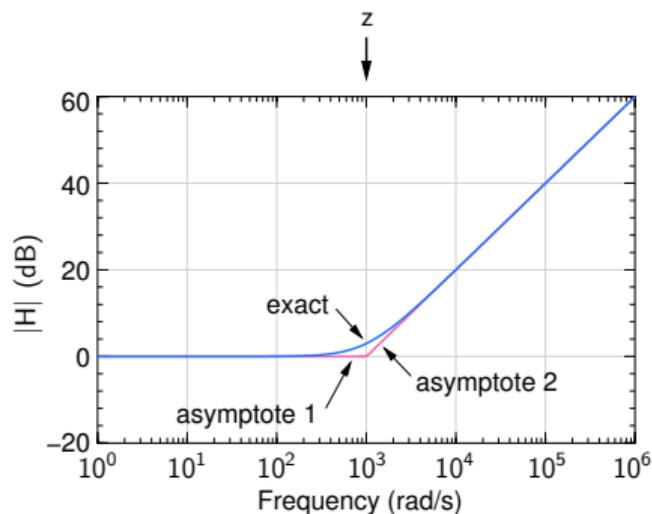
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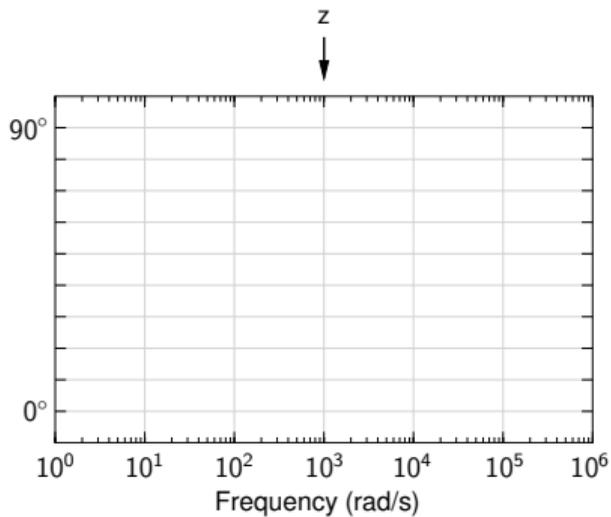
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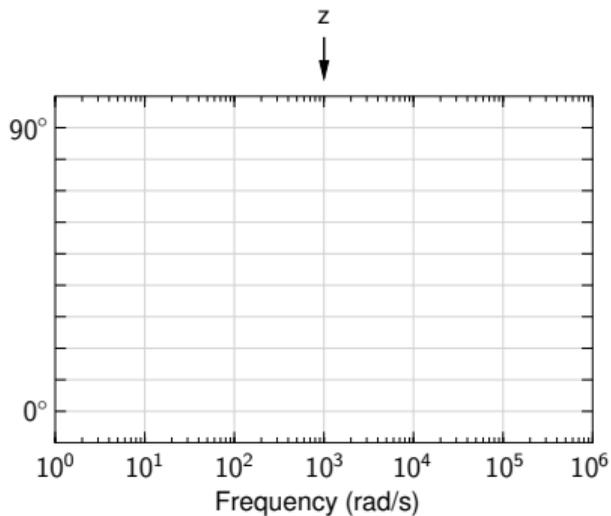
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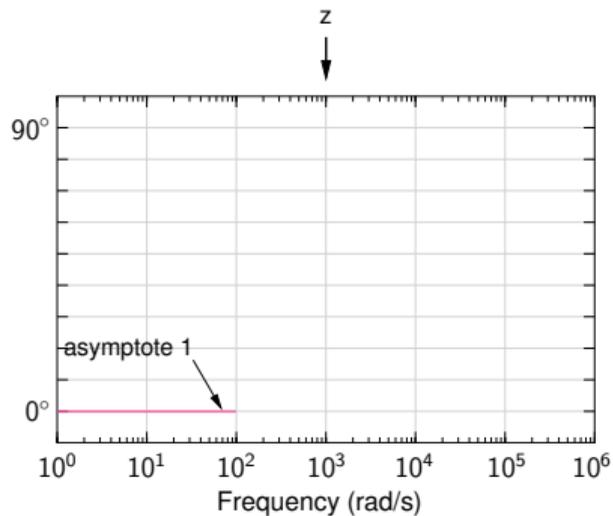


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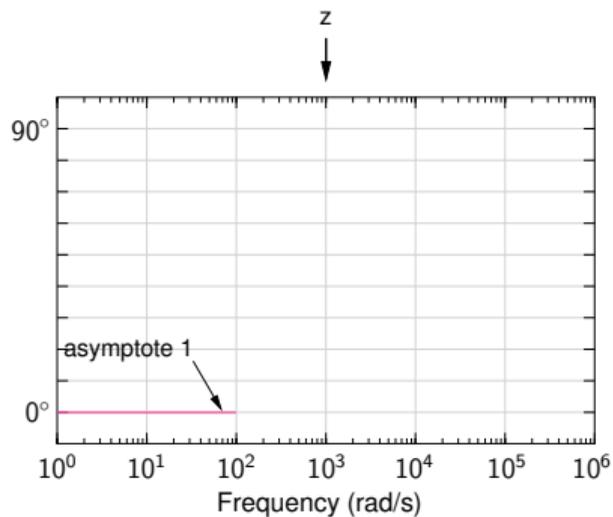


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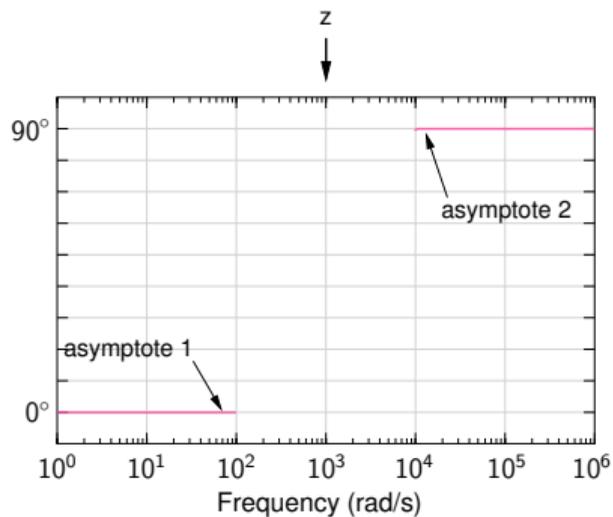
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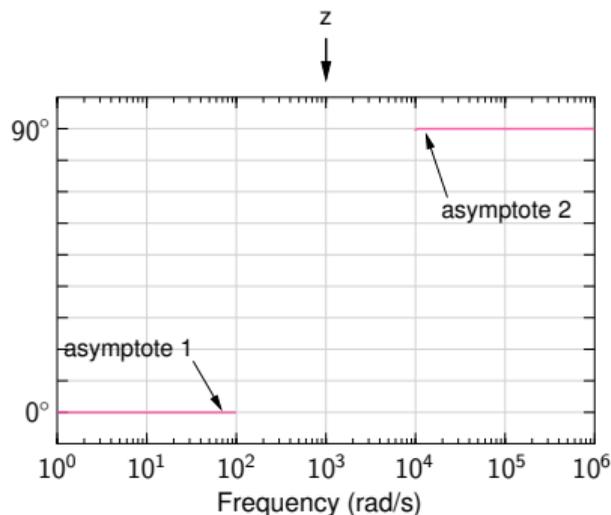
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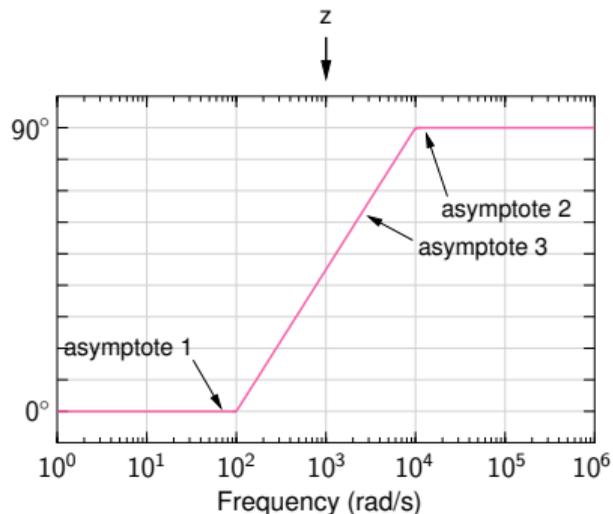
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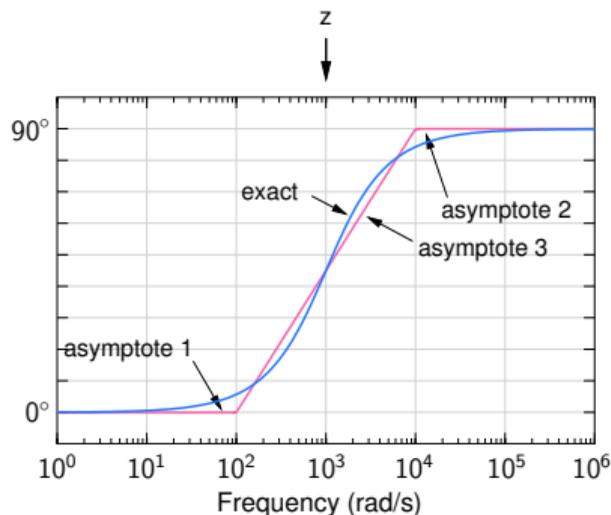
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$H(j\omega) = j\omega$ ,  $|H| = \omega \rightarrow |H| \text{ (dB)} = 20 \log \omega$ .

If  $\omega \rightarrow 10\omega$ ,  $\log \omega \rightarrow \log \omega + \log 10$ ,  $|H| \rightarrow |H| + 20 \text{ (dB)}$ ,

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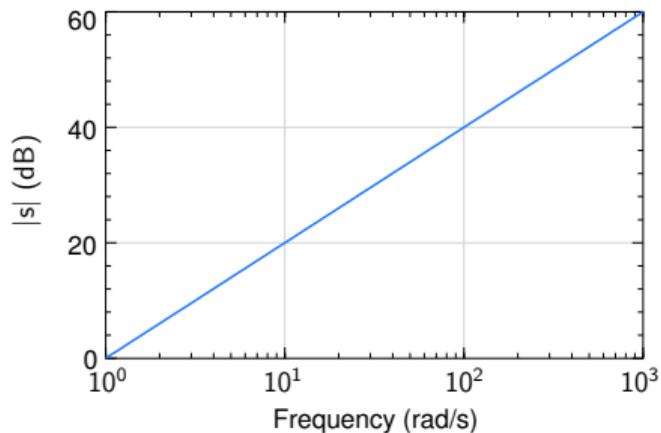
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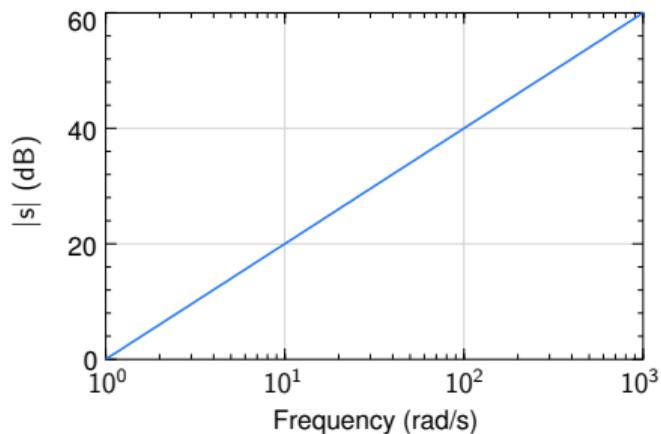
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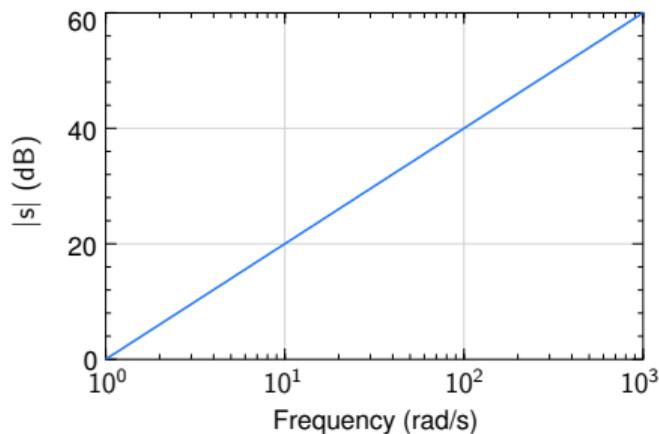
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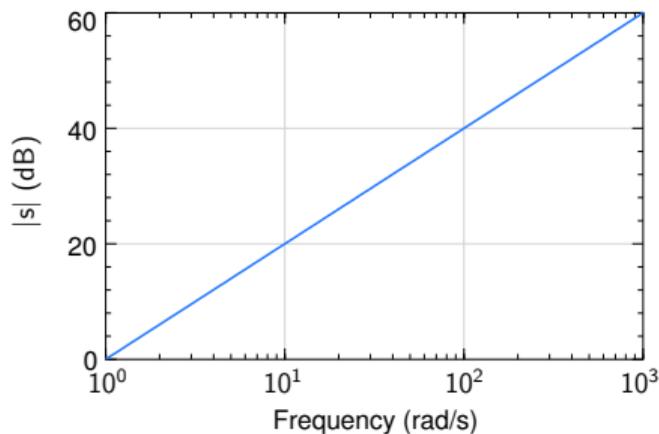
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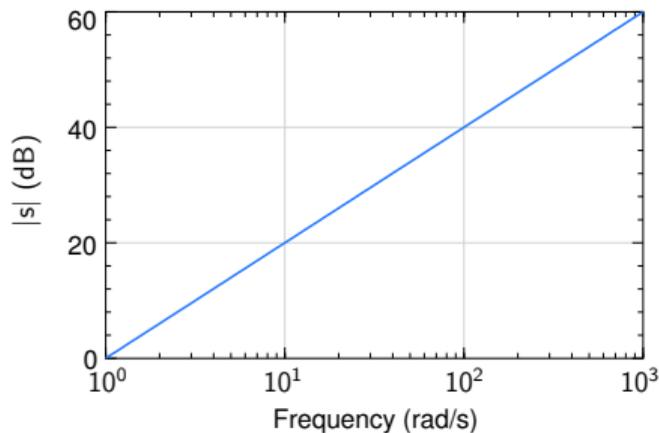
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If  $\omega \rightarrow 10\omega$ ,  $\log \omega \rightarrow \log \omega + \log 10$ ,  $|H| \rightarrow |H| + 40$  (dB),

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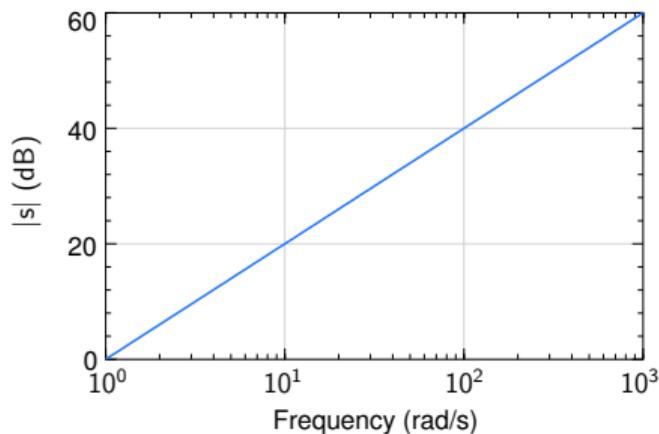
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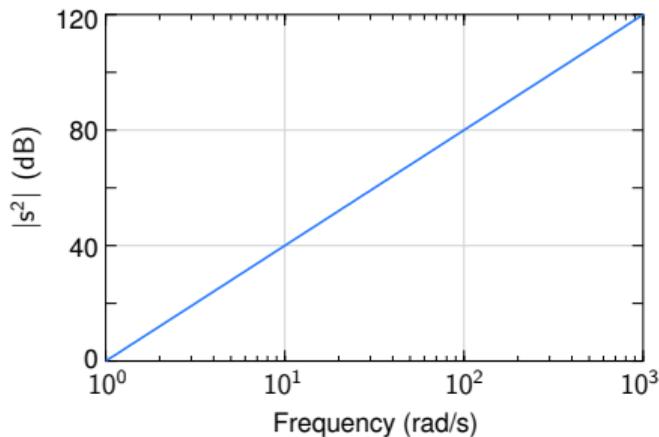
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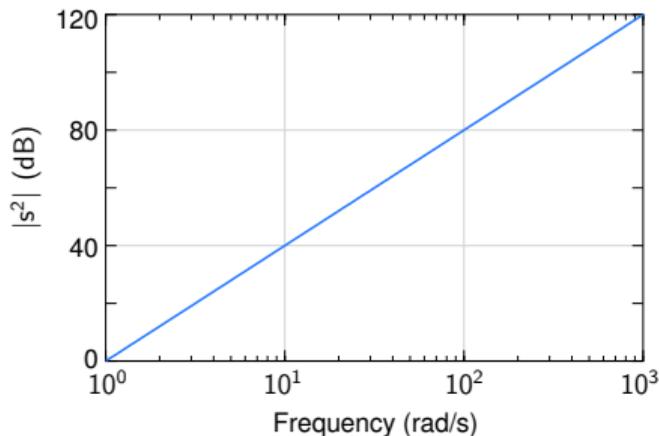
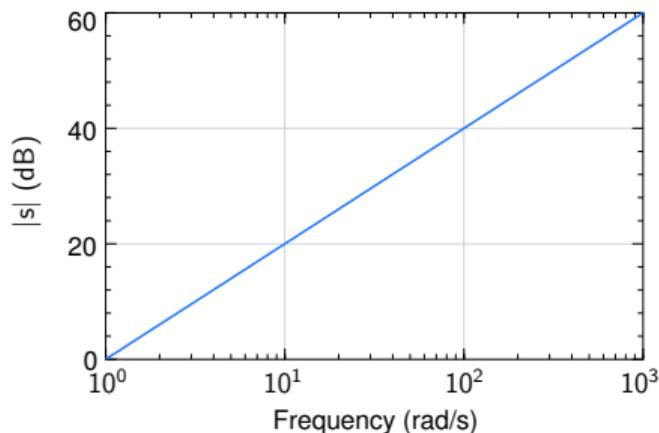
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Phase:

$H_1(j\omega)$  and  $H_2(j\omega)$  are complex numbers.

At a given  $\omega$ , let  $H_1 = K_1 \angle \alpha = K_1 e^{j\alpha}$ , and  $H_2 = K_2 \angle \beta = K_2 e^{j\beta}$ .

Then,  $H_1 H_2 = K_1 K_2 e^{j(\alpha+\beta)} = K_1 K_2 \angle (\alpha + \beta)$ .

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In the Bode phase plot, the contributions due to  $H_1$  and  $H_2$  also get added.

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In the Bode phase plot, the contributions due to  $H_1$  and  $H_2$  also get added.

The same reasoning applies to more than two terms as well.

Consider  $H(s) = \frac{10s}{(1 + s/10^2)(1 + s/10^5)}$ .

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Let  $H(s) = H_1(s) H_2(s) H_3(s) H_4(s)$ , where

$$H_1(s) = 10,$$

$$H_2(s) = s,$$

$$H_3(s) = \frac{1}{1 + s/p_1}, p_1 = 10^2 \text{ rad/s},$$

$$H_4(s) = \frac{1}{1 + s/p_2}, p_2 = 10^5 \text{ rad/s}.$$

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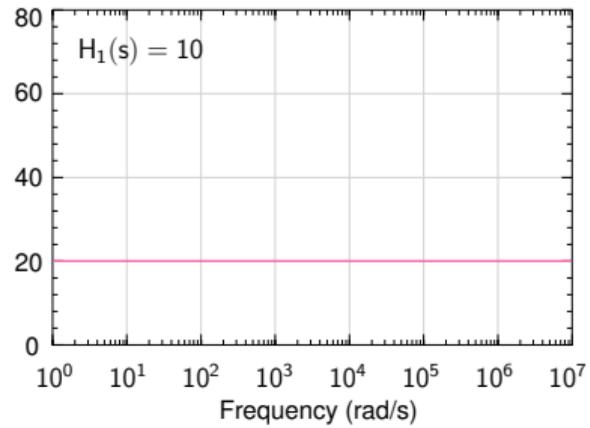
$$H_2(s) = s,$$

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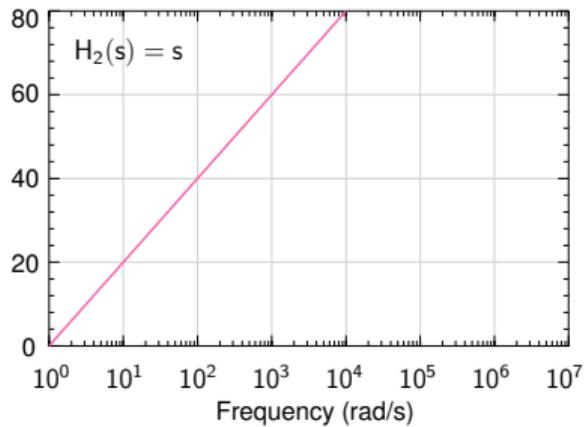
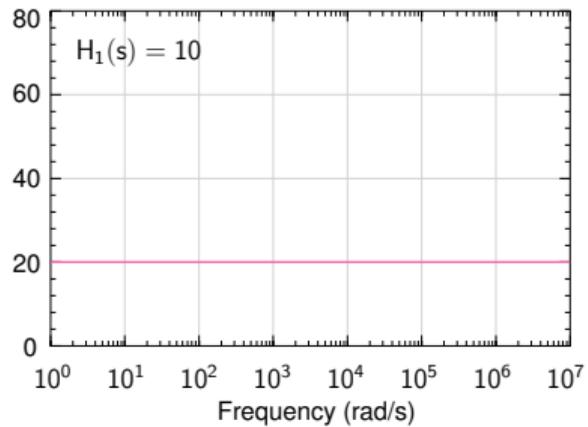
$$H_4(s) = \frac{1}{1 + s/p_2}, p_2 = 10^5 \text{ rad/s}.$$

We can now plot the magnitude and phase of  $H_1$ ,  $H_2$ ,  $H_3$ ,  $H_4$  *individually* versus  $\omega$  and then simply add them to obtain  $|H|$  and  $\angle H$ .

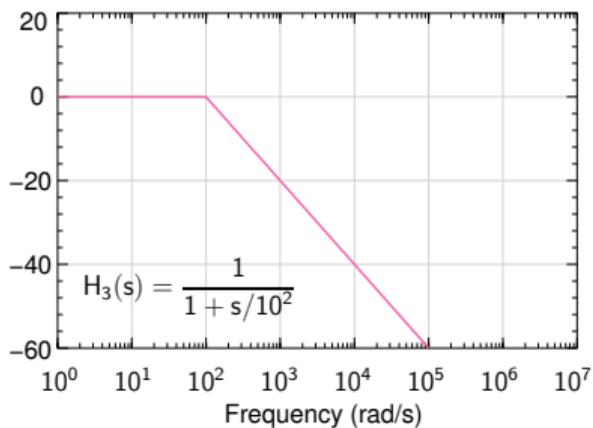
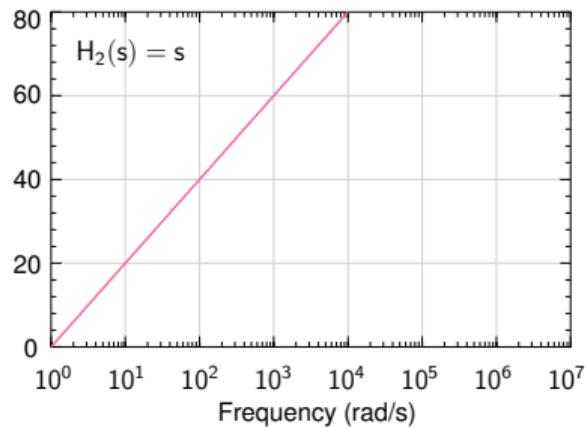
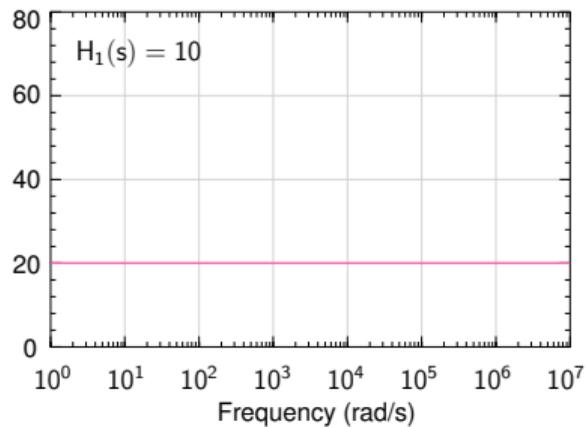
# Magnitude plot ( $|H|$ in dB)



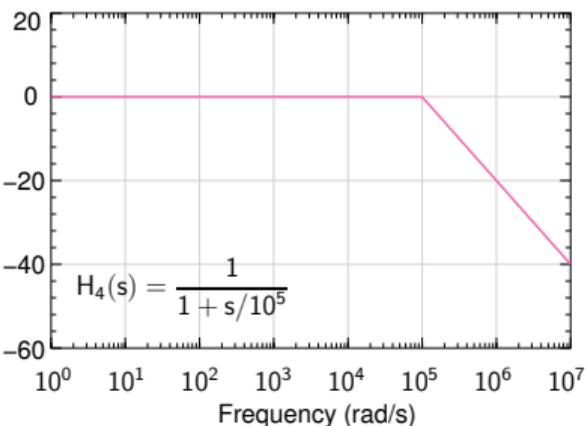
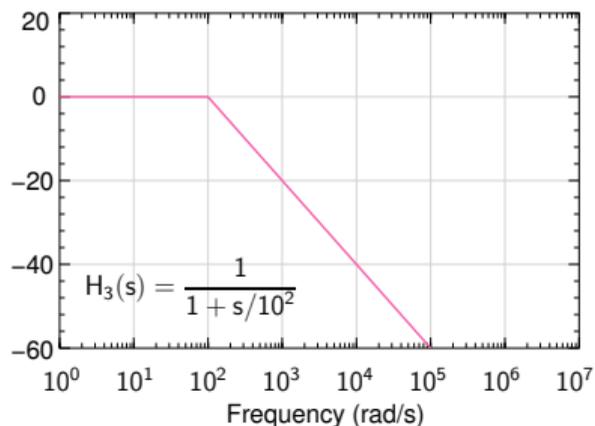
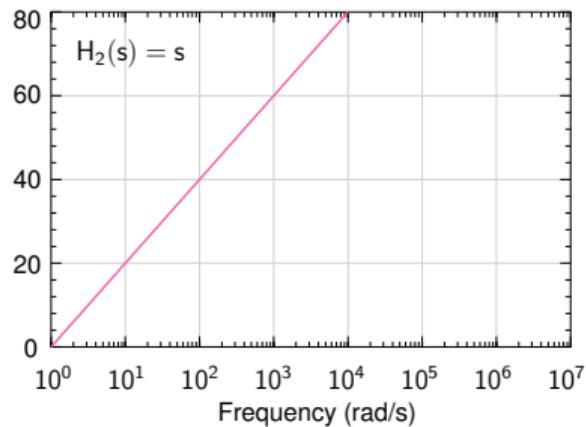
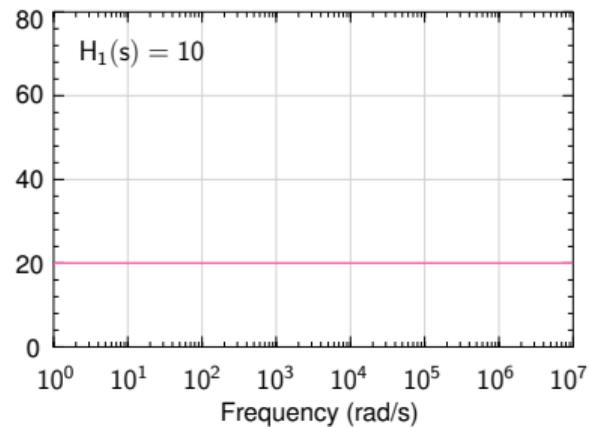
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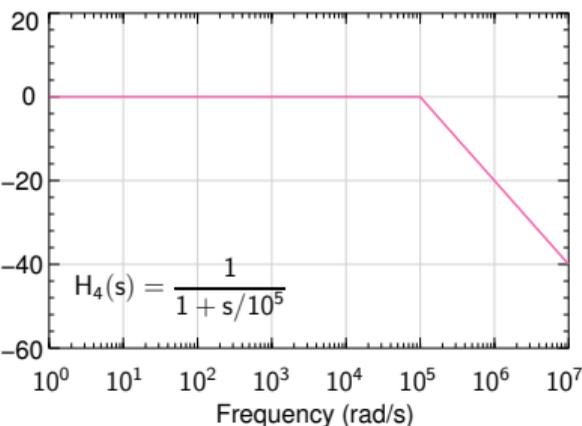
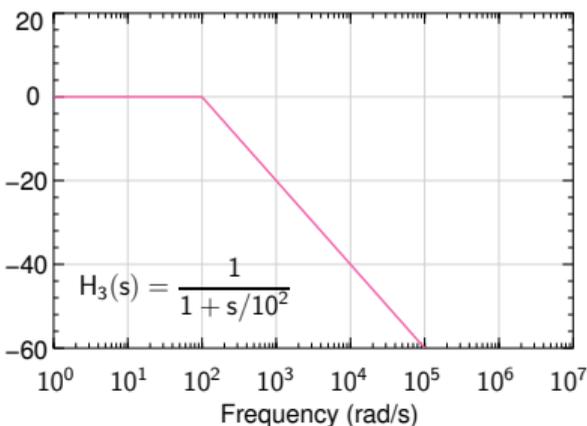
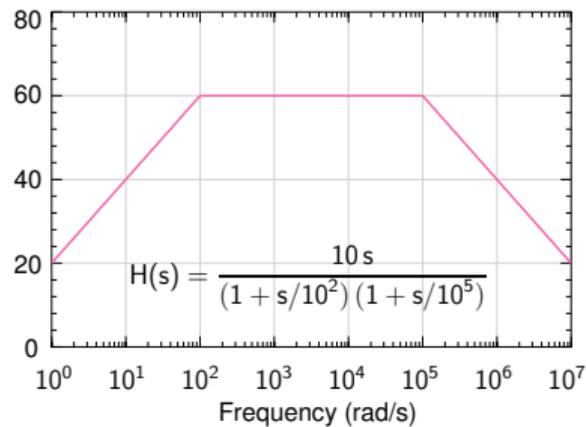
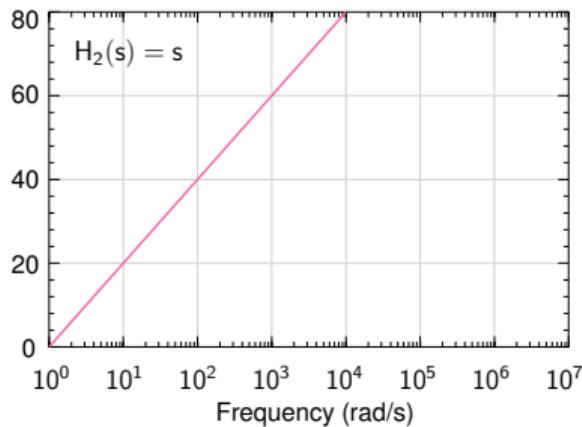
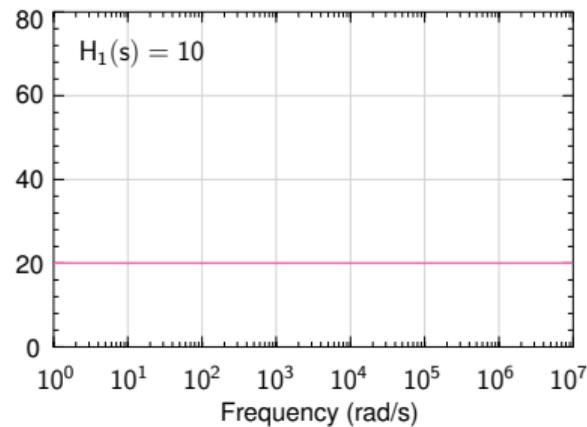
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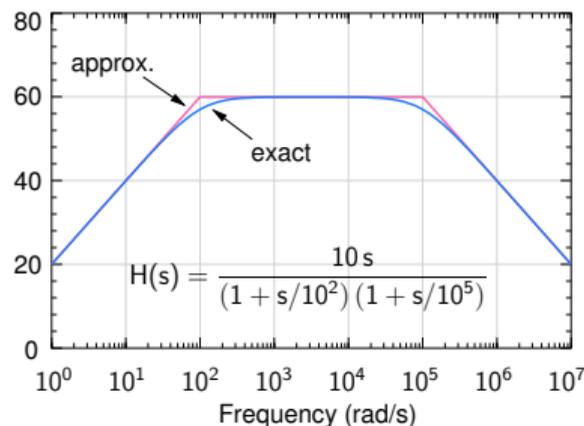
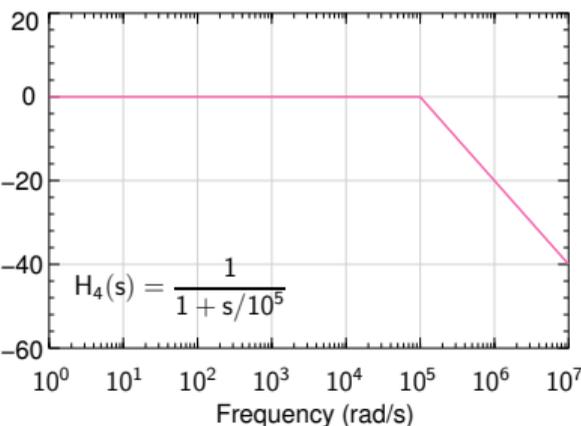
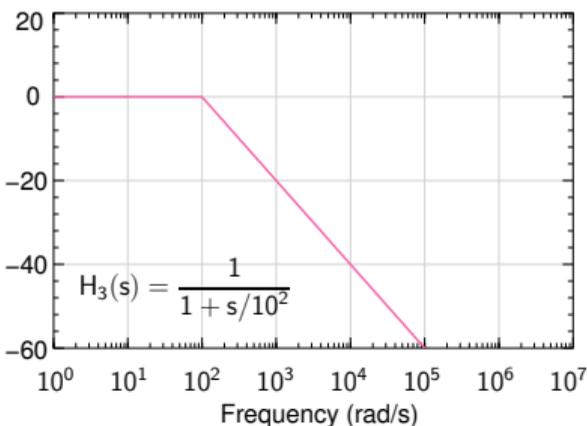
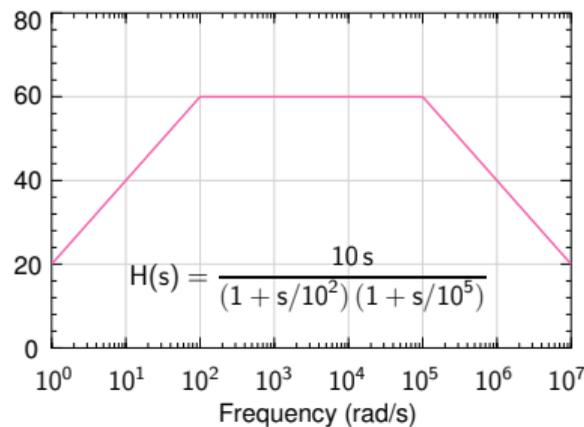
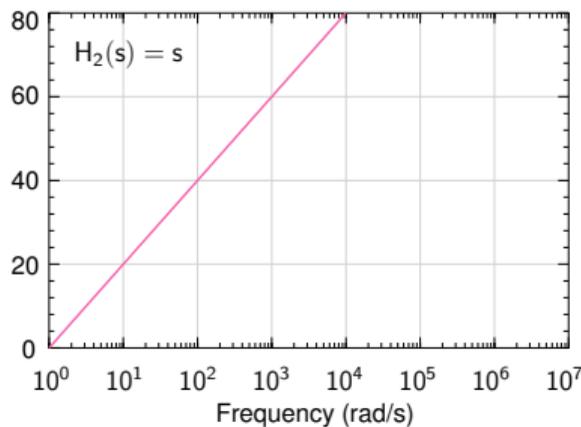
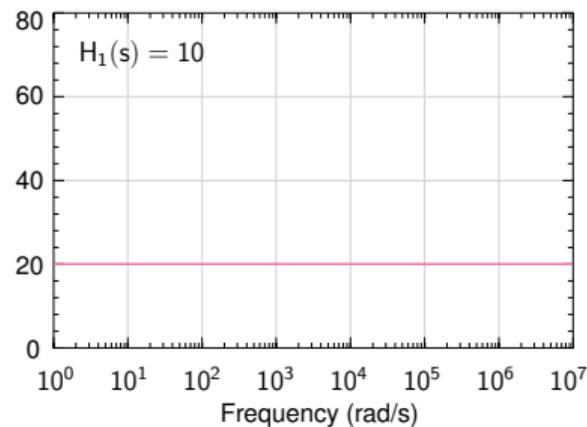
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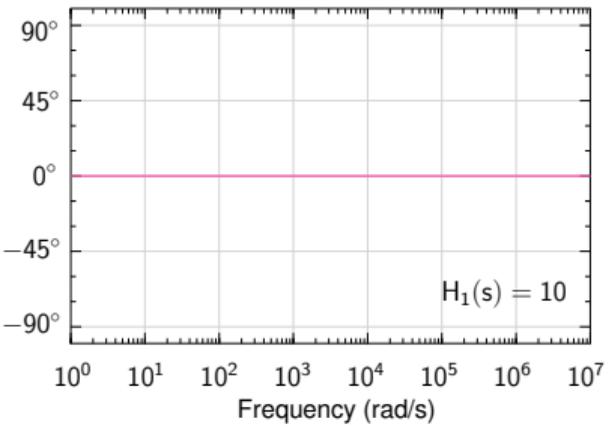
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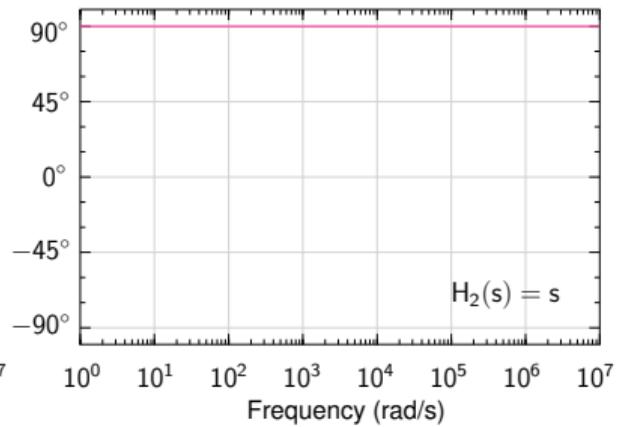
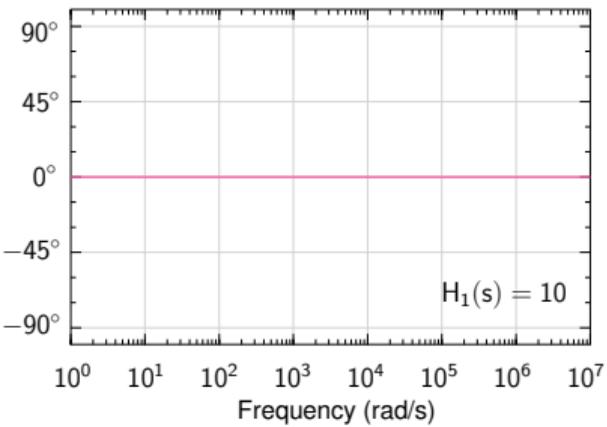
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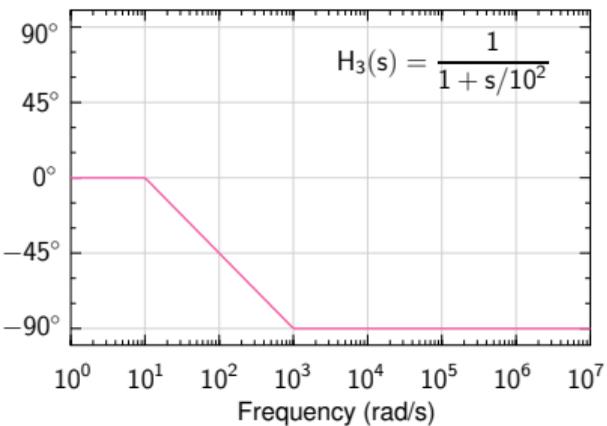
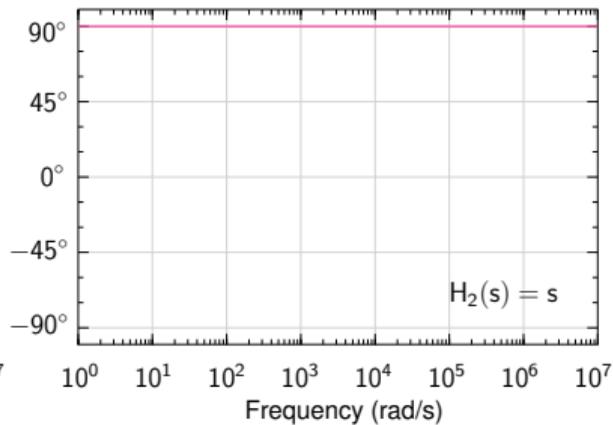
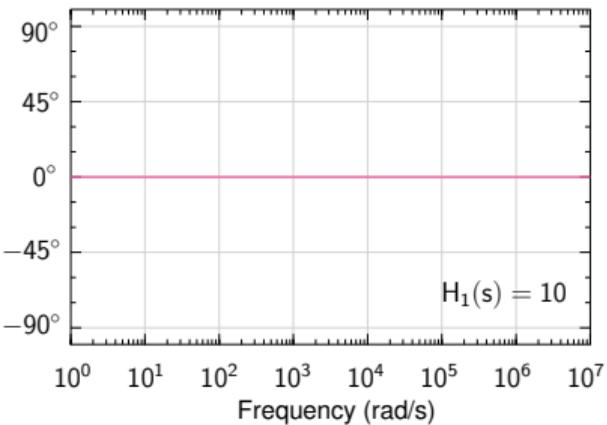
# Phase plot



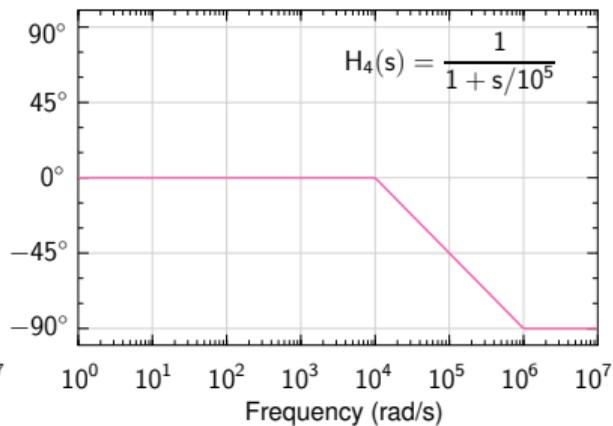
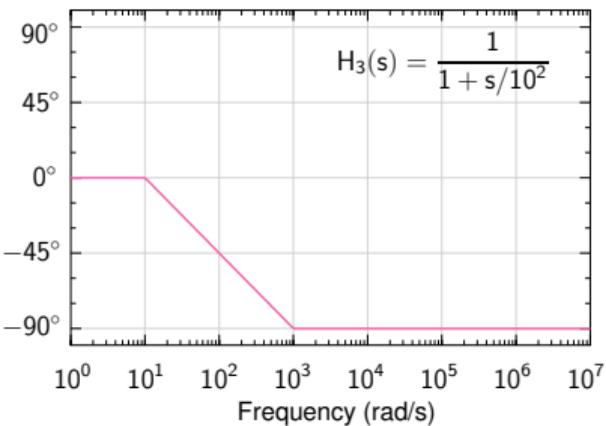
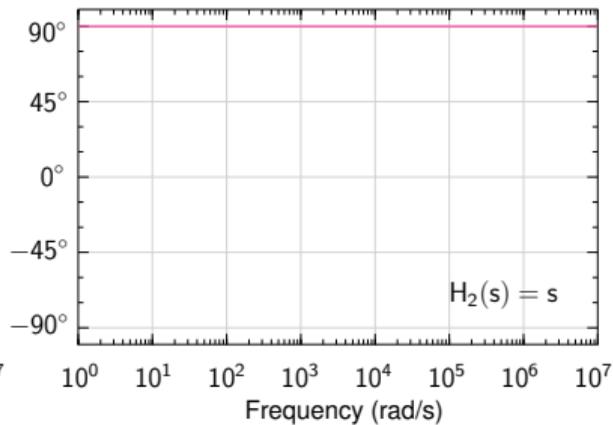
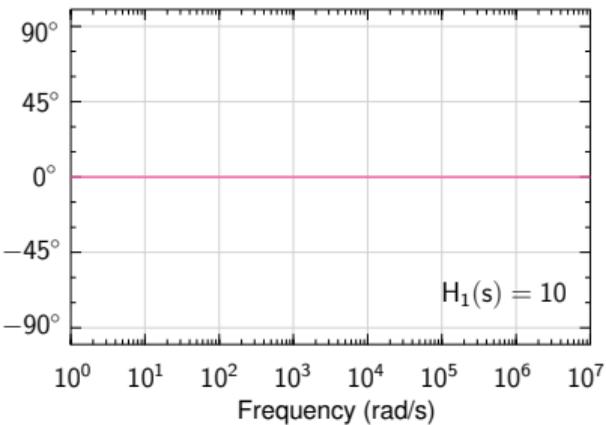
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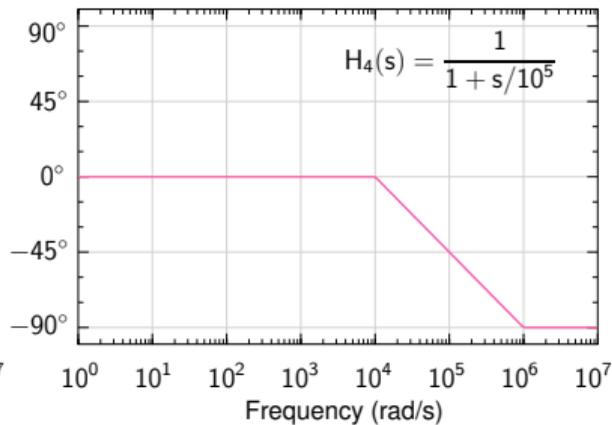
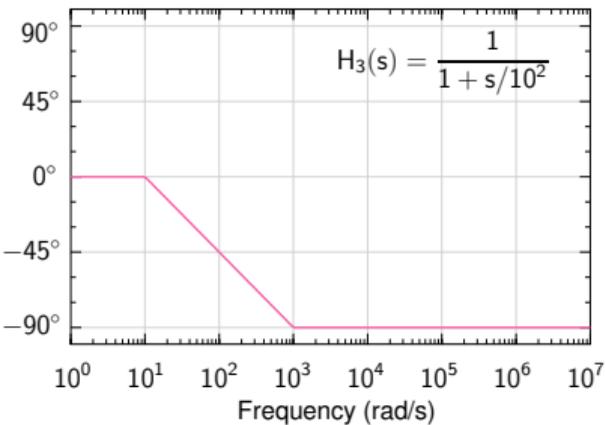
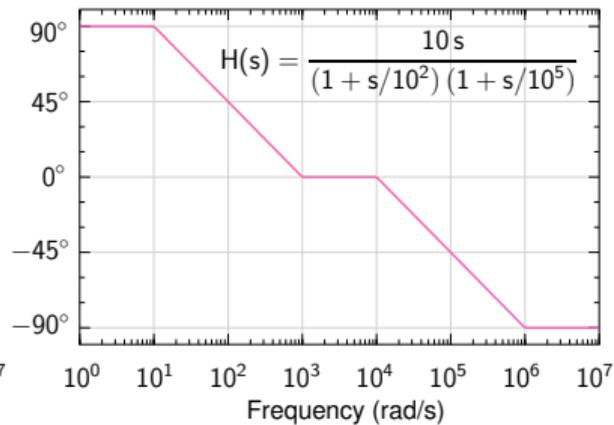
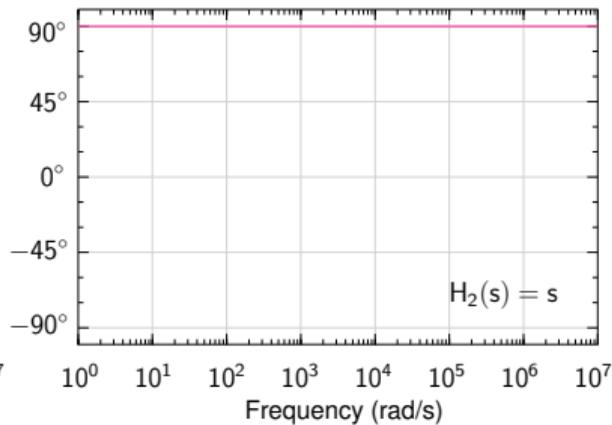
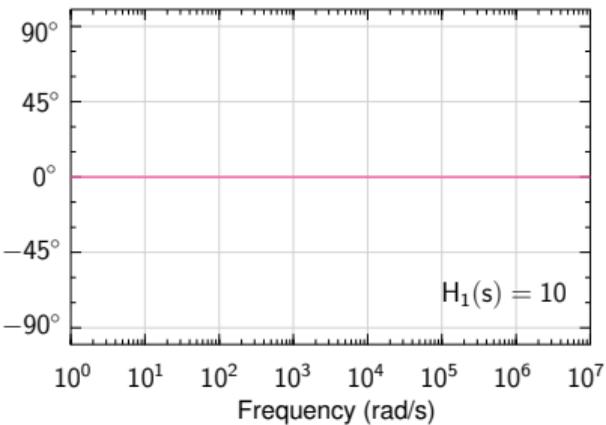
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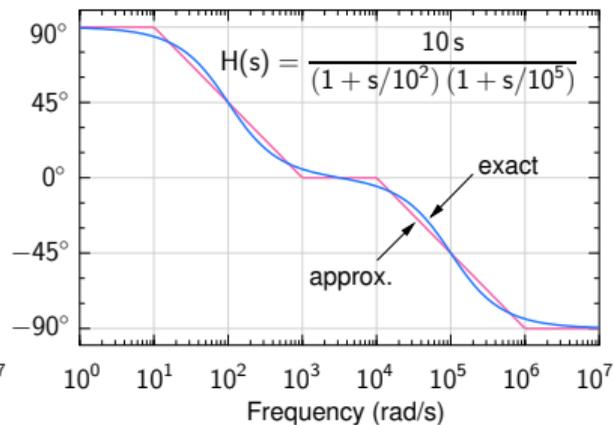
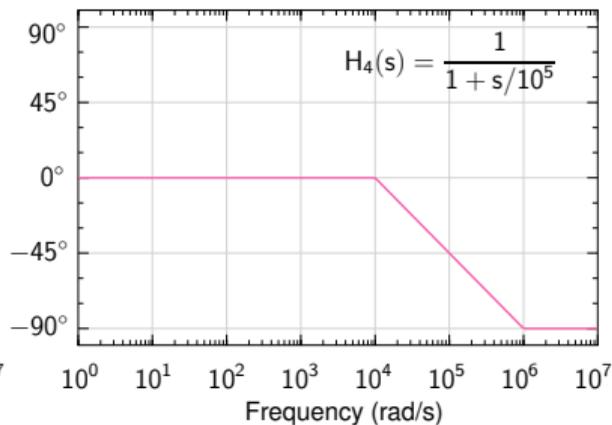
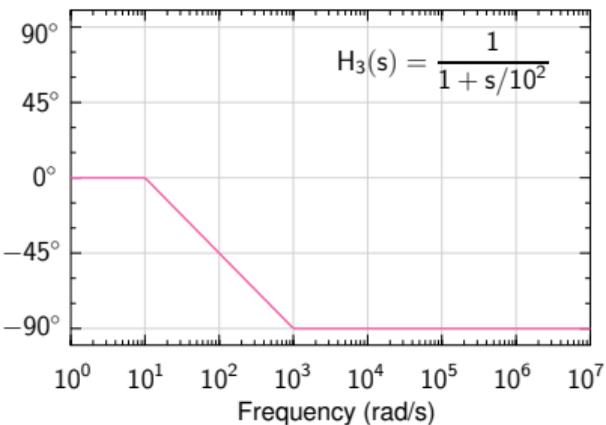
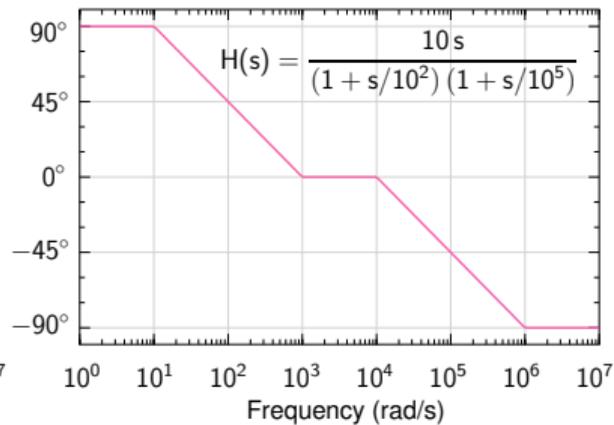
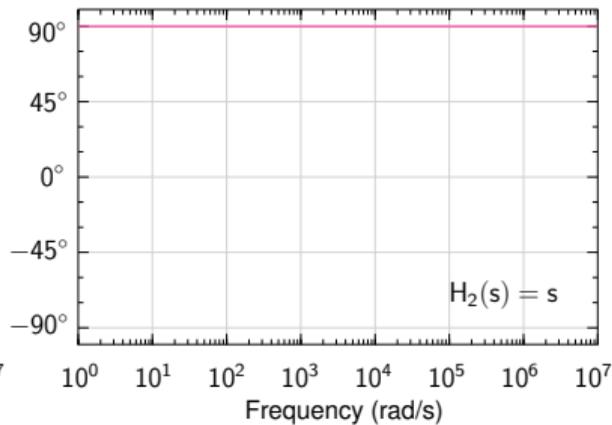
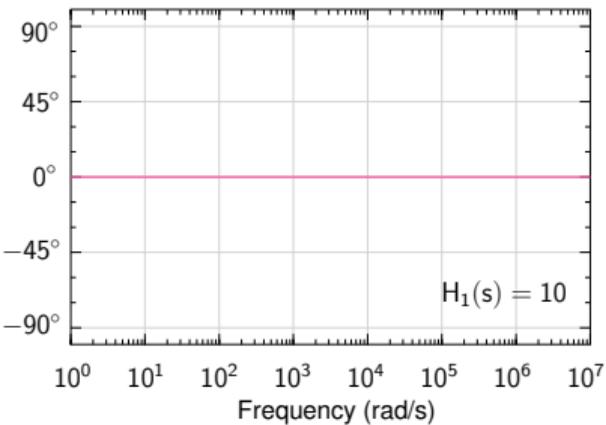
# Phase plot



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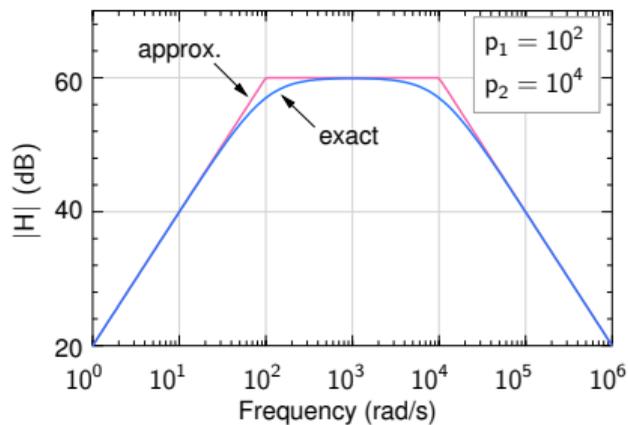
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- \* When the poles and zeros are not sufficiently separated, the Bode approximation should be used only for a rough estimate, followed by a numerical calculation. However, even in such cases, it does give a good idea of the *asymptotic* magnitude and phase plots, which is valuable in amplifier design.

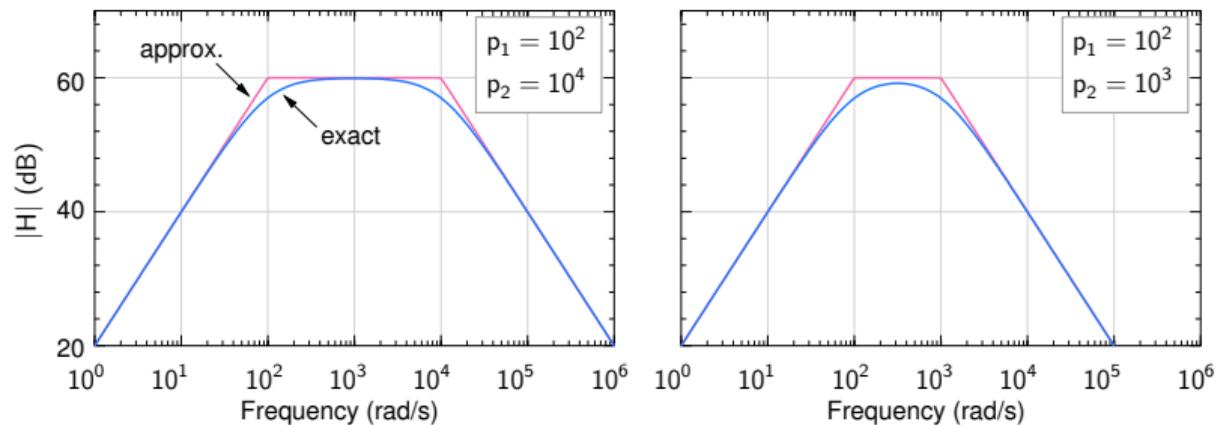
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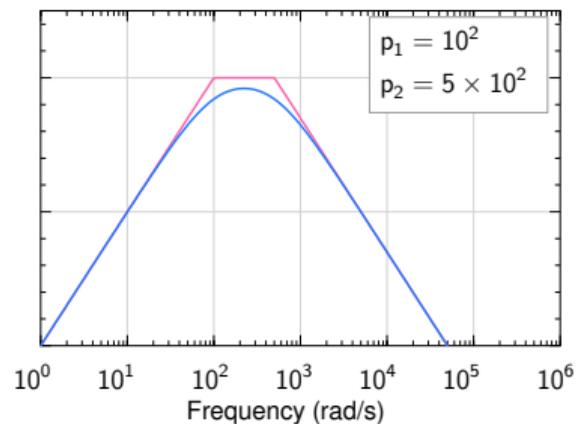
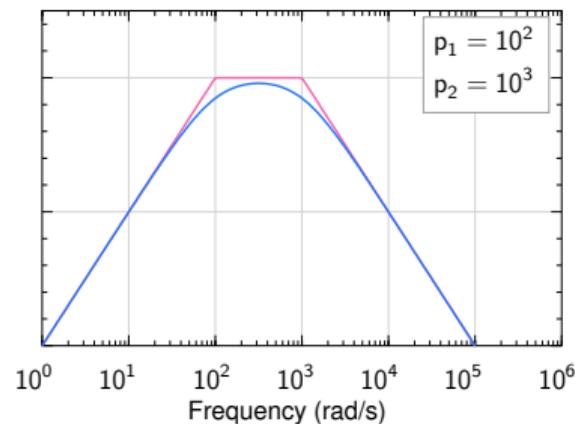
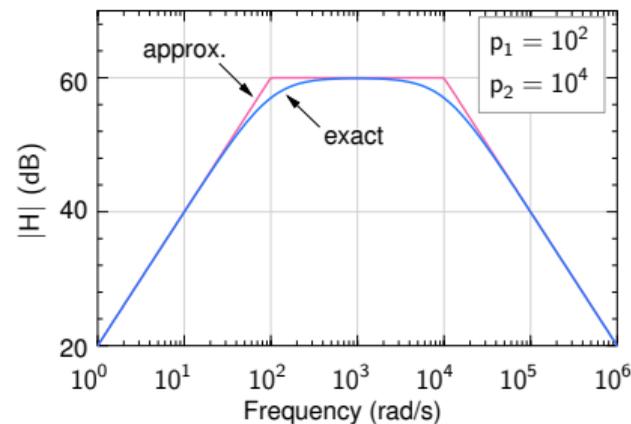
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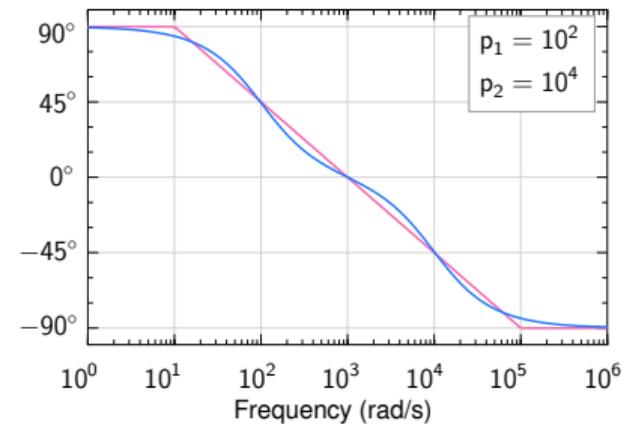
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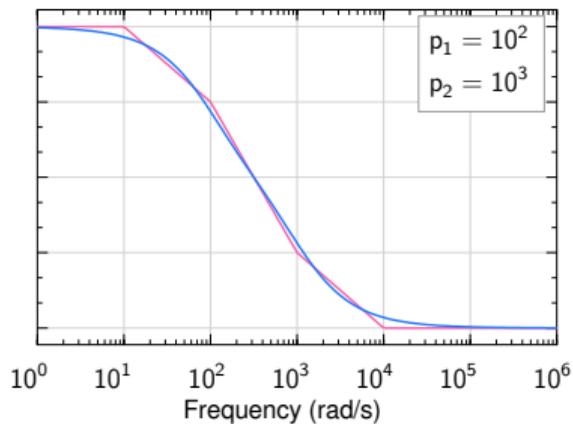
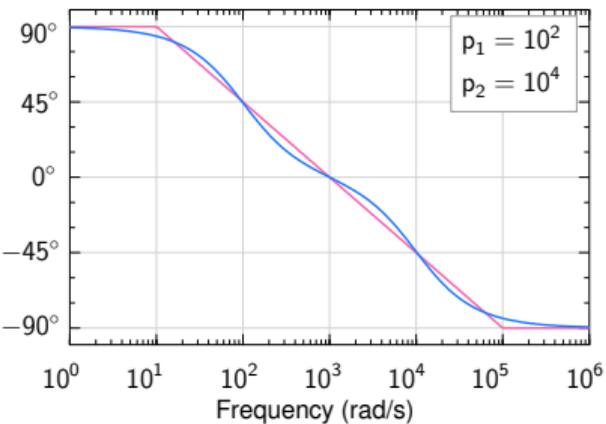
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